

25th anniversary
annual INCOSE
international symposium
Seattle, WA
July 13 - 16, 2015



Open Standards Simulation Workflow for Heterogeneous System Models

(e.g. FMI based simulation)

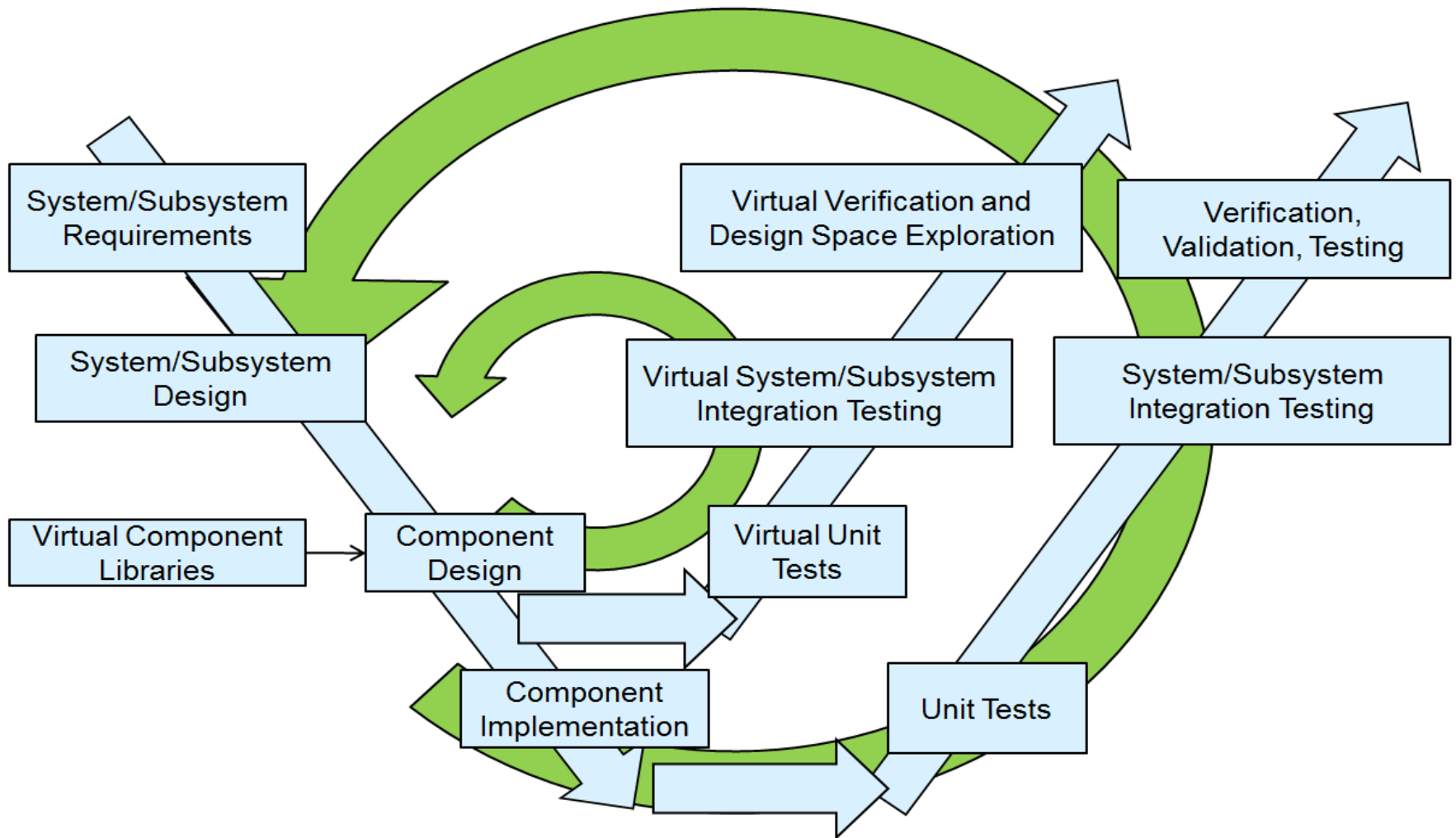
Henry Broodney, Lev Greenberg, Shinichi Hirose, Eldad Palachi – IBM

Agenda

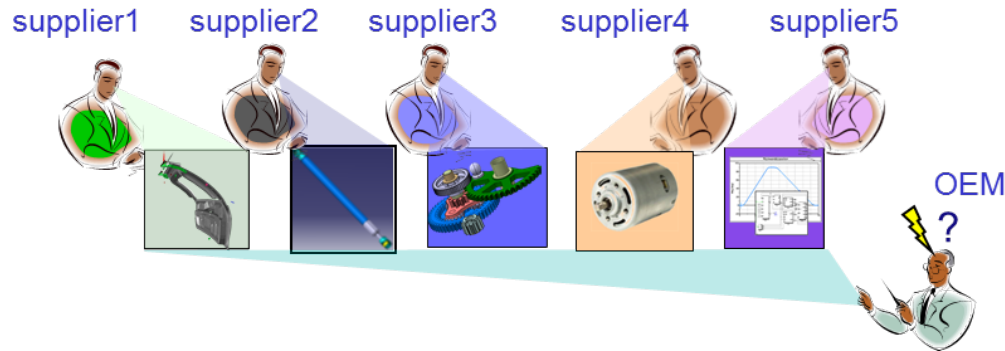


- A bit of history
- FMI in a nutshell
- Simulation workflow
- Somewhat technical...
- Couple of use cases
- What the future holds

V-model with left shift

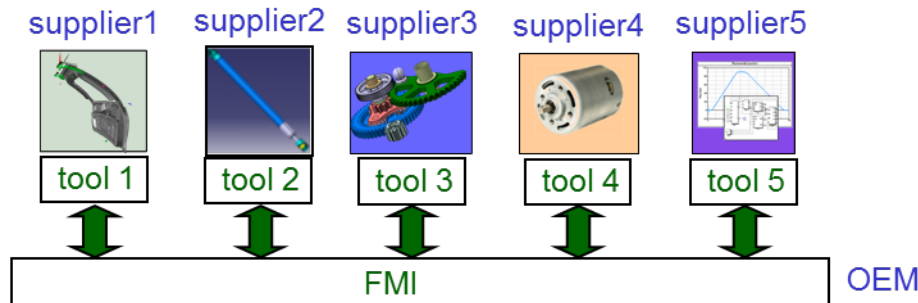


Need and solution



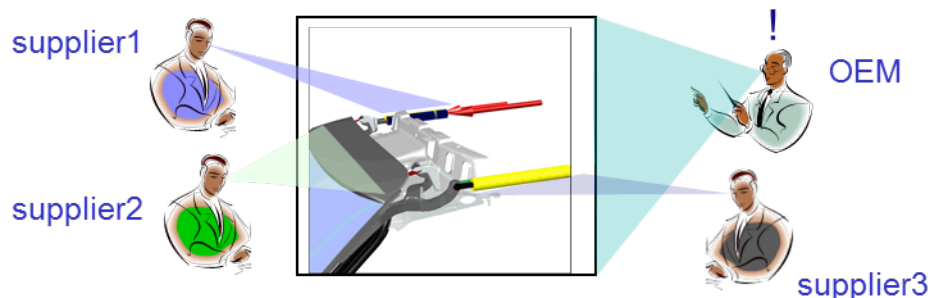
Problems / Needs

- Component development by supplier
- Integration by OEM
- Many different tools
- Supplier IP must be protected



Solution

- Industry standard for model interoperability for simulation
- Reuse of supplier models by OEM
- Protection of models' IP



Added Value

- Early verification of design
- Decreased tooling overhead
- Increased process efficiency and quality

Related work



- Models of Computation
 - Consider attending session 3.1 today (15:30)
- Cyber-Physical systems modeling
- Mathworks Simulink®
- Modelica®
- EU Framework projects
- OMG...

Functional Mockup Interface

The FMI development was part of the ITEA2 MODELISAR project (2008 - 2011; 29 partners, Budget: 30 Mill. €). From 2012 FMI is developed as Modelica Association project

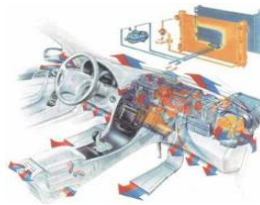
- FMI development initiated, organized and headed by Daimler AG
- Improved Software/Model/Hardware-in-the-Loop Simulation, of physical models from different vendors.
- Open Standard
- FMI Standard Releases
 - FMI 1.0 in 2010
 - FMI 2.0 in 2014
- Over 35 FMI compliant tools (Modelica tools, Simulink add-ons, Rhapsody, etc)
 - <https://www.fmi-standard.org/tools>



Engine
with ECU



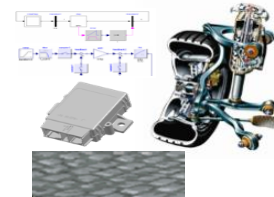
Gearbox
with ECU



Thermal
systems



Automated
cargo door

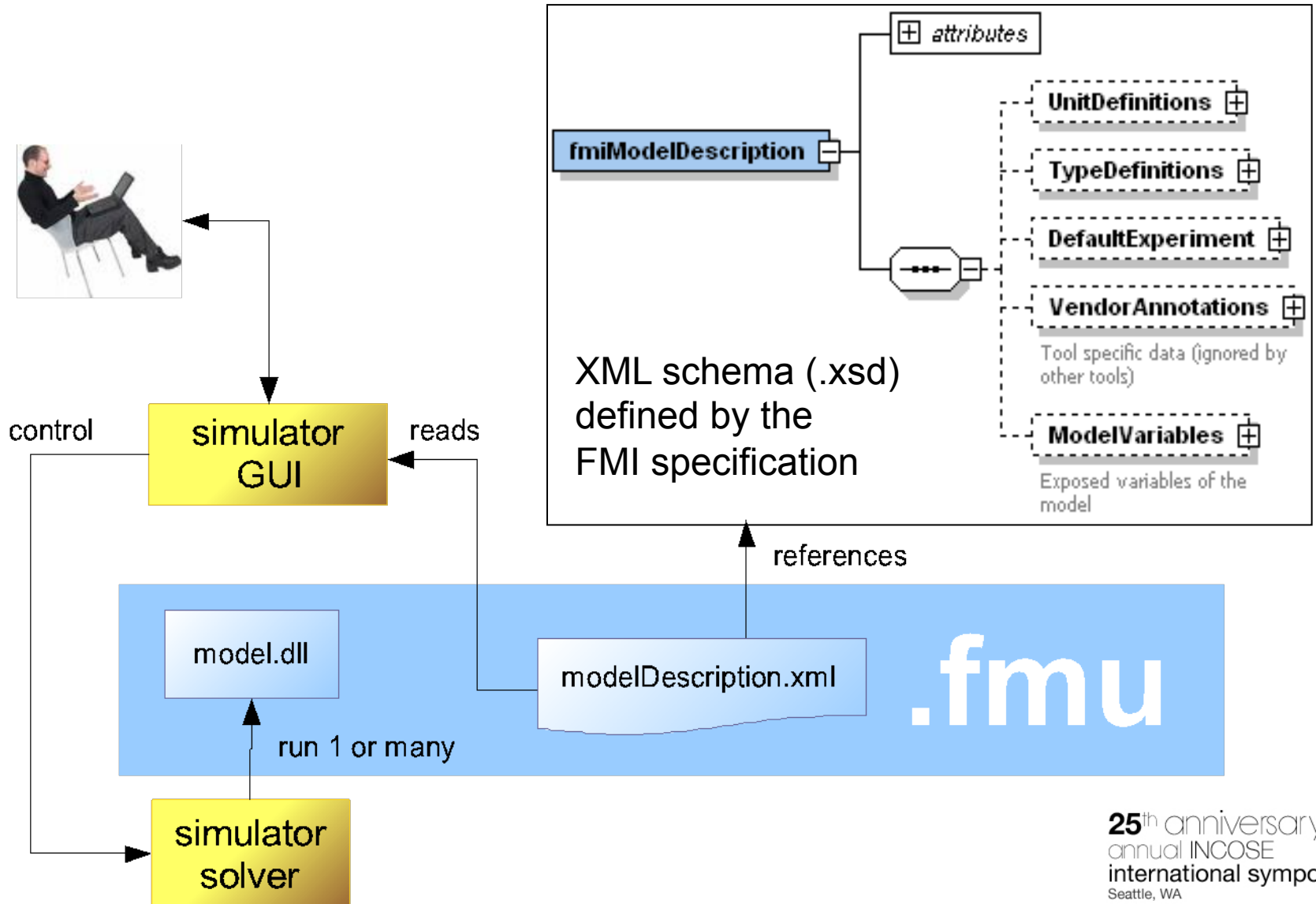


Chassis components,
roadway, ECU (e.g. ESP)

etc.

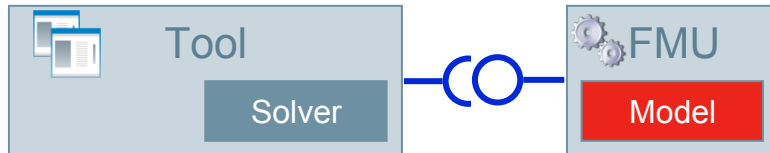
functional mockup interface for model exchange and tool coupling

Functional Mockup Unit (FMU)

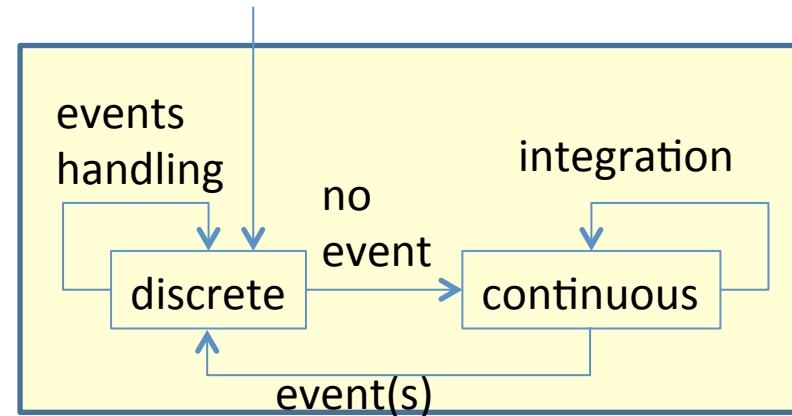


Flavors (modes)

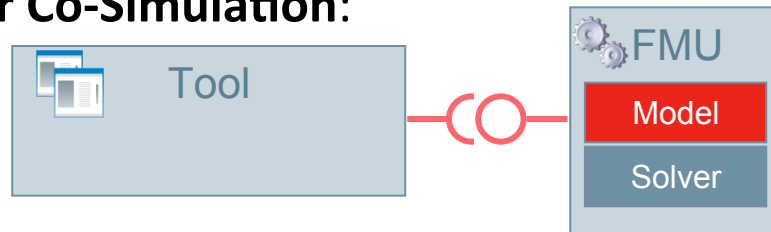
FMI for Model Exchange:



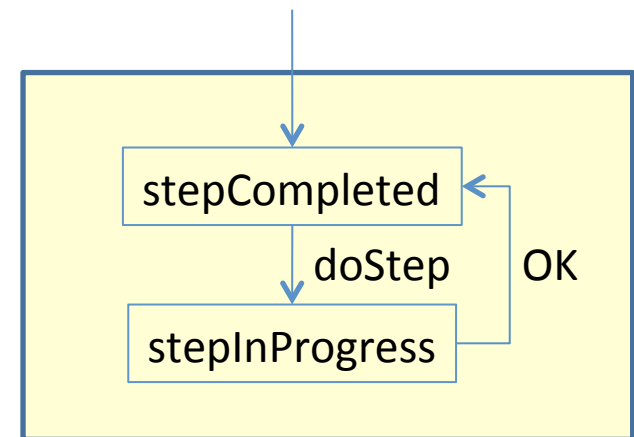
- FMU for ME doesn't contain ODE solver – hosting simulation tools need to provide it
- FMU exposes state variables and their derivatives



FMI for Co-Simulation:



- FMU for CS includes solver – hosting tools “only” communicate signals between FMUs and select communication step sizes



Tool availability

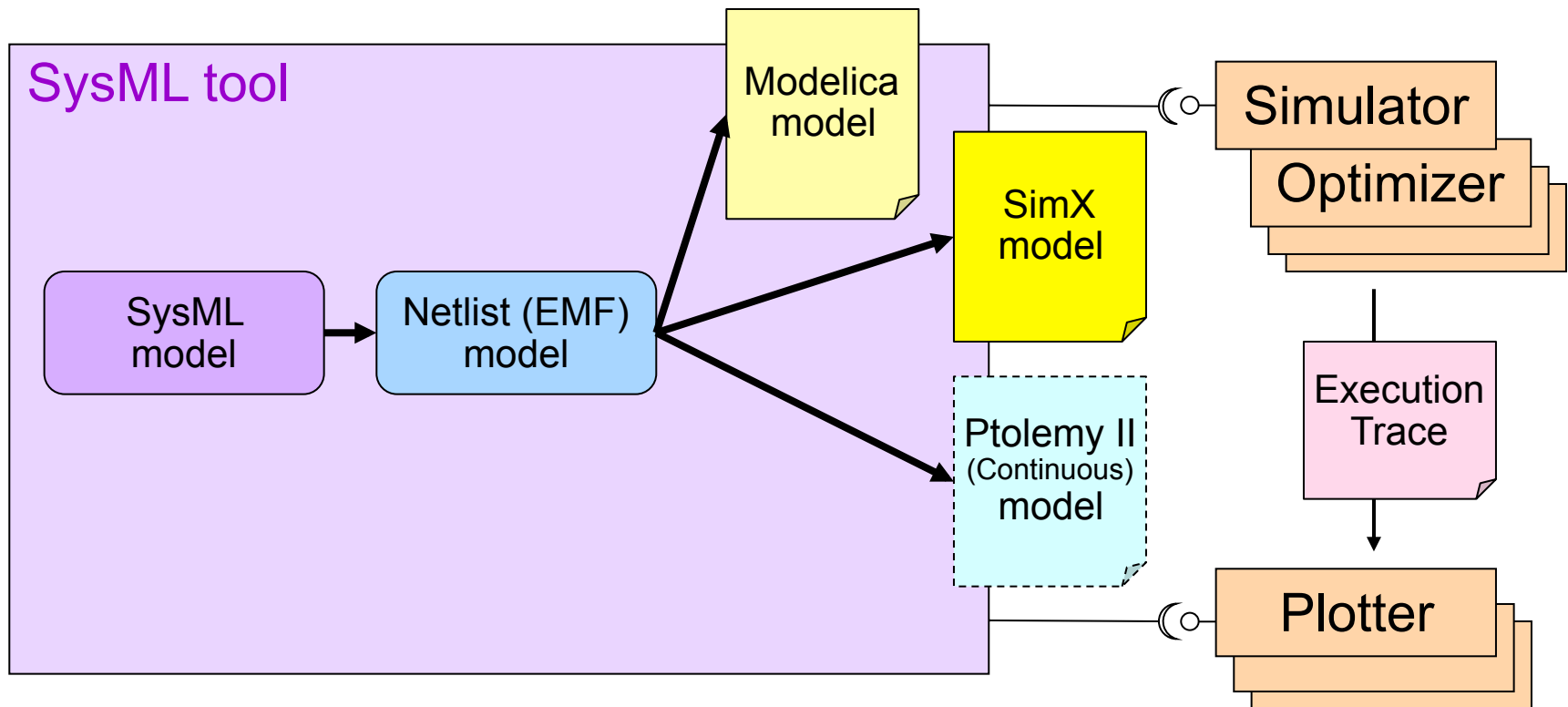


From www.fmi-standard.org

	Model Exchange		Co-Simulation	
	Export	Import	Slave	Master
FMI_1.0 67 (24)	22 (11)	30 (15)	31 (11)	40 (18)
FMI_2.0 20 (8)	4 (4)	5 (2)	8 (6)	14 (4)

Open Source Available!!

Hybrid Simulation Concept



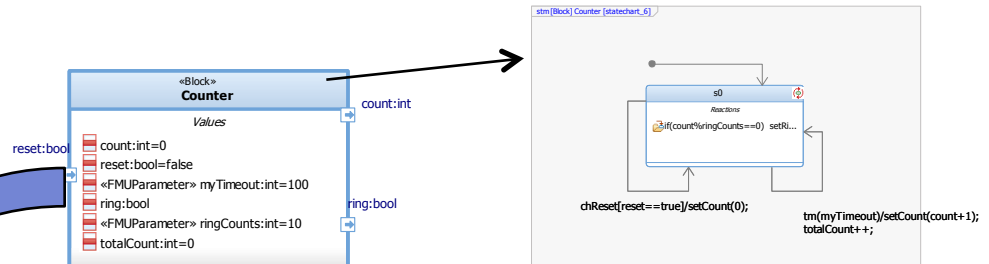
Workflow - export

Design behavioral
SysML block

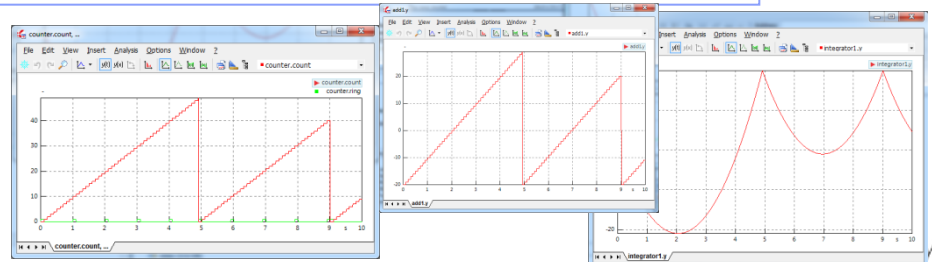
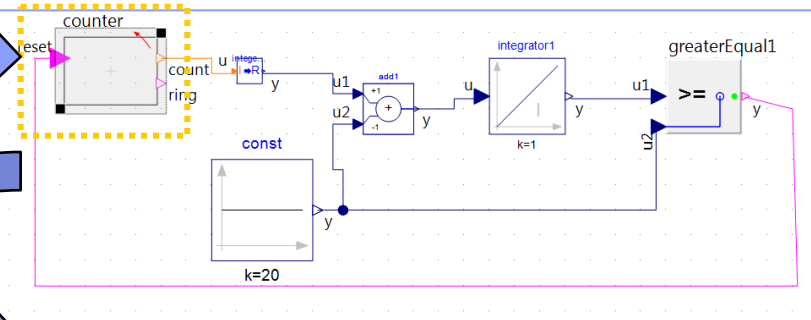
Export SysML to FMU

Import FMU and
compose the hybrid
system (SimX, Dymola,
OpenModelica)

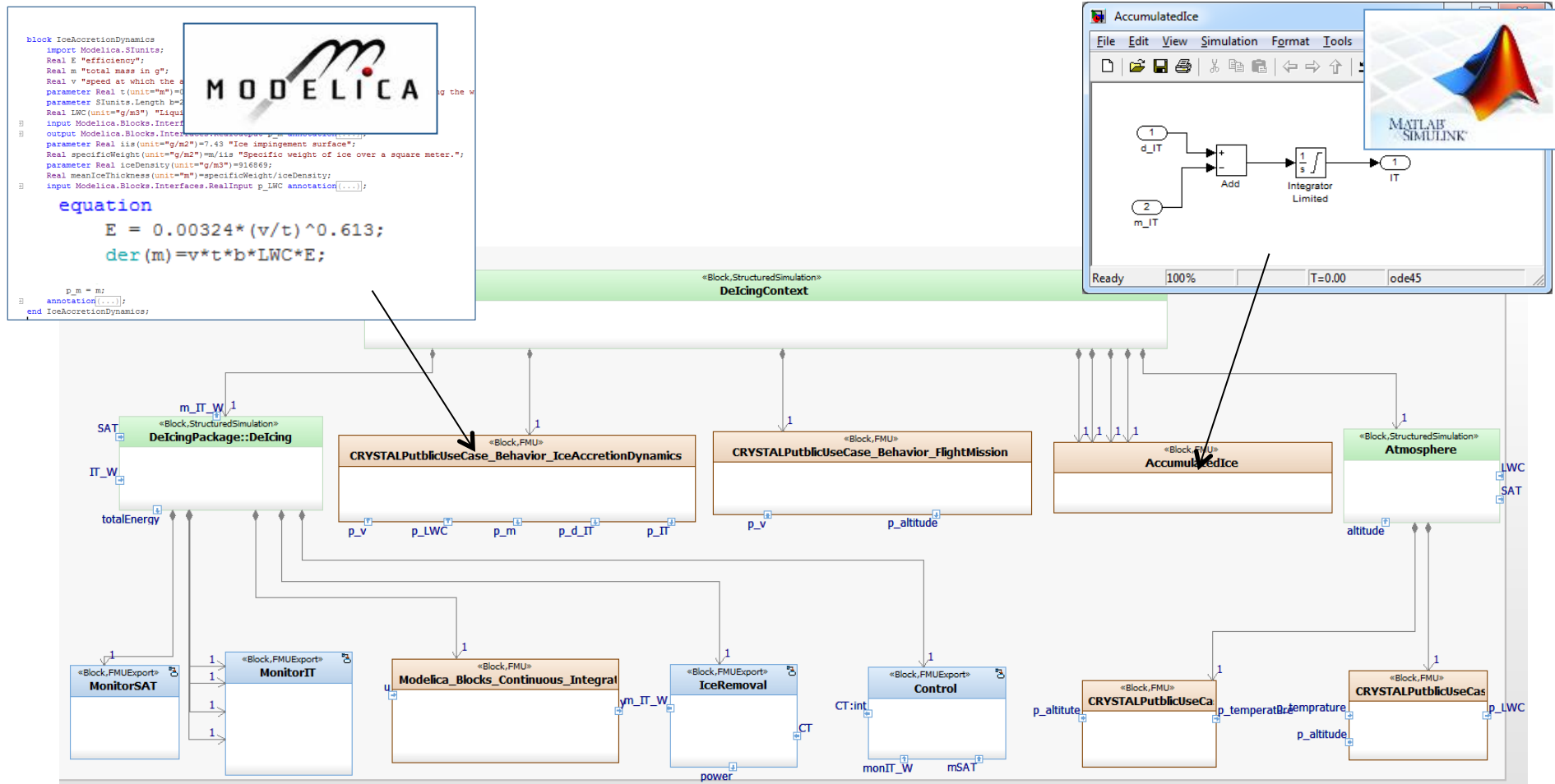
Simulate



```
<?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
<fmiModelDescription fmiVersion="1.0" modelName="Counter" modelIdentifier="Counter"
  <ModelVariables>
    <ScalarVariable name="count" valueReference="0" variability="discrete" cause
      <Integer start="0"/>
    </ScalarVariable>
    <ScalarVariable name="reset" valueReference="0" variability="discrete" cause
      <Boolean start="false"/>
    </ScalarVariable>
    <ScalarVariable name="ring" valueReference="1" variability="discrete" causal
      <Boolean/>
  </ModelVariables>
</fmiModelDescription>
```

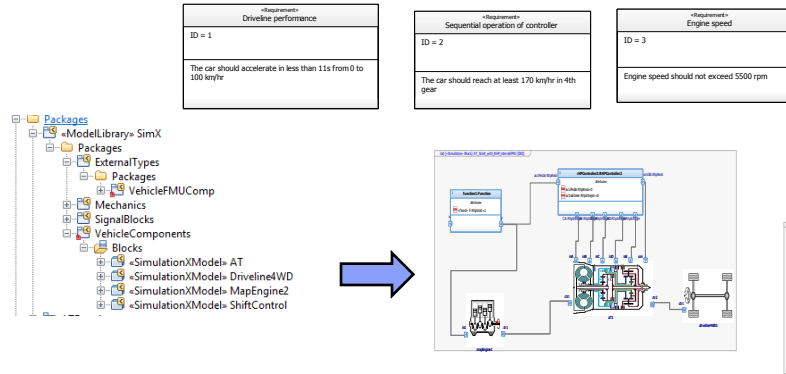


Workflow – import

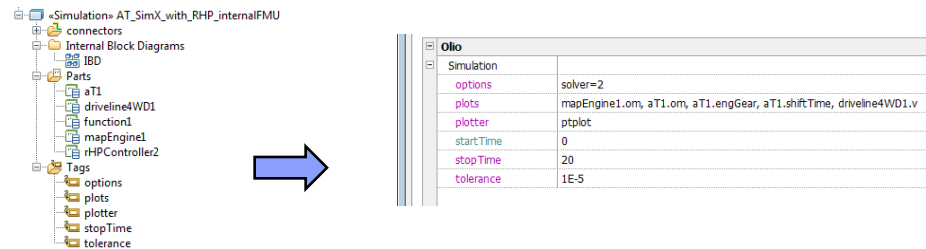


Workflow - full

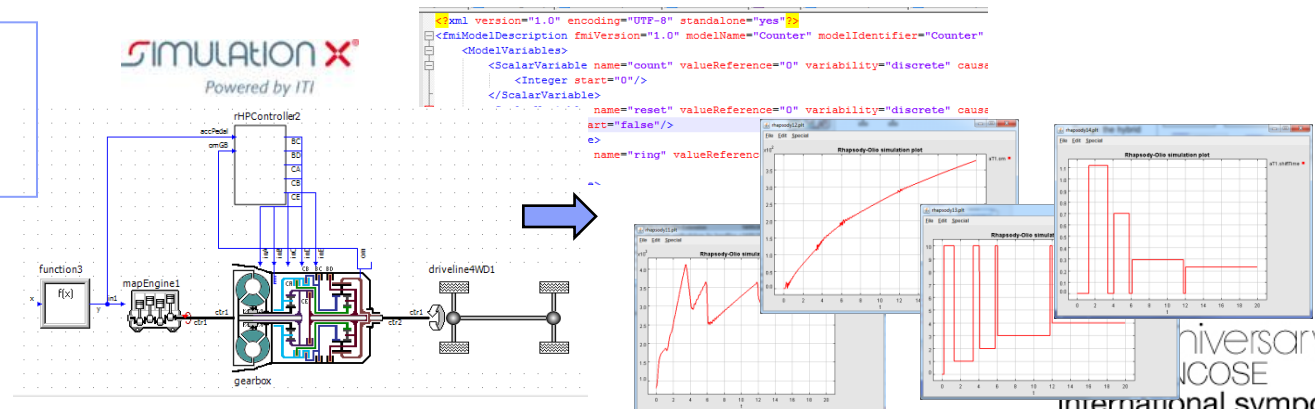
Design the hybrid system in SysML, including imported FMU



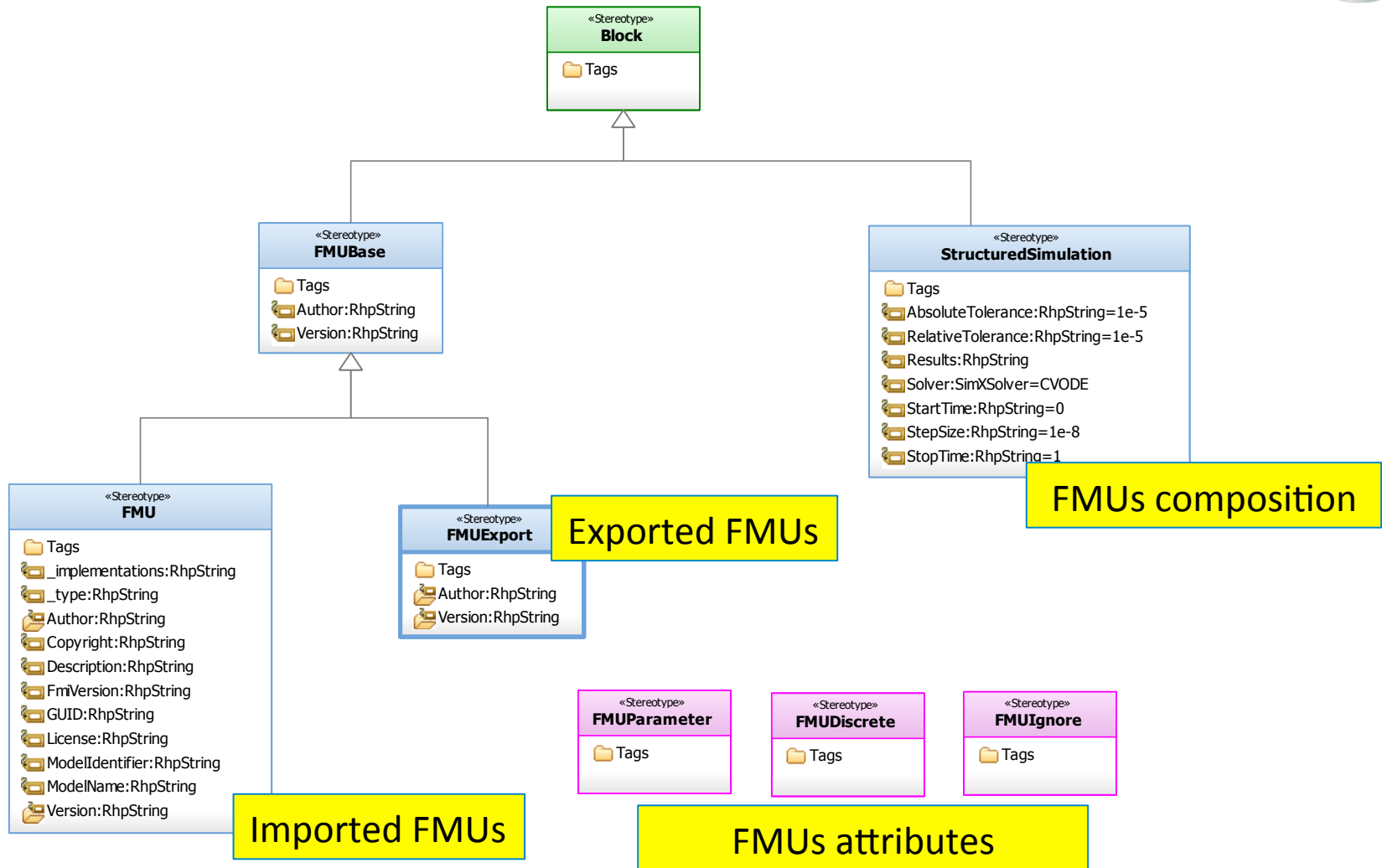
Define simulation parameters in SysML



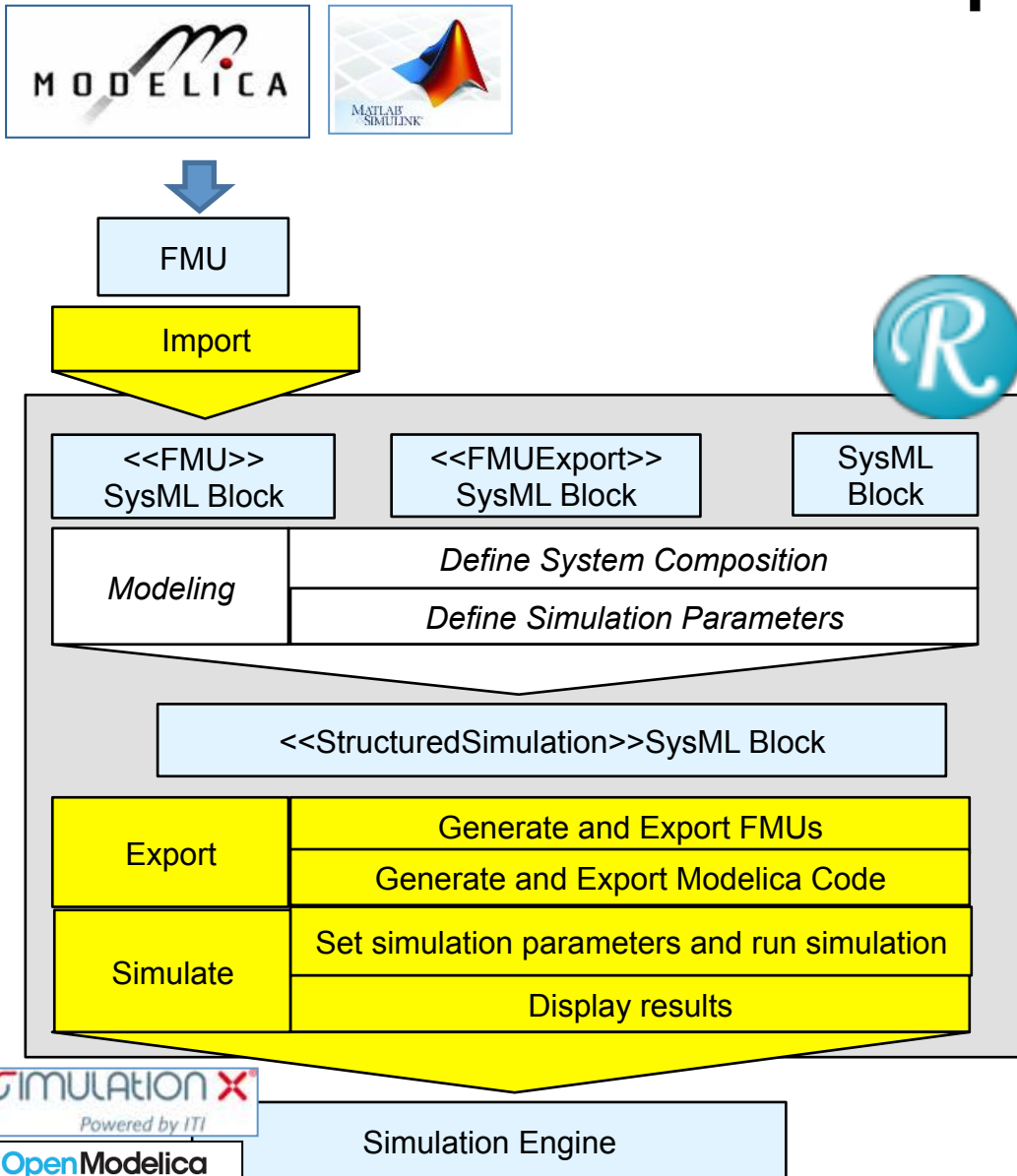
FMU generation, model export and simulation in SimX



FMI in SysML



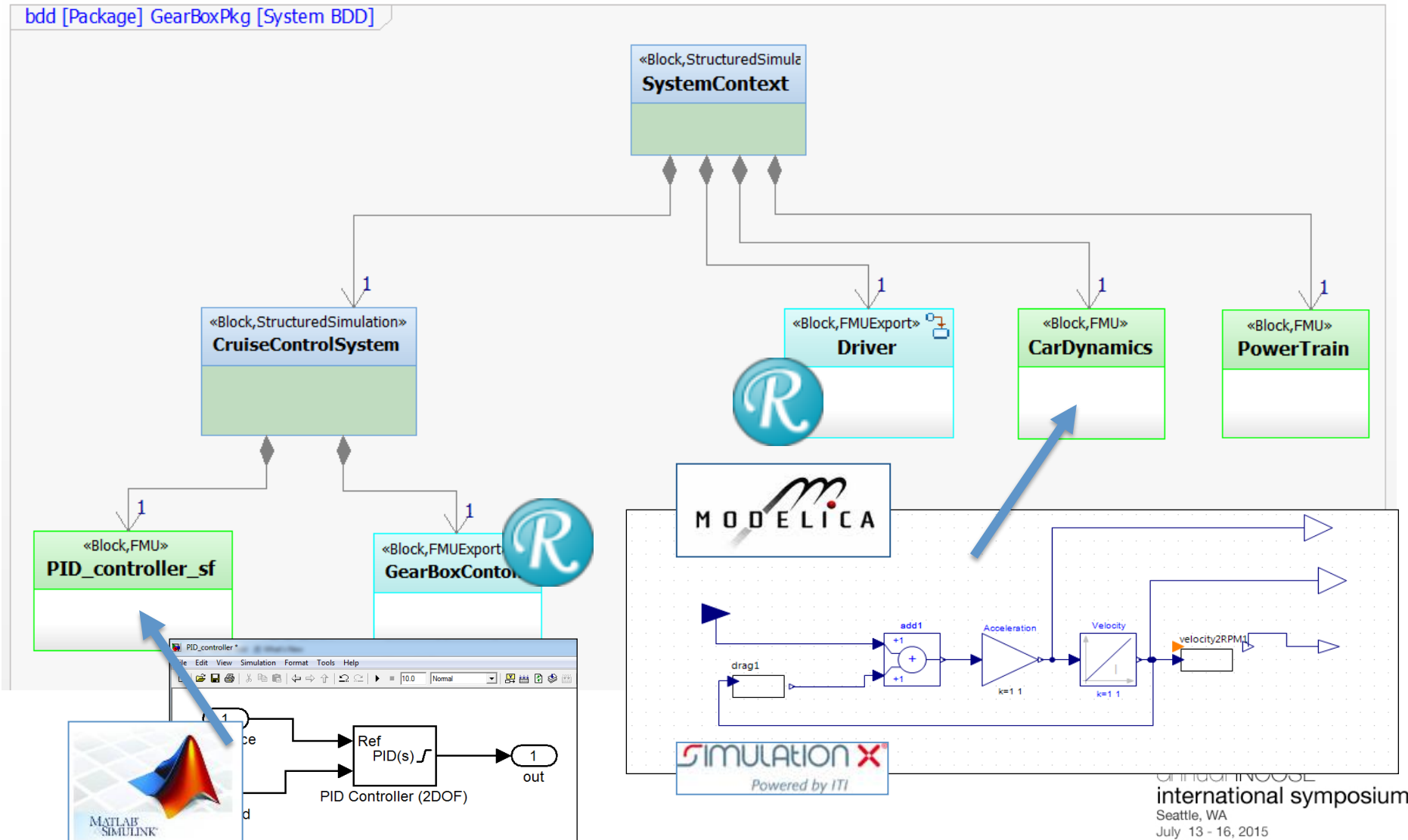
FMI in Rhapsody



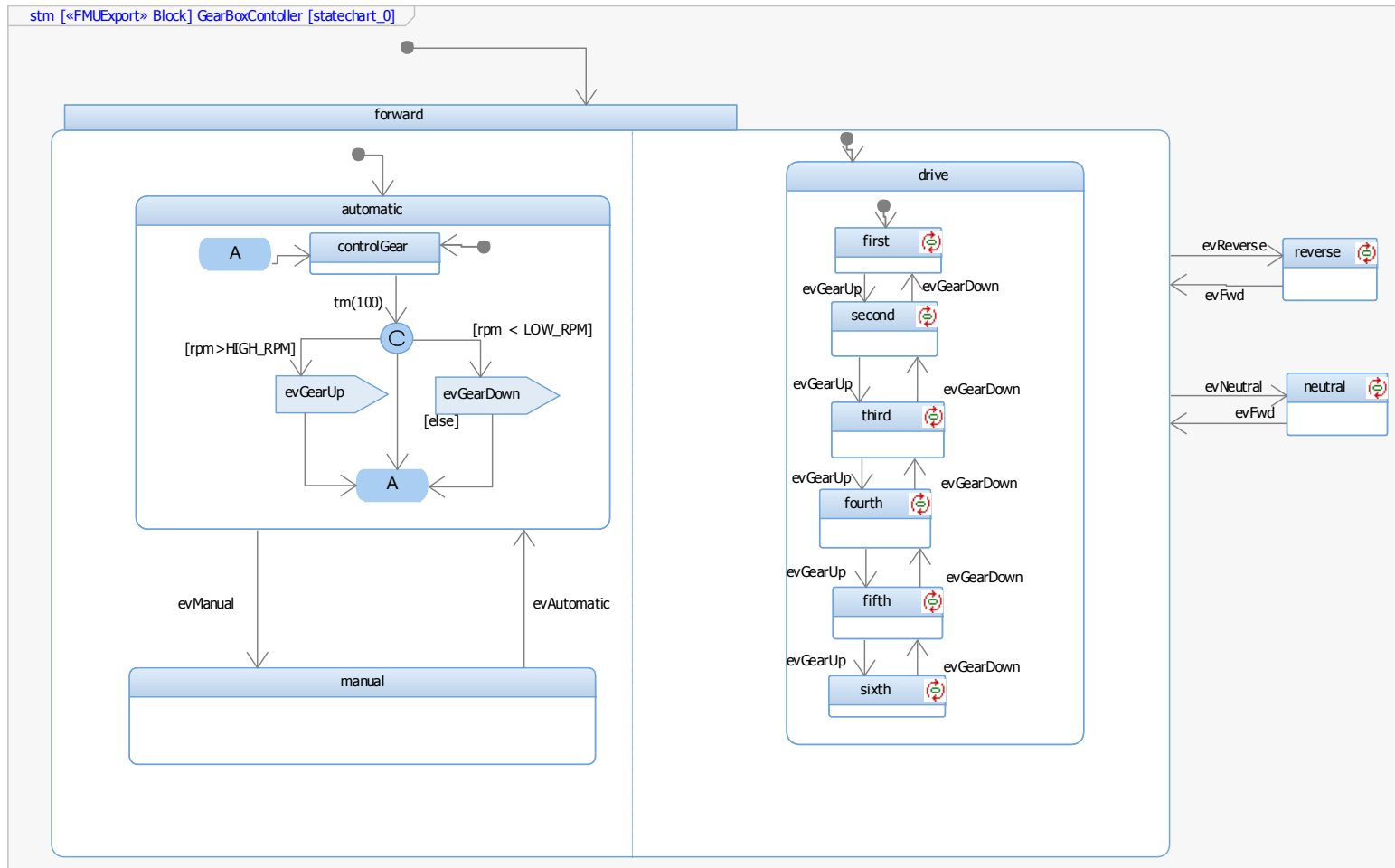
Features:

- Import FMI 1.0 (CS and ME)
- Generation FMUs from SysML
 - FMI 1.0 ME
 - no limitation on internal communications
- Hierarchical composition
- Net-list in Modelica
- Automatic plots generation

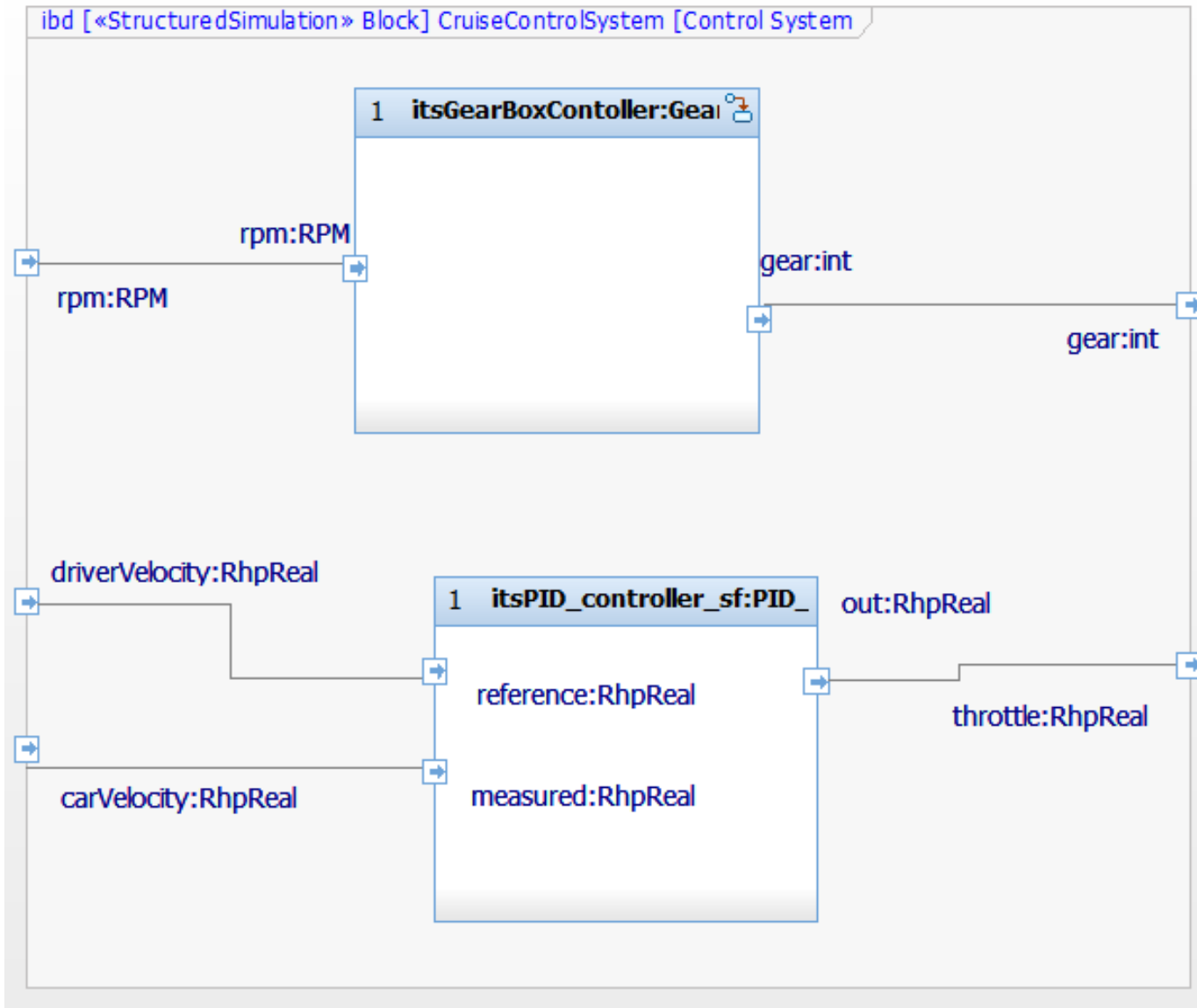
Cruise Control – block diagram



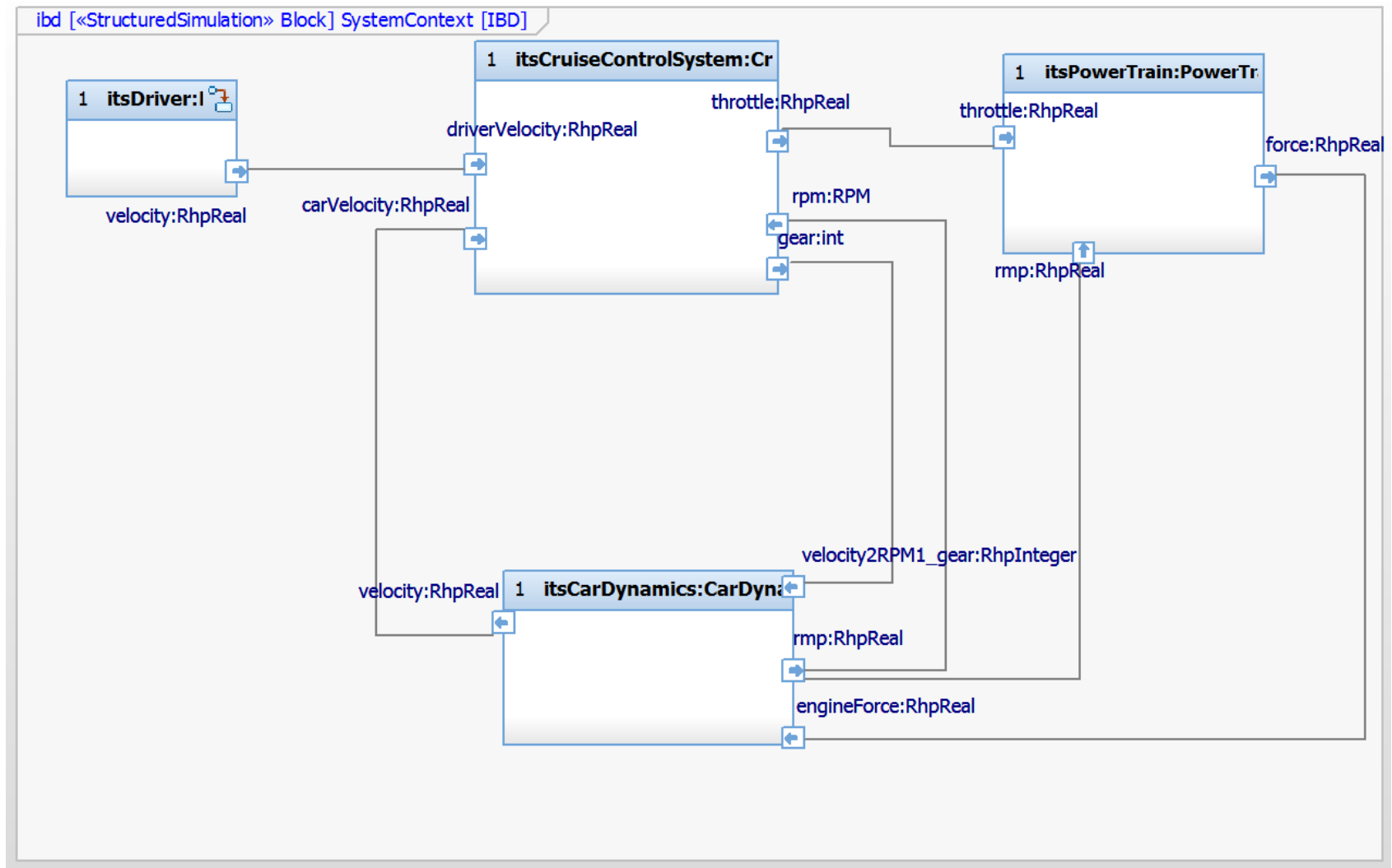
Cruise Control – Gearbox Controller



Cruise Control – internal structure



Car – internal structure



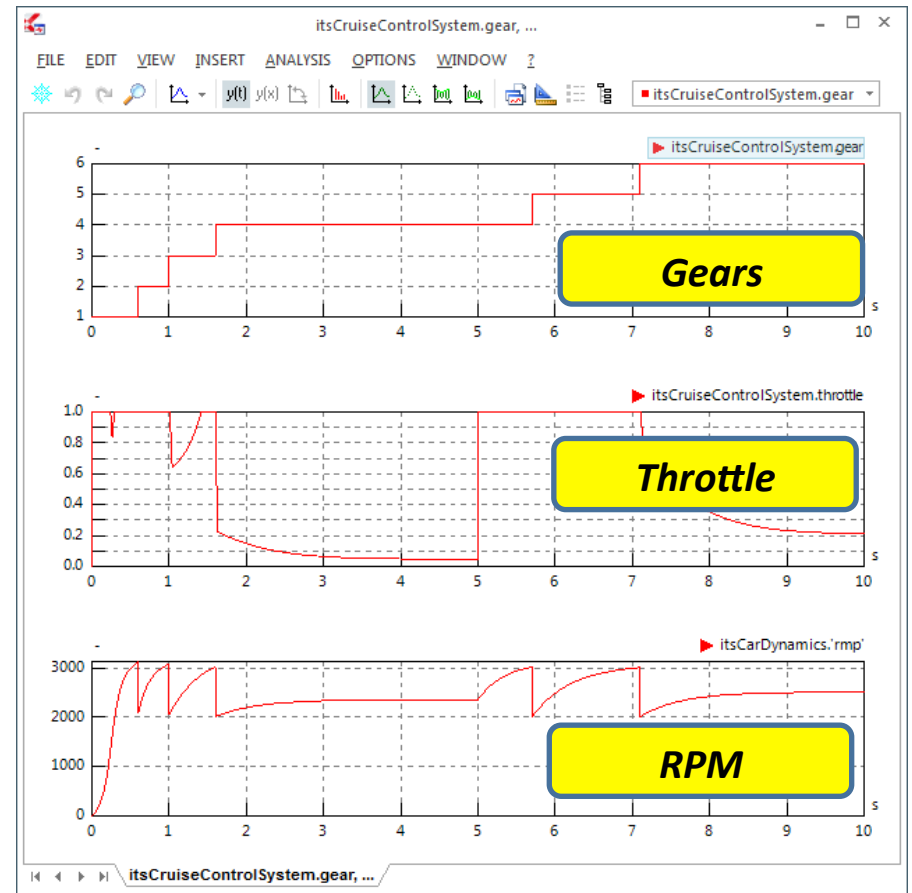
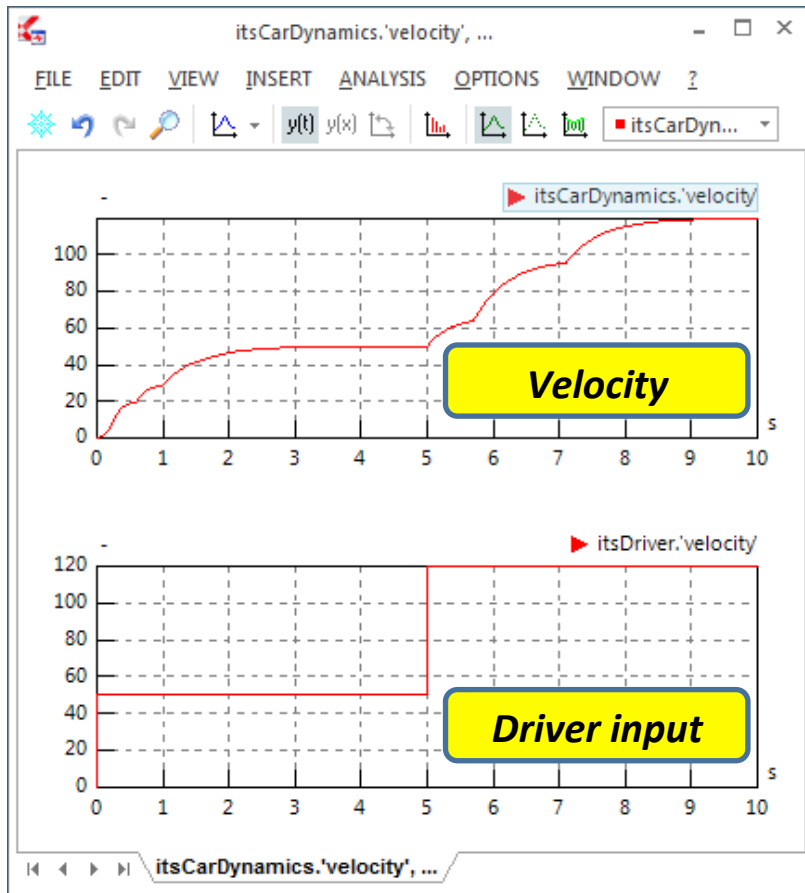
Simulation parameters

Block : SystemContext in GearBoxPkg

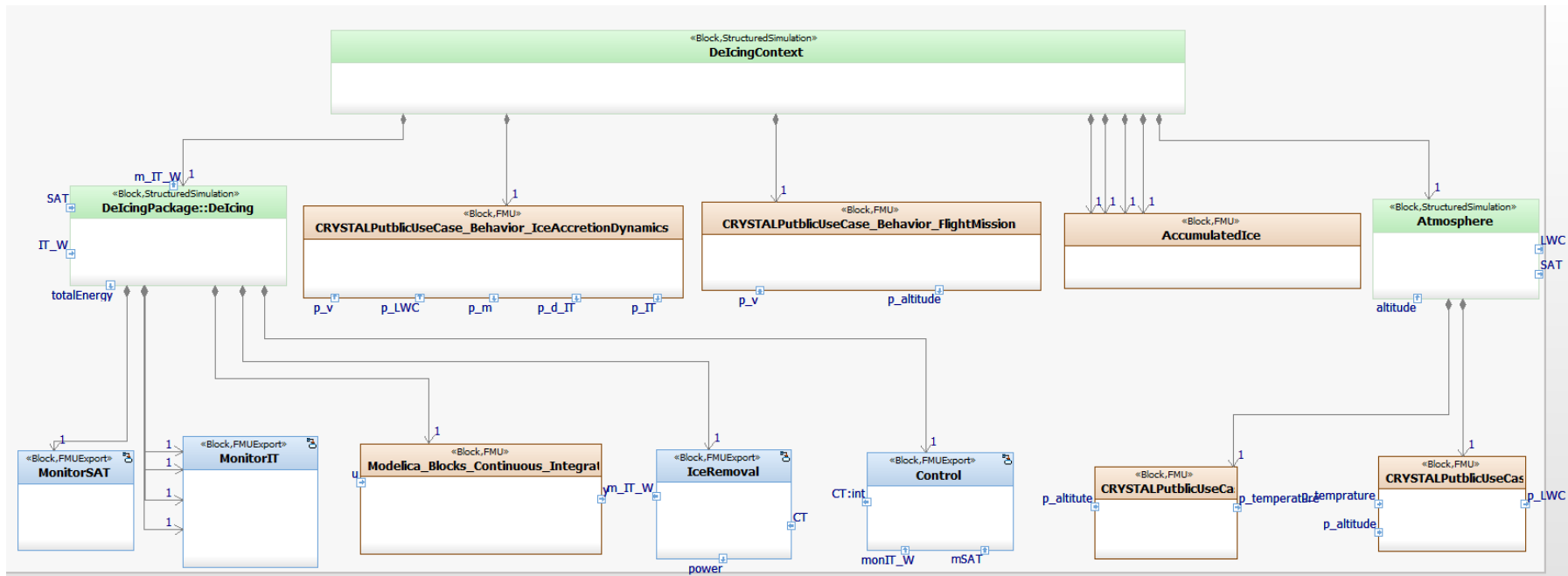
General	Description	Attributes	Flow Properties	Operations	Ports	Flow Ports	Full Ports	Proxy Ports	Constraints	Relations	Tags	Properties
												
[-] FMI												
[-] StructuredSimulation												
AbsoluteTolerance 1e-5												
RelativeTolerance 1e-5												
Results itsCarDynamics.velocity;itsDriver.velocity, itsCruiseControlSystem.gear;itsCruiseControlSystem.throttle;itsCarDynamics.rmp												
Solver CVMODE												
StartTime 0												
StepSize 1e-8												
Stop Time 10												

Top level block contains the simulation parameters

Simulation results

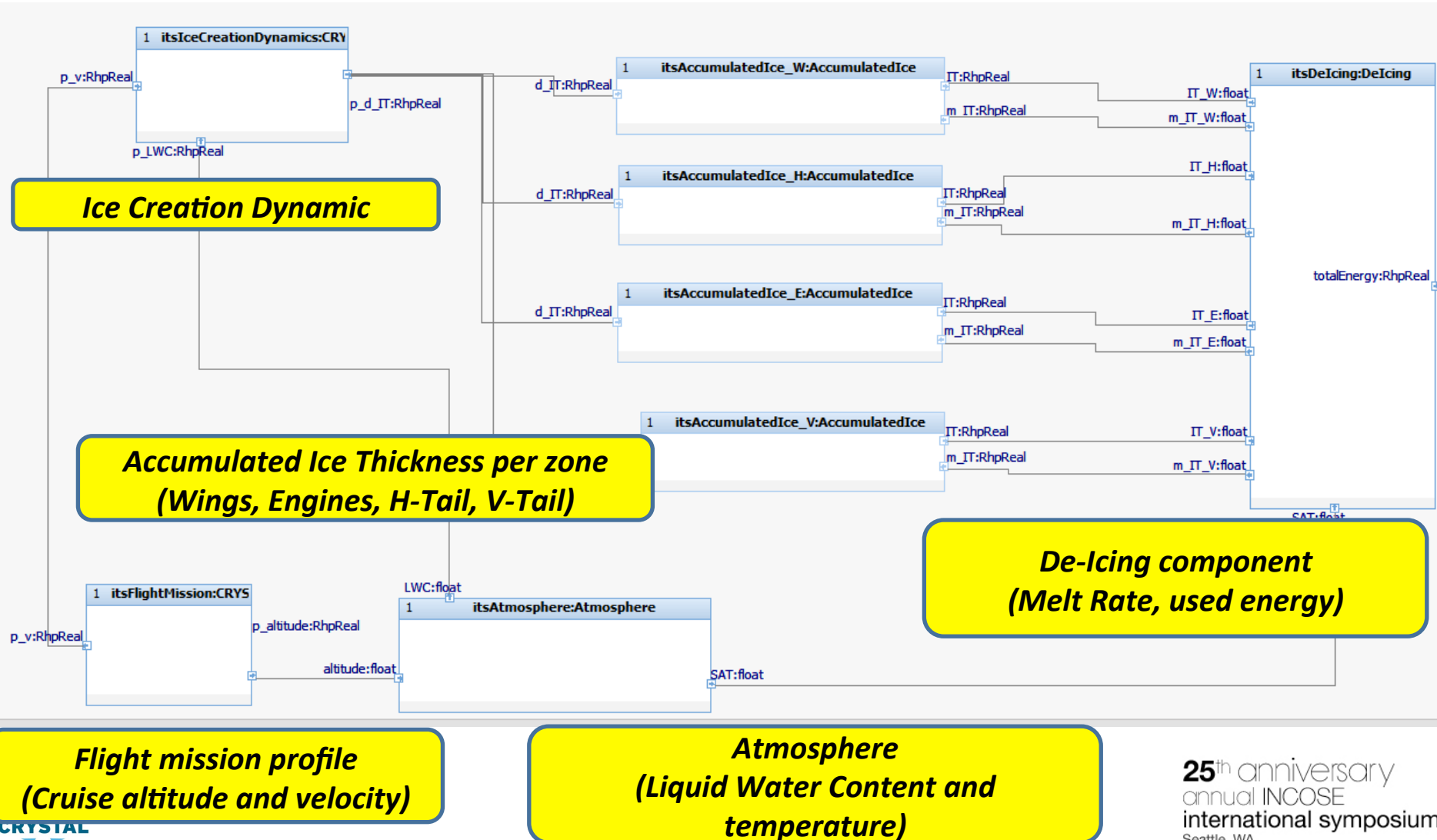


De-icing System

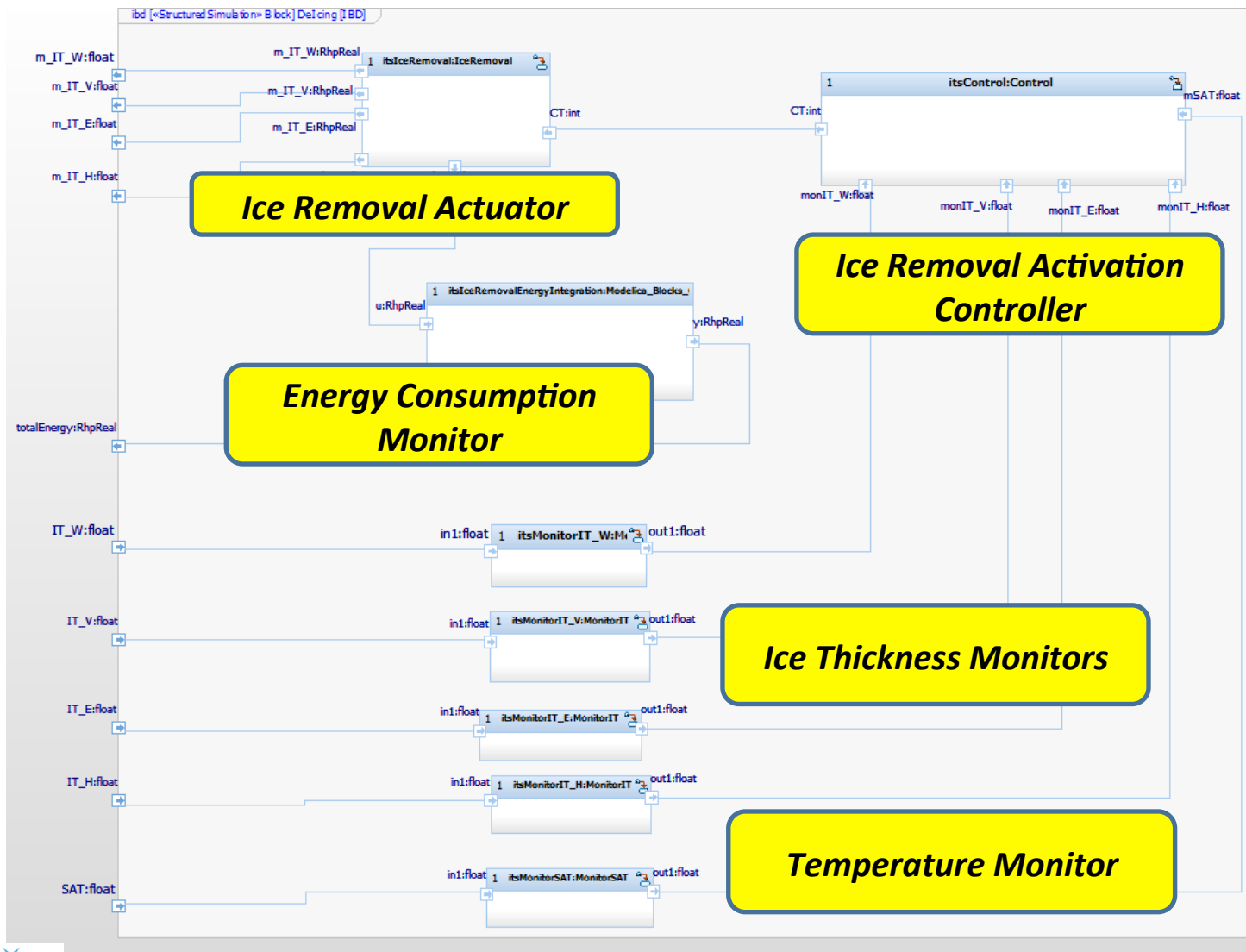




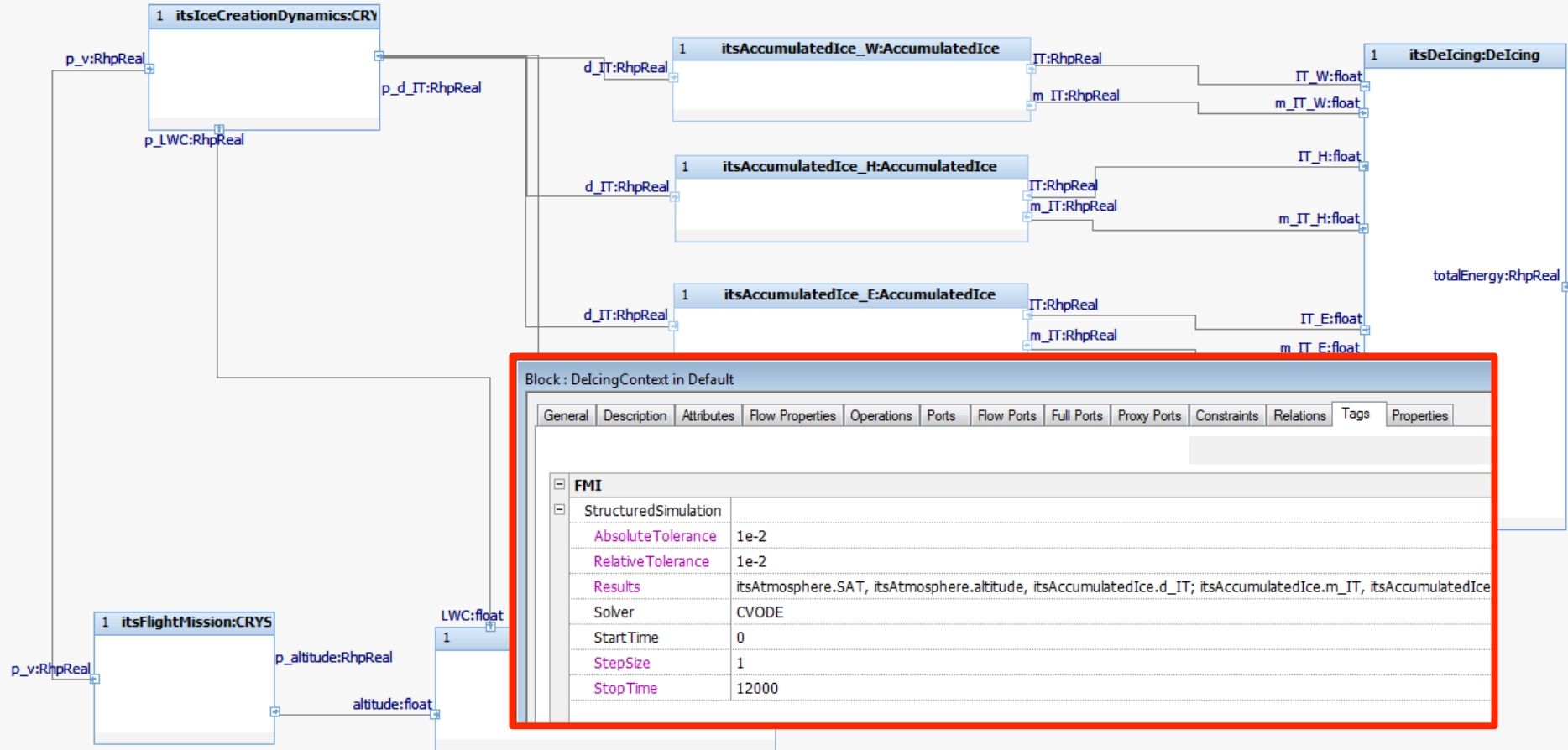
De-Icing Context IBD



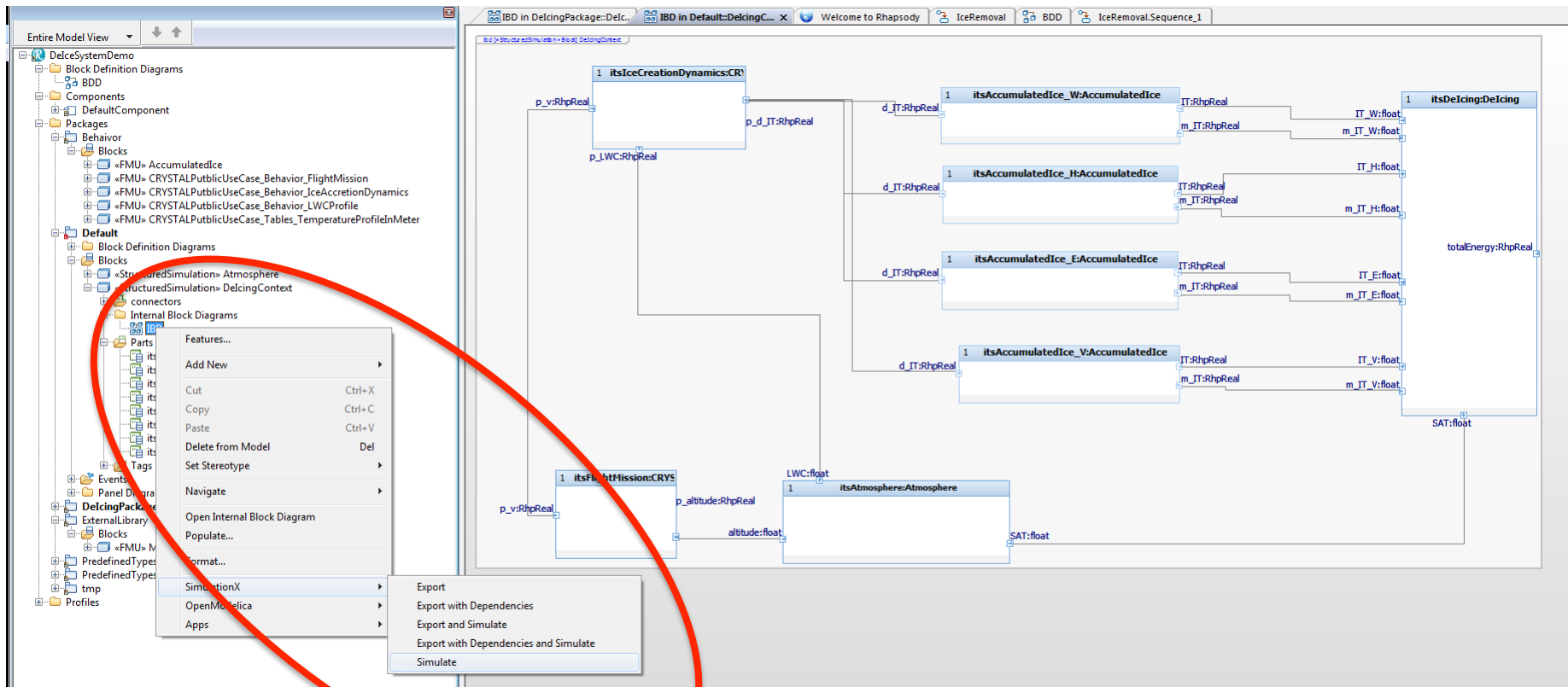
De-Icing IBD



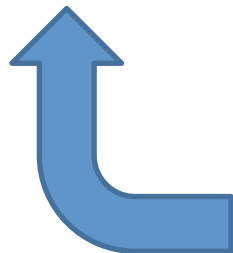
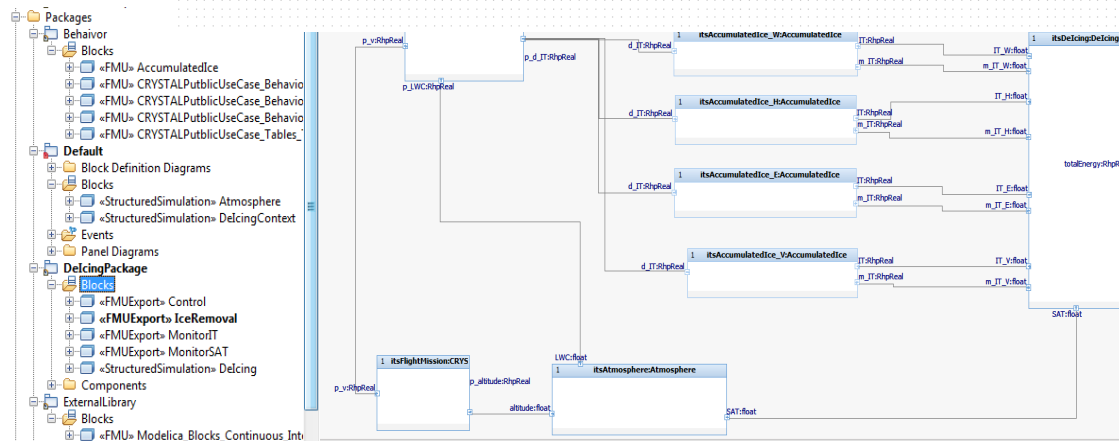
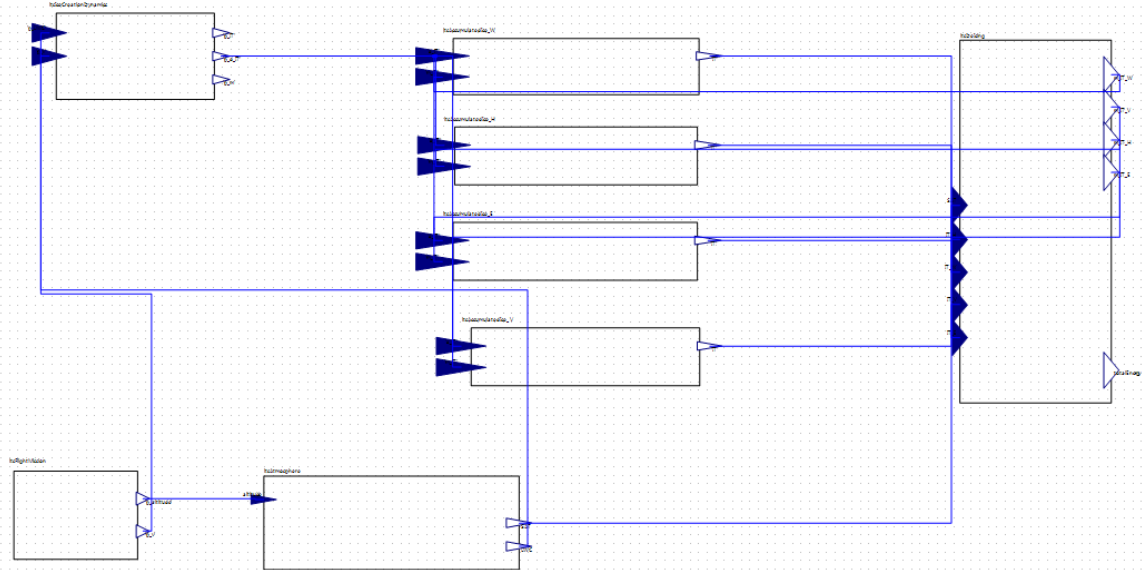
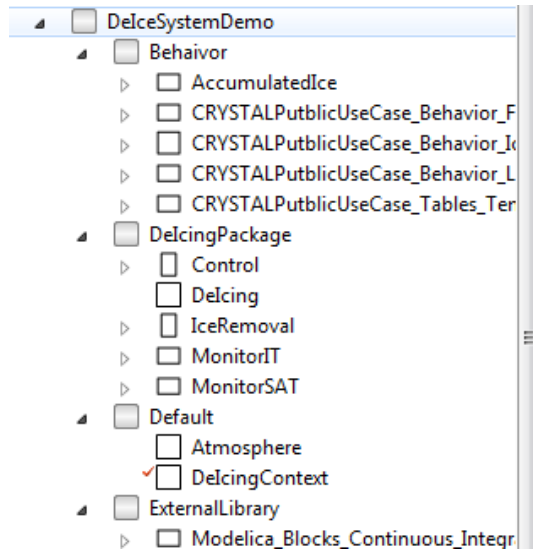
Simulation Parameters



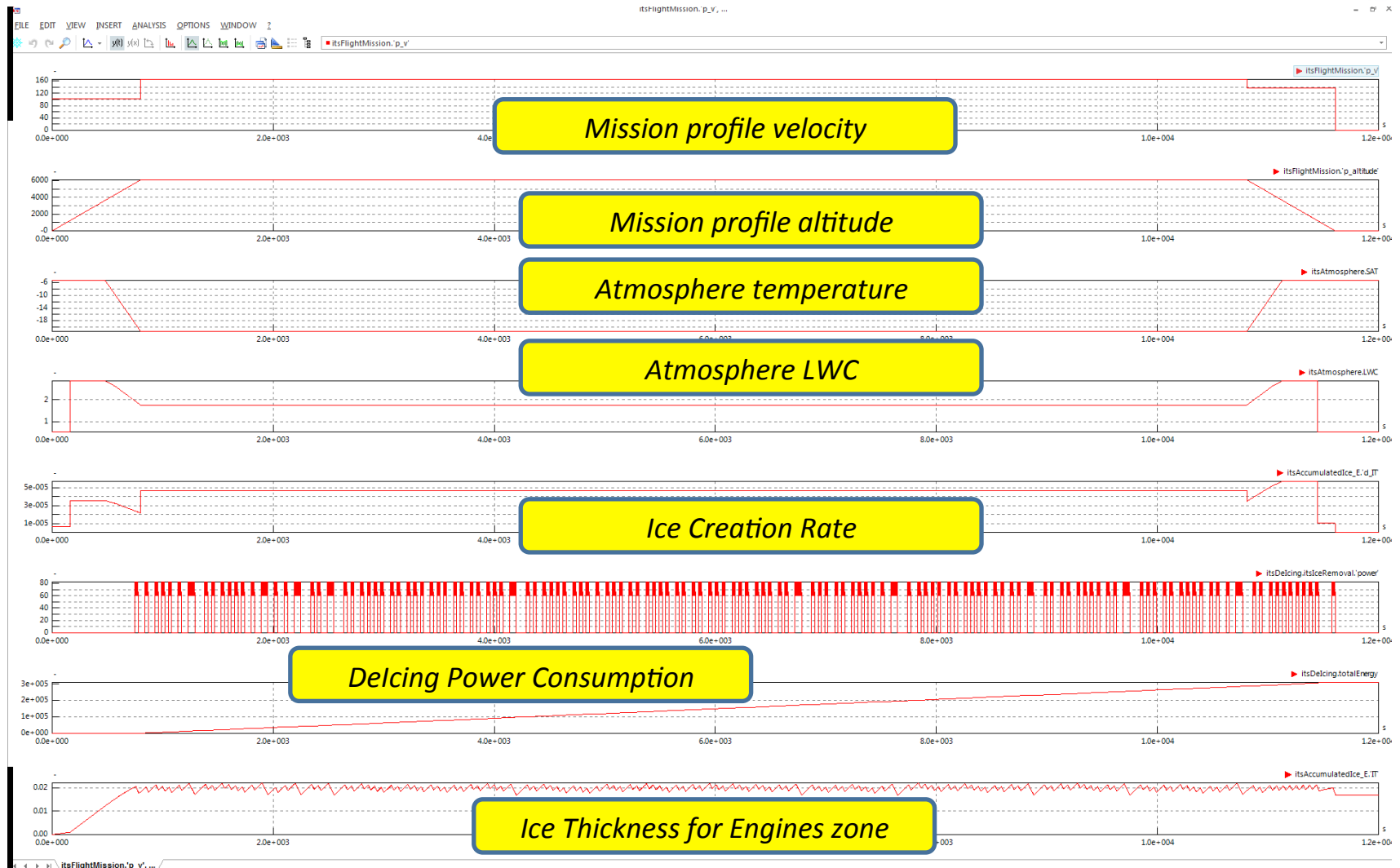
Export and simulation



Structure in OpenModelica



Simulation Results



FMI current drawbacks



- FMI for Co-simulation lacks event handling
 - a-periodic discrete models cannot be properly handled.
- No support for “absent signal” notion
- The standard does not dictate the composition method and language, thus tools use many incompatible approaches.

Future directions



- Address the above...
- Exploring FMU in-cloud execution and simulation as a service
- Distributed Simulation
- Models and IP management

Disclaimer: The materials and the messages in this presentation are unrelated to any current IBM offering or future plans and should not constitute a basis for purchasing decisions.



Thank you!!