



Agile Model-Based Systems Engineering (aMBSE)

Bruce Powel Douglass, Ph.D.

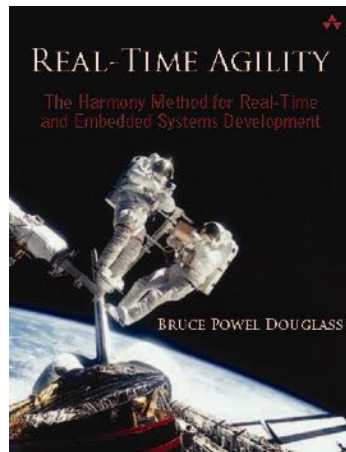
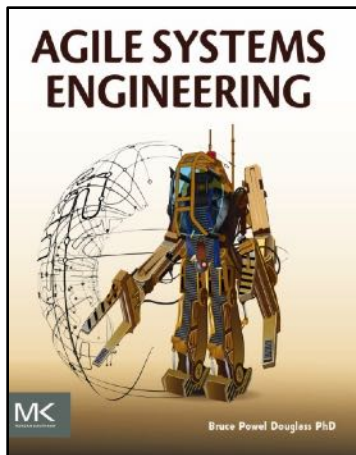
Chief Evangelist, Global Technology Ambassador

IBM IoT

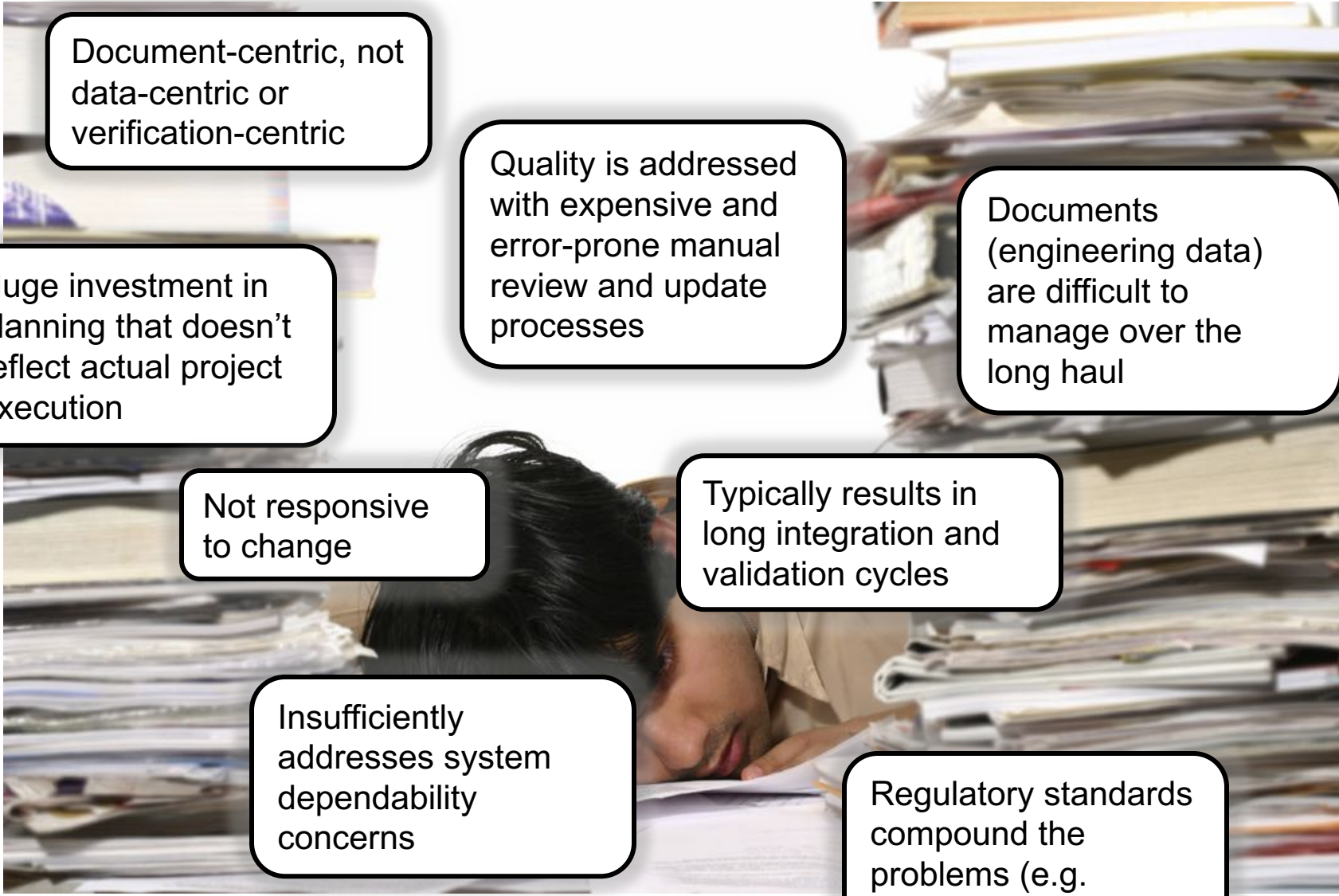
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IBM: www-01.ibm.com/software/rational/leadership/thought/BruceDouglass.html



State of the Practice for Systems Development



Document-centric, not data-centric or verification-centric

Huge investment in planning that doesn't reflect actual project execution

Quality is addressed with expensive and error-prone manual review and update processes

Documents (engineering data) are difficult to manage over the long haul

Not responsive to change

Typically results in long integration and validation cycles

Insufficiently addresses system dependability concerns

Regulatory standards compound the problems (e.g. DO0178, IEC 62304)

Key Concepts for Agility

Improve quality through *continuous feedback*

Verification

- Formal analysis
- Review
- Testing via execution or simulation

Validation: Customer feedback (*meet the need*)

- Correctness
- Appropriateness
- Usability

Dependability: Analysis of safety, reliability, & security

Primarily build *executable things*
Verify them continuously
This means MODELS

Efficiency through

- Concentrate on high-value tasks
- Avoid rework
- Paying attention to how you're doing against goals
 - Project retrospective
 - Risk management

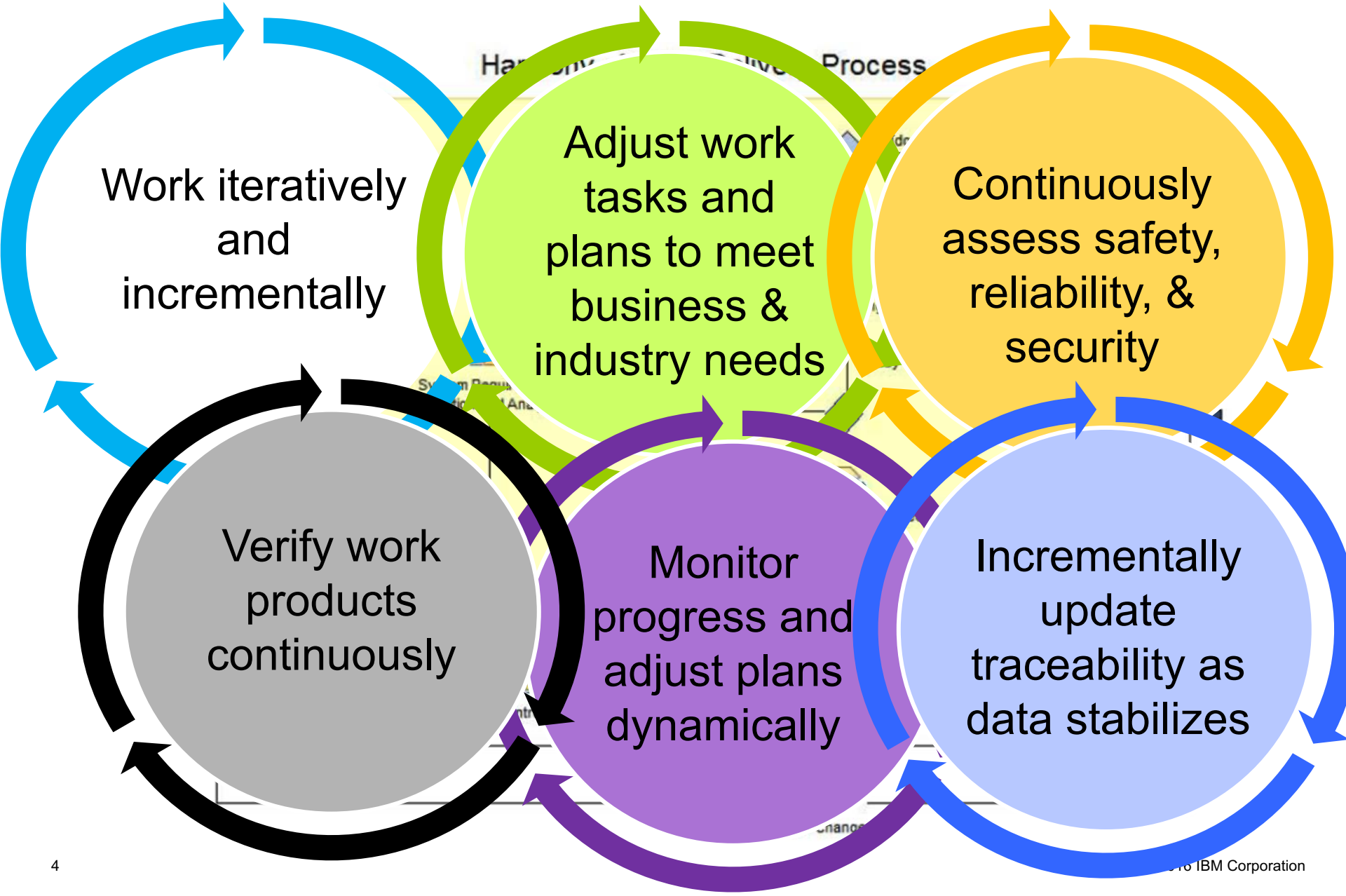
Active and continuous risk mitigation
Monitor project success

Planning

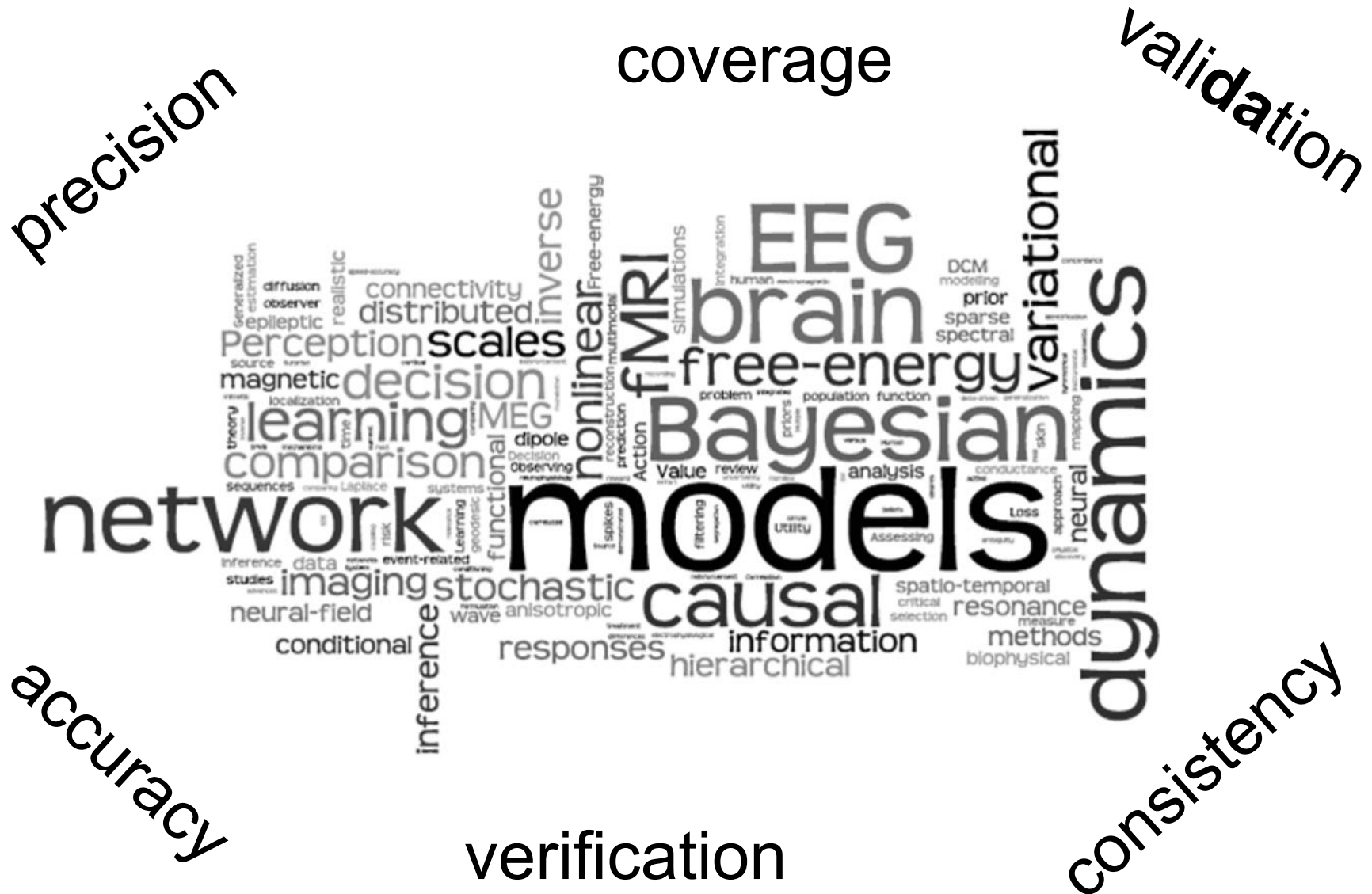
- Don't plan beyond the fidelity of the information you have
- Plan enough but not more than that
- Adjust plans based on "truth on the ground" (metrics)

Dynamic planning
Responsive to Change

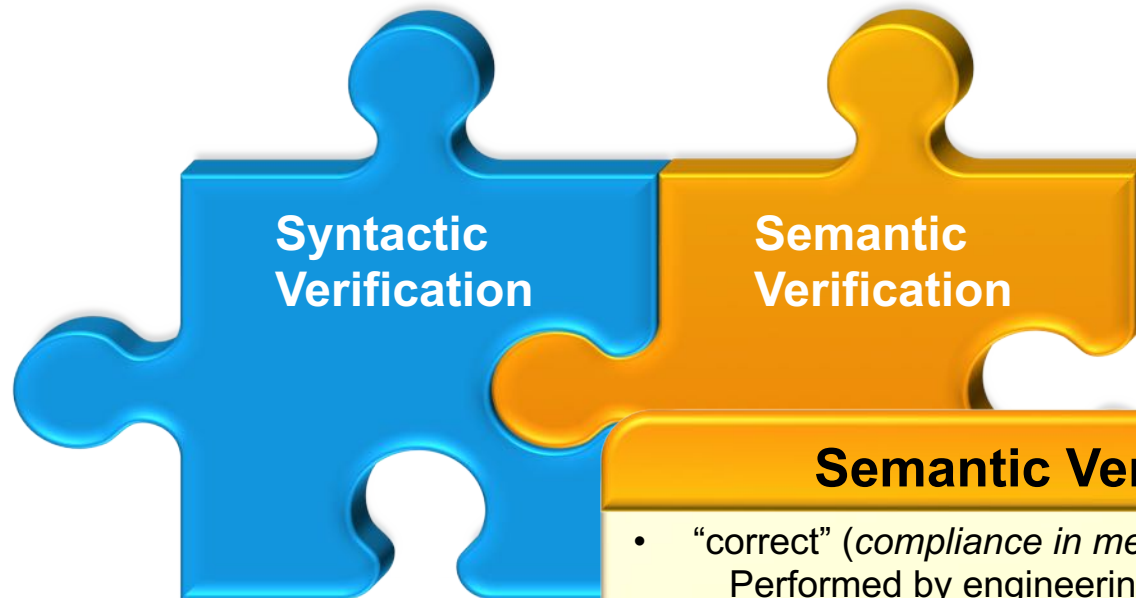
What does “agile” mean for Systems Engineering?



Computable models are essential for Agile MBSE



What do we mean by “verification”?



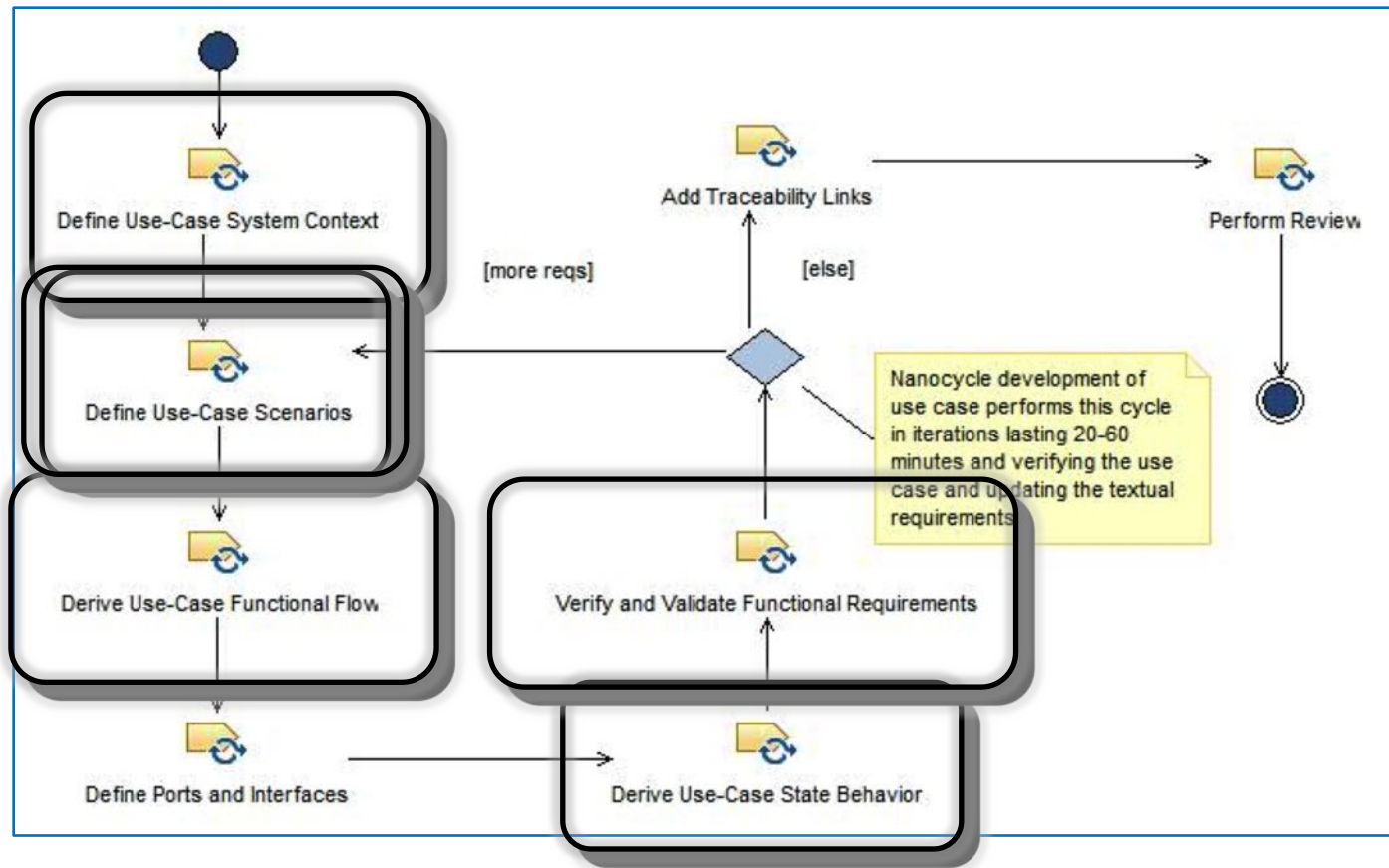
Syntactic Verification

- “well-formed” (*compliance in form*)
Performed by quality assurance personnel
- **Audits** – work tasks are performed as per plan and guidelines
- **Syntactic review** – work products conform to standard for organization, structure and format

Semantic Verification

- “correct” (*compliance in meaning*)
Performed by engineering personnel
- Three basic techniques
- **Testing** – requires executability of work products, impossible to fully verify
- **Formal methods** – strongest but hard to do and subject to invariant violation
- **Semantic review** (subject matter expert & peer) – most common, weakest means

Scenario Driven Use Case Construction / Verification



Making it Agile

Loop

Loop

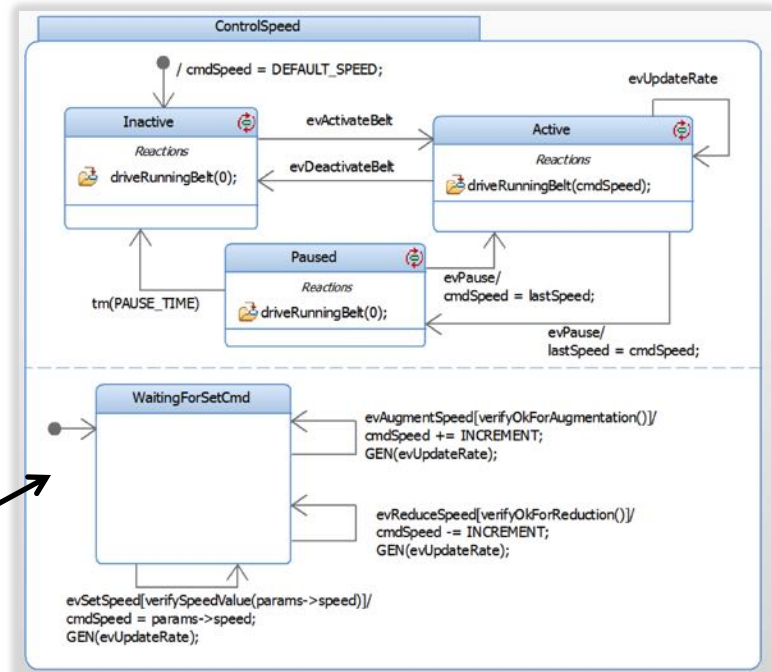
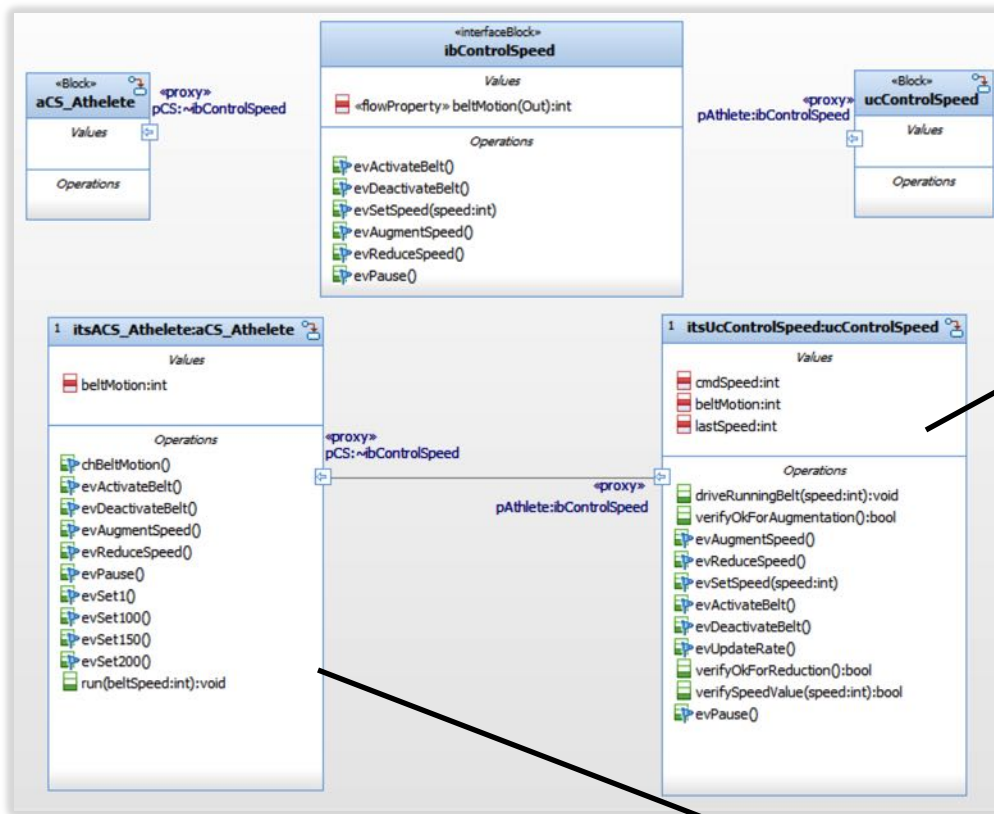
< 1 hr

Conceptualize requirement aspect
Incrementally augment model
Verify

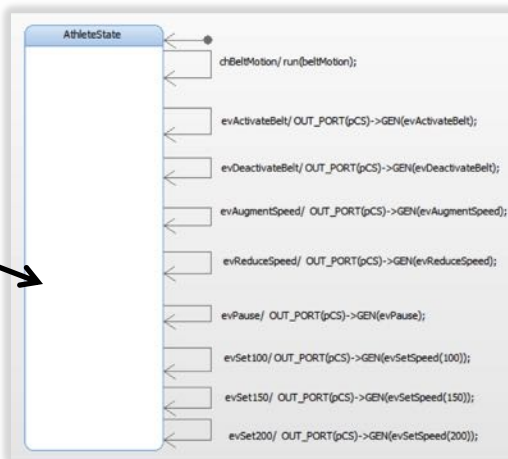
Repeat until all requirements added

Repeat for all use cases

High Fidelity Models are verifiable



... and may be built and verified incrementally, enabling agility



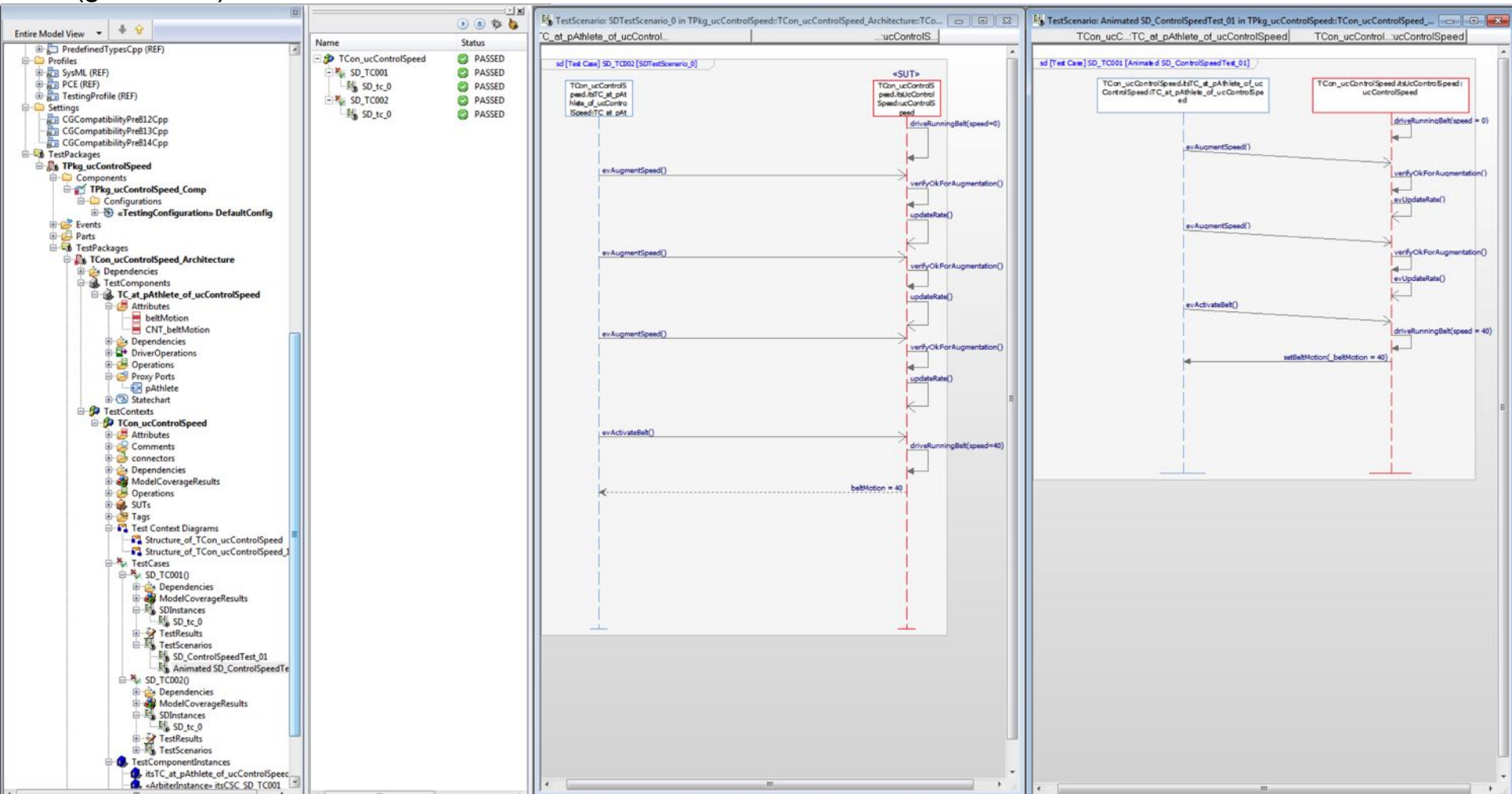
Verification may be manually done or via Test Conductor

Test Architecture
(generated)

Test outcome

Test case definition

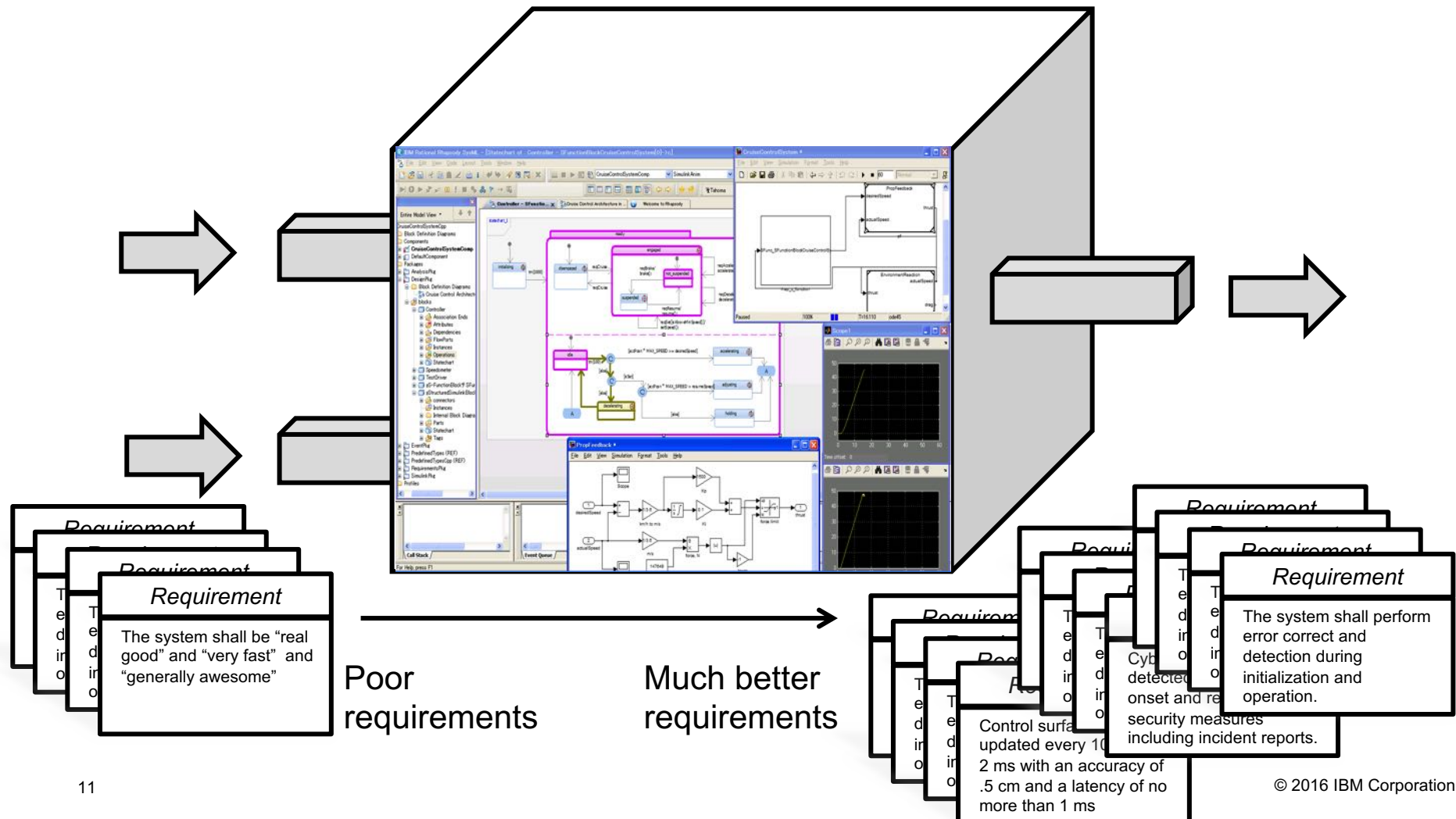
Test case test case result



Test Conductor implements the OMG UML Testing Profile standard

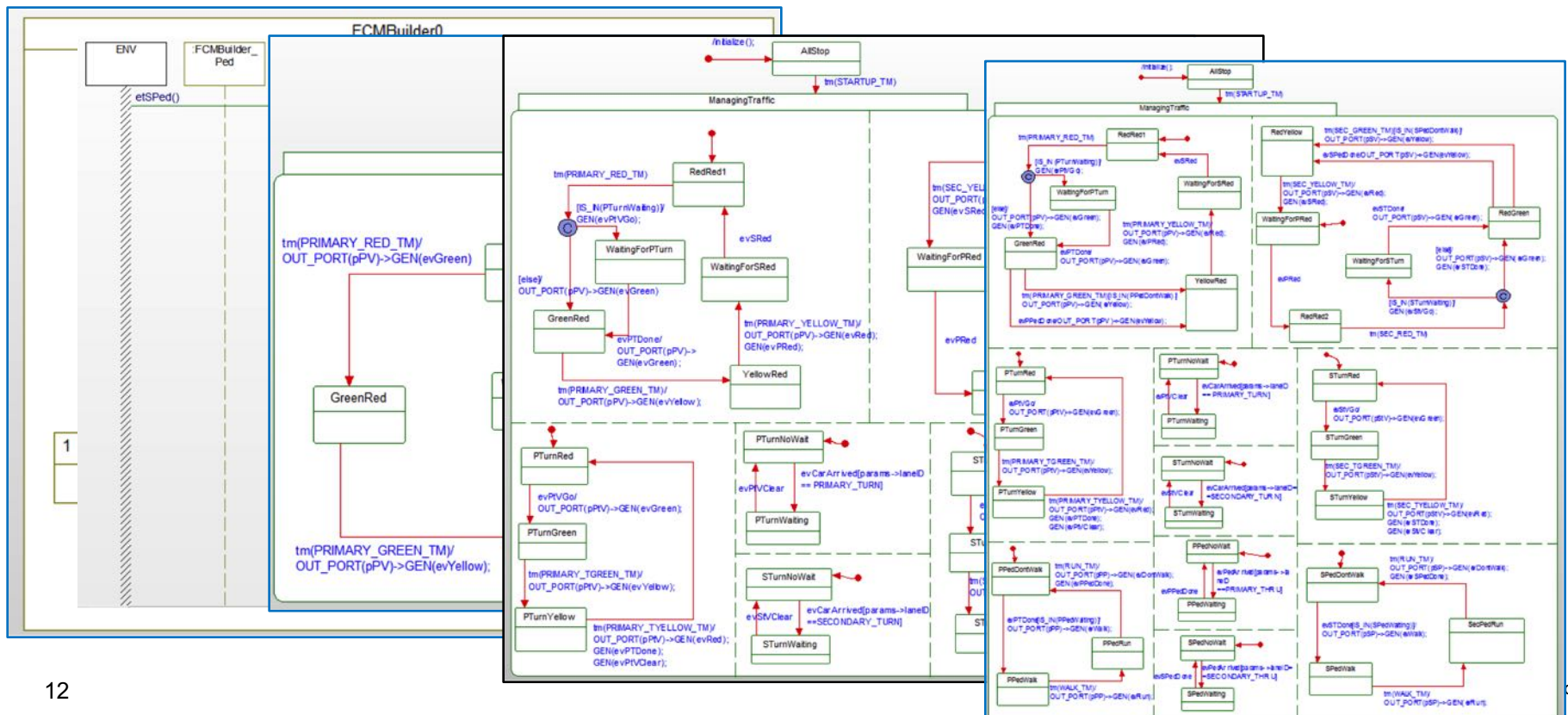
Functional Analysis via Executable Requirements?

- A functional requirement is a *specification of an input-output control or data transformation or flow*
- A quality of service requirements is a specification of how well a control or data transformation is achieved



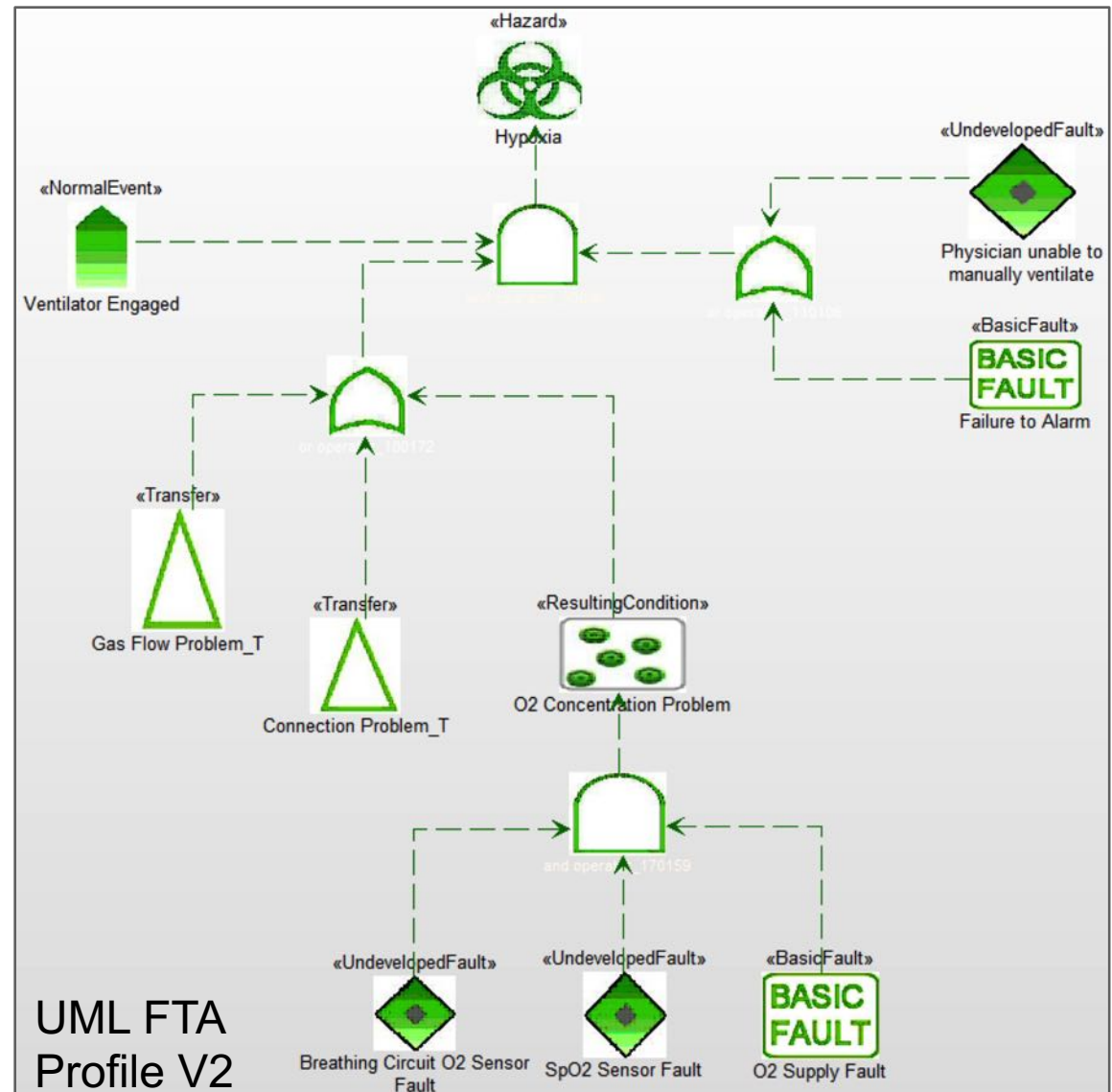
Test-Driven Development for MBSE Work Products

- The principle behind TDD is to develop and apply test cases as you develop a system to demonstrate that it is correct
 - This is done in parallel with the system development and *not* ex post facto
 - This is about *defect avoidance* not so much *defect identification and repair*
- TDD applies to the development of complex system use case, architecture and design models

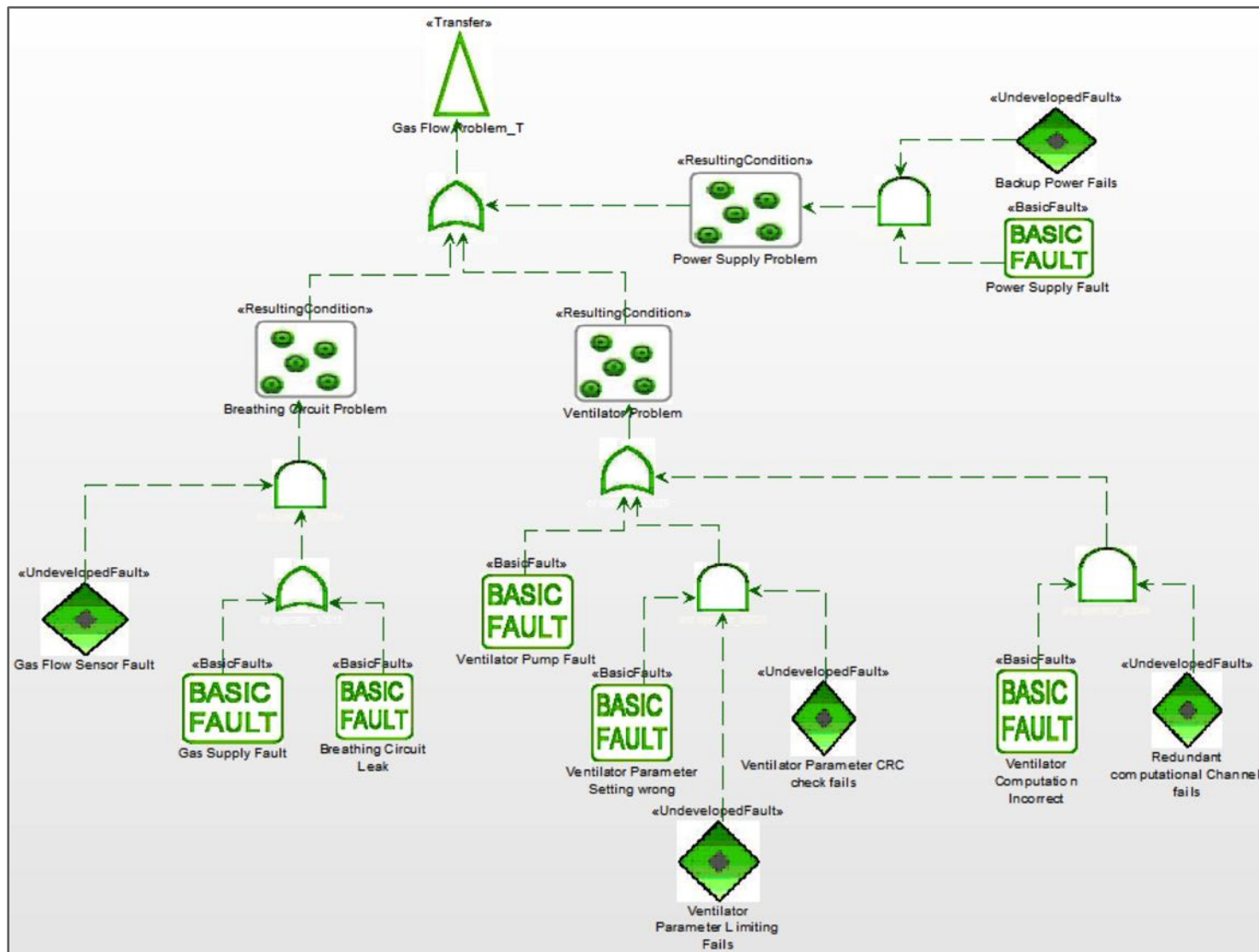


Integrated Safety and Reliability Analysis

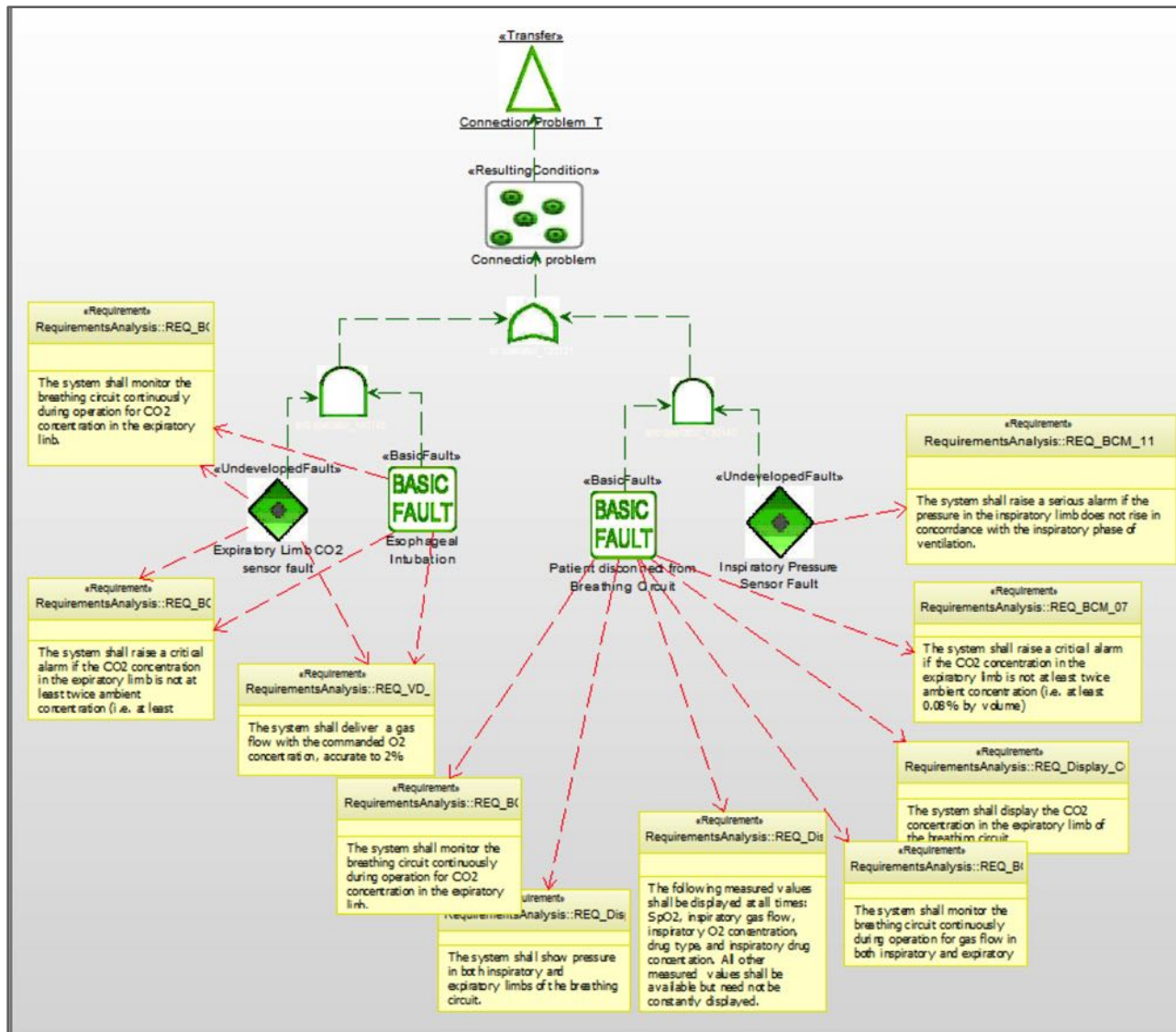
- Fault Tree Analysis (FTA) connects *hazards* with logical combinations of events, conditions, errors, and faults
- Allows you to identify
 - Effects of combinations of conditions and events on safety
 - Safety measures
 - Safety requirements
 - Impacts of architectural, technological, and design choices on safety

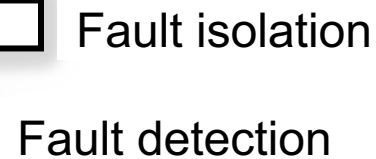


Integrated Safety and Reliability Analysis



Mapping Requirements to Fault Tree Analysis

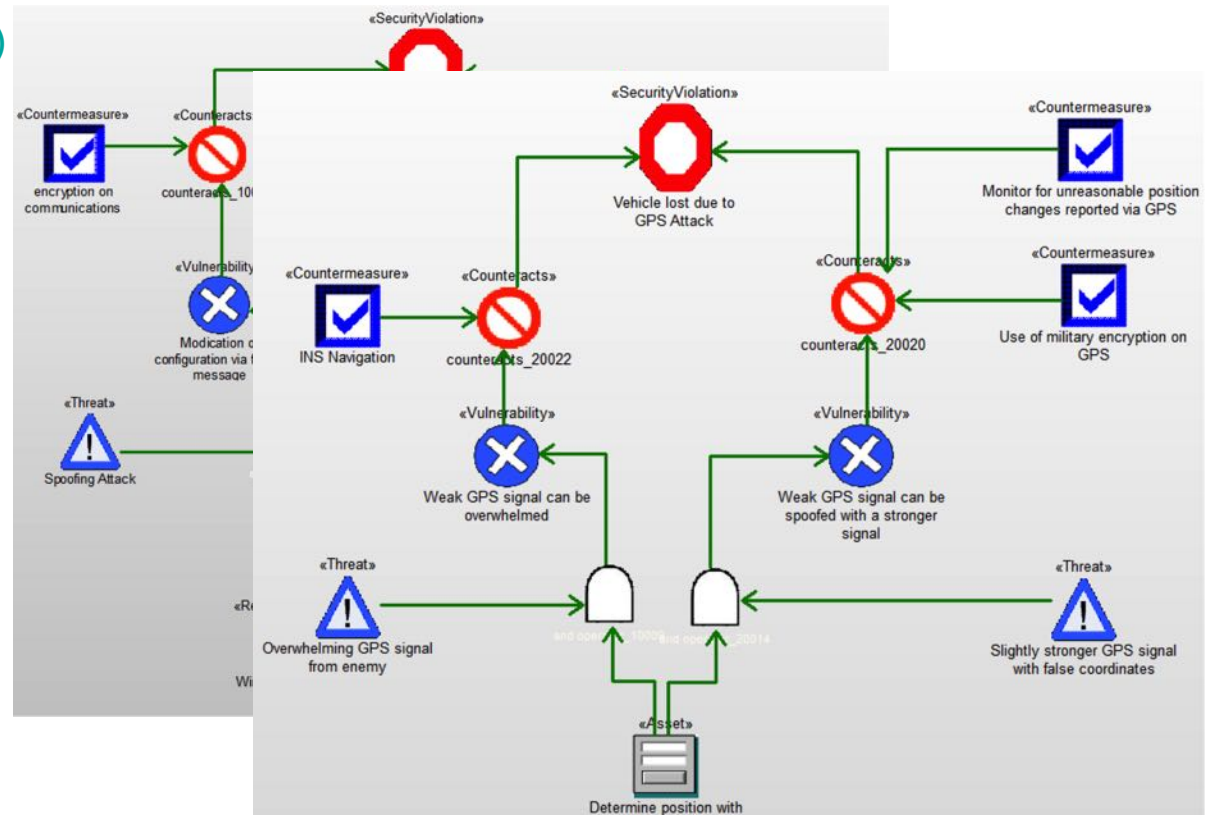




Model-Based Threat Analysis

■ Security Analysis Diagram (SAD) is like a Fault Tree Analysis (FTA) but for security, rather than safety

- It looks for the logical relation between assets, vulnerabilities, attacks, and security violations
- Permits reasoning about security
 - What kind?
 - How much?
 - Risk assessments
 - Cost of security penetration
 - Adequacy of countermeasures
 - Who has access to assets



Threat Analysis Table

Asset value is the value of the asset to be protected (1=very low, 10=very high).										
Likelihood is the probability of the attack (1=very low, 10=certain).										
Reproducibility refers to how easy it is to reproduce the attack (for example, does it depend on timing or other circumstances?) (1=hard, 10=very easy).										
Exploitability refers to how easy it is to launch the attack (1=very easy, 10=very hard).										
Breadth is the a measure of the extent of the attack. How widespread is it or how many systems are affected? (1=few, 10=very many).										
Discoverability is how easy is it for outsiders to find out about and exploit the vulnerability (1=very easy, 10=very hard).										
Threat Priority is the product of the above values and is used to prioritize the threats for countermeasures.										
These are in the range of 1 - 10										
Asset	Vulnerability	Threat Vector	Asset Value	Likelihood of attack	Reproducibility	Exploitability	Breadth	Discoverability	Threat Priority	Countermeasure
Patient Demo-graphic Data	Access via Ethernet	Input validation weak	4	7	9	4	1	9	9072	Internal encryption
	Access via USB	Auto-execution of USB SW	4	7	9	3	1	9	6004	Internal encryption
	Access via packet snooping	Messages sent in plain text	4	7	9	5	1	8	10080	Message encryption



Documents are generated automatically from engineering work in models

Typical auto-generated documentation includes

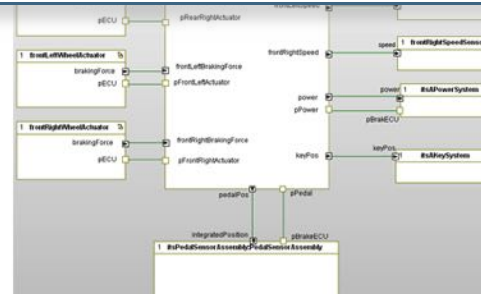
- **Traceability matrix**
- **Hazard Analysis**
- **FMEA / FMECA**
- **Cyberphysical threat analysis table**
- **Interface Control Document**
- **Design Description**
- **Architecture Notebook**

[illegible]

lysis

Fault tolerance time units	Probability	Severity	Risk	Safety integrity level
minutes	1.00E-02	8	8.00E-02	3
milliseconds	1.00E+04	4	3.00E+04	3
minutes	1.00E+05	4	4.00E+05	4
minutes	1.00E+04	2	2.00E+04	2
minutes	1.00E+03	4	4.00E+03	4
minutes	1.00E+05	5	4.00E+05	5

Asset	Vulnerability	Threat Vector	Asset Value	Likelihood of attack	Reproducibility	Exploitability
Patient Demographic Data	Access via Ethernet	Input validation weak	4	7	9	4
	Access via USB	Auto-execution of USB SW	4	7	9	3
	Access via packet snooping	Messages sent in plain text	4	7	9	5



Harmony Agile MBSE Delivery Process

Rational. Method Composer

Search this Site:

Team (IBM)

- Welcome to the Rational Harmony Agile Model-Based Systems Engineering
- Getting Started
- Delivery Processes
- Practices
- Roles Sets
- Tasks
- Work Products
- Guidance
- Tools
- Release Info

Welcome to the Rational Harmony Agile Model-Based Systems Engineering

The Rational Harmony Agile Model-Based Systems Engineering (aMBSE) process is a delivery process for the development of systems engineering data and work product using both model-based systems techniques with UML and SysML but is at the same time agile and incorporates agile practices for improved quality and engineering efficiency.

Main Description

Harmony aMBSE
Agile Model-Based Systems Engineering

Stakeholder Requests

System Requirements

System Analysis

Architectural Analysis

Architectural Design

Handoff to downstream Engineering

Interdisciplinary Implementation

Iteration Backlog

Iteration Retrospective

Iteration (Month)

Nanocycle (Hour)

Daily Meeting

Generate Requirements

Update Dependability

Verify Engineering Data

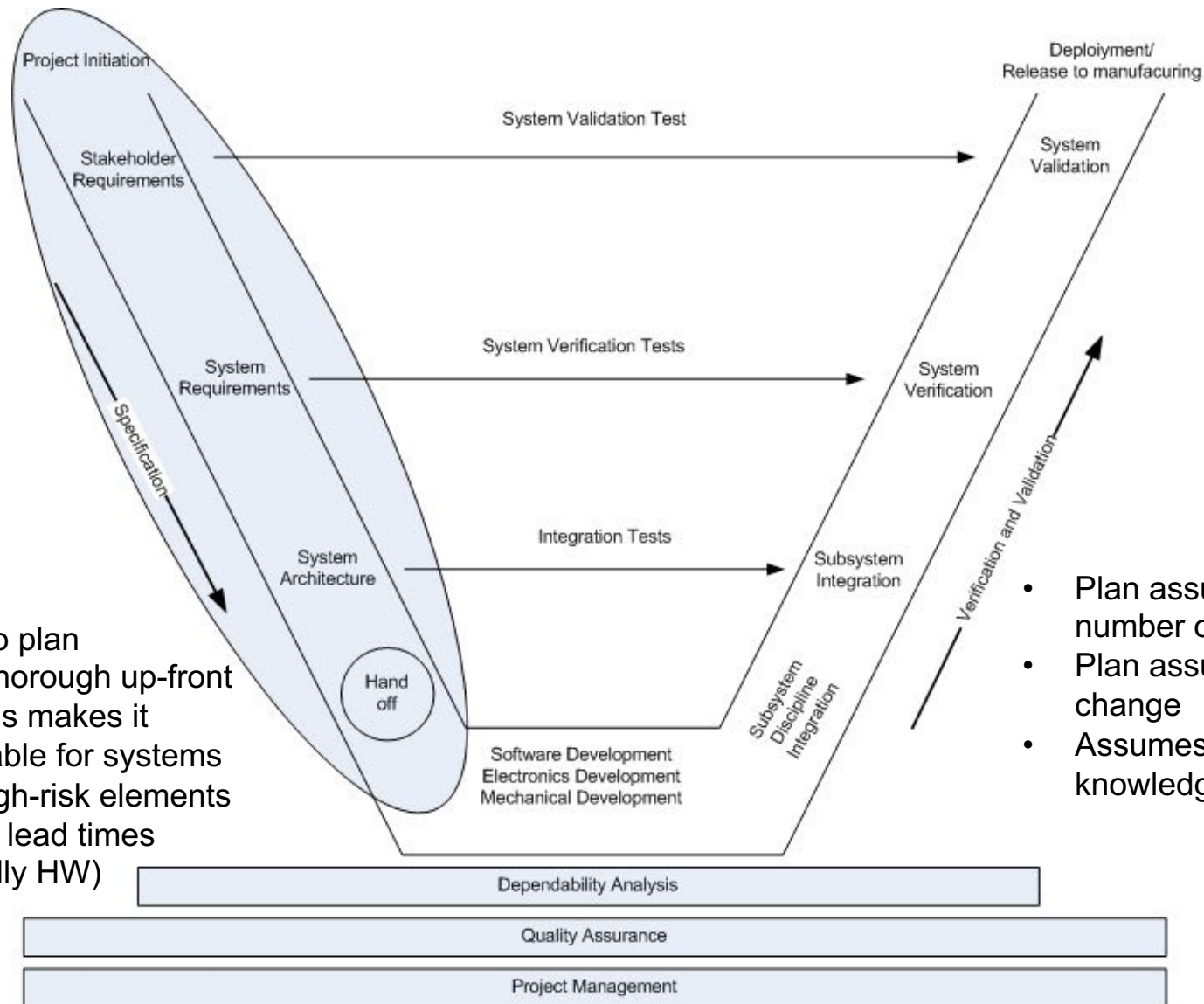
Use Case Modeling

UML and SysML

With the initial release of the UML in 1995, systems engineers had a standard language in which they could express requirements, architectures, designs, and other kinds of engineering data. However, there was widespread belief that the Unified Modeling Language (UML) itself was too "software oriented" for general use in systems engineering which led to the development and release of the Systems Modeling Language (SysML). UML and SysML provide a number of key advantages for the development of system engineering data:

- Precision of engineering data
- Data consistency across work products and engineering activities
- A common source for engineering truth
- Improved visualization and comprehension of engineering data
- Ease of integration of disparate engineering data
- Improved management and maintenance of engineering data

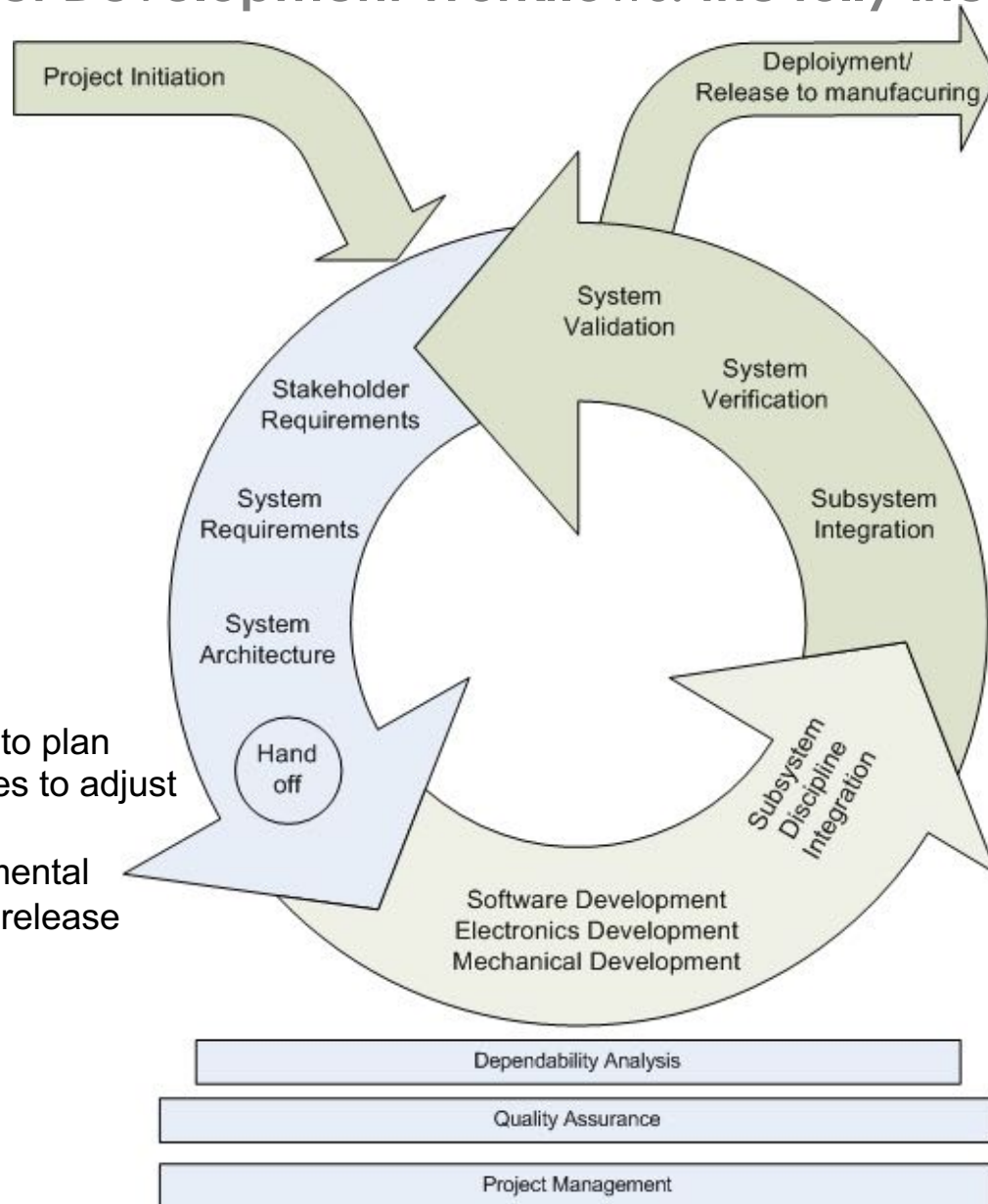
Overall Product Development Workflows: the standard V



- Easy to plan
- More thorough up-front analysis makes it applicable for systems with high-risk elements of long lead times (typically HW)

- Plan assumes small number of minor defects
- Plan assumes little or no change
- Assumes “infinite knowledge”

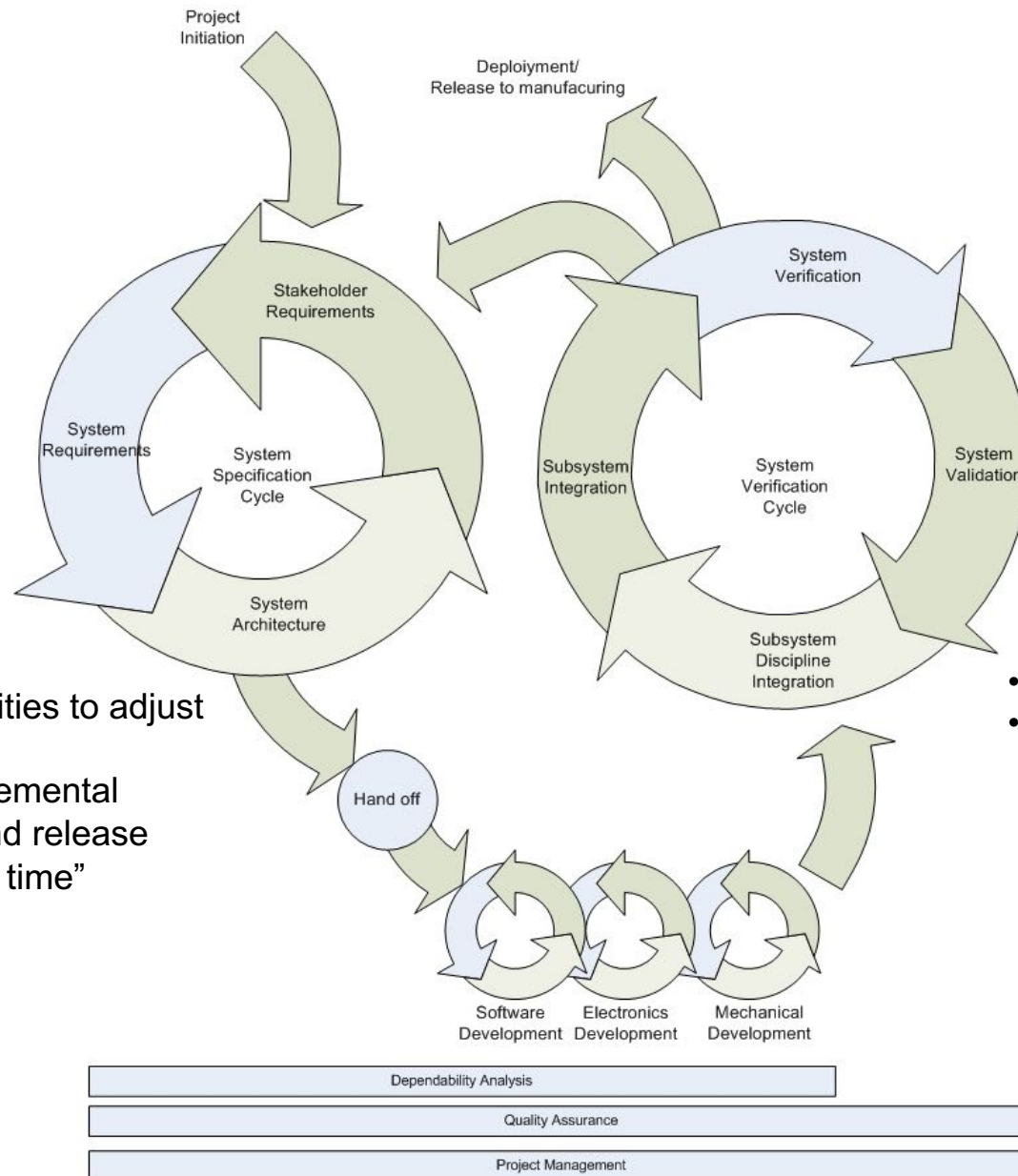
Overall Product Development Workflows: the fully incremental



- Relatively easy to plan
- Has opportunities to adjust plans
- Supports incremental verification and release

- Has “dead time” because different people are working on different activities
- May be inappropriate for high-risk items of long lead time (typically hardware)

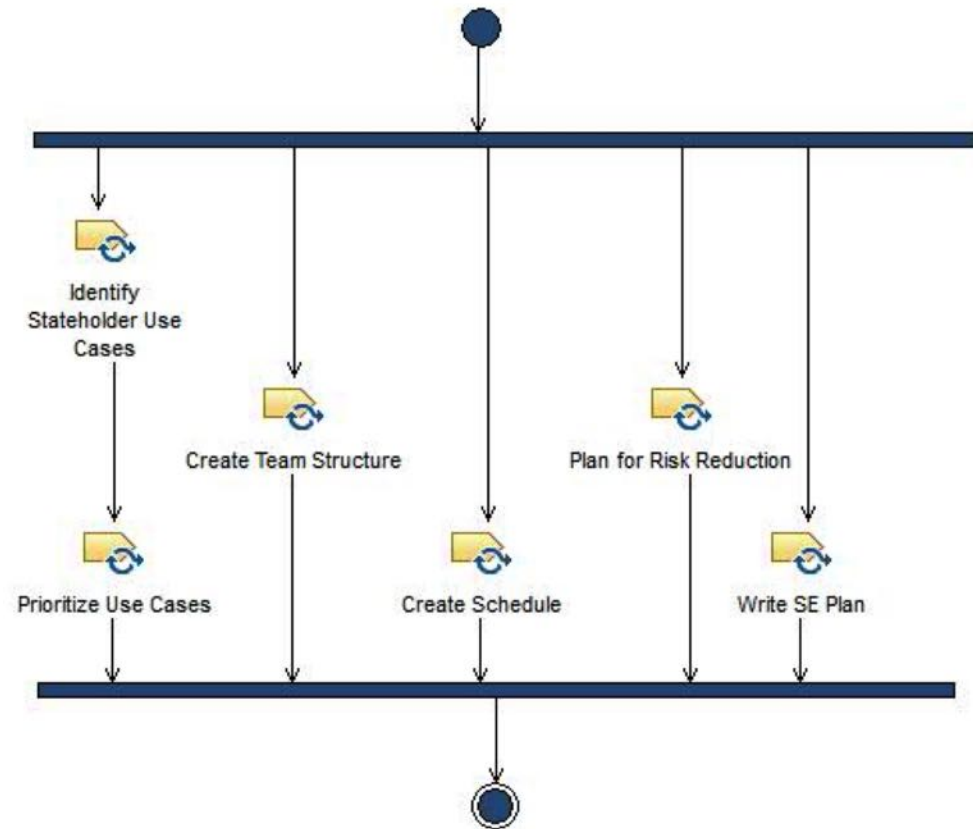
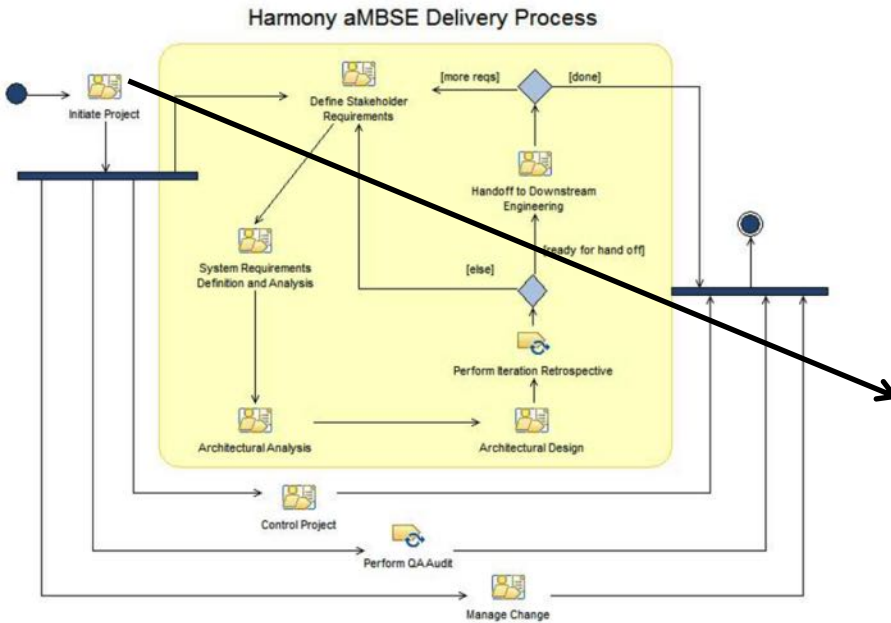
Overall Product Development Workflows: the hybrid agile V



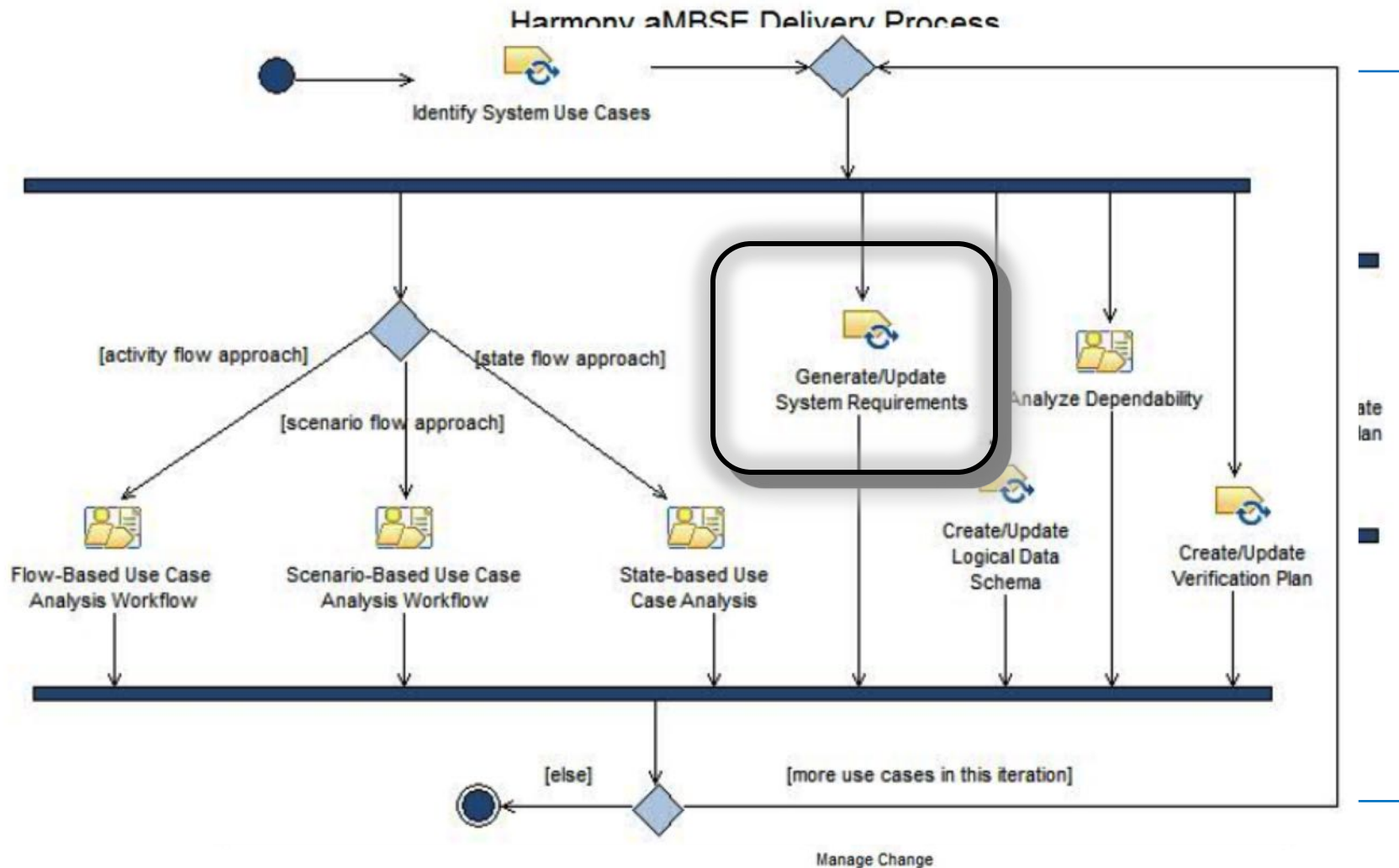
- Has opportunities to adjust plans
- Supports incremental verification and release
- Has no “dead time”

- Complex to plan
- Requires work to keep work activities coordinated

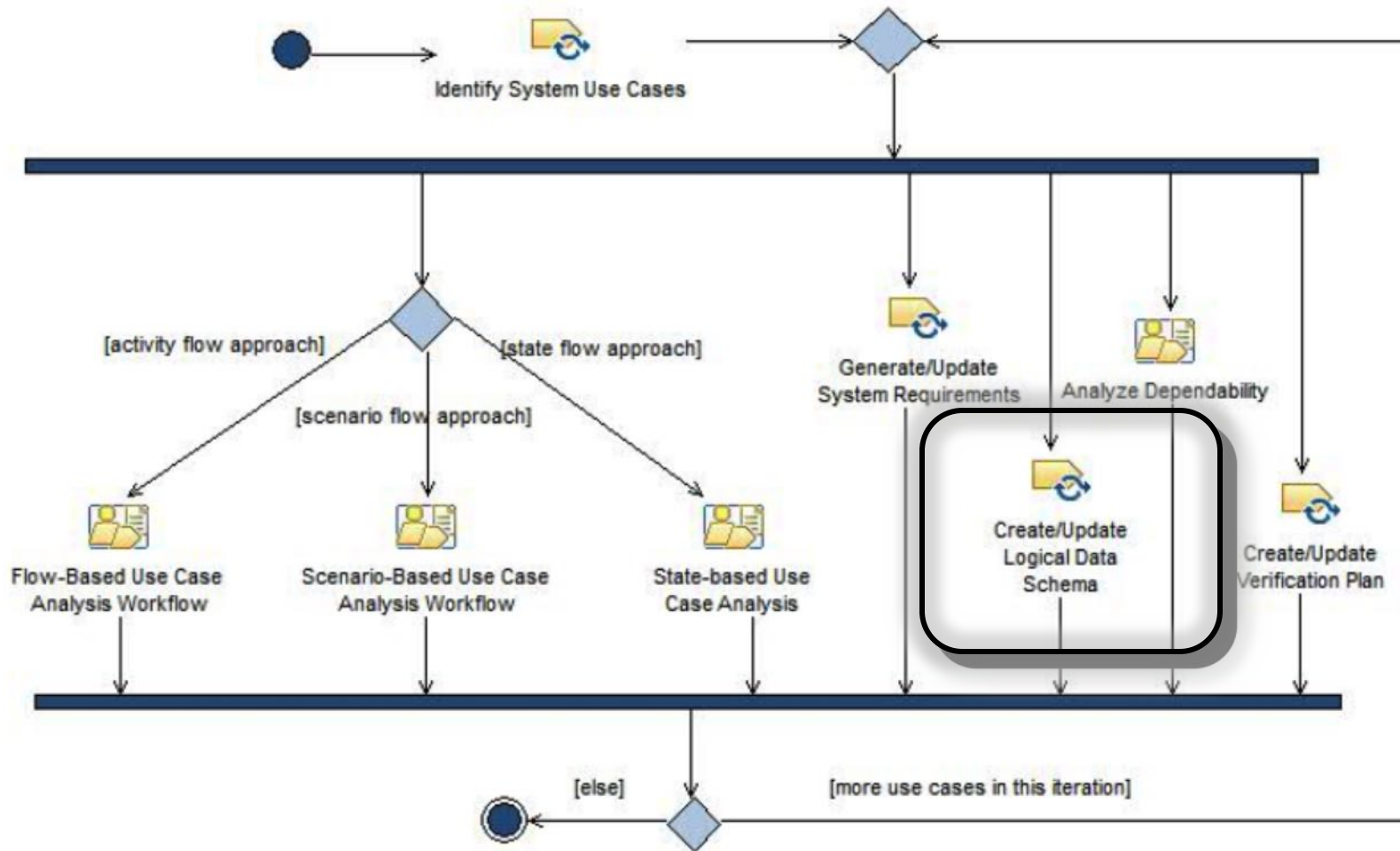
Initiate project



Harmony Process for Agile MBSE

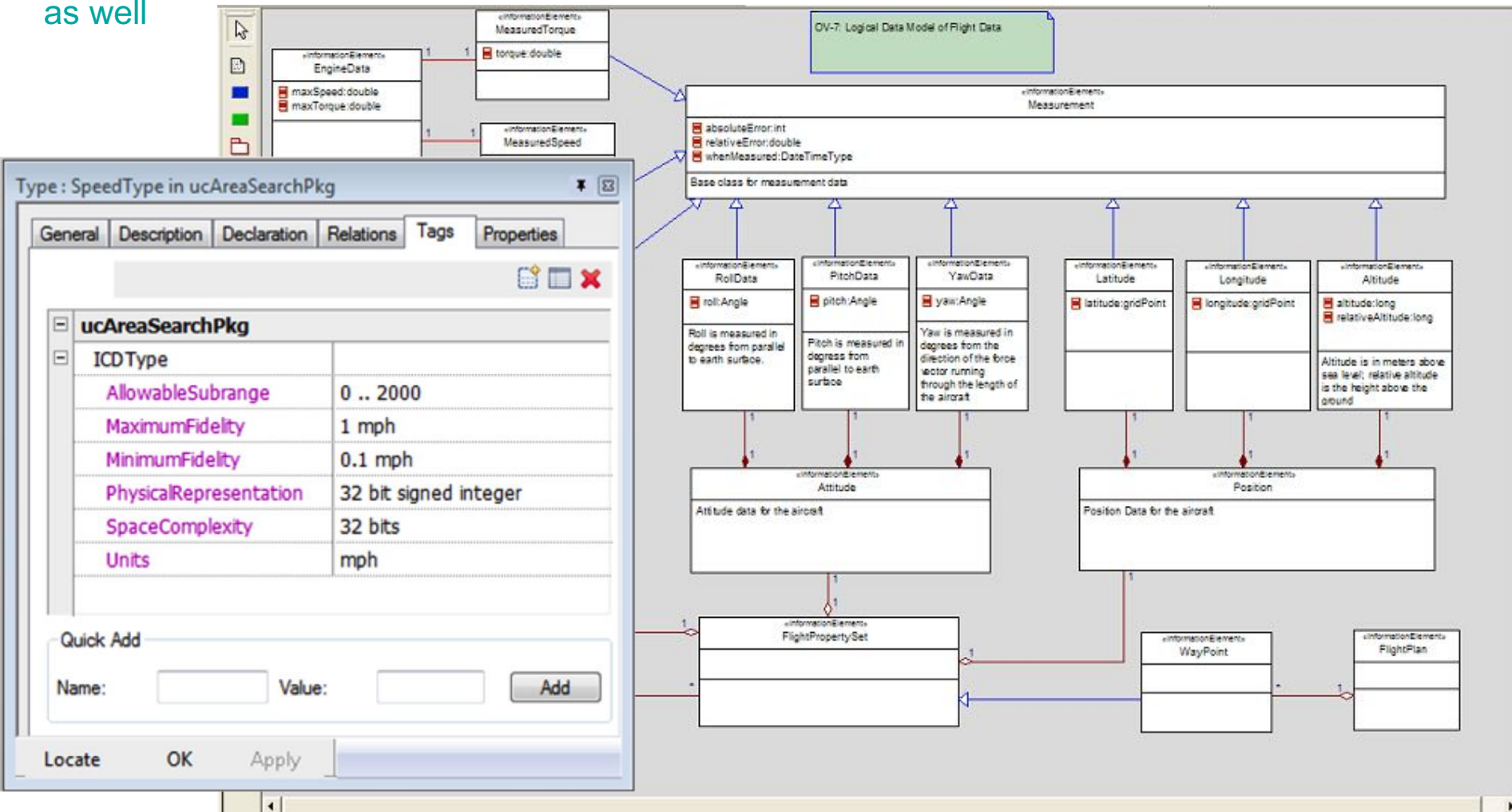


Harmony Process for Agile MBSE

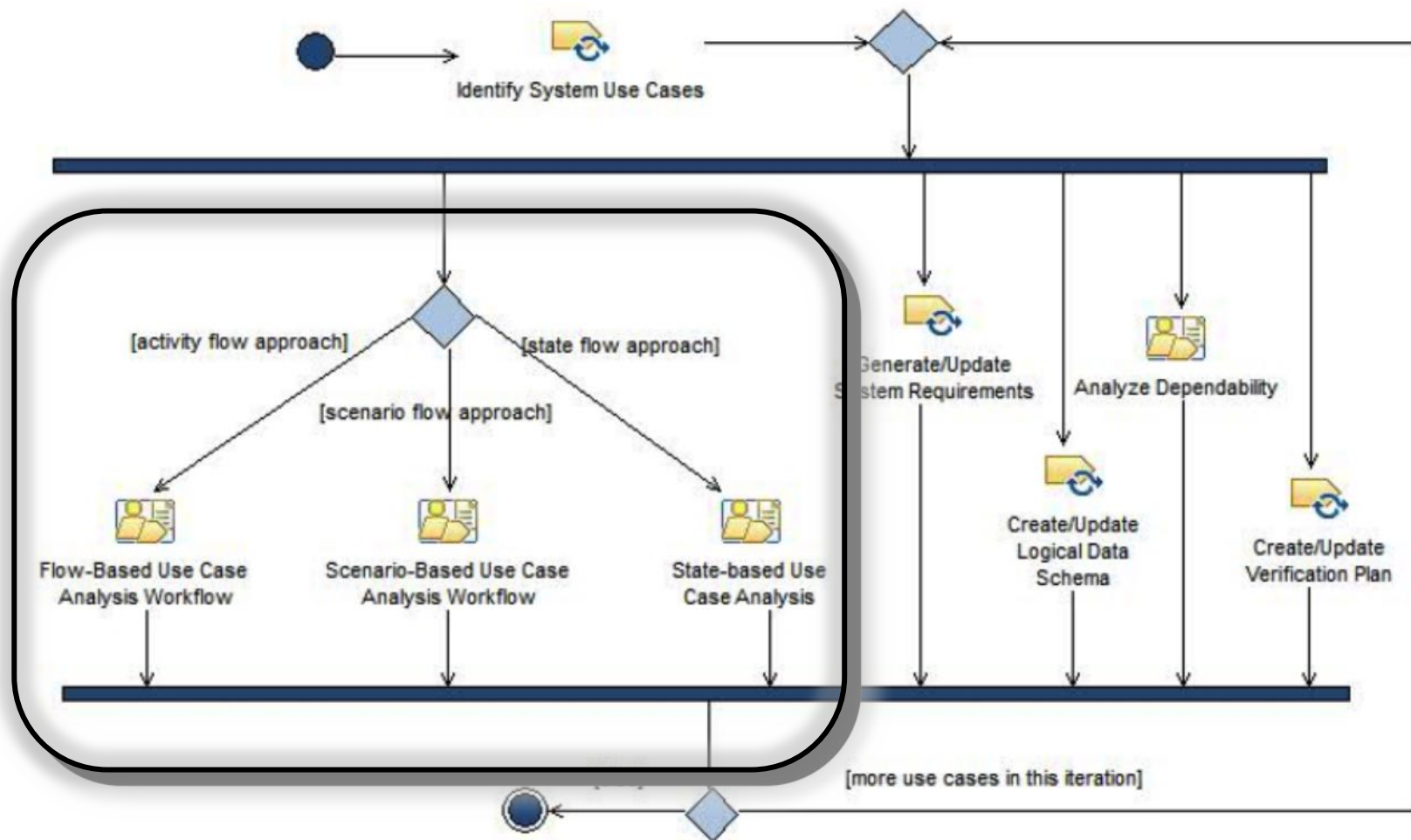


Logical Data Schema Modeling

- A logical data schema identifies the logical properties of important data elements and types and the relations among such data elements and their metadata
- Although the name is “data schema” it includes physical, materiel, and energy flows specification as well



Harmony aMBSE: System Requirements Def & Analysis



Alternative approaches to Build Executable Model of UC

Alternative 1: Scenario Based		Alternative 2: Flow Based		Alternative 3 State Based	
Create model context	<i>Block Diagram</i>	Identify functional flow large-scale view	<i>Activity diagram</i>	Create Model Context	<i>Block Diagram</i>
Identify sequences of messages between system use case and actors	<i>Sequence Diagram</i>	Derive sequences from functional flow	<i>Sequence diagram</i>	Create executable state machine	<i>State Diagram</i>
(optional) cluster sequences together as flows	<i>Activity Diagram</i>	Create model context	<i>Block Diagram</i>	Identify interfaces	<i>Block Diagram</i>
Identify interfaces	<i>Block Diagram</i>	Identify interfaces	<i>Block Diagram</i>	Derive sequences from functional flow	<i>Sequence diagram</i>
Create executable state machine	<i>State Diagram</i>	Create executable state machine	<i>State Diagram</i>	Execute State machine	<i>Model execution views</i>
Execute State machine	<i>Model execution views</i>	Execute State machine	<i>Model execution views</i>	Repeat until all requirements and sequence variants covered	
Repeat until all requirements and sequence variants covered		Repeat until all requirements and sequence variants covered			

Today's Example: High Performance Treadmill: SpeedDemon™

■ Biometrics

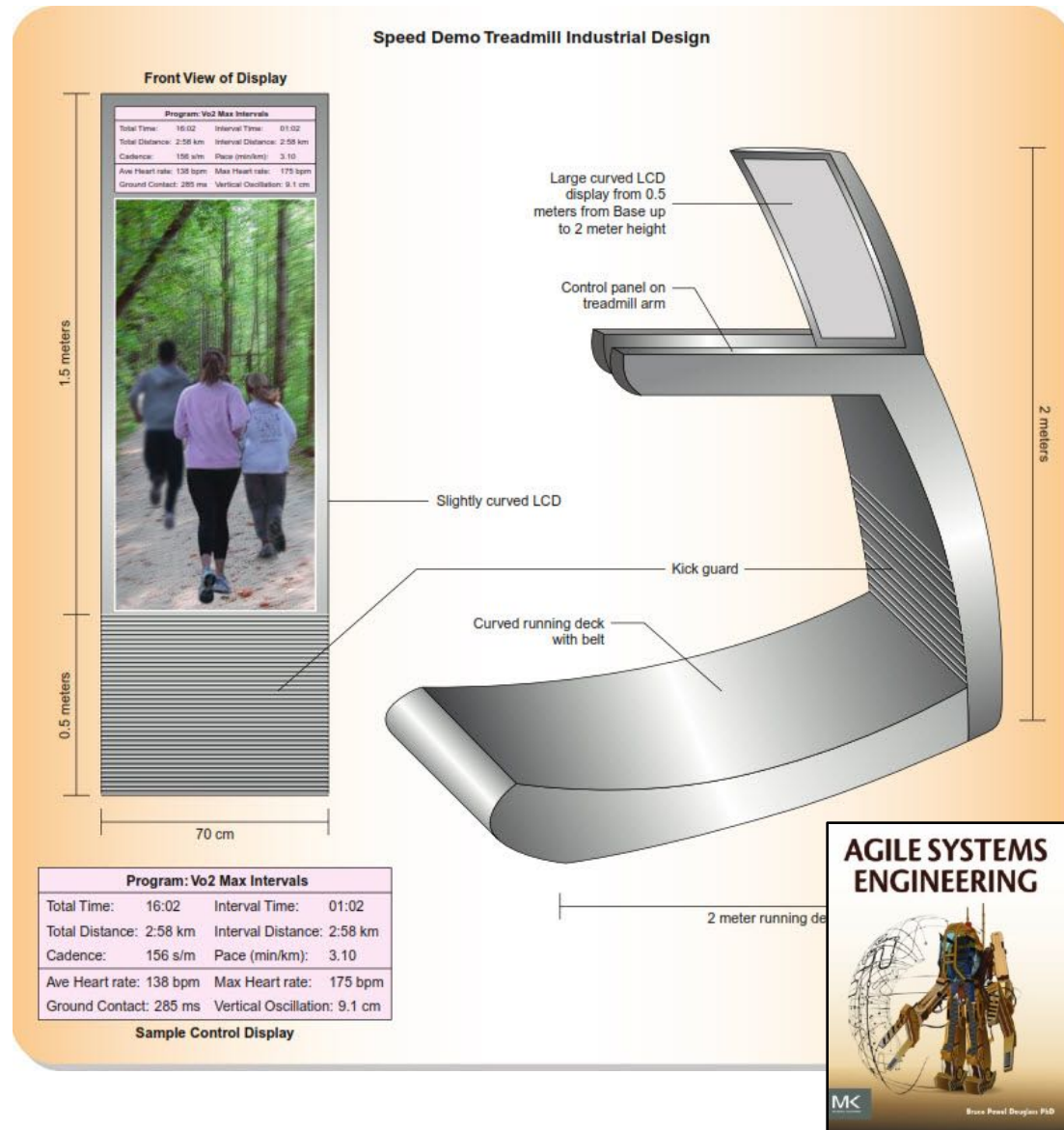
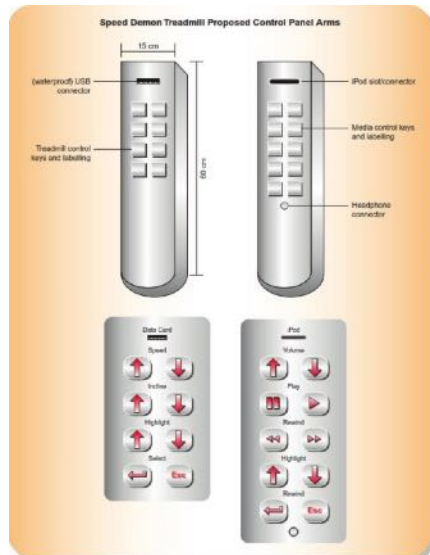
- Heart rate
- Speed
- Power / VO_2 max
- Elapsed time/interval time
- Ground contact time
- Vertical oscillation
- Cadence

■ Programmable protocols (workouts)

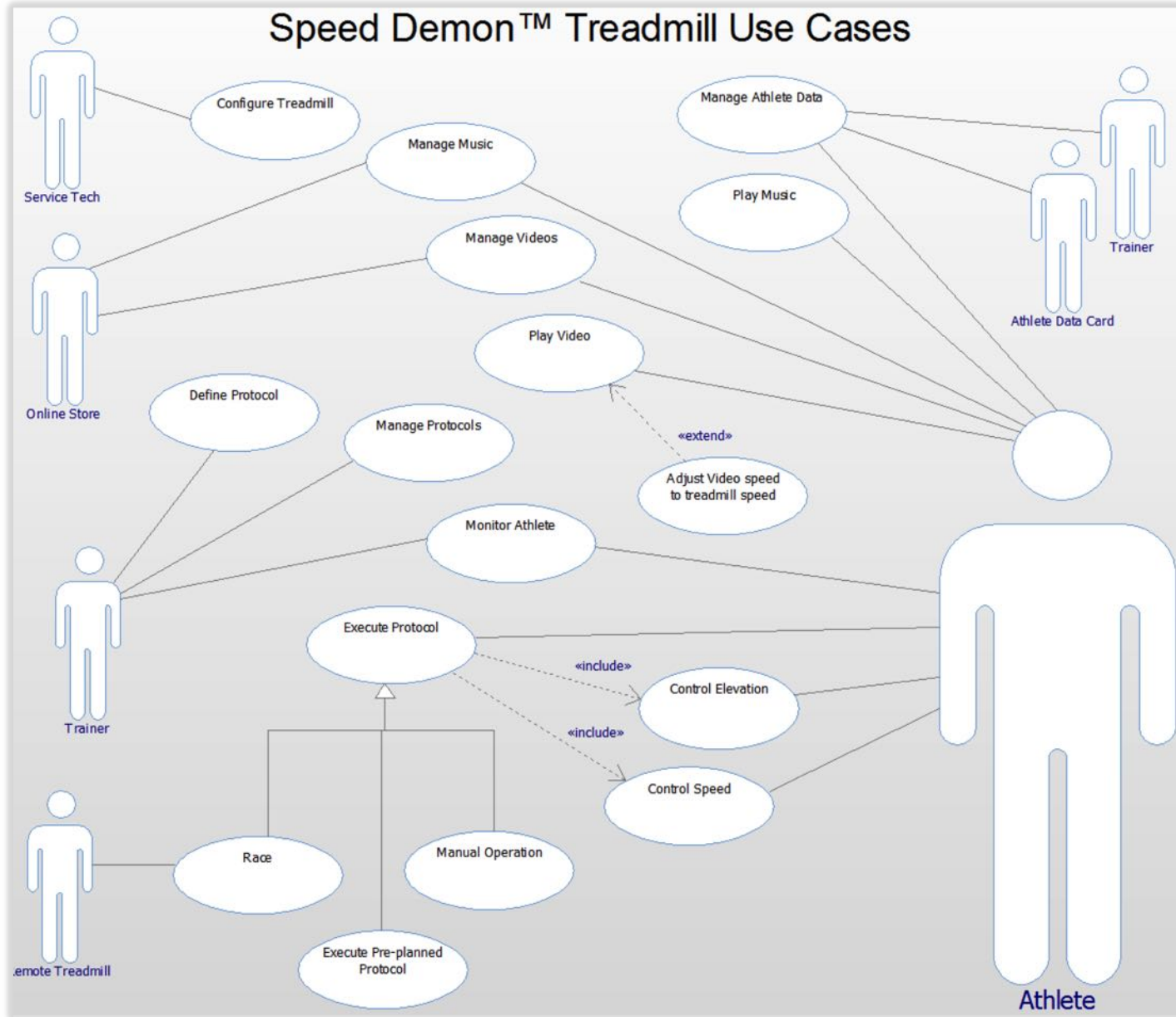
■ Performance storage and analytics

■ Music and video playlists

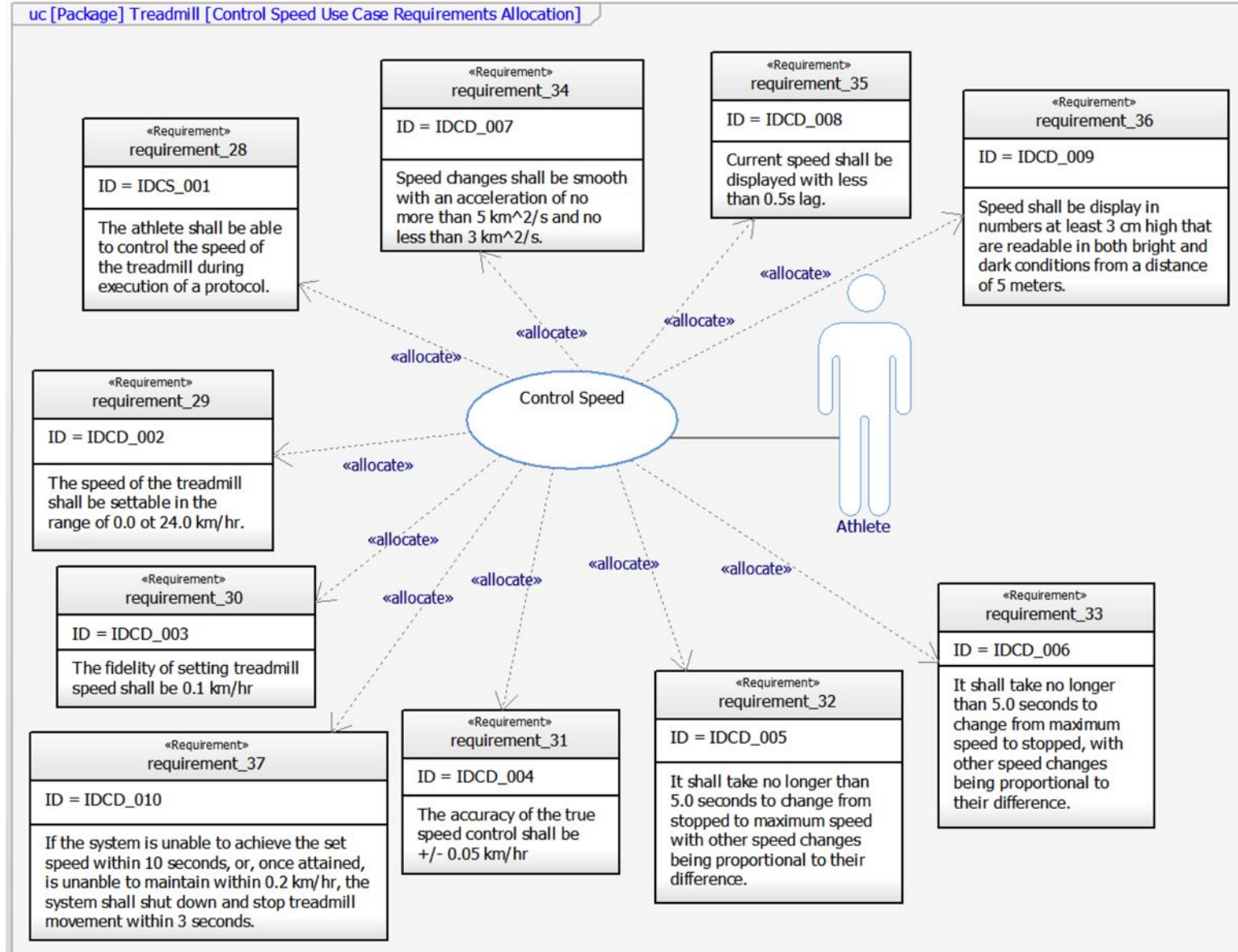
■ Virtual racing (simulated or over-the-web)



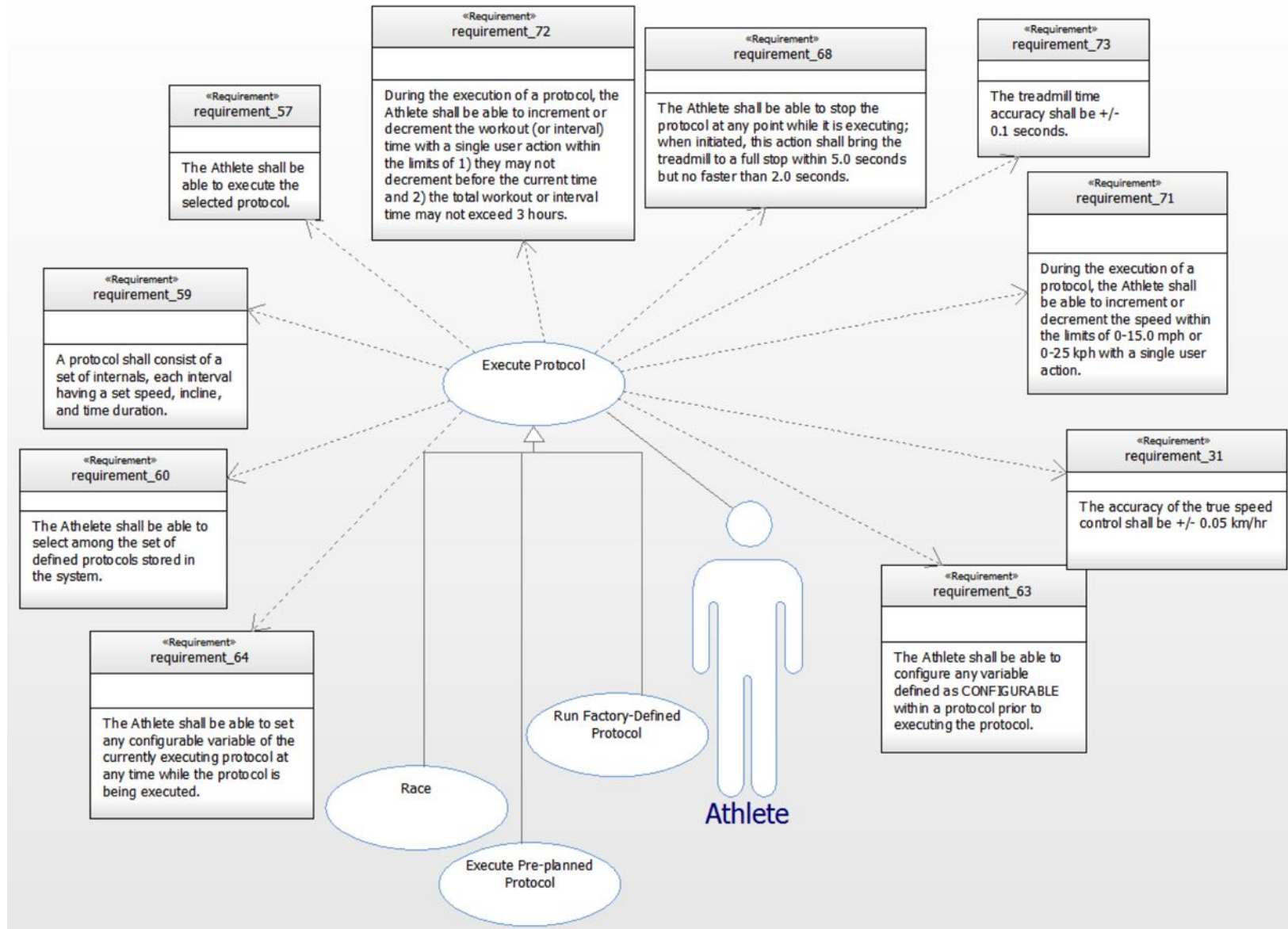
SpeedDemon Use Cases



Allocation of requirements to Control Speed Use Case



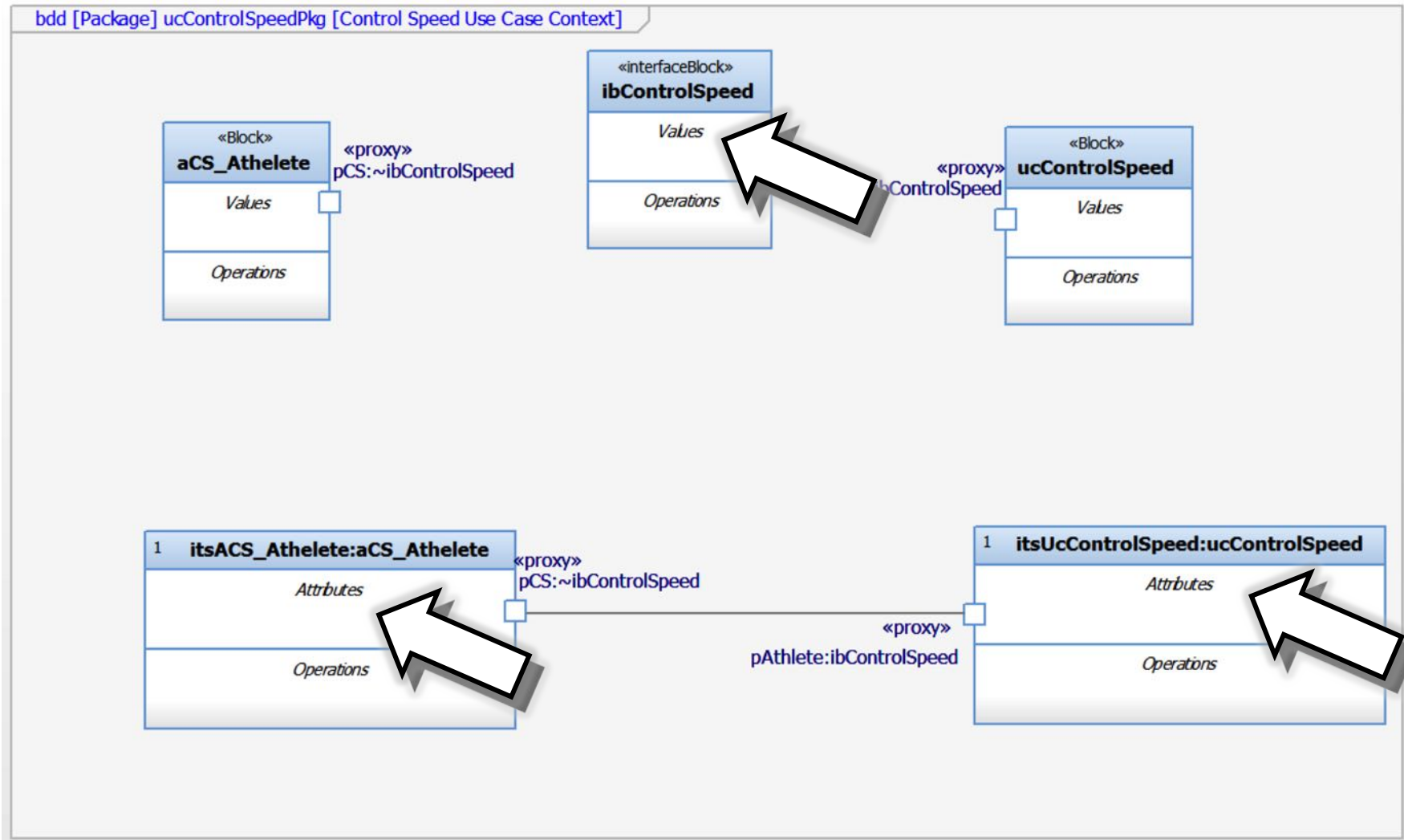
Allocate Requirements to Execute Protocol Use Case



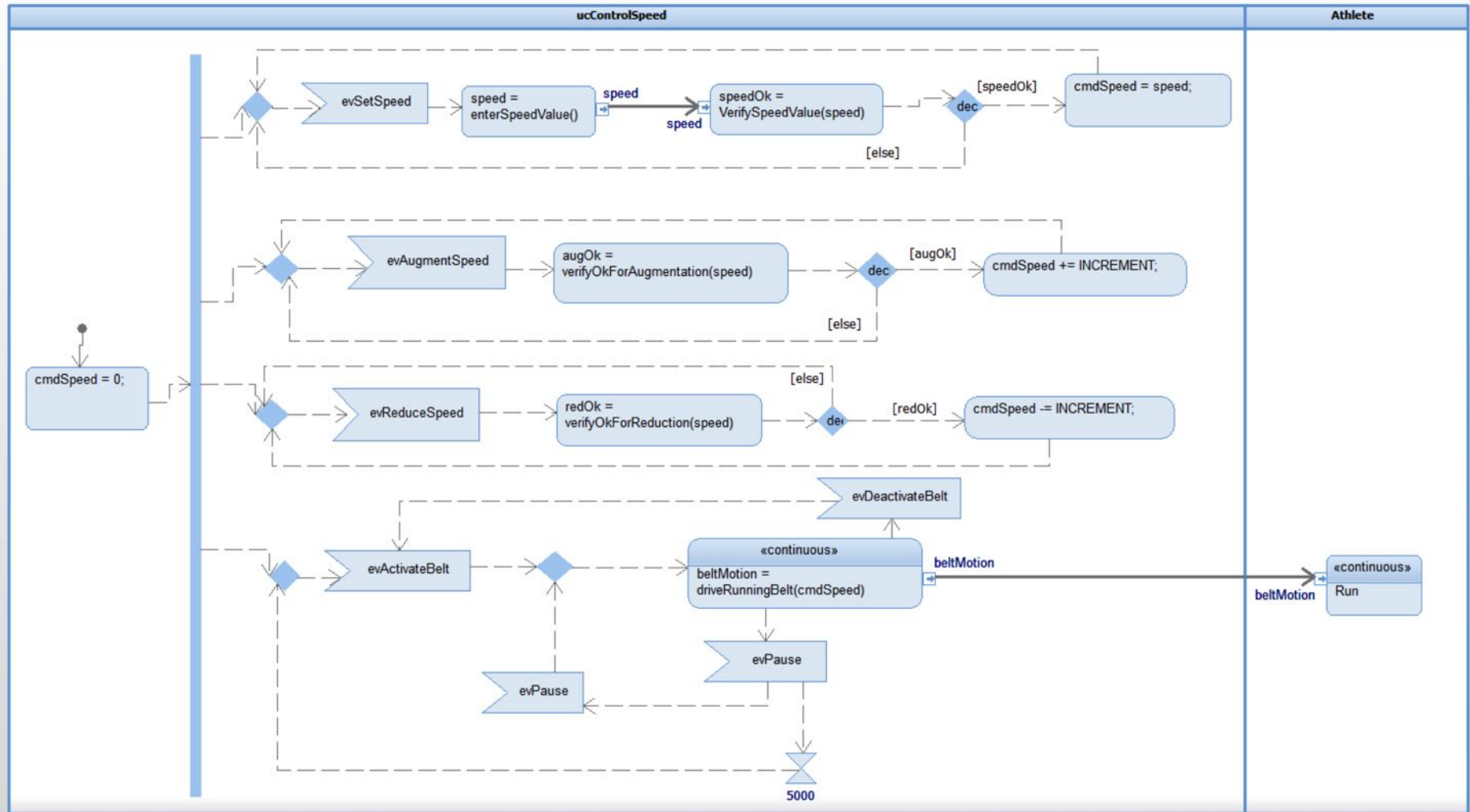
Showing allocations within a matrix (generated)

	<input type="checkbox"/> Control Elevation	<input type="checkbox"/> Control Speed	<input type="checkbox"/> Monitor Athlete	<input type="checkbox"/> Execute Protocol	<input type="checkbox"/> Define Protocol	<input type="checkbox"/> Manage Protocols	<input type="checkbox"/> Play Music	<input type="checkbox"/> Manage Music	<input type="checkbox"/> Play Video	<input type="checkbox"/> Manage Videos	<input type="checkbox"/> Run Factory-Defined Protocol	<input type="checkbox"/> Race	<input type="checkbox"/> Adjust Video speed to treadmill speed	<input type="checkbox"/> Configure Treadmill	<input type="checkbox"/> Manage Athlete Data
requirement_24															
requirement_25															
requirement_26															
requirement_28		✓ requirement_28													
requirement_29		✓ requirement_29													
requirement_30		✓ requirement_30													
requirement_31		✓ requirement_31		↘ requirement_31											
requirement_32		✓ requirement_32													
requirement_33		✓ requirement_33													
requirement_34		✓ requirement_34													
requirement_35		✓ requirement_35													
requirement_36		✓ requirement_36													
requirement_37		✓ requirement_37													
requirement_48															↘ requirement_48
requirement_49															↘ requirement_49
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requirement_63				↘ requirement_63							↘ requirement_63				
requirement_64				↘ requirement_64							↘ requirement_64				
requirement_65											↘ requirement_64_0				
requirement_66											↘ requirement_65				
requirement_67											↘ requirement_66				
requirement_68				↘ requirement_68							↘ requirement_67				
requirement_71				↘ requirement_71							↘ requirement_68				
requirement_72				↘ requirement_72											
requirement_73				↘ requirement_73											

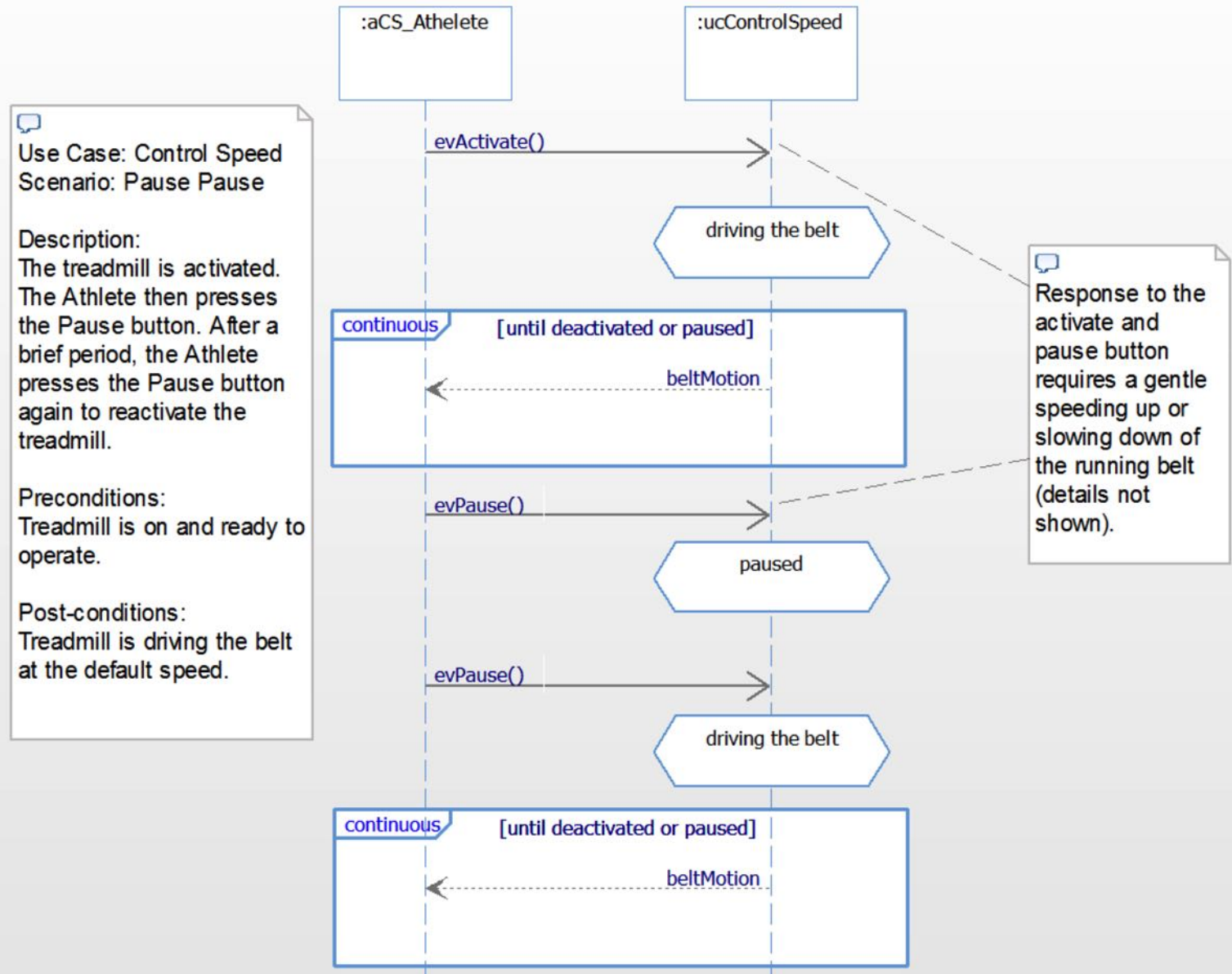
Create context for use case execution model



Creating an activity diagram to show behavioral flows



Create scenarios from activity diagram



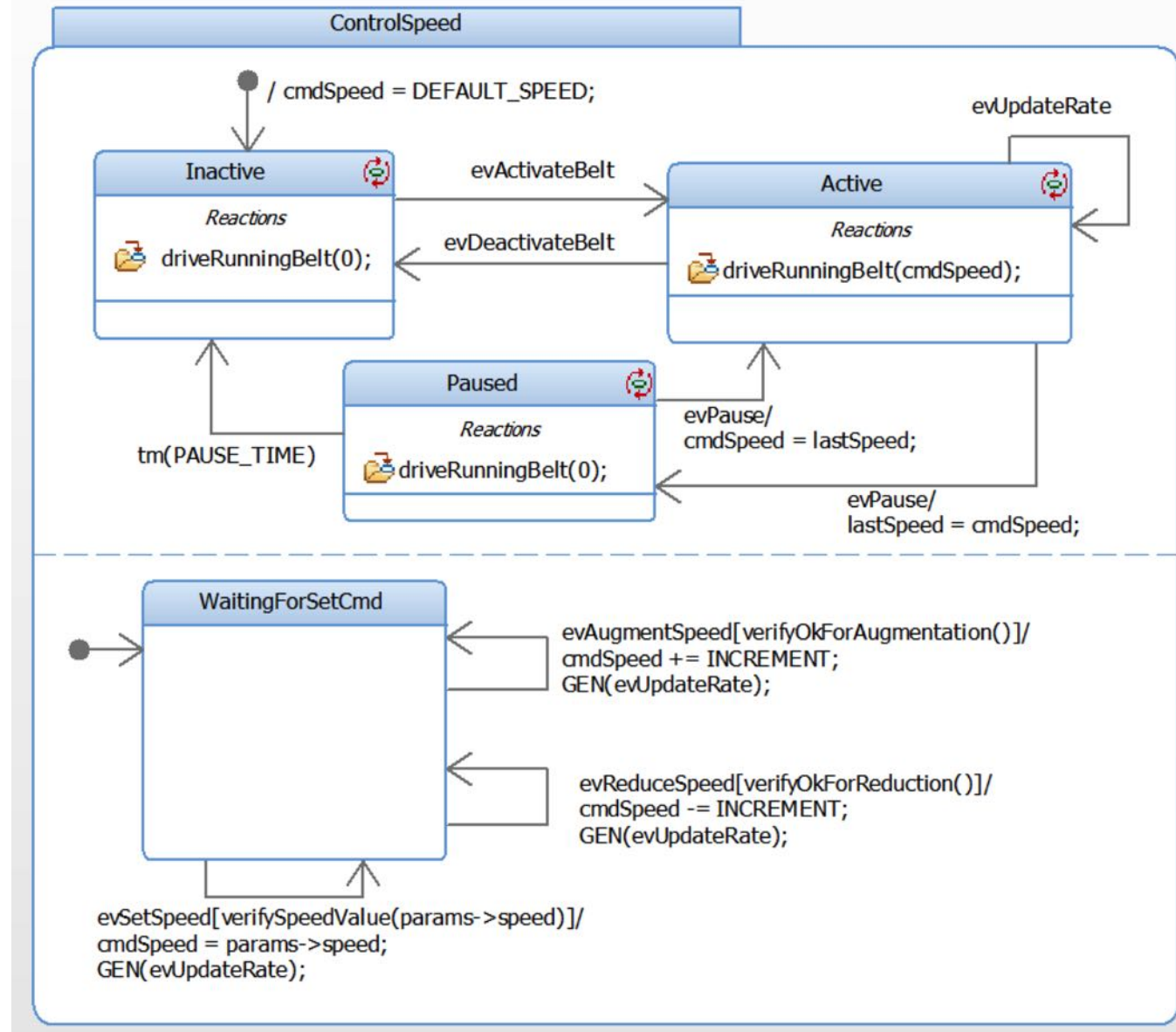
Create Behavioral Model Realizing Requirements for Use Case

Notes

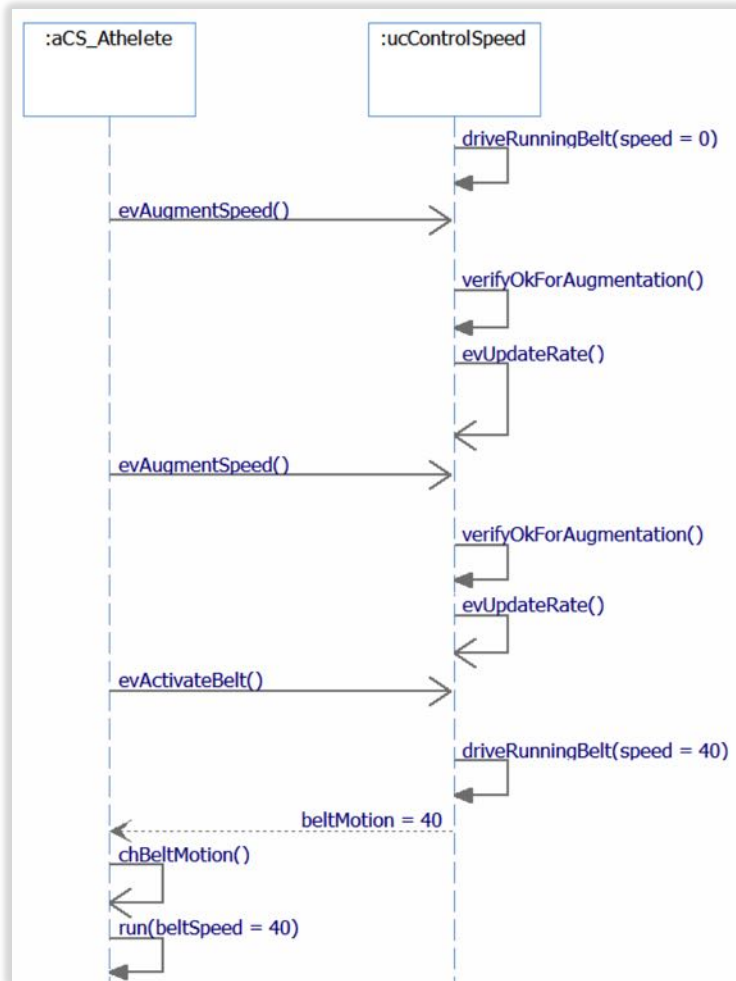
- This is after several Model-Verify–Elaborate iterations
- Start with 2-4 states, and add more each nanocycle iteration

Questions still remain

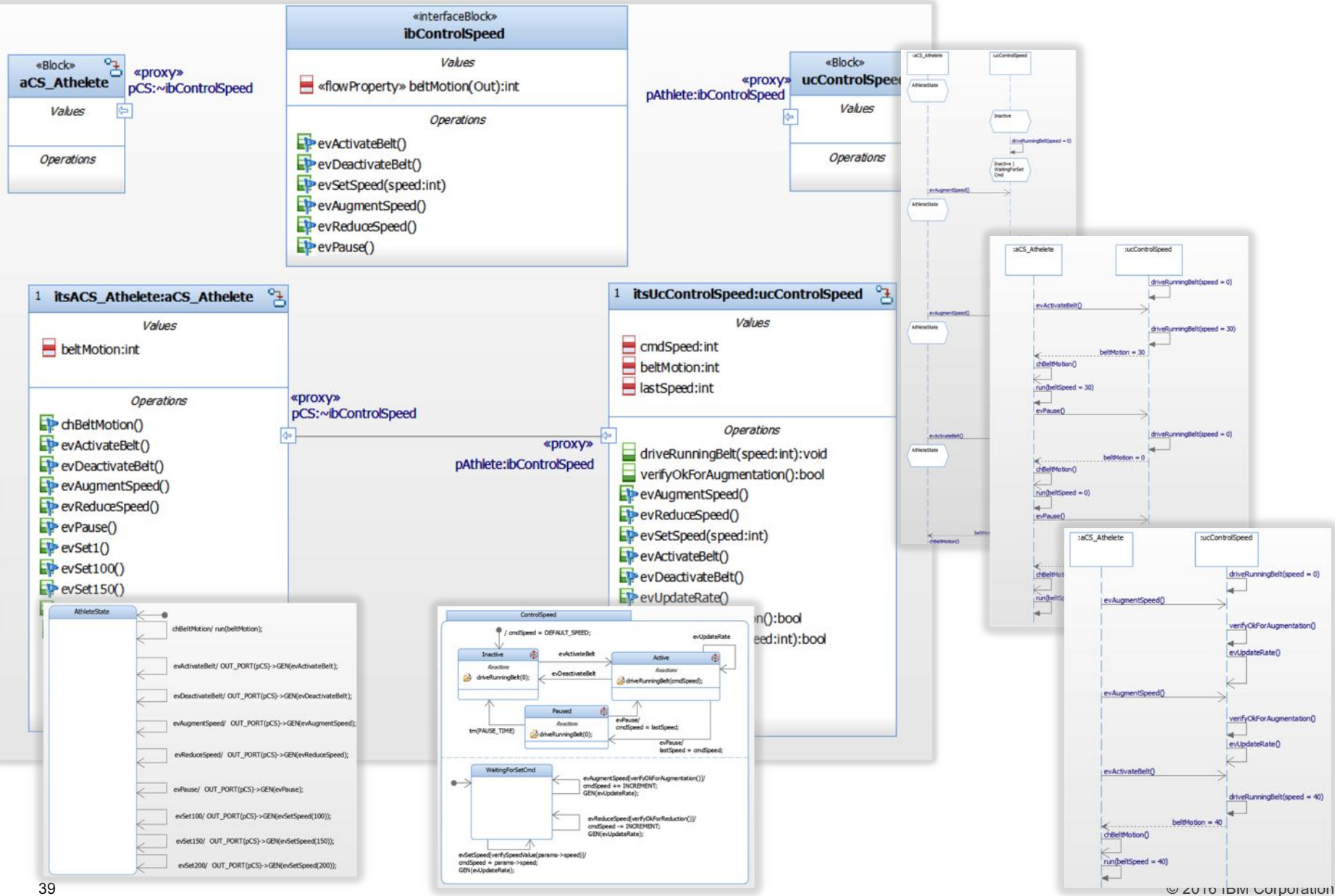
- Can the system be commanded into OFF directly?
- How are timing requirements verified?
- Reqs for degraded operation are now discovered to be inadequate – **add new reqs!**



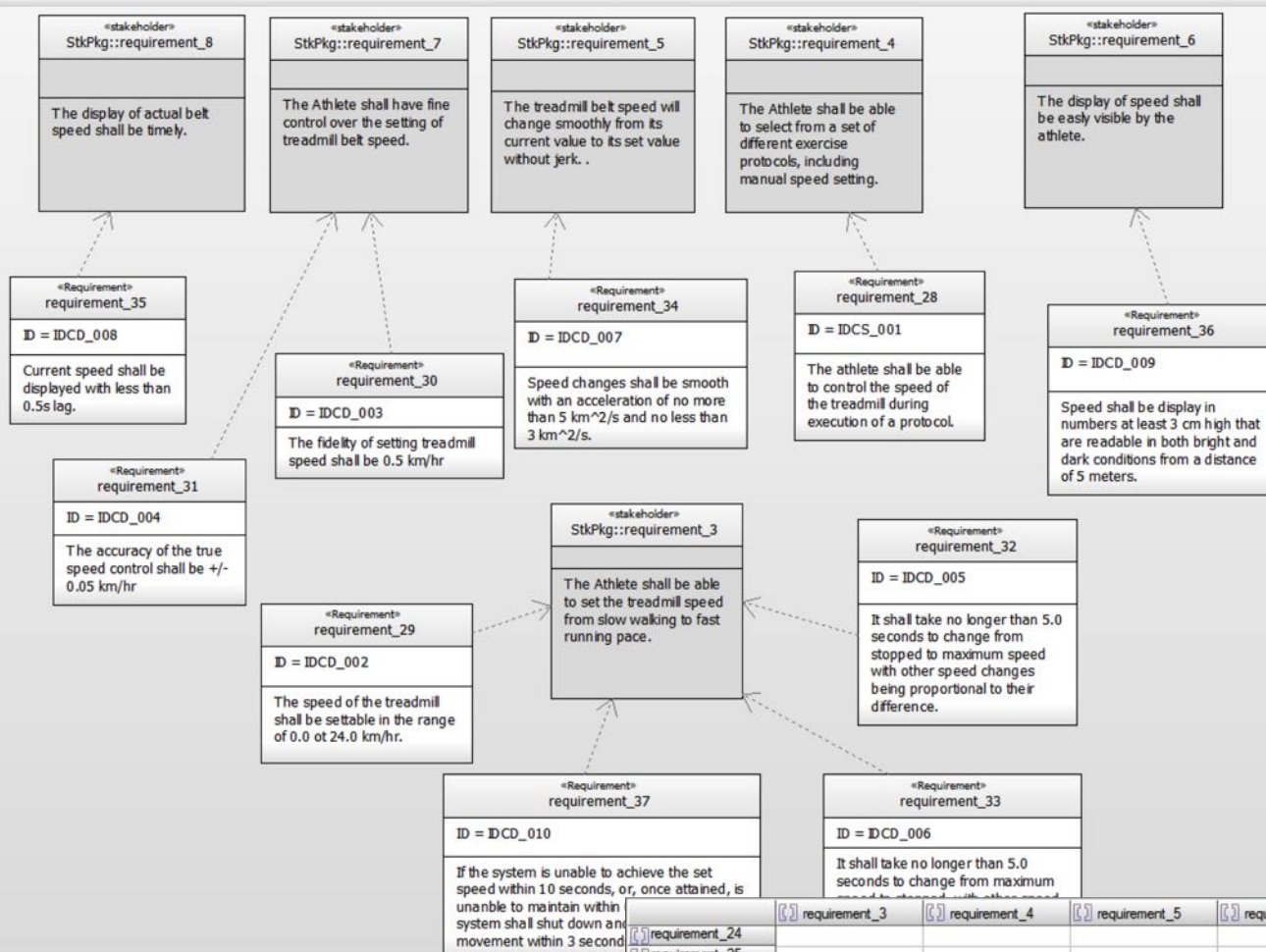
Verify Requirements Adequacy Through Execution



Identify gaps – add missing reqs – elaborate model - reexecute



Add traceability



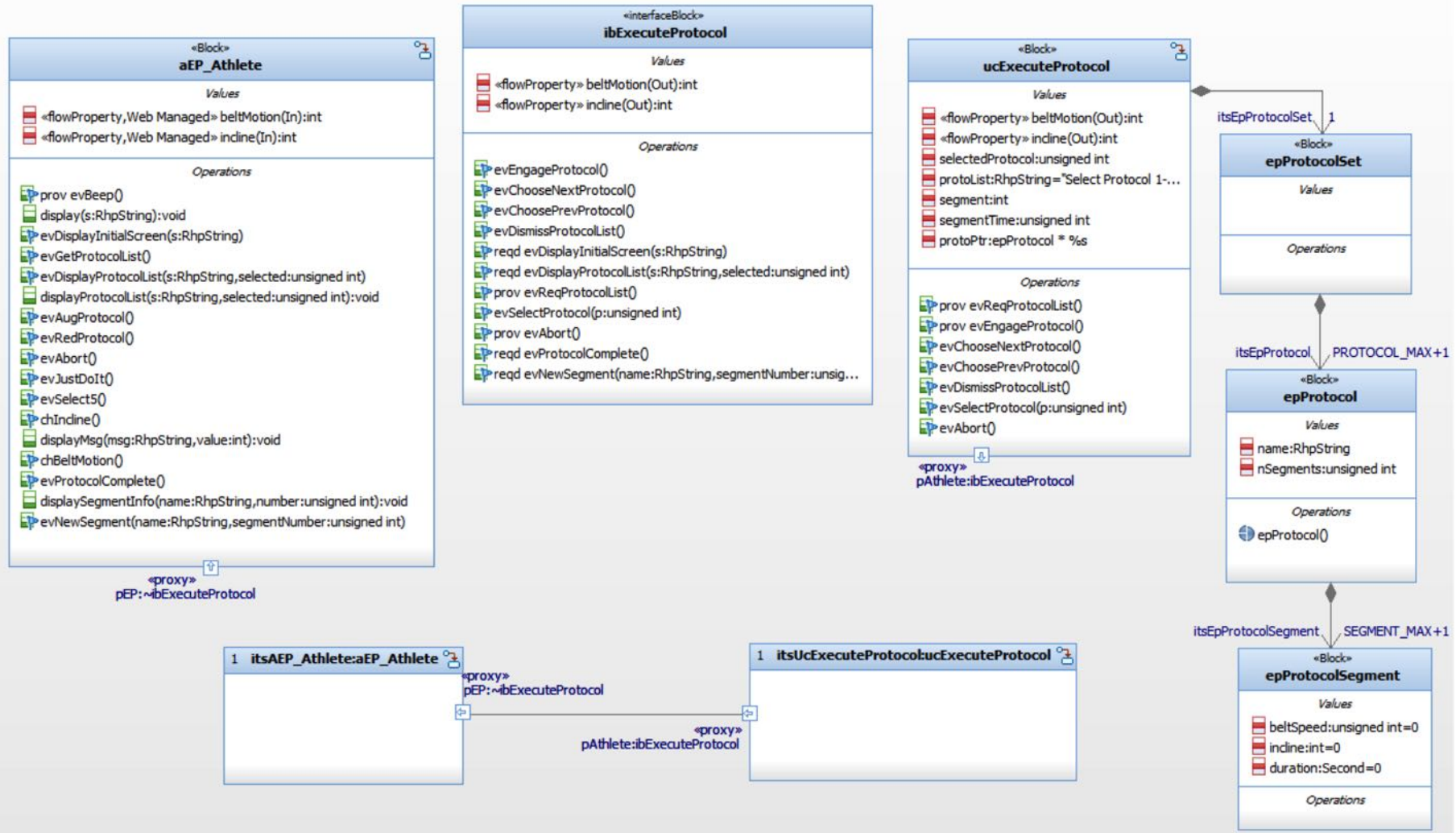
Stakeholder requirements

System requirements

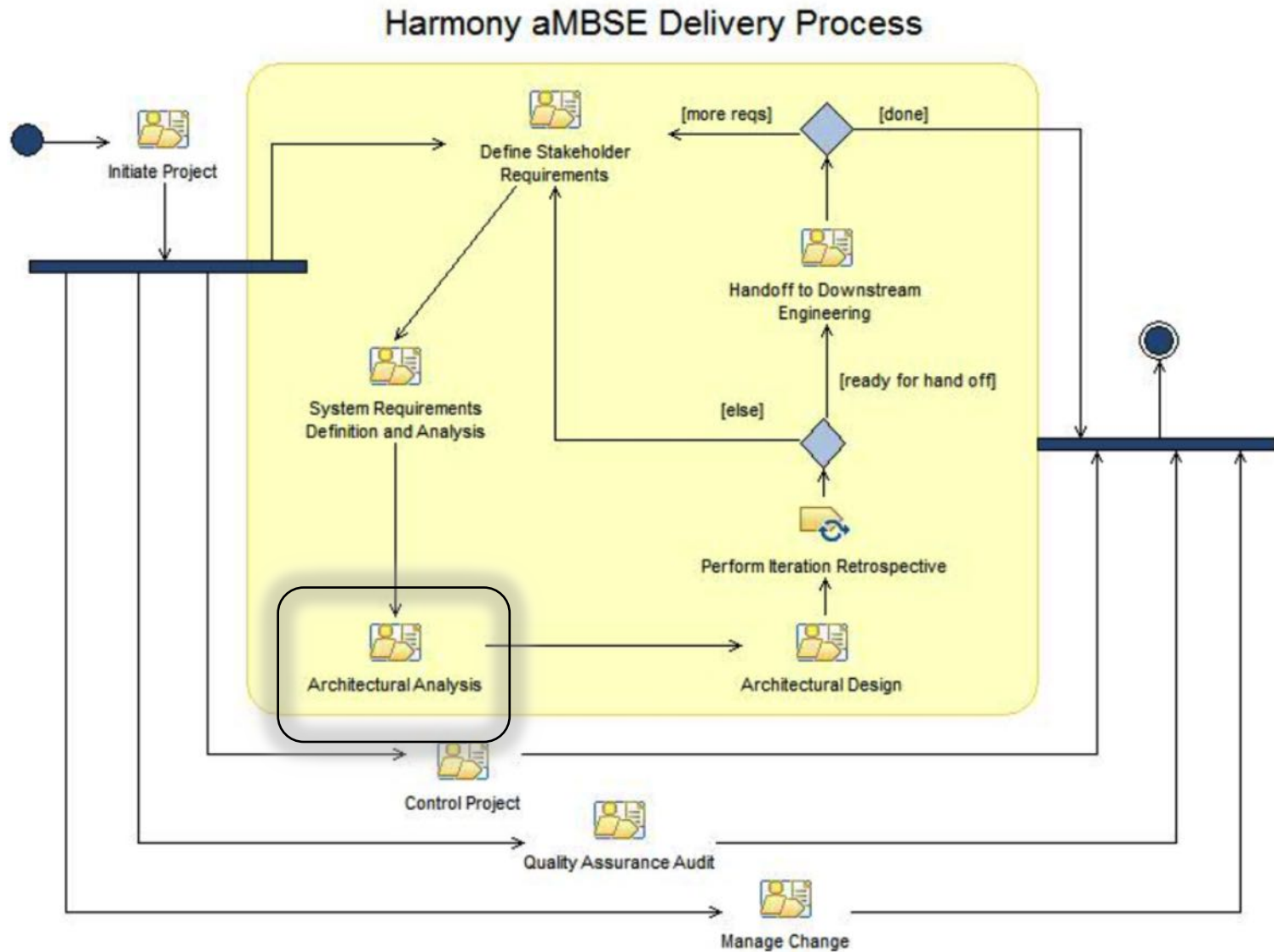
Generated trace matrix

	requirement_3	requirement_4	requirement_5	requirement_6	requirement_7	requirement_8
requirement_24						
requirement_25						
requirement_26						
requirement_28		requirement_4				
requirement_29	requirement_3					
requirement_30					requirement_7	
requirement_31					requirement_7	
requirement_32	requirement_3					
requirement_33	requirement_3					
requirement_34			requirement_5			
requirement_35						requirement_8
requirement_36				requirement_6		
requirement_37	requirement_3					

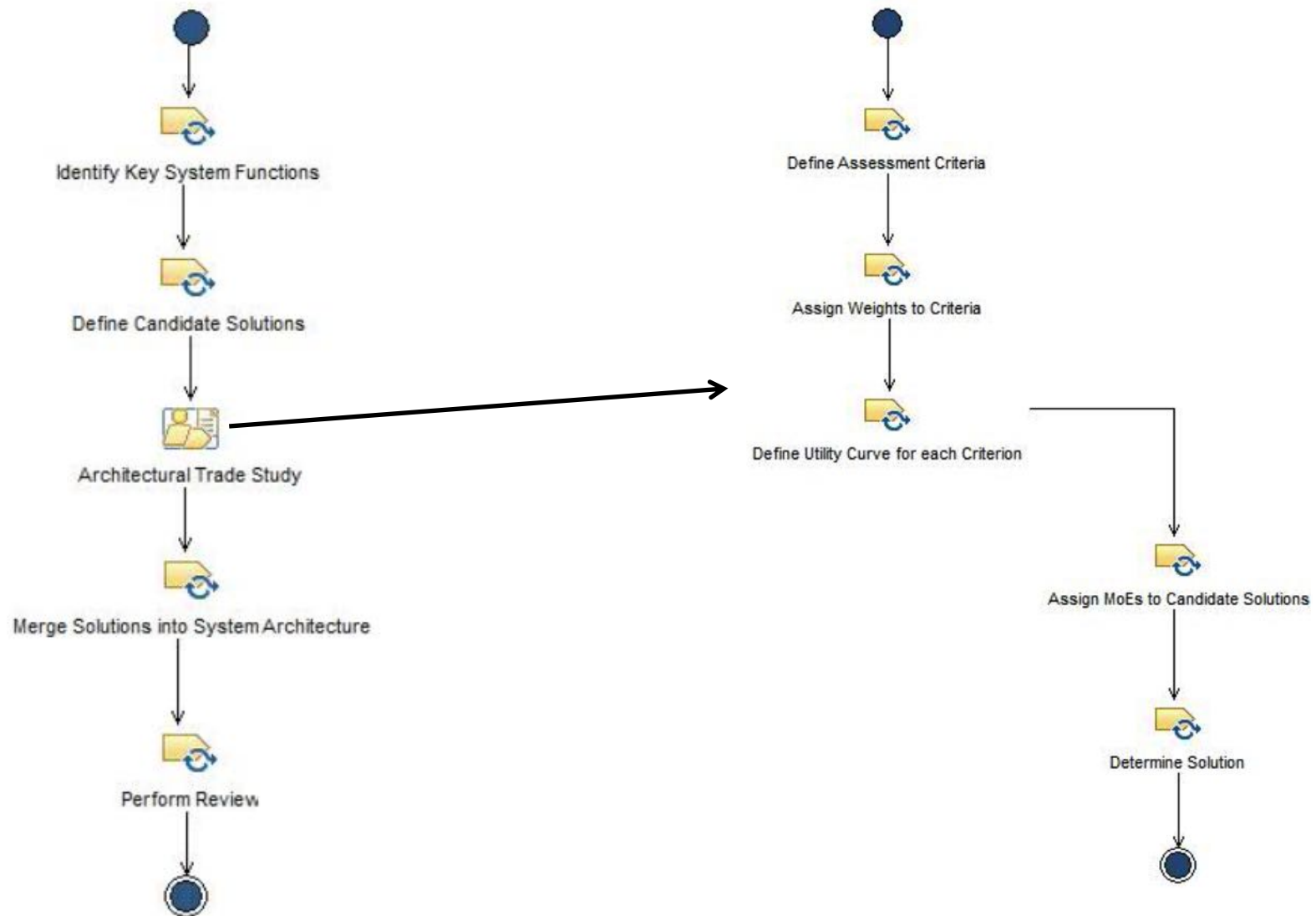
Generate Logical Interfaces



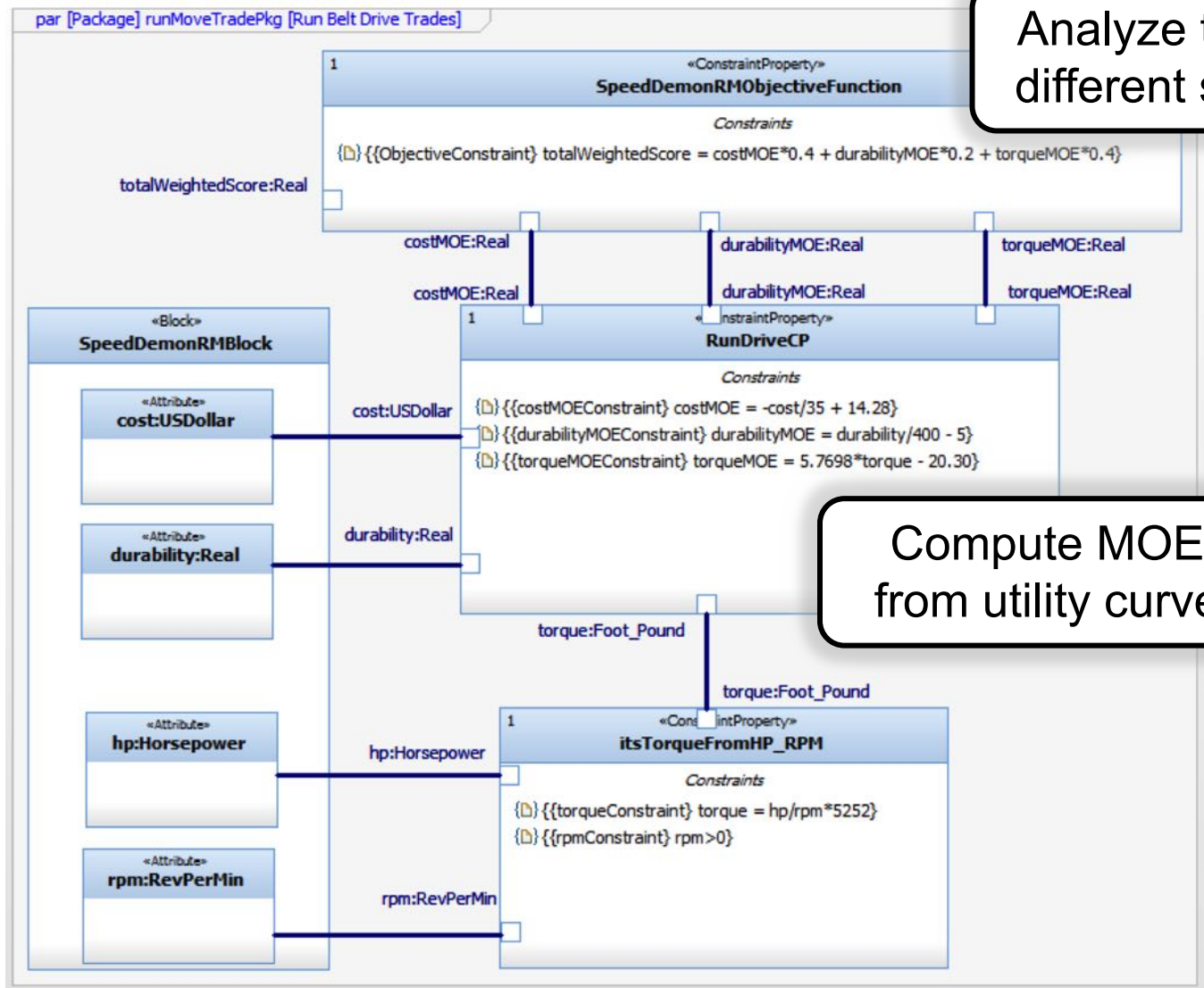
Systems Architectural Analysis



Systems Architectural Analysis



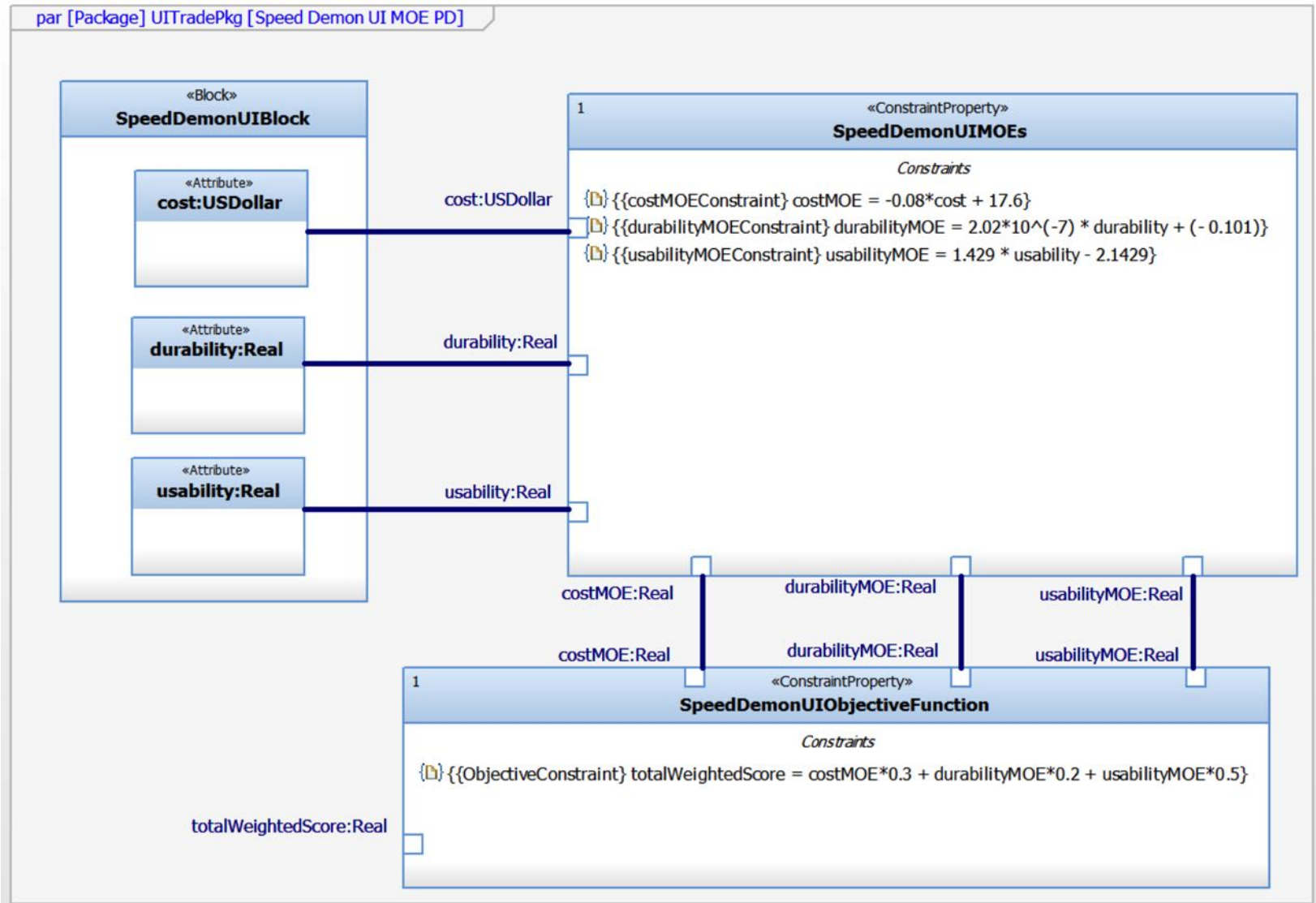
SysML Parametric Diagram for Trades for SpeedDemon Motor



Analyze trades of different solutions

Compute MOEs from utility curves

SysML Parametric Diagram for Trades for UI system



Outputs of the trade analysis

PM_1CV									
Name	Type	Original Value	Value	Min.	Max.	Command			
Trade Study PD	Parametric Diagram								
VOLUME_UPPER_LIMIT	Real	15.0	15.0			Fix			
COST_UPPER_LIMIT	Real	250.00	250.00			Fix			
MONTHS_UPPER_LIMIT	Real	120	120			Fix			
Pacemaker	Pacemaker								
cost	USDollar	150	150			Fix			
deviceLifetime	Month	100	100			Fix			
volume	CC	9.8	9.8			Fix			
PacemakerMOEs	PacemakerMOEs								
cost	USDollar		150						
lifetime	Month		100						
volume	CC		9.8						
costMOE	Real		4						
lifetimeMOE	Real		8.333333333...						
volumeMOE	Real		3.466666666...						
COST_UPPER_LIMIT	Real		250.00						
MONTHS_UPPER_LIMIT	Real		120						
VOLUME_UPPER_LIMIT	Real		15.0						
costConstraint	Constraint	costMOE = 1...	costMOE = 1...						
lifetimeConstraint	Constraint	lifetimeMOE = 1...	lifetimeMOE = 1...						
volumeConstraint	Constraint	volumeMOE = 1...	volumeMOE = 1...						
PacemakerObjectiveFunc	PacemakerObjectiveFunc								
costMOE	Real		4						
lifetimeMOE	Real		8.333333333...						
volumeMOE	Real		3.466666666...						
OverallScore	Real		5.626666666...						
ObjectiveFunction	Constraint	OverallScore = 1...	OverallScore = 1...						

Ready [4 free variable(s), 4 equation(s)]

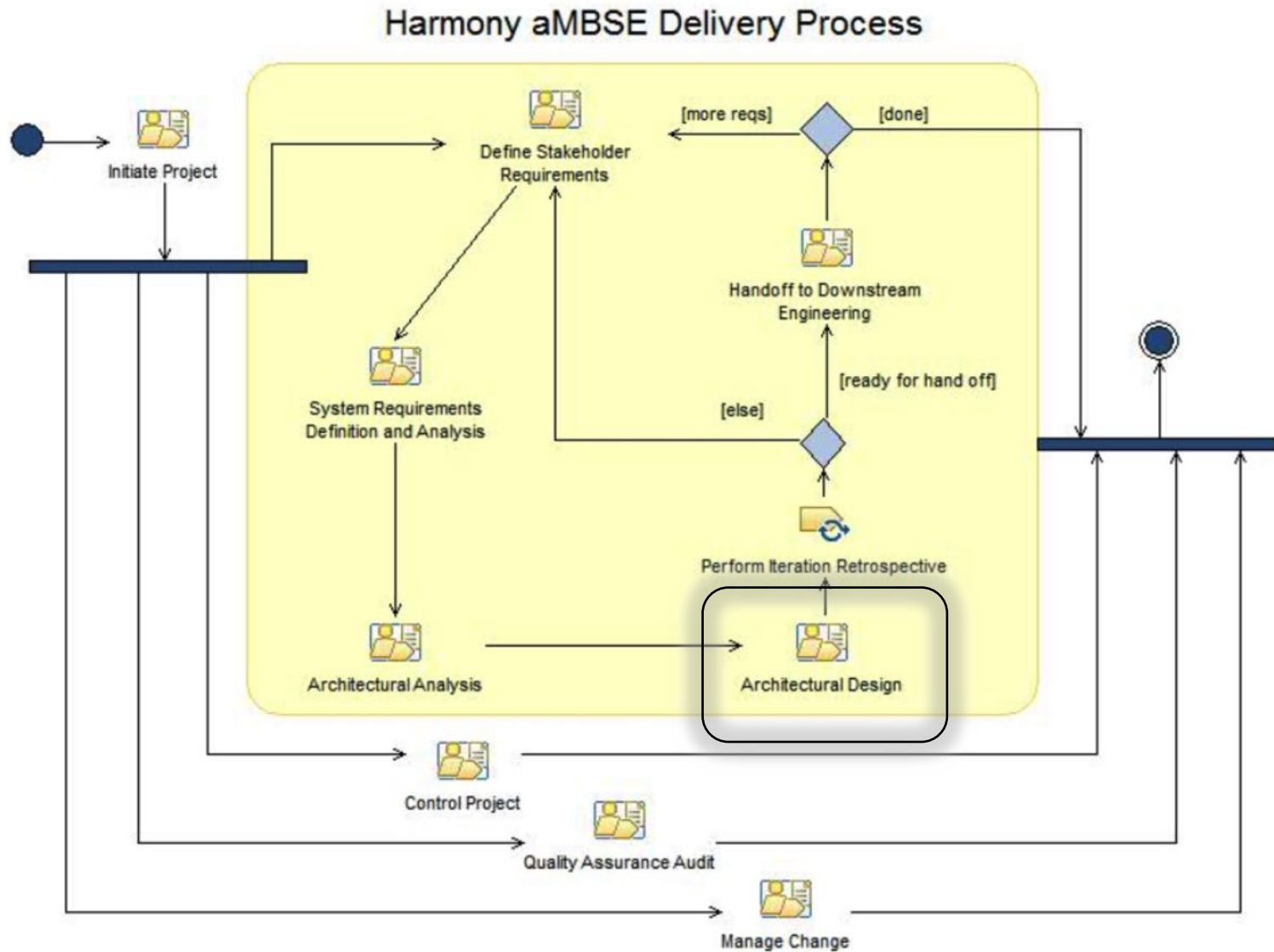
PM_2CV									
Name	Type	Original Value	Value	Min.	Max.	Command			
Trade Study PD	Parametric Diagram								
VOLUME_UPPER_LIMIT	Real	15.0	15.0			Fix			
COST_UPPER_LIMIT	Real	250.00	250.00			Fix			
MONTHS_UPPER_LIMIT	Real	120	120			Fix			
Pacemaker	Pacemaker								
cost	USDollar	110	110			Fix			
deviceLifetime	Month	80	80			Fix			
volume	CC	6	6			Fix			
PacemakerMOEs	PacemakerMOEs								
cost	USDollar		110						
lifetime	Month		80						
volume	CC		6						
costMOE	Real		5.600000000...						
lifetimeMOE	Real		6.666666666...						
volumeMOE	Real		6						
COST_UPPER_LIMIT	Real		250.00						
MONTHS_UPPER_LIMIT	Real		120						
VOLUME_UPPER_LIMIT	Real		15.0						
costConstraint	Constraint	costMOE = 1...	costMOE = 1...						
lifetimeConstraint	Constraint	lifetimeMOE = 1...	lifetimeMOE = 1...						
volumeConstraint	Constraint	volumeMOE = 1...	volumeMOE = 1...						
PacemakerObjectiveFunc	PacemakerObjectiveFunc								
costMOE	Real		5.600000000...						
lifetimeMOE	Real		6.666666666...						
volumeMOE	Real		6						
OverallScore	Real		6.196666666...						
ObjectiveFunction	Constraint	OverallScore = 1...	OverallScore = 1...						

Ready [4 free variable(s), 4 equation(s)]

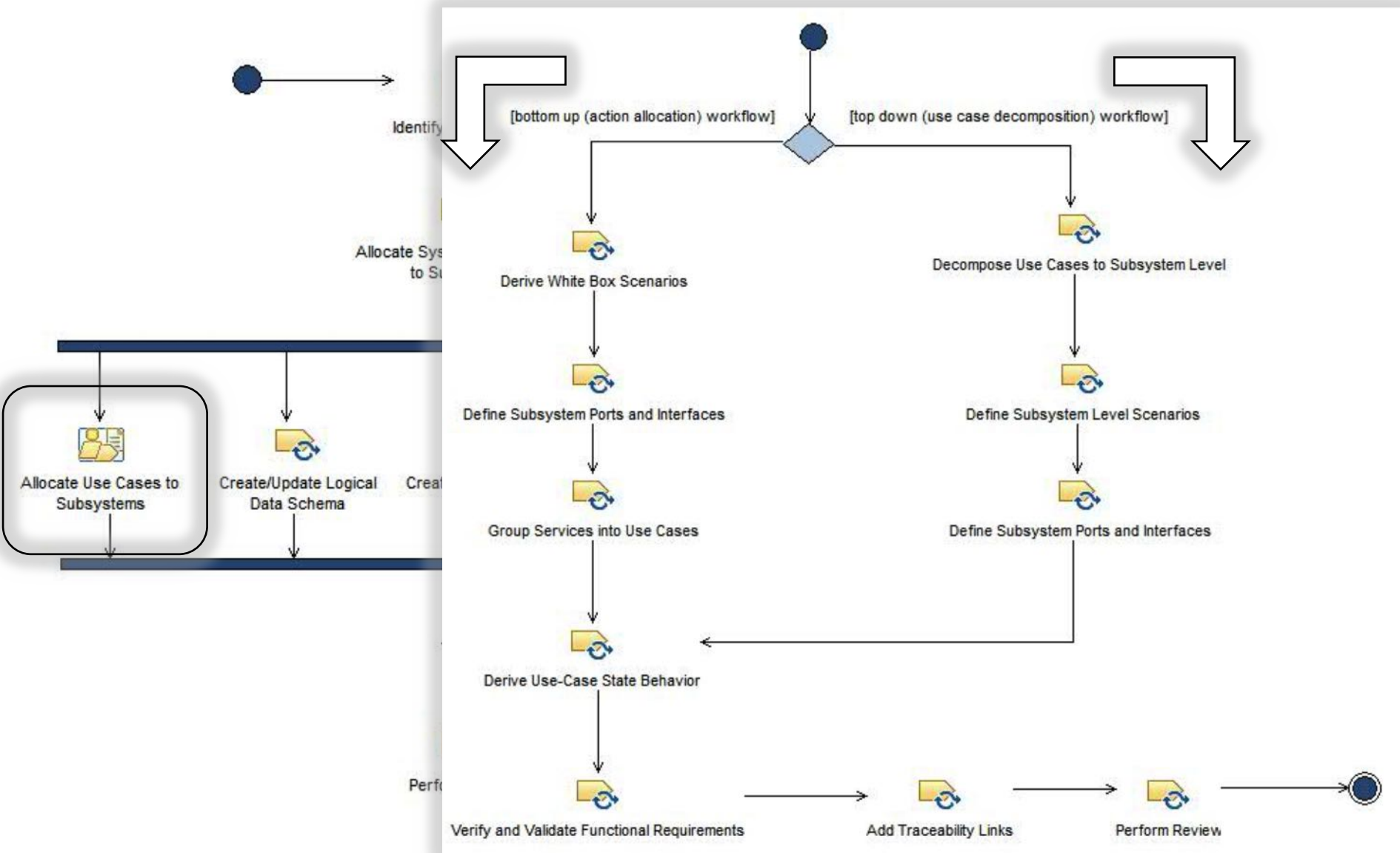
PM_3CV									
Name	Type	Original Value	Value	Min.	Max.	Command			
Trade Study PD	Parametric Diagram								
VOLUME_UPPER_LIMIT	Real	15.0	15.0			Fix			
COST_UPPER_LIMIT	Real	250.00	250.00			Fix			
MONTHS_UPPER_LIMIT	Real	120	120			Fix			
Pacemaker	Pacemaker								
cost	USDollar	250	250			Fix			
deviceLifetime	Month	120	120			Fix			
volume	CC	15	15			Fix			
PacemakerMOEs	PacemakerMOEs								
cost	USDollar		250						
lifetime	Month		120						
volume	CC		15						
costMOE	Real		0						
lifetimeMOE	Real		10						
volumeMOE	Real		0						
COST_UPPER_LIMIT	Real		250.00						
MONTHS_UPPER_LIMIT	Real		120						
VOLUME_UPPER_LIMIT	Real		15.0						
costConstraint	Constraint	costMOE = 1...	costMOE = 1...						
lifetimeConstraint	Constraint	lifetimeMOE = 1...	lifetimeMOE = 1...						
volumeConstraint	Constraint	volumeMOE = 1...	volumeMOE = 1...						
PacemakerObjectiveFunc	PacemakerObjectiveFunc								
costMOE	Real		0						
lifetimeMOE	Real		10						
volumeMOE	Real		0						
OverallScore	Real		4						
ObjectiveFunction	Constraint	OverallScore = 1...	OverallScore = 1...						

Ready [4 free variable(s), 4 equation(s)]

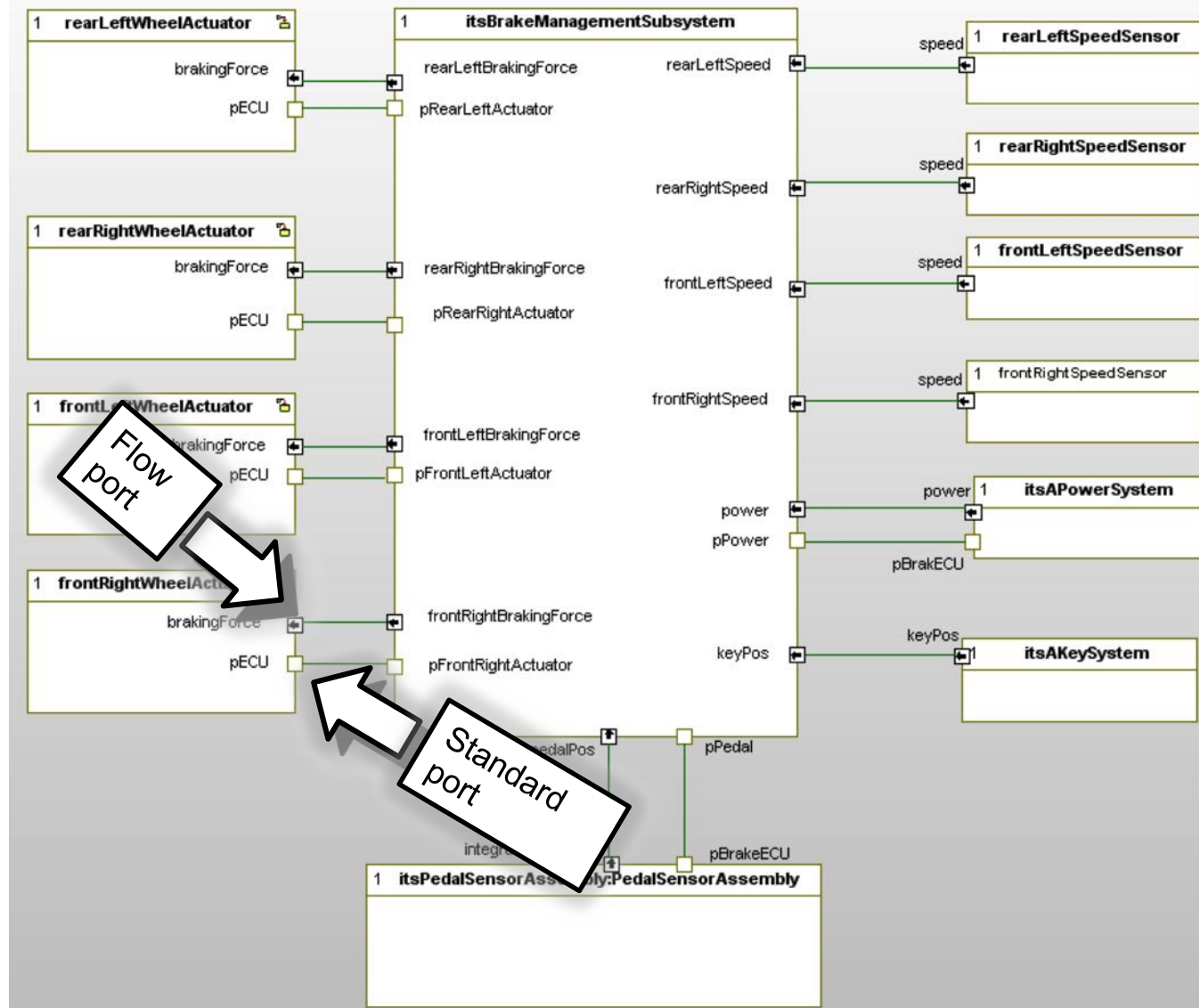
Architectural Design



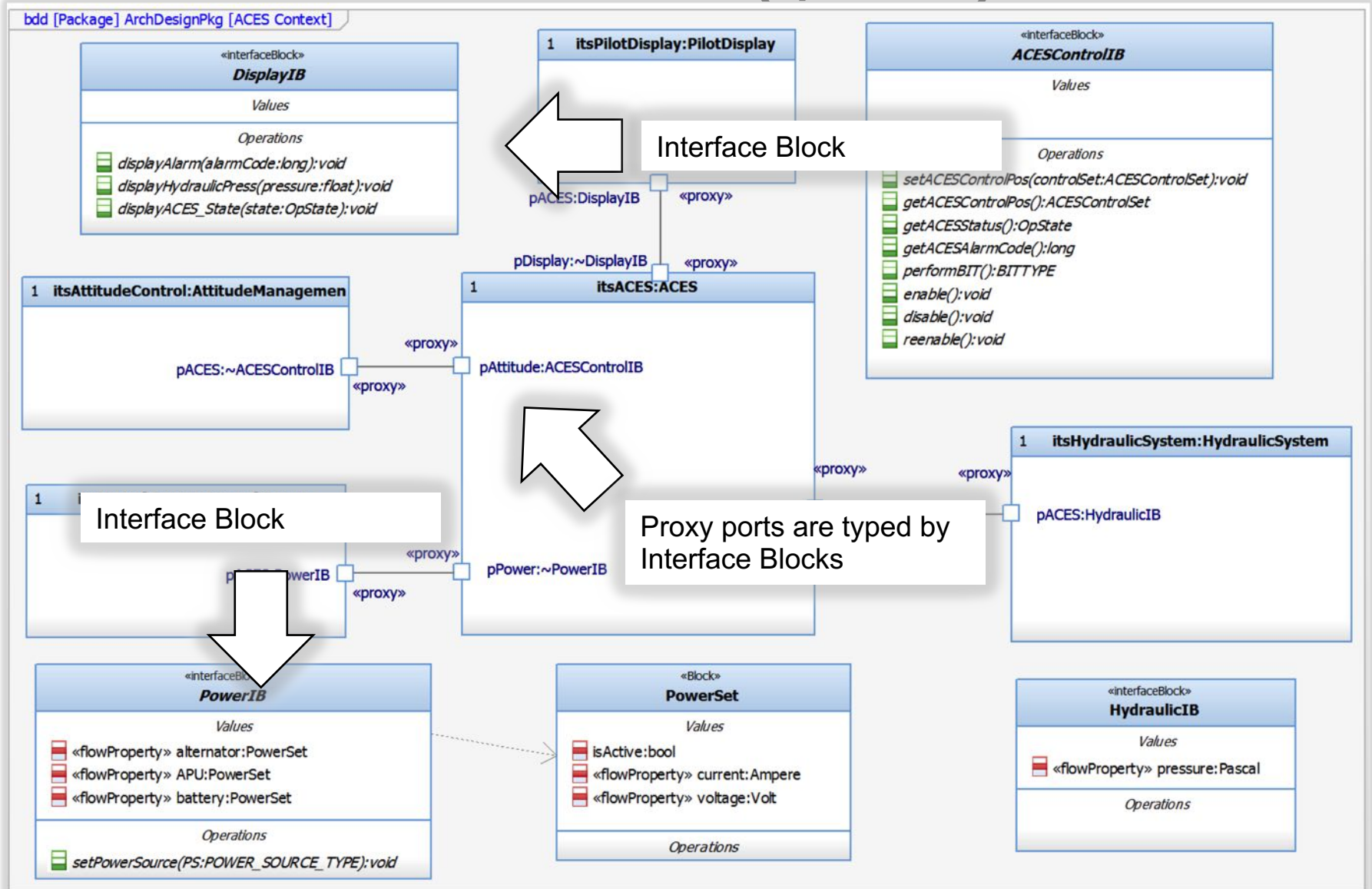
Activity: Allocate Use Cases to Subsystems



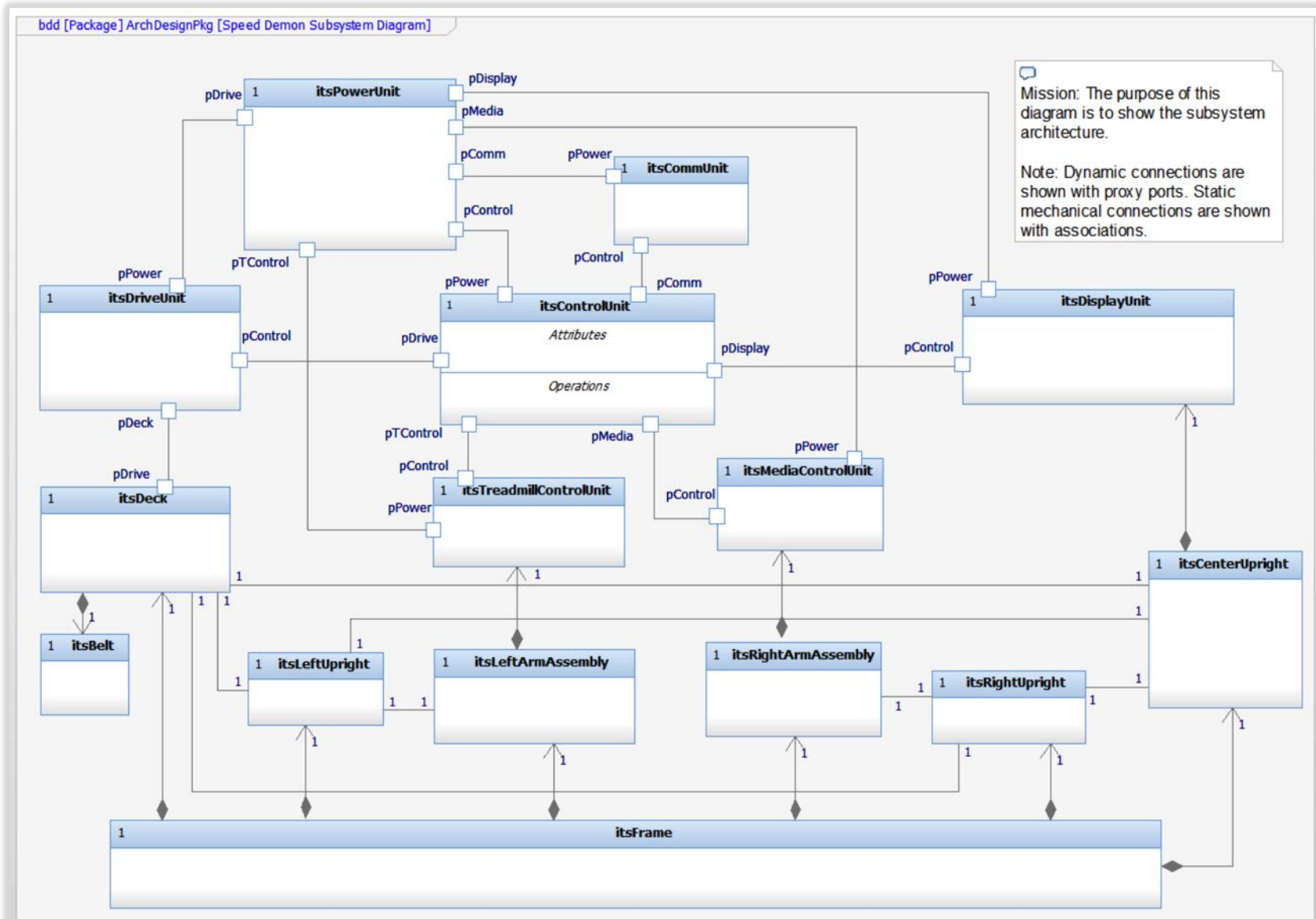
Architecture View for Control Flow (UML & SysML 1.2)



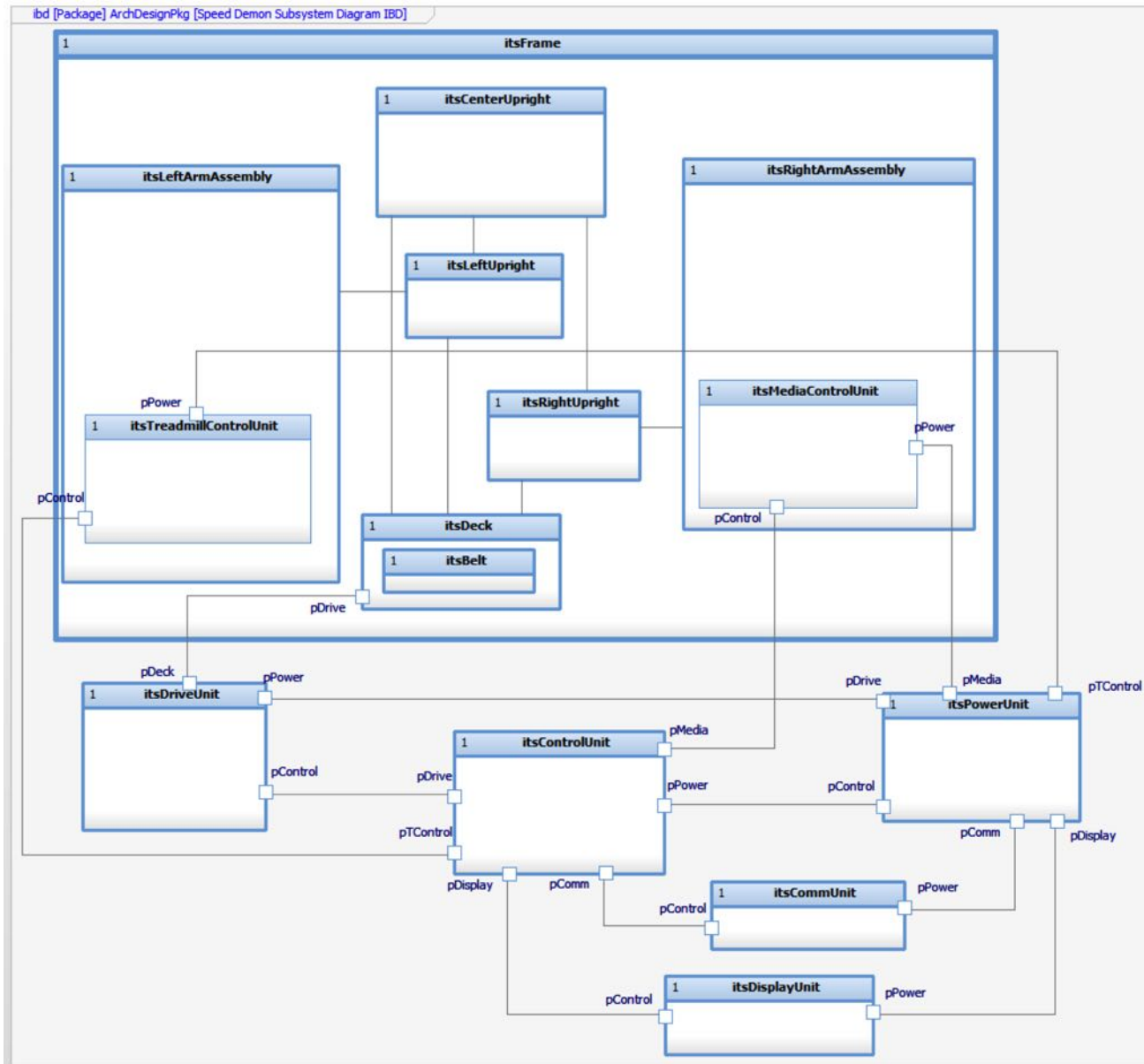
Architecture View for Control Flow (SysML 1.3)



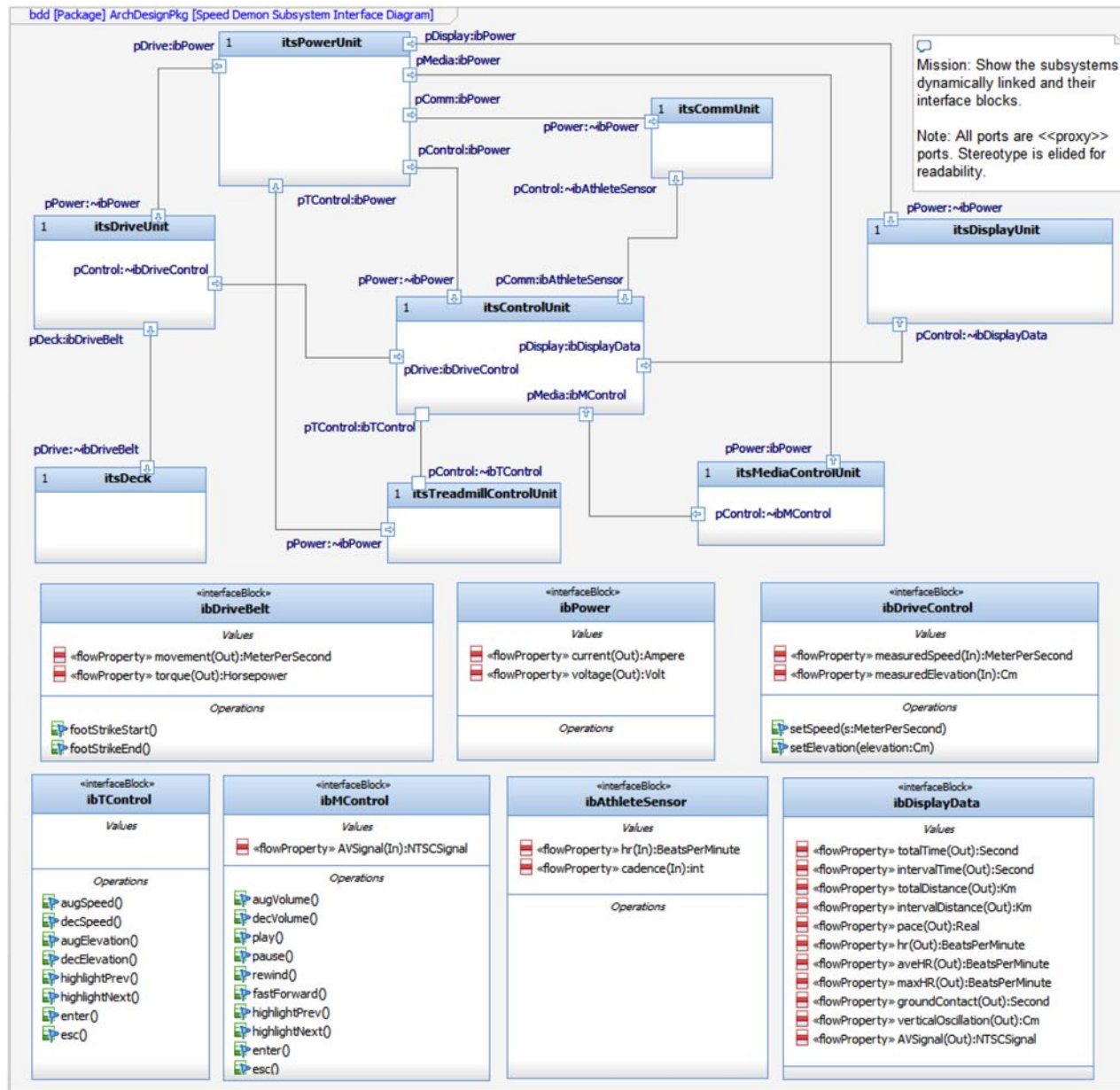
Architectural View – Subsystem Diagram



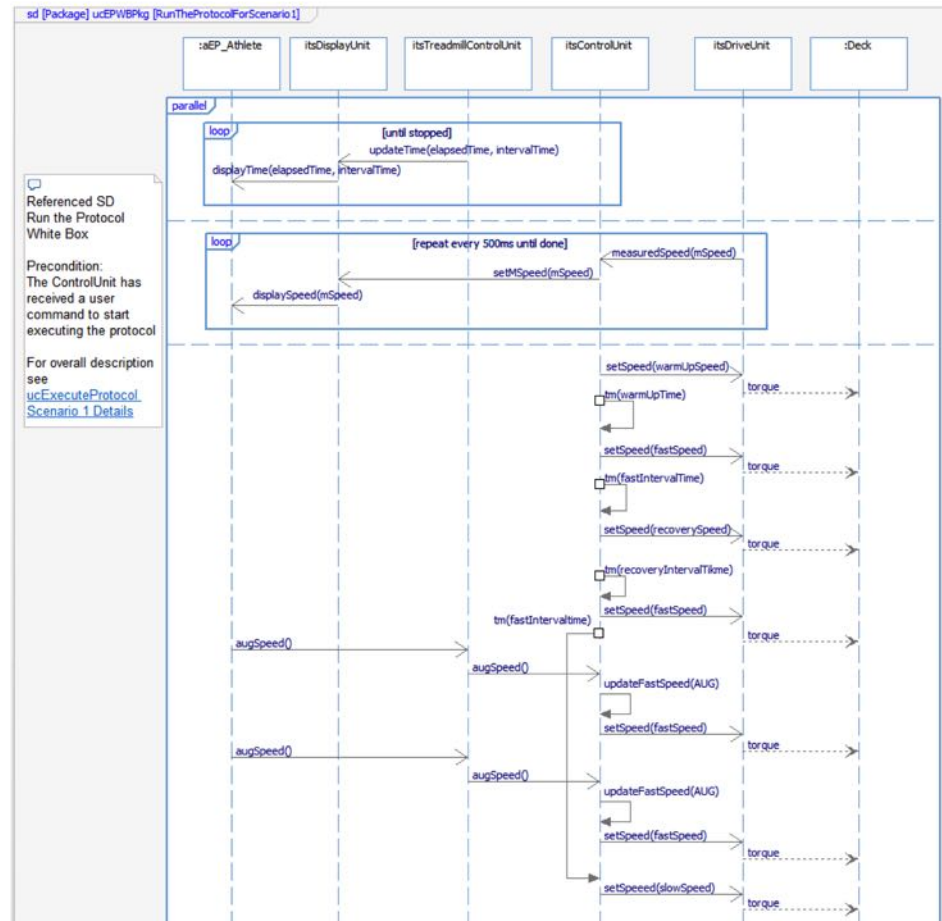
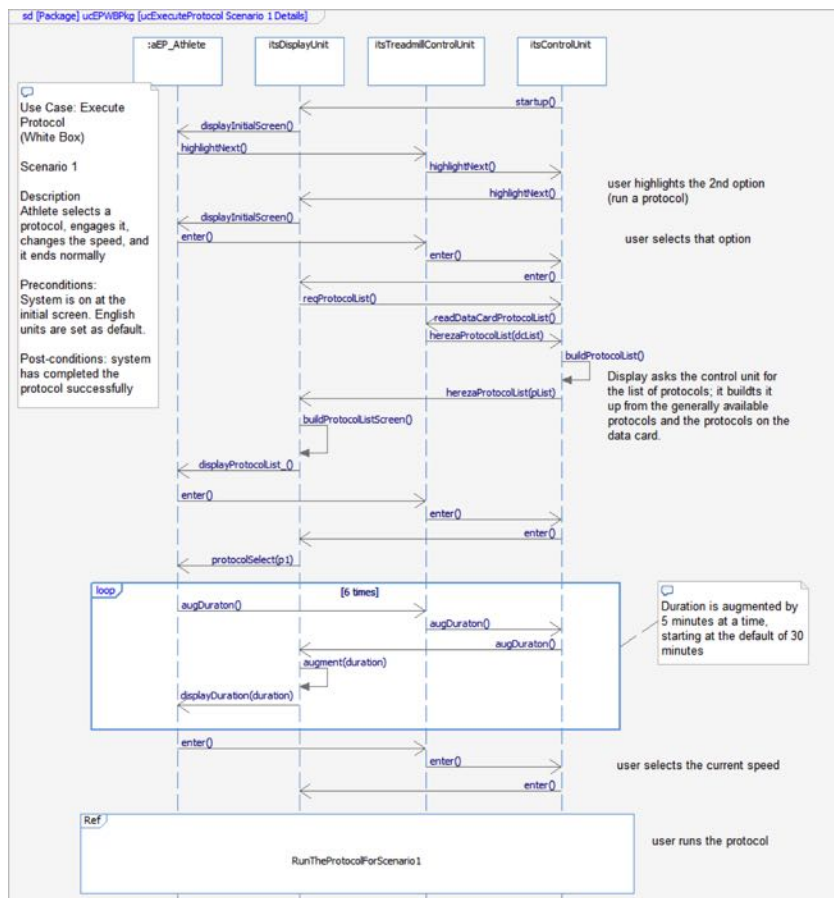
Architectural View – Subsystem Detail Structure



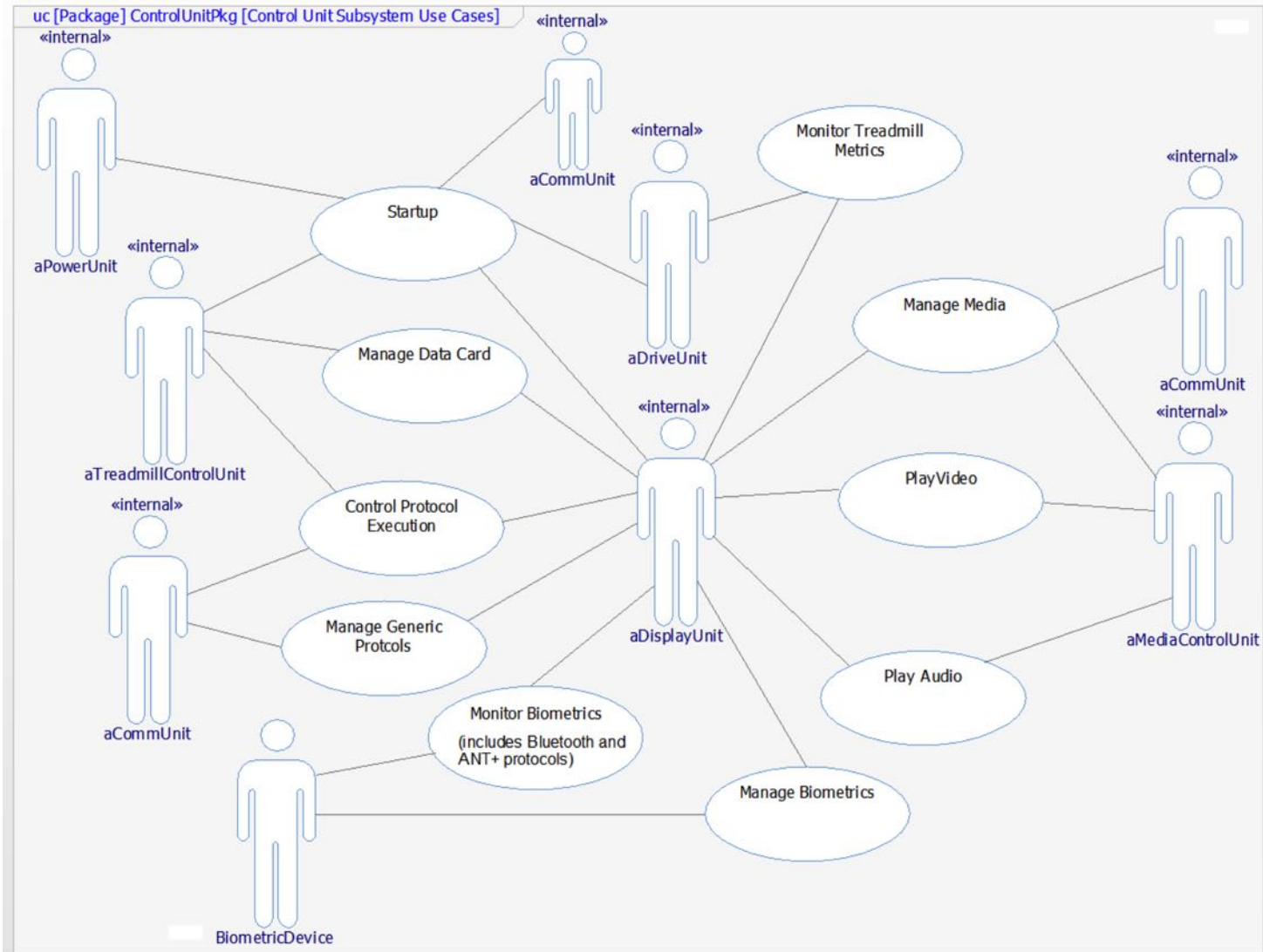
Architecture with (logical) subsystem interfaces



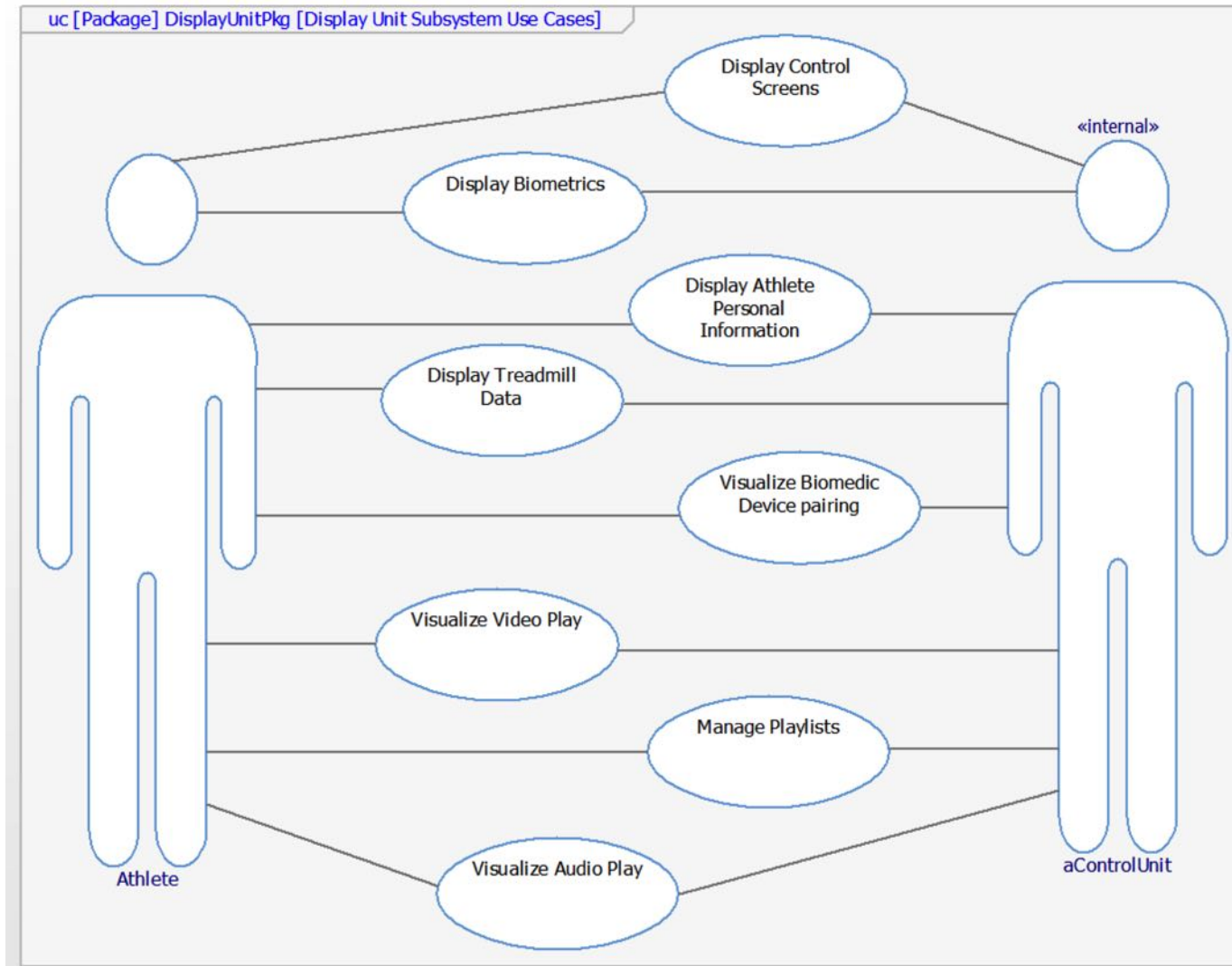
Architectural Verification via Simulation/Execution



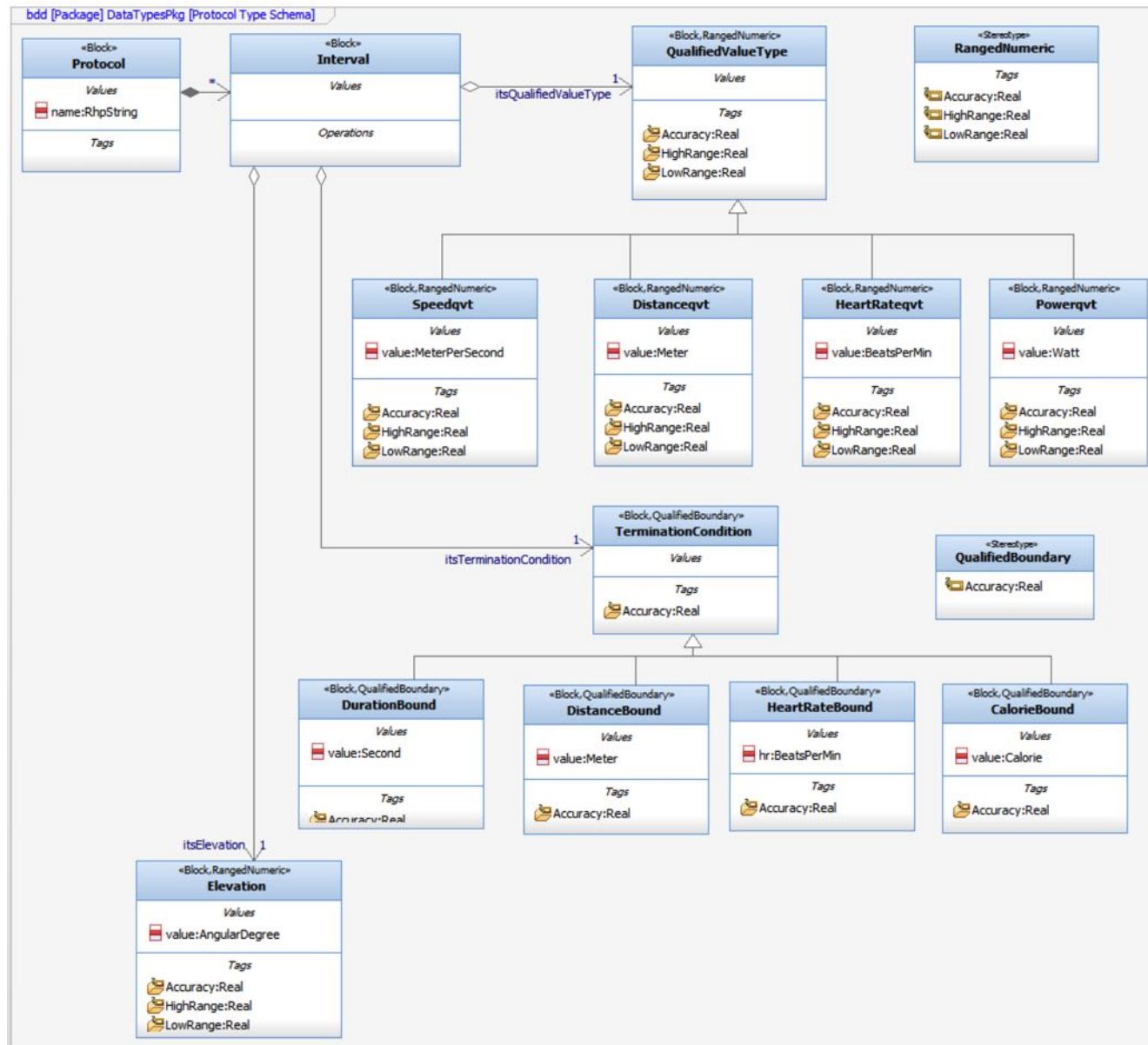
Subsystem Specification (Control Unit)



Subsystem Specification (Display Unit)



Update / Elaborate Data/Flow Schema



Capturing ICDs in the Model

- ICDs are not just a list of services but include:

- For each Service
 - Functional Description
 - Preconditions
 - Postconditions
 - Invariants
 - Performance
 - Error handling
 - Synchronization type
- For each parameter

Description

Type

Units

Valid subrange

Default value

- This metadata can be easily added as tags defined in stereotypes

The image displays two overlapping windows from the IBM Rational Model Architect software, showing the 'Stereotype : ICDType in ucAreaSearchPkg' and 'Stereotype : ICDService in ucAreaSearchPkg' property editors. Both windows have tabs for 'General', 'Description', 'Relations', 'Tags', and 'Properties'. The 'Local' section of each window contains a table of properties.

Stereotype : ICDType in ucAreaSearchPkg

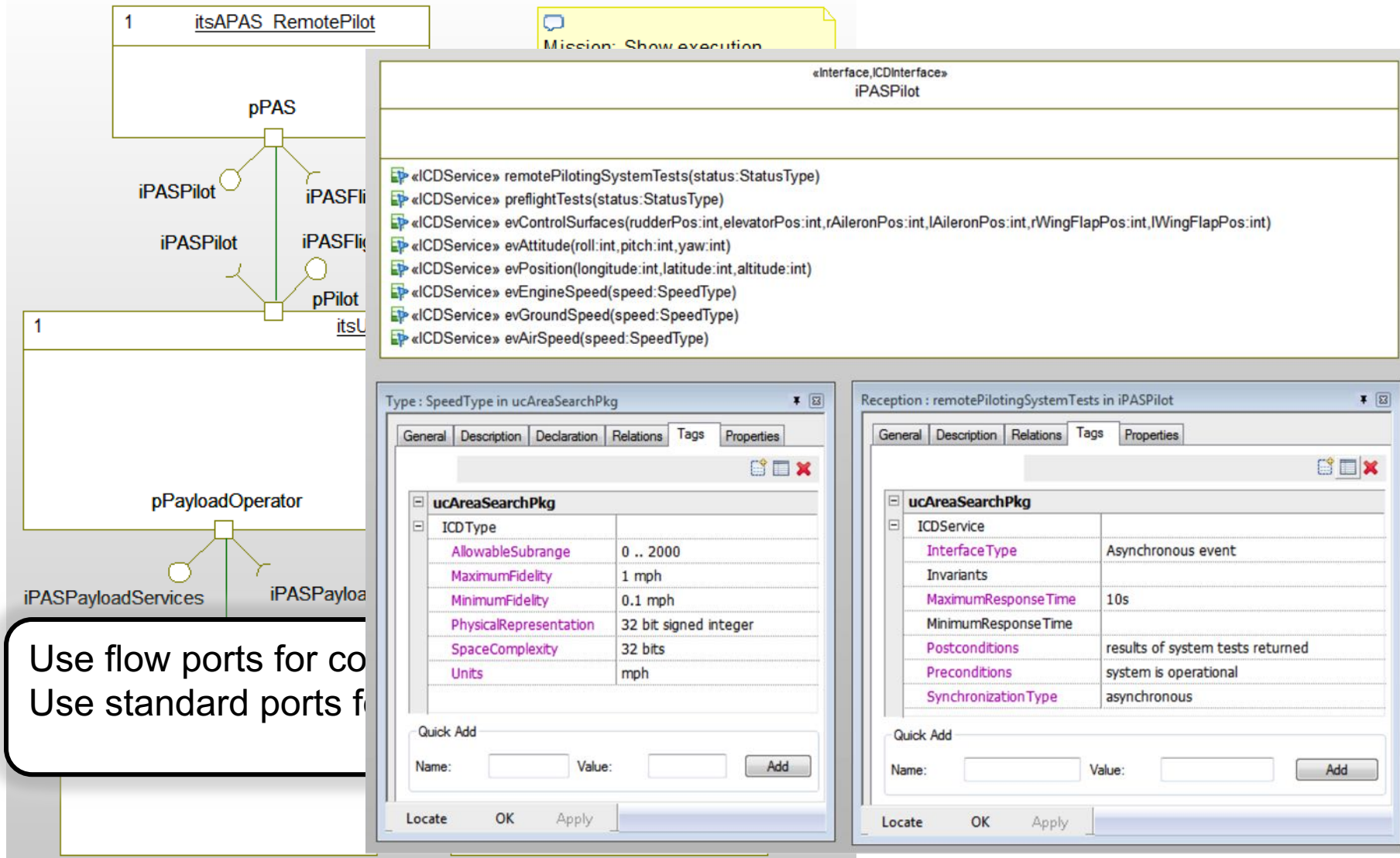
Local	
AllowableSubrange	
MaximumFidelity	
MinimumFidelity	
PhysicalRepresentation	
SpaceComplexity	
Units	

Stereotype : ICDService in ucAreaSearchPkg

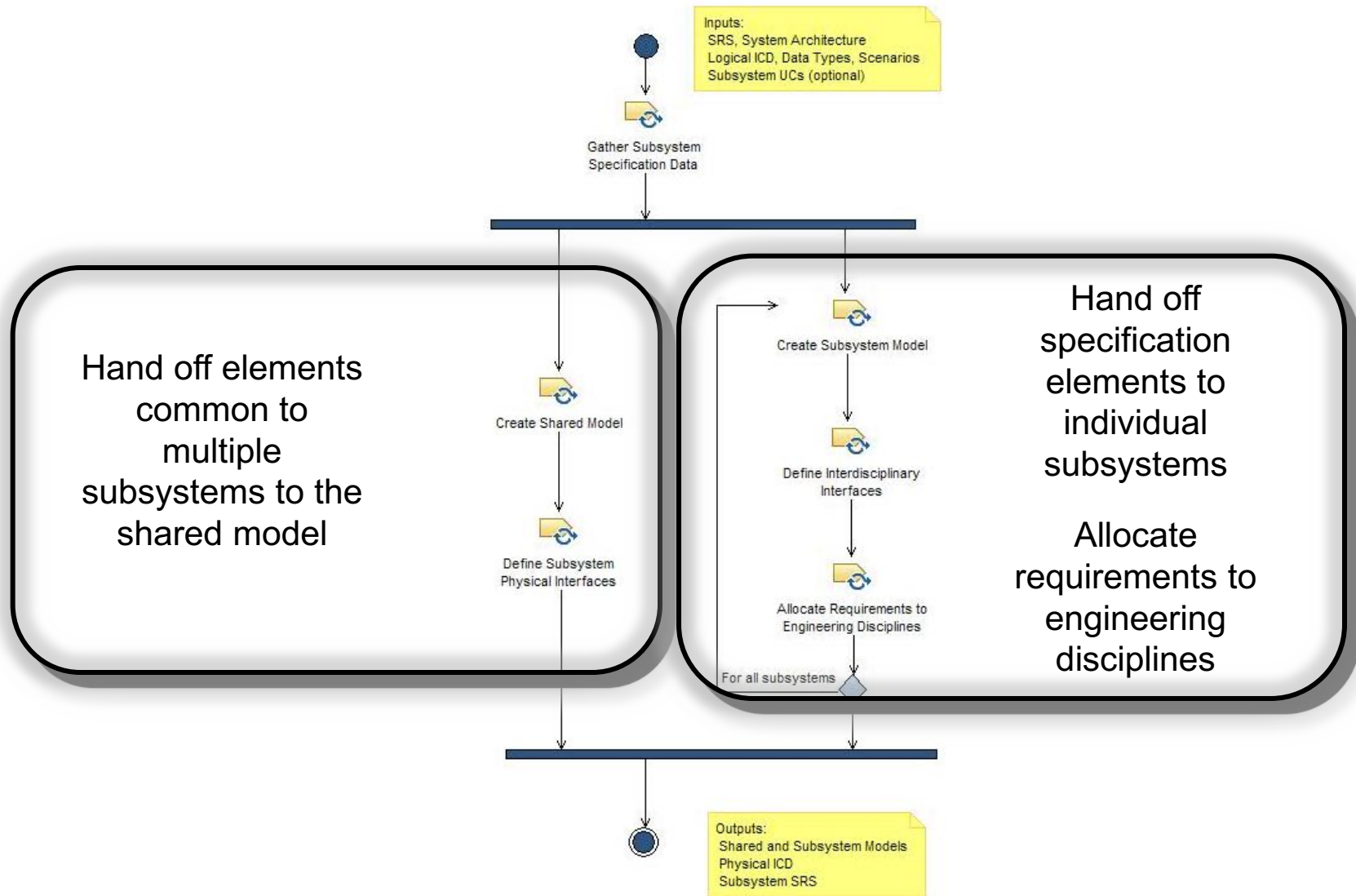
Local	
InterfaceType	
Invariants	
MaximumResponseTime	
MinimumResponseTime	
Postconditions	
Preconditions	
SynchronizationType	

At the bottom of the ICDService window, there is a 'Quick Add' section with 'Name:' and 'Value:' input fields and an 'Add' button. The bottom of the window also features 'Locate', 'OK', and 'Apply' buttons.

Capturing ICDs in the Model



Hand off Workflow

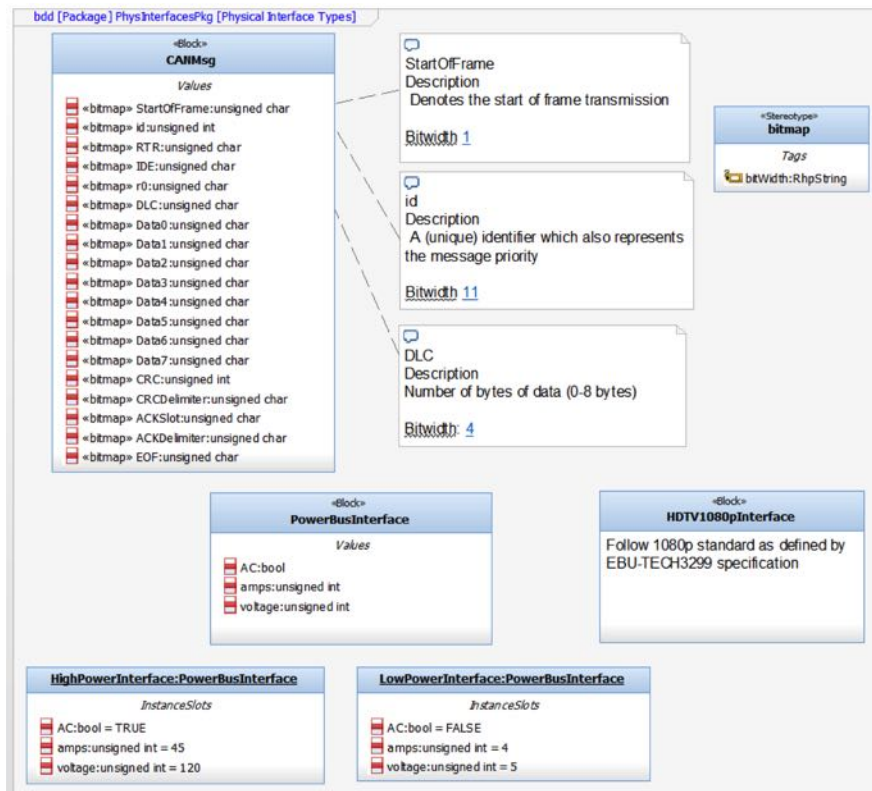


Convert Logical to Physical Interfaces

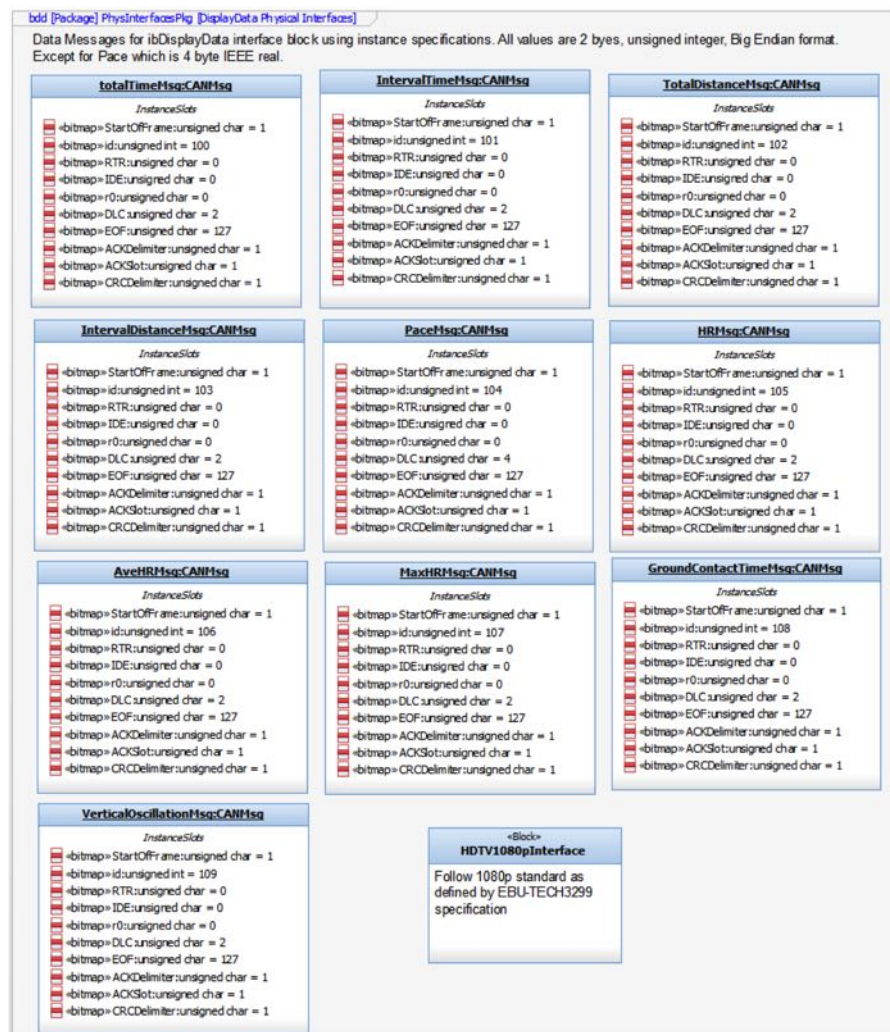


Logical Interfaces

SpeedDemon Physical Interfaces (using CAN™ Bus)

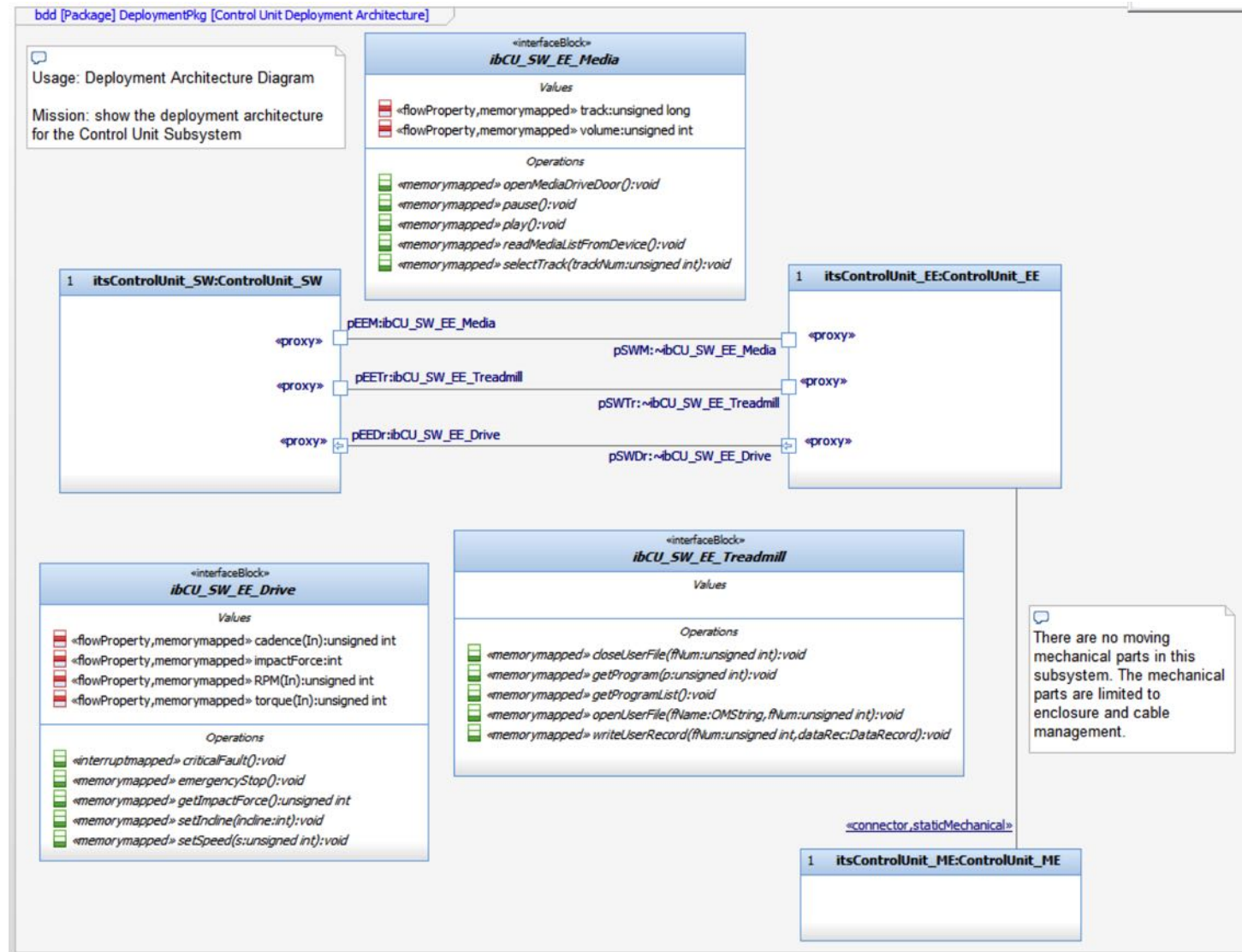


Interface structure specification



Instance specifications for messages

Subsystem Deployment Architecture (SW-EE-ME)



Instance Specs for SW-EE Interfaces in Control Unit

bdd [Package] DeploymentPkg [Details of iBCU_SW_EE_Drive interface block]

Mission: show the interface details for the SW-EE interface for drive control in the Control Unit Subsystem

**«interfaceBlock»
iBCU_SW_EE_Drive**

Values

- «flowProperty, memorymapped» cadence(In):unsigned int
- «flowProperty, memorymapped» impactForce:int
- «flowProperty, memorymapped» RPM(In):unsigned int

Operations

- «interruptmapped» criticalFault():void
- «memorymapped» emergencyStop():void
- «memorymapped» getImpactForce():unsigned int
- «memorymapped» setIncline(Incline:int):void
- «memorymapped» setSpeed(s:unsigned int):void

**«flowProperty, memorymapped»
impactForce:int**

Returns impact force in Kg

Tags

- Bitmap:RhpString=A000:0014-A000:0017 4 byte unsigned integer
- direction:FlowDirection=Unspecified
- Numer_Of_Bytes:RhpString=4
- Range_High:RhpReal=500
- Range_Low:RhpReal=0
- Start_Address:RhpString=A000:0014
- Timing_Constraints:RhpString
- Usage:RhpString=Read only access

**«flowProperty, memorymapped»
RPM(In):unsigned int**

Returns the current measured drive RPM

Tags

- Bitmap:RhpString=A000:0010-A000:0013 4-byte unsigned integer
- direction:FlowDirection=In
- Numer_Of_Bytes:RhpString=4
- Range_High:RhpReal=10,000
- Range_Low:RhpReal=0
- Start_Address:RhpString=A000:0010
- Timing_Constraints:RhpString
- Usage:RhpString=Read only access

**«memorymapped»
setSpeed(unsigned int):void**

This command to the electronics sets the speed of the drive unit controlling the belt.

Tags

- Bitmap:RhpString=A000:0000 - A000:0003 Write 4 byte speed value
- Numer_Of_Bytes:RhpString=4
- Range_High:RhpReal=0
- Range_Low:RhpReal=800
- Start_Address:RhpString=A000:0000
- Timing_Constraints:RhpString
- Usage:RhpString=Write the speed value in the 4 byte block. ...

**«memorymapped»
setIncline(Incline:int):void**

The command to the electronics sets the degree of incline of the deck. Value is 10° the angle in degrees (e.g. value of -35 means an angle of -3.5 degrees)

Tags

- Bitmap:RhpString=A000:0006-A000:0007 2-byte integer ...
- Numer_Of_Bytes:RhpString=2
- Range_High:RhpReal=200
- Range_Low:RhpReal=-100
- Start_Address:RhpString=A000:0006
- Timing_Constraints:RhpString
- Usage:RhpString=Write sets the commanded value; read ...

**«flowProperty, memorymapped»
cadence(In):unsigned int**

Returns the currently measured cadence value in 2 bytes with units of steps/minute (of both legs)

Tags

- Bitmap:RhpString=A000:000A-A000:000B 2 byte unsigned integer
- direction:FlowDirection=In
- Numer_Of_Bytes:RhpString=2
- Range_High:RhpReal=220
- Range_Low:RhpReal=0
- Start_Address:RhpString=A000:000C
- Timing_Constraints:RhpString
- Usage:RhpString=Read only access

**«interruptmapped»
criticalFault():void**

This electronic service generates an interrupt when a critical fault occurs. The data at the specified data address is the 2-byte error code.

Tags

- Byte_Width:RhpString=2
- Data_Address:RhpString=A100:0000
- Data_Field_Type:RhpString=unsigned integer
- Interrupt_number:RhpString=0x0018

**«memorymapped»
emergencyStop():void**

Writing a nonzero value causes an emergency stop. Writing #0000 re-enables movement.

Tags

- Bitmap:RhpString=A000:0008-A000:0009 2 byte unsigned integer
- Numer_Of_Bytes:RhpString=2
- Range_High:RhpReal=0
- Range_Low:RhpReal=#FFFF
- Start_Address:RhpString=A000:0008
- Timing_Constraints:RhpString=Emergency stop engages
- Usage:RhpString=Non-zero write engages function

**«flowProperty, memorymapped»
torque(In):unsigned int**

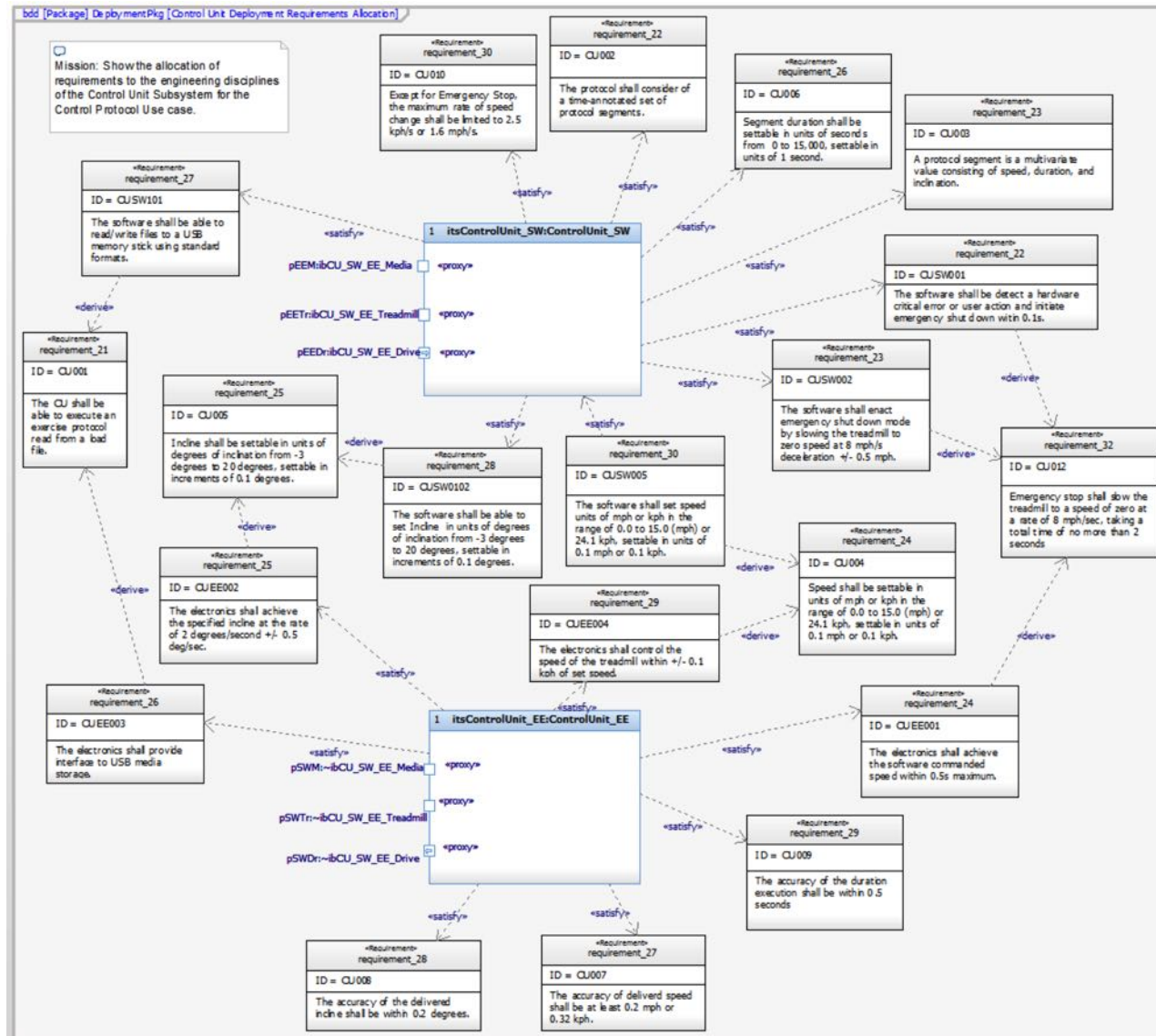
Returns the current measured drive torque in 4 bytes. Units of 0.01 Foot-Pounds (e.g. 400 is 4.0 ft-lbs)

Tags

- Bitmap:RhpString=A000:000C-A000:000F 4 byte unsigned integer
- direction:FlowDirection=In
- Numer_Of_Bytes:RhpString=4
- Range_High:RhpReal=1500
- Range_Low:RhpReal=0
- Start_Address:RhpString=A000:000C
- Timing_Constraints:RhpString
- Usage:RhpString=Read only access

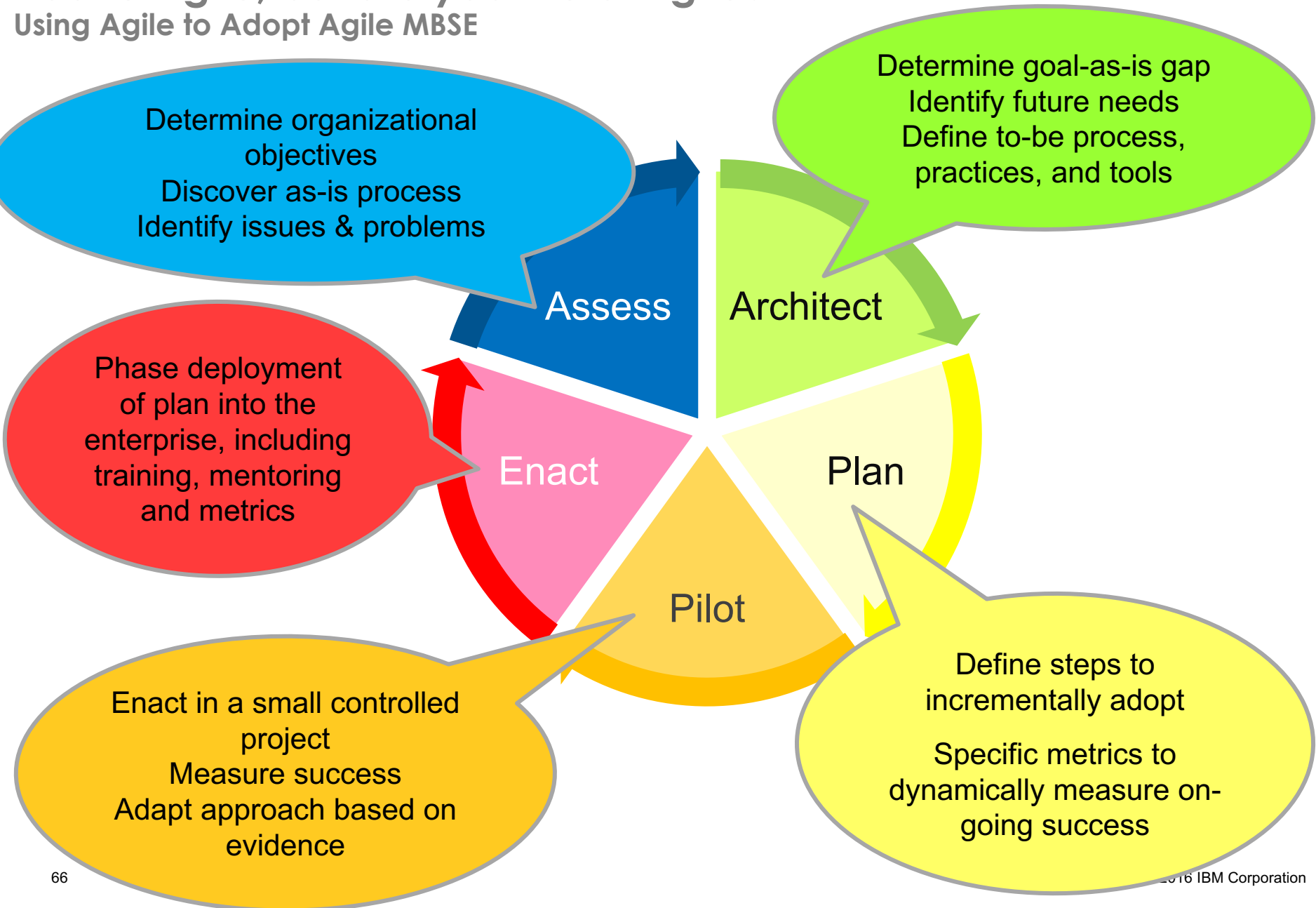
Usage: Write the speed value in the 4 byte block. Reading the value reads the current speed of the treadmill (note: this is not necessarily the value just written). Speed is in units (0.01 m/sec) so a value of 671 is 6.71 m/sec

Allocation on Subsystem requirements to engineering disciplines



You're Agile, but are you Meta-Agile?

Using Agile to Adopt Agile MBSE



Summary

MBSE provides
precision and
verifiability to the SE
Process

Agile methods add
quality, responsiveness
and adaptability to the
process

Continuous verification
allows you to avoid
costly defects

Adopt Agile in an
incremental, measured
fashion for best results

IBM's Rational tooling
supports MBSE and agile
methods

IBM's Harmony Process
defines an agile MBSE
process with industry best
practices

References

