

Graphical Representation of Situation Awareness in Joint Cognitive Systems

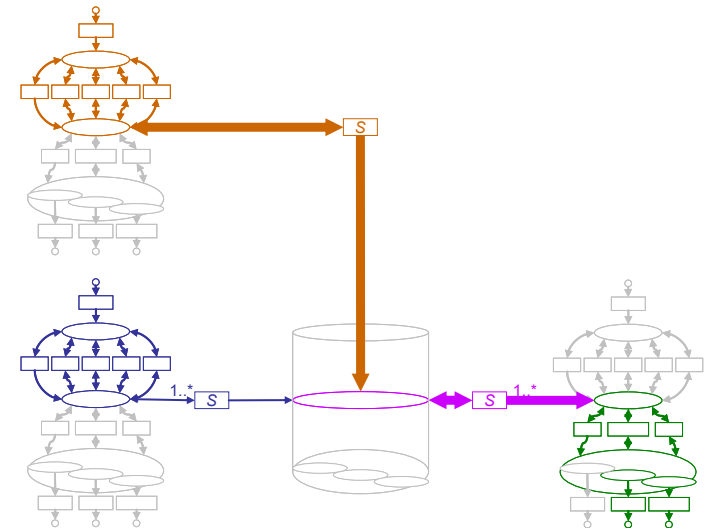
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Central idea

- Charting of joint cognitive systems (humans & machines) to examine:
 - Where is situation awareness being held (or lost)?
 - How is situation awareness used in the system's workflows?
 - How can we make improvements (via design, technology)?



Overview

- Situation awareness (SA) as a focus of systems engineering
- Graphical representation of
 - SA in an individual agent
 - SA across multiple agents
 - Architectures for joint cognitive systems
- Case Study - Field artillery with digital technologies



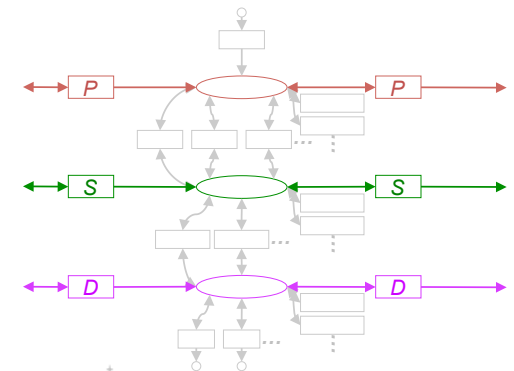
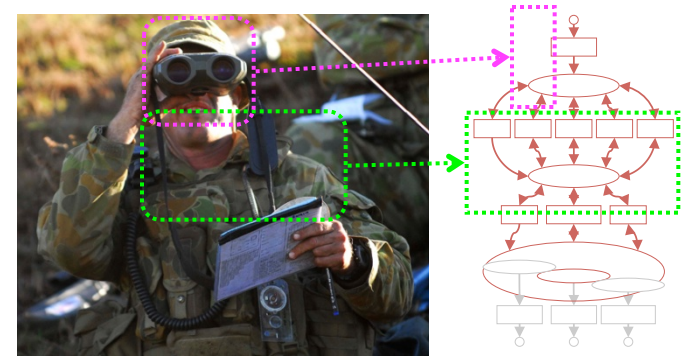
Why is situation awareness topical?

- SA is fundamental to effective human functioning in complex systems (Endsley et al, 2007)
- “Enhanced situational awareness leads to better decision-making” (Australian Defence Force Network Centric Warfare Roadmap, 2009)
- *but*
 - Systems engineers lack methods for studying SA in joint cognitive systems (humans & machines)
 - Extant methods are for engineering the human-machine interface to individual people

Mica R Endsley, Robert Hoffman, David Kaber, and Emilie Roth. 2007. Cognitive Engineering and Decision Making: An Overview and Future Course. *Journal of Cognitive Engineering and Decision Making* 1 (1):1-21.

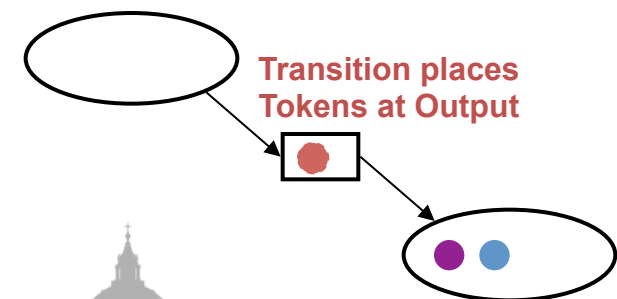
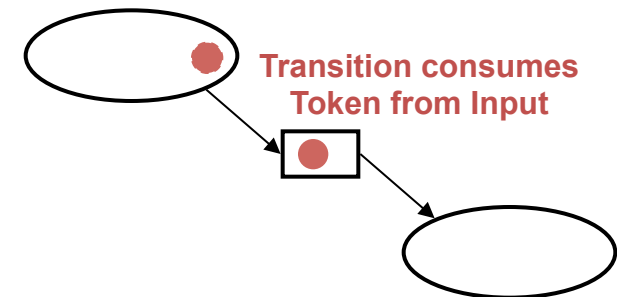
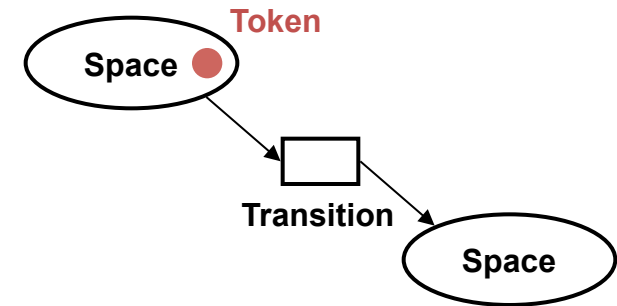
Approach

- “Enable an engineer to study a joint cognitive system as if they were using circuit schematics to study an electronic system”
 - Building block encapsulating SA in an individual agent
 - Rules for assembling agents into systems & workflows



Underlying notation

- Coloured Petri Nets
 - Spaces hold tokens
 - Up to some capacity
 - Transitions between spaces
 - Consume tokens from inputs
 - Place tokens at outputs
 - Tokens have colour
 - Transitions can operate differently
- Timed Coloured Petri Nets
 - Transitions
 - Have duration
 - May wait for trigger time



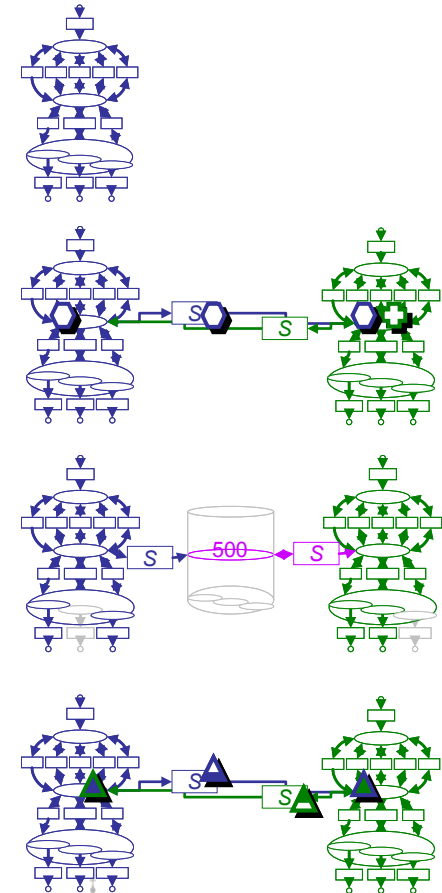
Graphical representation

- SA in an individual agent
- SA across multiple agents
- Architectures for joint cognitive systems



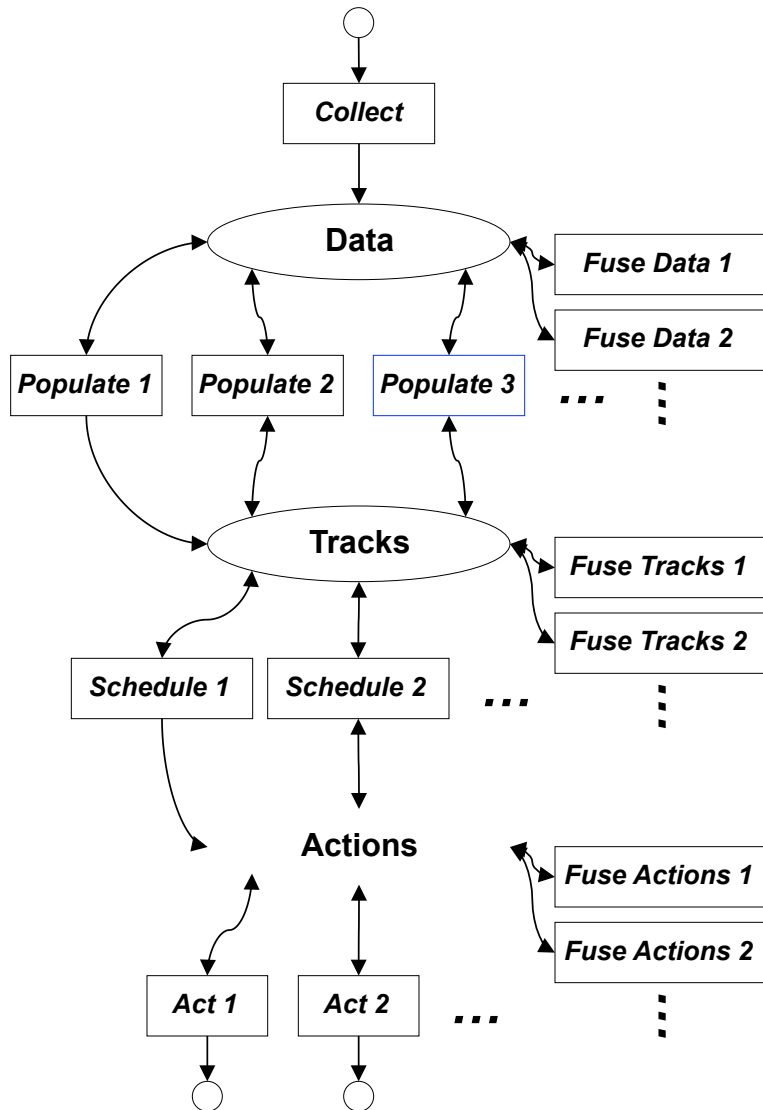
Design patterns

- Schools of thought on fostering SA in joint cognitive systems
 - Individual SA
 - SA is held in a single agent
 - Shared SA
 - Agents have SA over the same tracks
 - Distributed cognition
 - SA is held in mediating artefacts with high storage capacity
 - Compatible SA
 - Agents can have different but compatible perceptions of objects in the environment



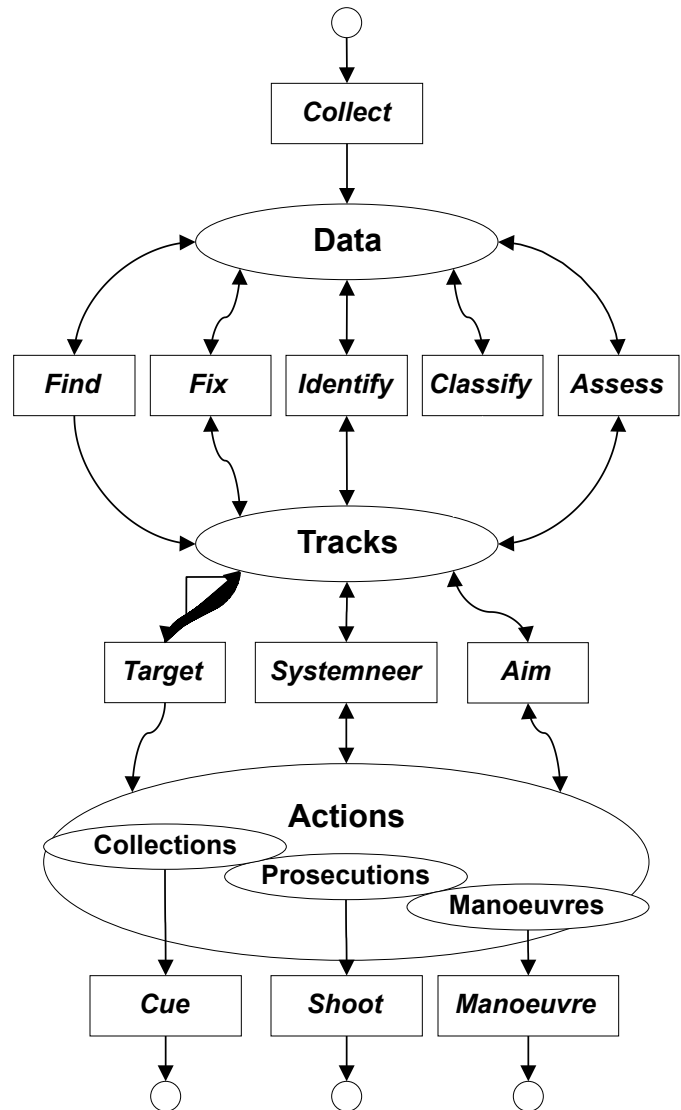
P M Salmon, N A Stanton, G H Walker, D P Jenkins, *Distributed Situation Awareness*, Ashgate 2009.

Building-Block – DTA Agents



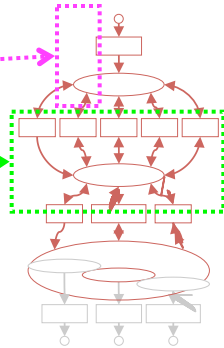
- Collect **data**
 - «Location» at «Time» was measured as «Measurements»
- Populate **tracks** = Situation Awareness
 - Over «Time Interval», «Object» has / will have «Property» with «Value»
- Schedule **actions**
 - [At «Time»] [«Actor Object»] will «Act» [on «Target Object»] [using «Subsystem»] [directed at «Location»]
- Perform actions
- Fusion (data/tracks/actions)

Sensor-Shooter DTA Template

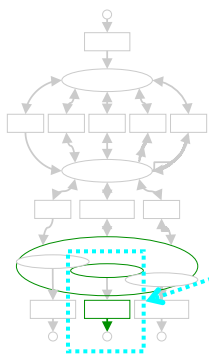


- Specialised tracks
 - Objects in battlespace
- Specialised actions
 - Cueing of sensors
 - Shooting weapons
 - Manoeuvres
- Tracks to actions
 - Target an object
 - Select a system to use
 - Aim at a location × time

Agents implement portions of a DTA Template



- Soldier
 - Collects data (via eyes, binoculars)
 - Populates tracks on entities
 - Schedule targets for prosecution
- Artillery unit
 - Acts to prosecute



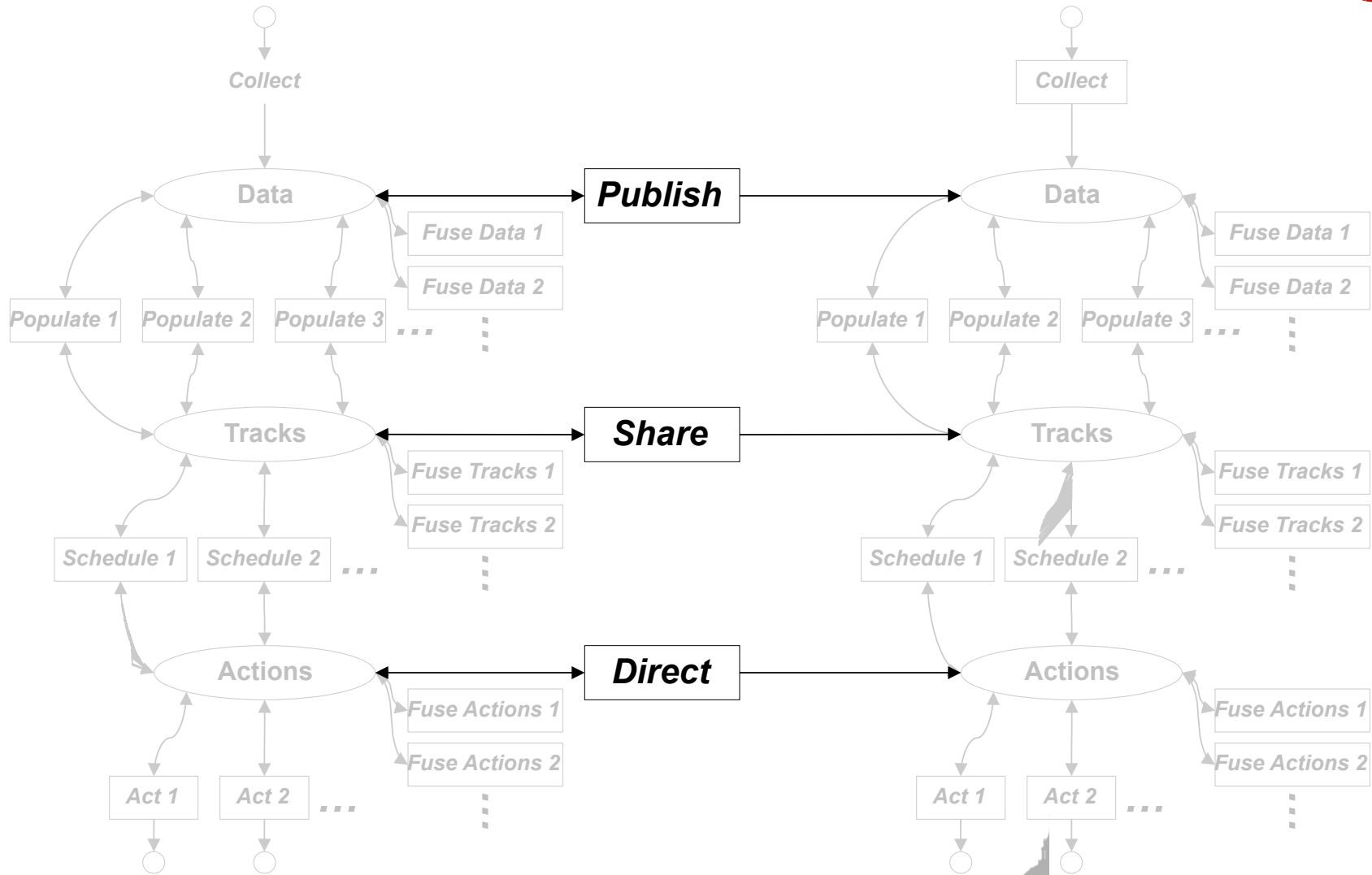
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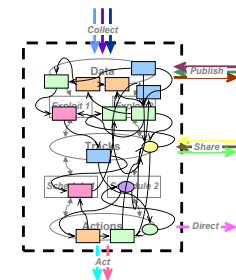
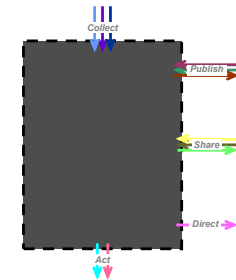
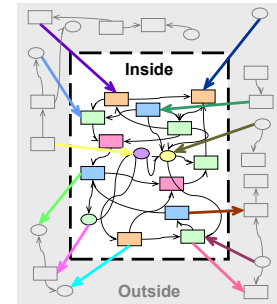


Rules for composing DTA Agents



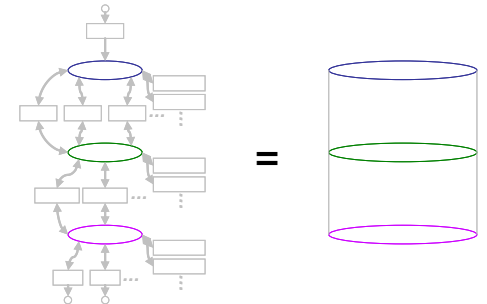
Principles for modelling real-world systems

- Identify system boundaries and cross-boundary transactions
 - Free Body Diagram
- Match cross-boundary transactions to DTA composition rules
 - Black Box Analysis
- Match internal processes with DTA template
 - White Box Analysis

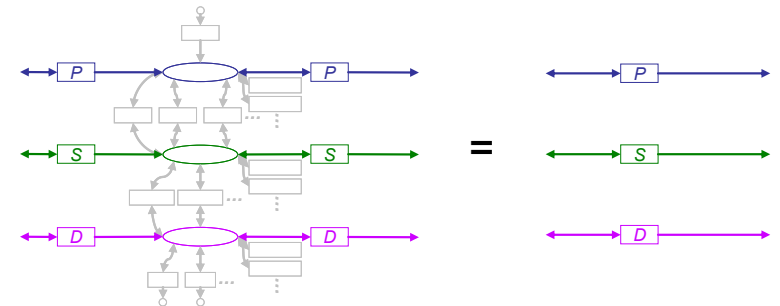


Special cases

- Storage-only agent
 - Stores information but does not process it



- Relay agent
 - Show the agent in full if it is *persistent*
 - Show only the transaction if it is *non-persistent*



Persistent

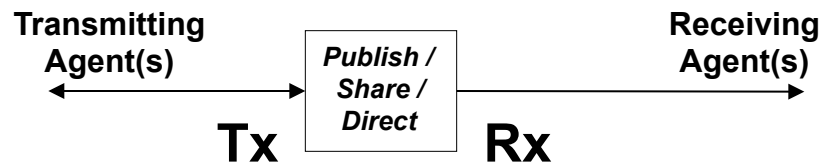
Non-persistent

Graphical representation

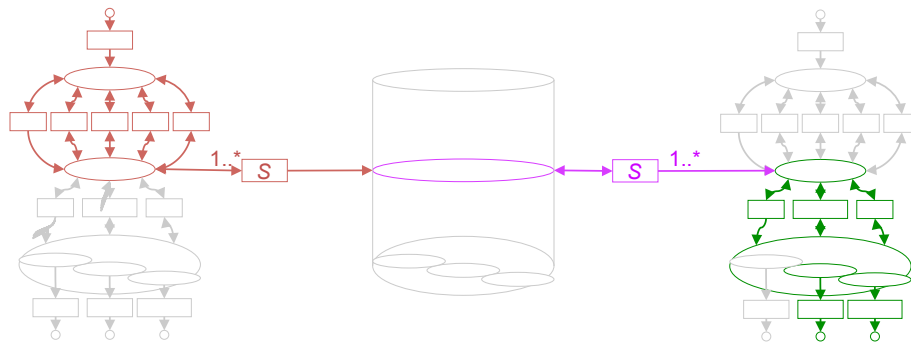


- SA in an individual agent
- SA across multiple agents
- Architectures for joint cognitive systems



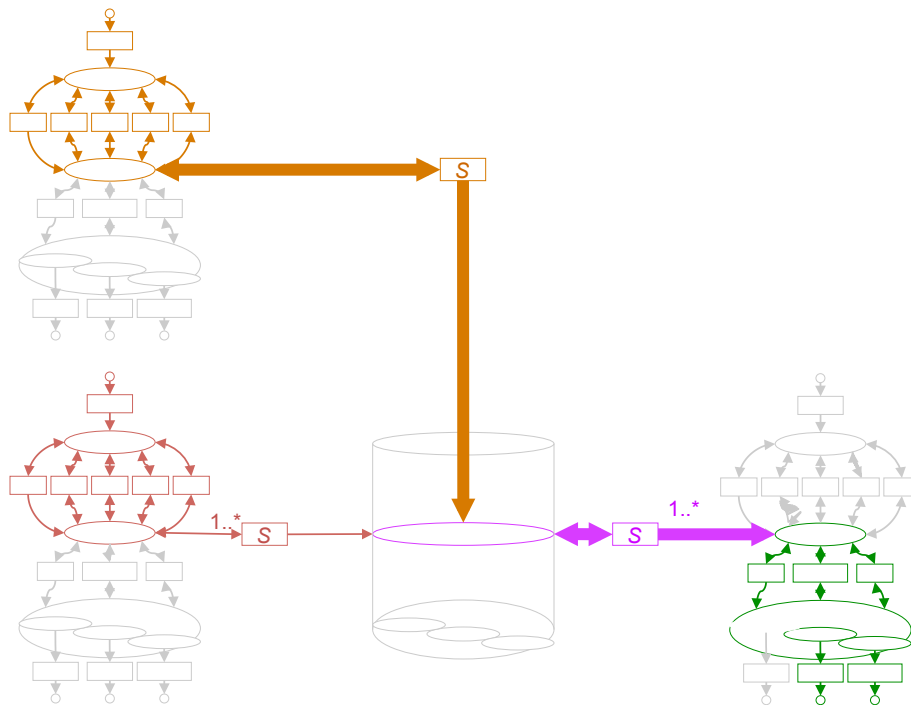
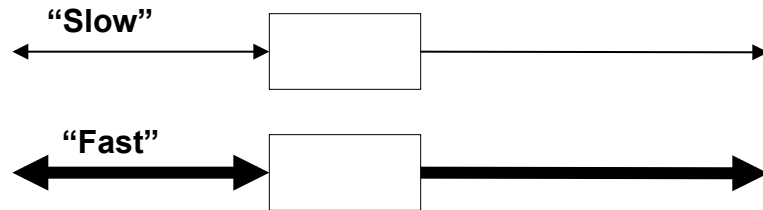


- **1** Exactly 1 agent (default)
- **1...#** Up to # agents
Arbitrarily many agents
- (and must have Tx = 1 or Rx = 1)



1...* agents shares tracks with
1 agent (storage-only),
which shares with **1...*** agents

Speed & Tempo



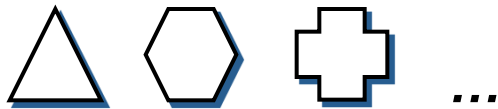
- **Line thickness** denotes speed and/or tempo
 - Transitions that occur quickly (*high speed*)
 - Transitions that occur frequently (*high tempo*)

1 agent shares tracks at high tempo and

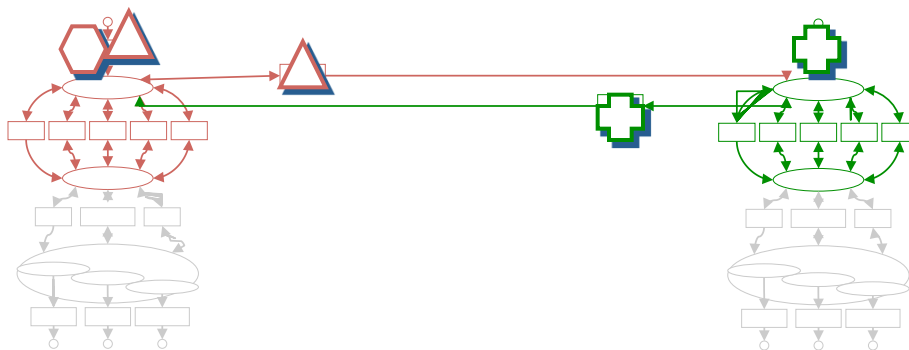
1...* agents shares tracks at slow tempo

with 1 agent (storage-only), which shares in fast time with 1...* agents

Different Data



- ***Data Icons*** denote different data



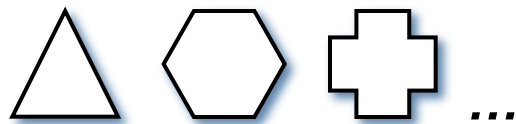
Agent collects  

Agent collects 

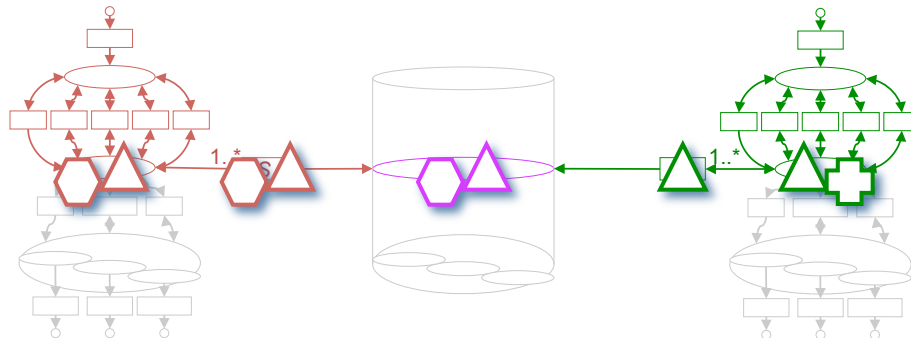
  are published

 is not published

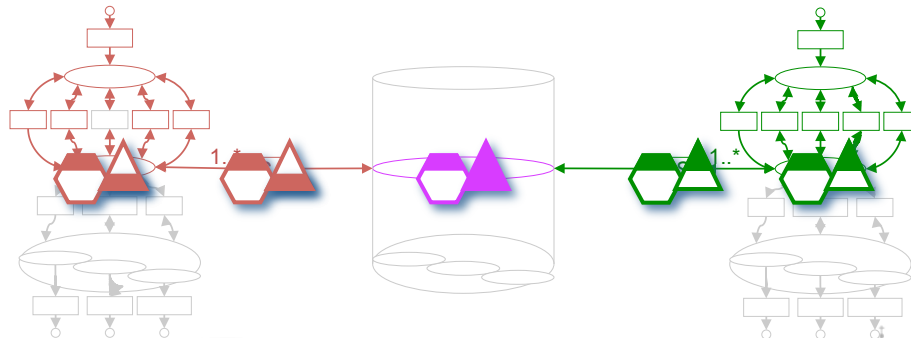
Different Objects / Properties



- **Track Icons** denote different [classes of] object
- **Bands** denote different properties of tracks

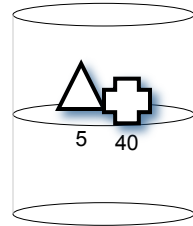
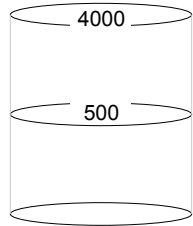


Sharing tracks on  
Tracks on  are not shared

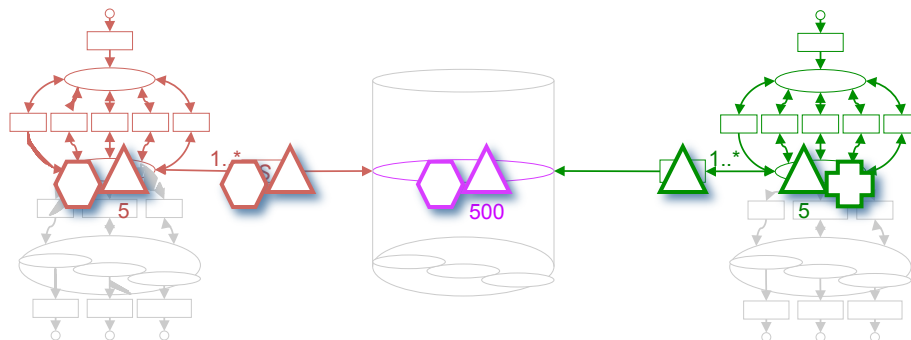


Sharing same property of 
Sharing different properties of 

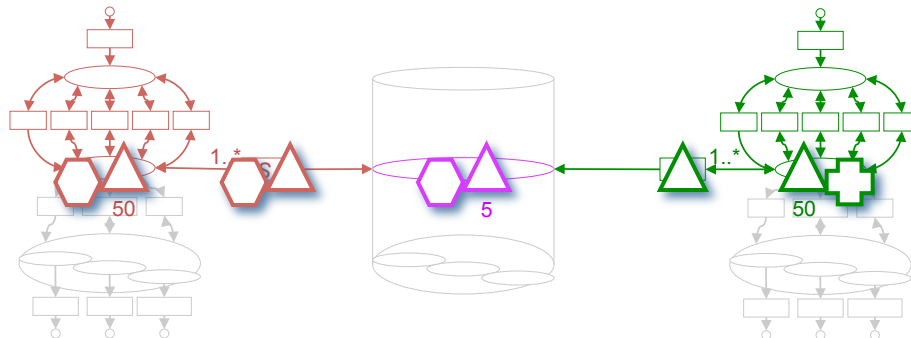
Storage Capacity



• **Annotations** for number of tokens that can be held



Bulk of \triangle are stored in the **central agent**



Bulk of \triangle are stored in the **edge agents**

Case Study

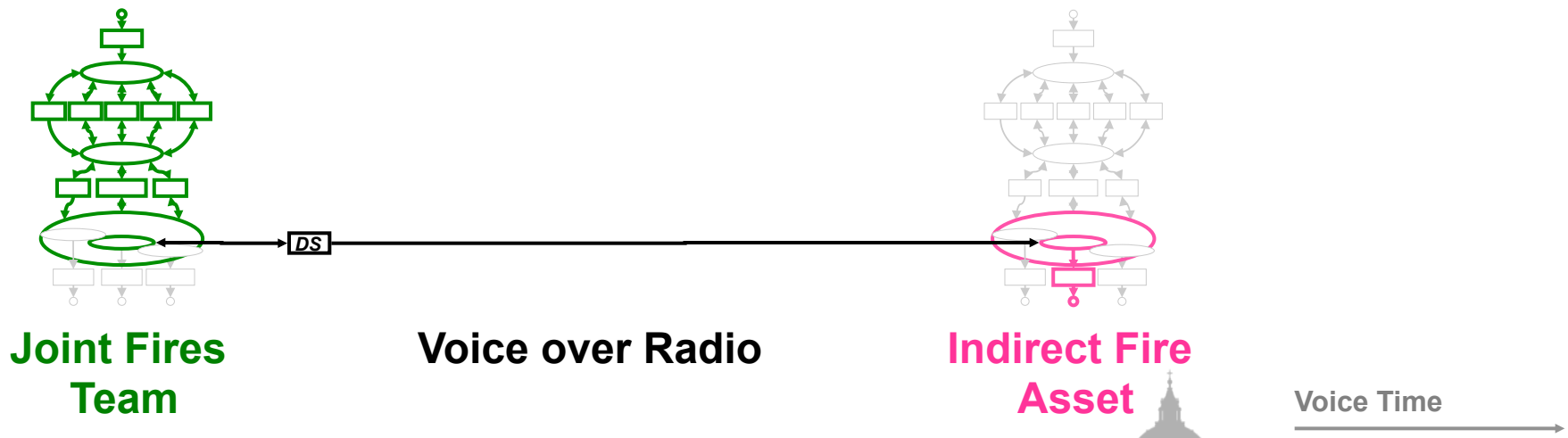
- Field artillery
 - Cannon, rockets, mortars
 - Modern operations characterised by *indirect fires*
 - Artillery does not have direct line-of-sight to the target
 - Inherently networked, invites improvement via digital-tempo systems



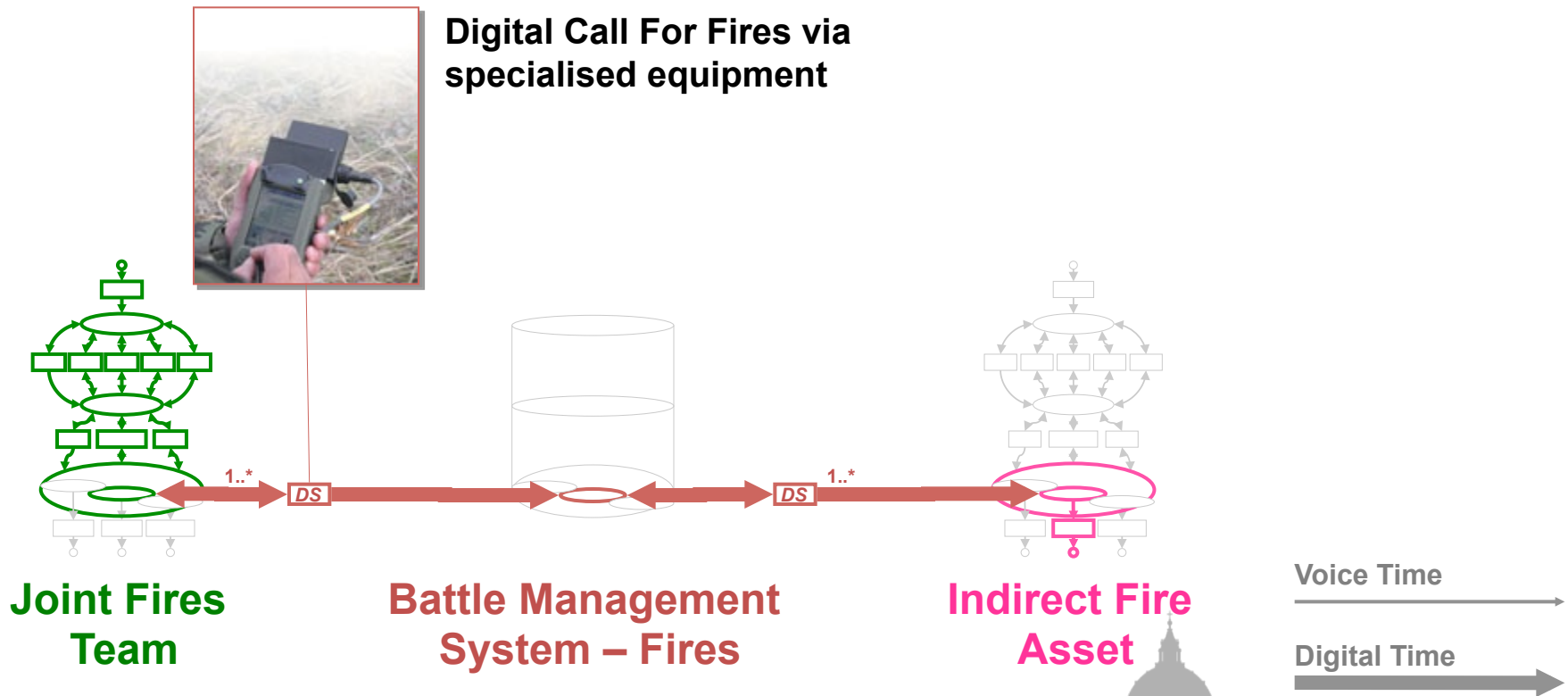
Options and opportunities from BMS-F?
(Battle Management System – Fires)



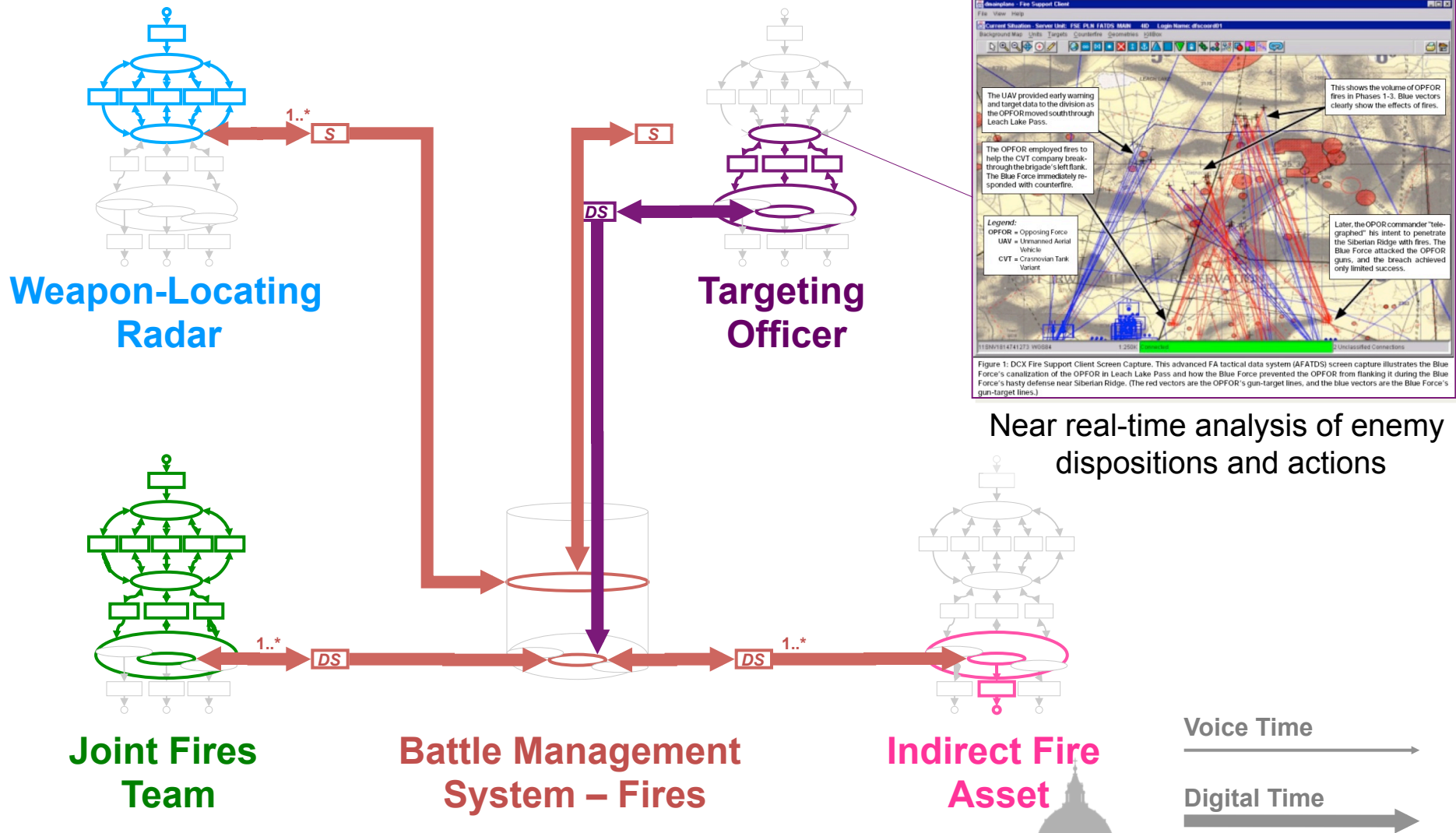
Baseline System



Digital Call for Fires

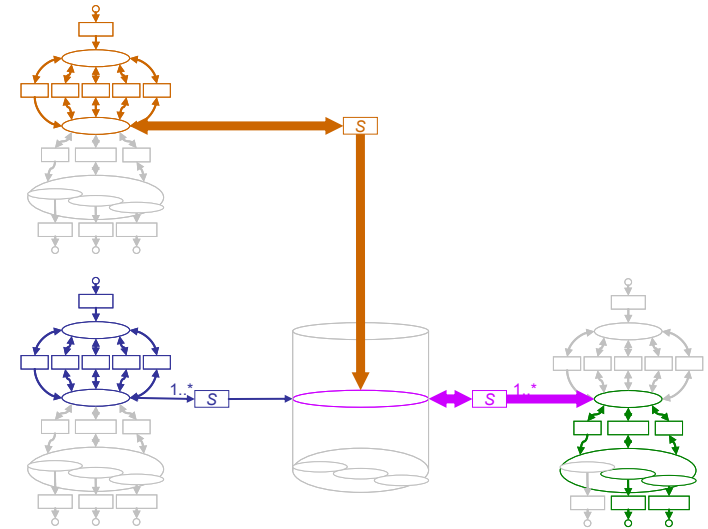


Near Real-Time Analysis



Conclusion

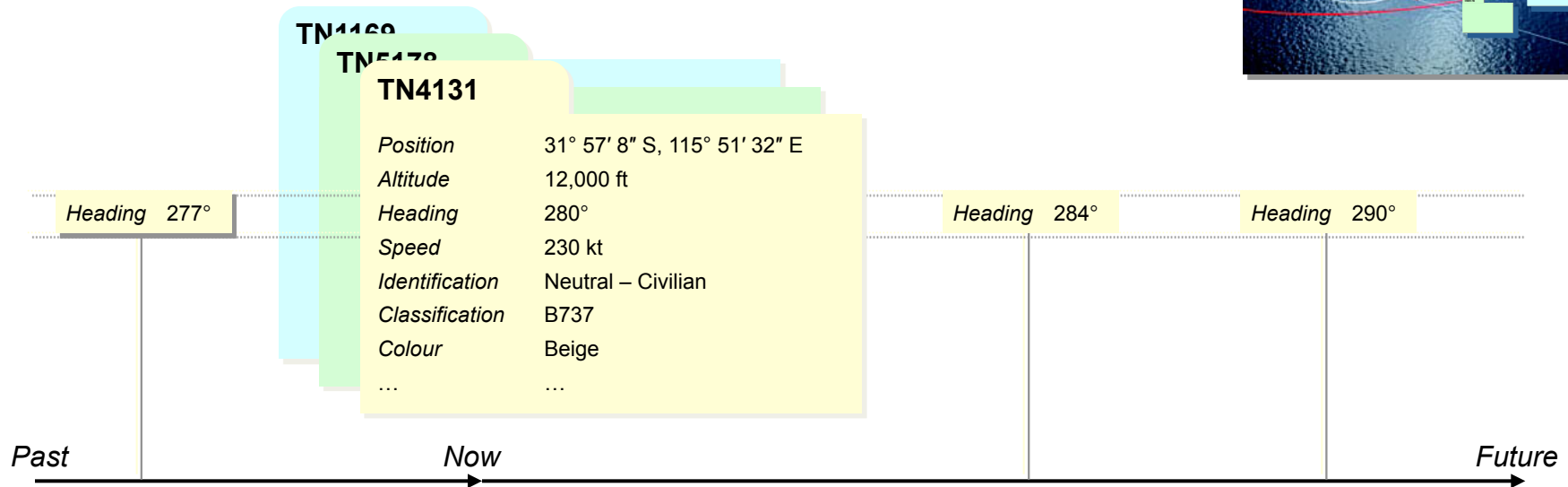
- Charting of joint cognitive systems (humans & machines) to examine:
 - Where is situation awareness being held (or lost)?
 - How is situation awareness used in the system's workflows?
 - How can we make improvements (via design, technology)?
- Applied to systems engineering the Australian Defence Force for Network-Centric Warfare



DTA Agent embeds Endsley model of SA

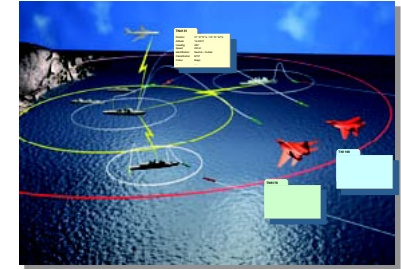
Perception of elements
in current situation

Level I «Object»



Tracks

Over «Time Interval», «Object» has / will have
«Property» with «Value»



Comprehension of current situation

Level II «Property» with «Value»

Projection of future status

Level III «Time Interval»

Endsley, Mica R. 1995. Toward a Theory of Situation Awareness in Dynamic Systems.
Human Factors 37 (1):32-64.