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# Integrating an Upgraded Constituent System in a System of Systems: A SysML case study

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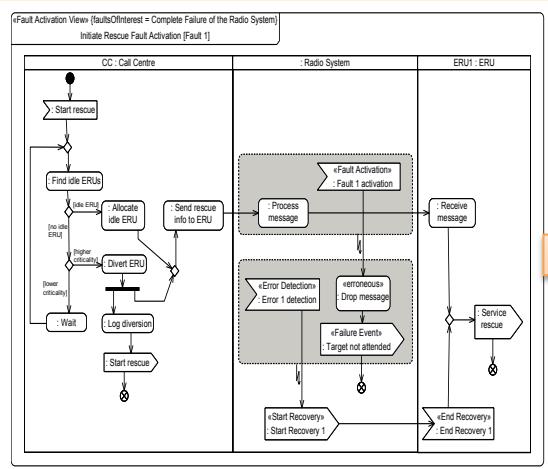
# Introduction

- SoSs are comprised of elements that are themselves independent systems
- Often exhibit:
  - Operational & managerial independence
  - Distribution
  - Reliance placed on emergence
  - Evolution
- Challenging aspects include:
  - Operational & Managerial Independence of Constituent Systems
  - Complexity of confirming/refuting SoS-level properties
  - Semantic heterogeneity



# COMPASS

[www.thecompassclub.org](http://www.thecompassclub.org)



## Architectural Modelling

- SoS Modelling Frameworks
- ... instantiated to domains
- **SoS Modelling patterns & profiles**, e.g. Fault-Error-Failure
- Guidelines on negotiation, requirements, integration, test, etc.

process CallCentreProc = begin  
actions

```
MERGE1(r) =  
(dcl e: set of ERUID @ e := findIdleERUs();  
(do e = {} -> DECISION2(r) |  
e <> {} -> (dcl e1: ERUID @  
e1 := allocateIdleERU(e, r);  
MERGE2(e1, r))  
end)) ...
```

process InitiateRescue =  
CallCentreProc [| SEND\_CHANNELS |]  
RadioSystemProc [| RCV\_CHANNELS |] ERUsProc

## Underpinning Formalisms

- Behavioural semantics of SoS
- Tight link to modelling frameworks
- Cope with multiple paradigms.
- Compositional Design
- Dynamic response to adaptation & evolution
- Covering **cyber elements**, physical, human, economic, social, ...



## Tool-supported V&V:

- Exploration of Design Space
- Efficient verification by model-checking and proof
- Test generation
- Simulation
- Tools Robustness
- Conformance during evolution, and emergence

# Outline

1. Integration in an SoS
2. Introduction to the case study
3. Application of the Integration Framework
  - Constituent system identification process
  - Integration process
  - Validation process
4. Conclusions

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# Integration in an SoS

- An SoS is a system comprising components which are each independent systems themselves
  - Constituent parts operated and managed separately
  - Large-scale, distributed
  - Emergent behaviour
  - Continually evolving

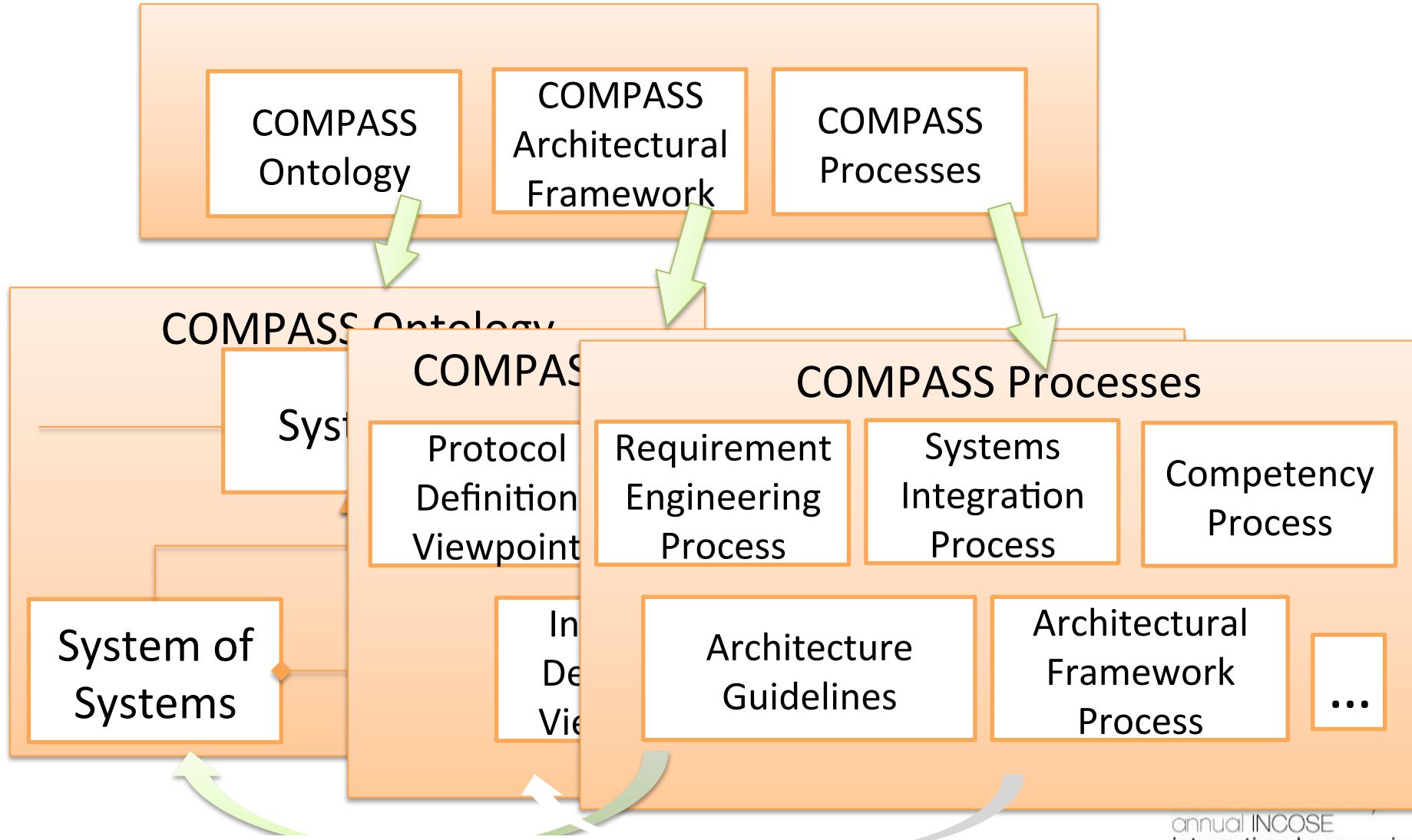
# Integration in an SoS

- Integration a key challenge for an SoS
  - SoSs are continually changing
- Several activities covered by “integration”
  - e.g. ensuring no negative effects felt after a changed/new constituent is integrated
- Modelling is important for SoSs
  - Scale and SoS operating environment difficult to replicate in a lab
  - Testing accurately difficult/expensive

# Architectural Modelling

- We follow **COMPASS** architectural approach
  - patterns and guidelines
- Use collections of *modelling patterns* to define SoS structure and behaviour
- COMPASS architectural modelling approach also includes *guidelines* for SoS integration and development lifecycles

# COMPASS Approach



# Outline

1. Integration in an SoS
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# Case Study: Road Traffic Management



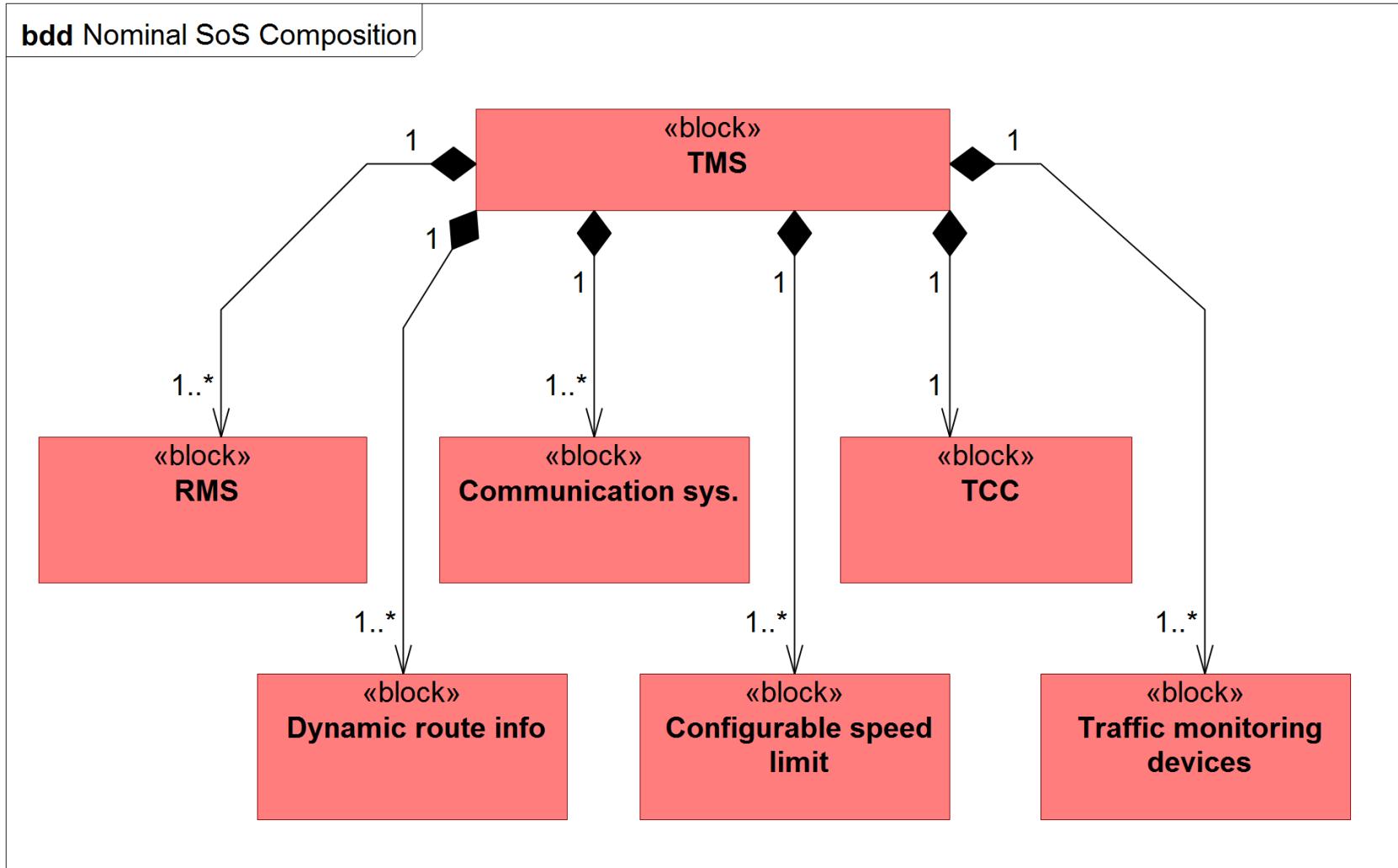
- Traffic Management System (TMS) collects information about conditions and traffic flow
- Takes actions to achieve traffic behaviour goals:
  - improving efficiency of the road network
  - ensuring road safety
  - reducing the impact accidents, blockages etc
  - reducing environmental impact
- Inter-urban road network in the Netherlands

# Case Study: Road Traffic Management

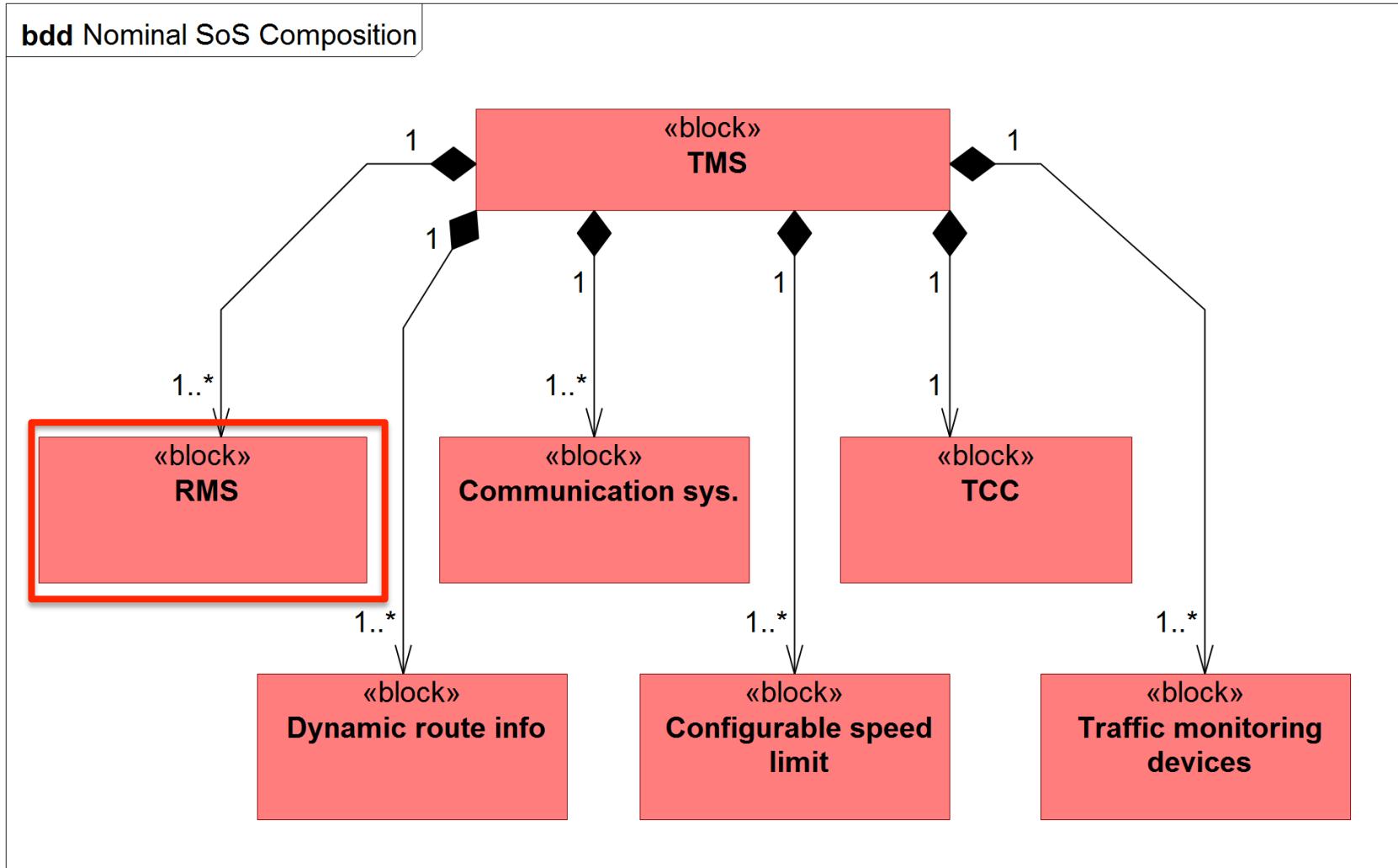


- Wide variety of CSs
  - Traffic monitoring systems
  - Systems for influencing traffic flow
  - Control rooms
- Interact with TMSs operated by third parties in adjacent regions

# Road Traffic Management

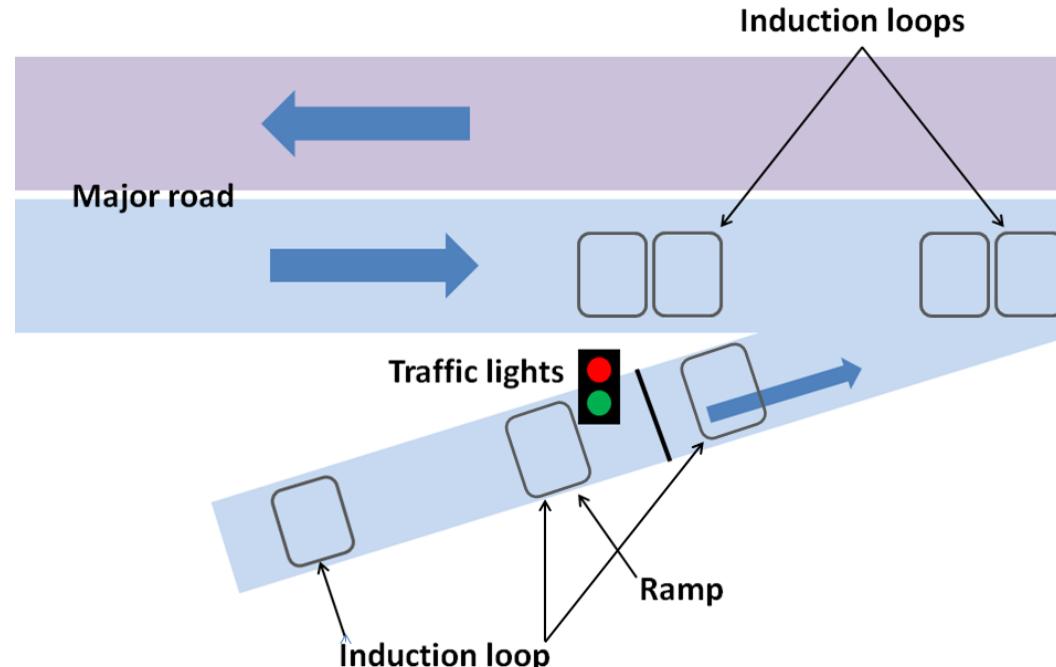


# Road Traffic Management



# Case Study: Road Traffic Management

- Ramp meter system (RMS)
  - Two-phase traffic lights control vehicle rate
  - Prevents bottlenecks and improves vehicle distribution
  - Can reduce accidents caused by high speed merges.





# Case Study: Road Traffic Management

- An RMS typically has access to data about traffic in its immediate vicinity
- The RMS operates in one of several modes:
  - Fixed-time mode
  - Responsive mode – responds to current traffic conditions:
    - Responsive/Isolated mode
    - Collaborative mode

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# Scenario

- We assume that we are adding a newly evolved version of a single RMS
- There are already RMSs in the SoS
- We use the COMPASS Integration Framework to model this scenario
- We use a requirements process designed for SoSs, SoS-ACRE, to capture requirements

# COMPASS Integration Framework



CIF provides a coherent set of views & concepts to:

- Identify a number of Viewpoints required for the integration of SoSs
- Describe sequences of activities that should be carried out
- Provide guidance on how the activities should be implemented



# COMPASS Integration Framework

Modelling a change in a single RMS:

## 1. **Constituent system identification.**

Captures and models requirements and CSs.

## 2. **Integration.** Captures and models interfaces and how they connect.

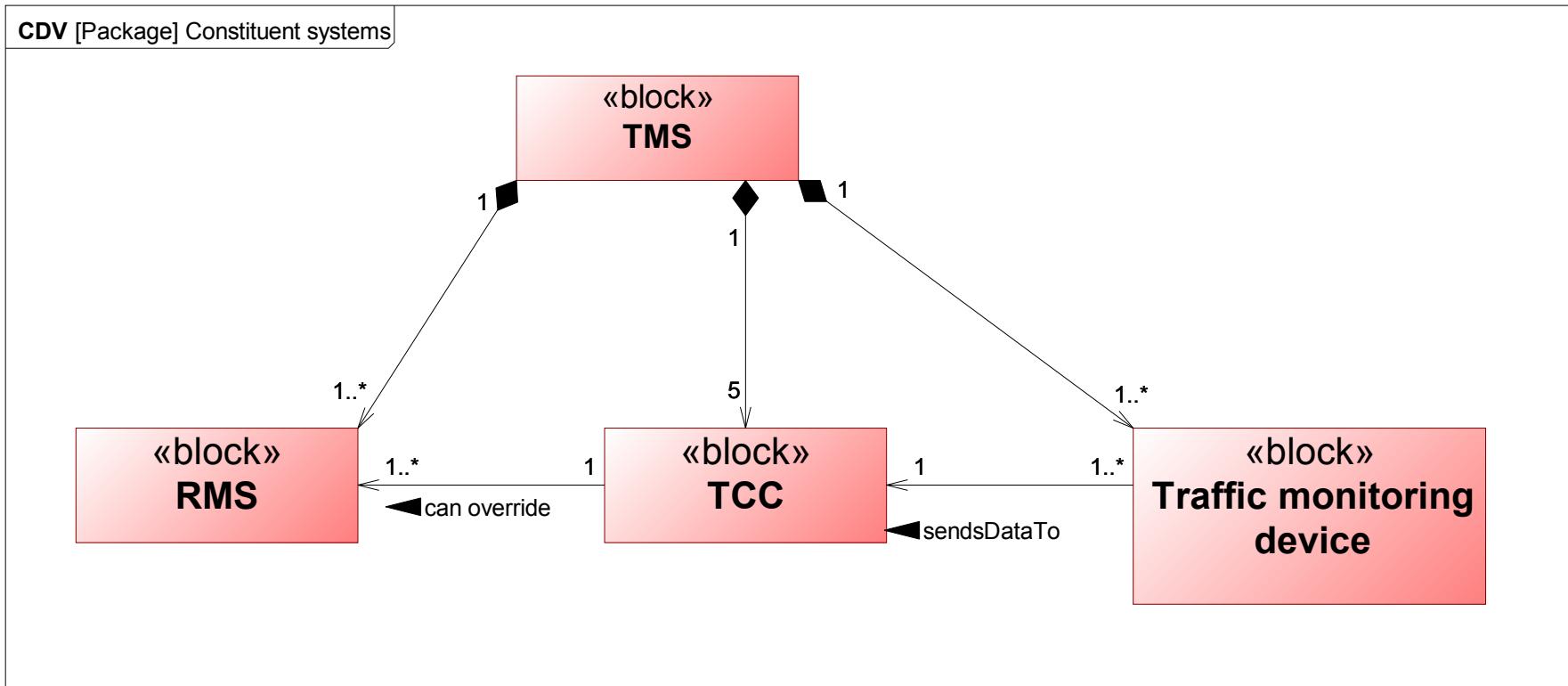
## 3. **Validation.** Identifies scenarios for validating the models.

Repeat the process twice: once for existing RMS (RMSv1), once for new version (RMSv2).

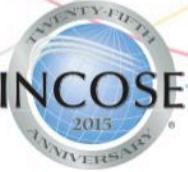
# Constituent System Identification



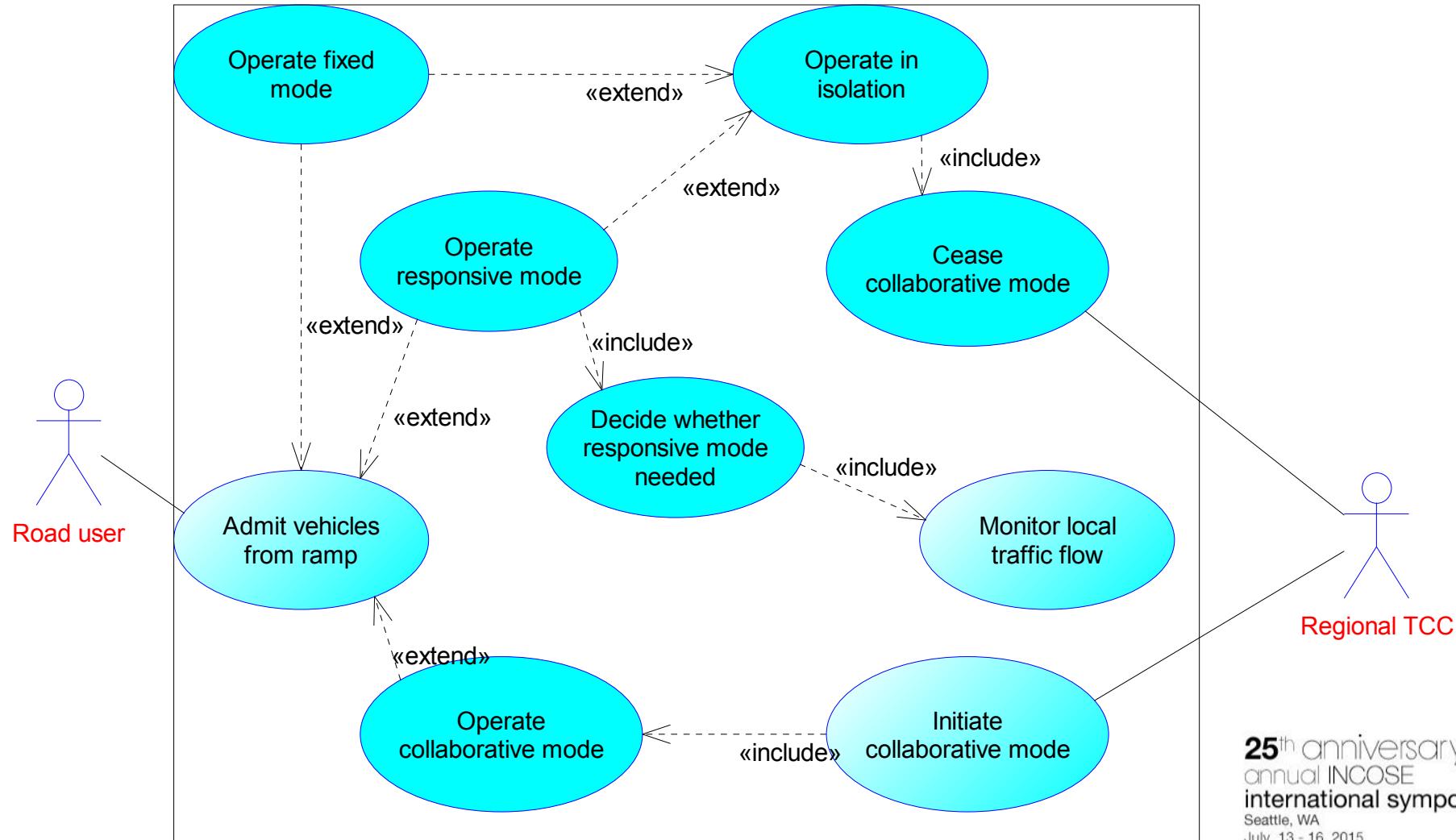
## Context Definition Viewpoint



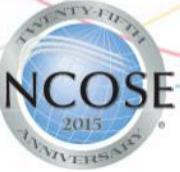
# Constituent System Identification



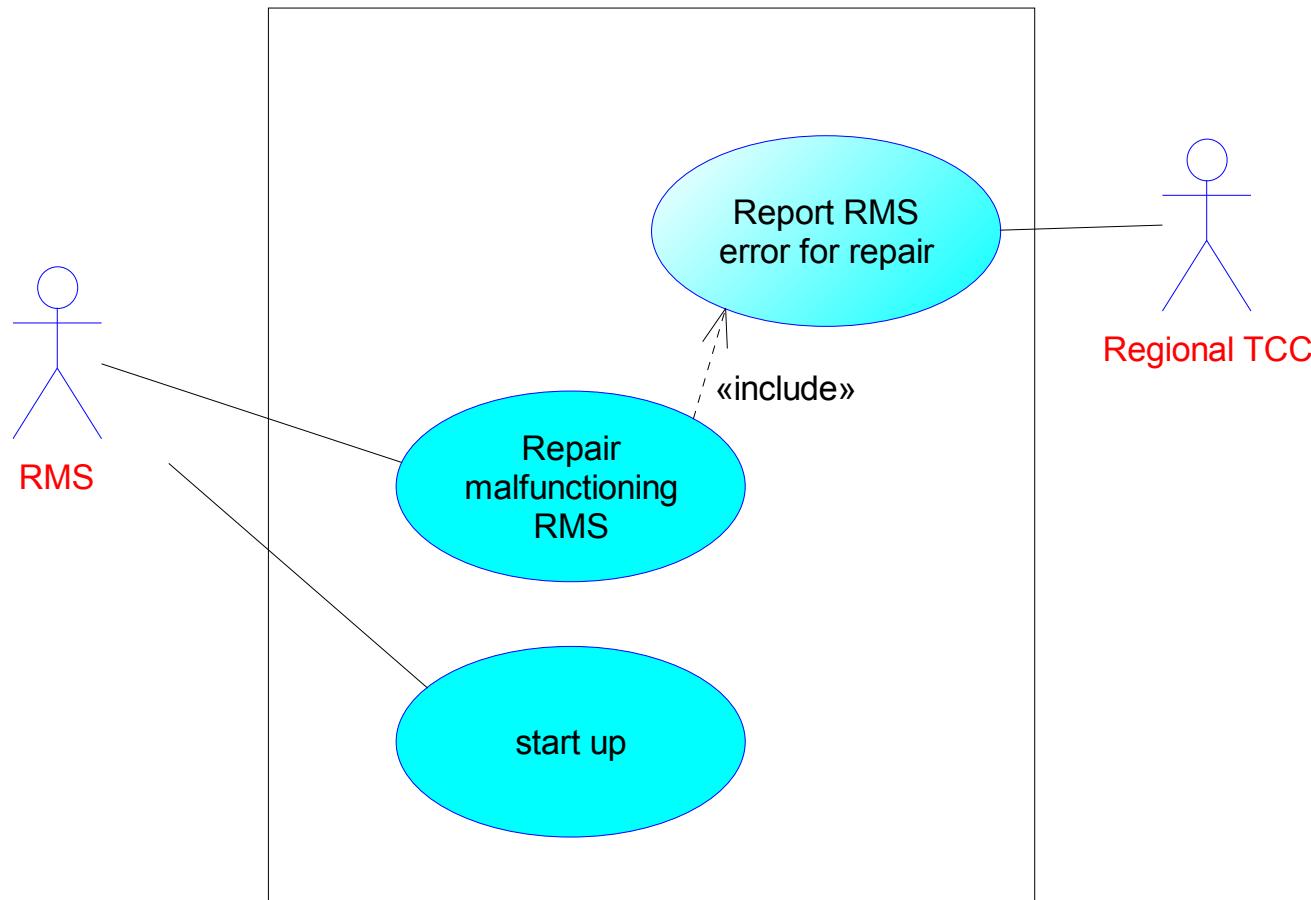
## Requirement Context Viewpoint: RMS POV



# Constituent System Identification



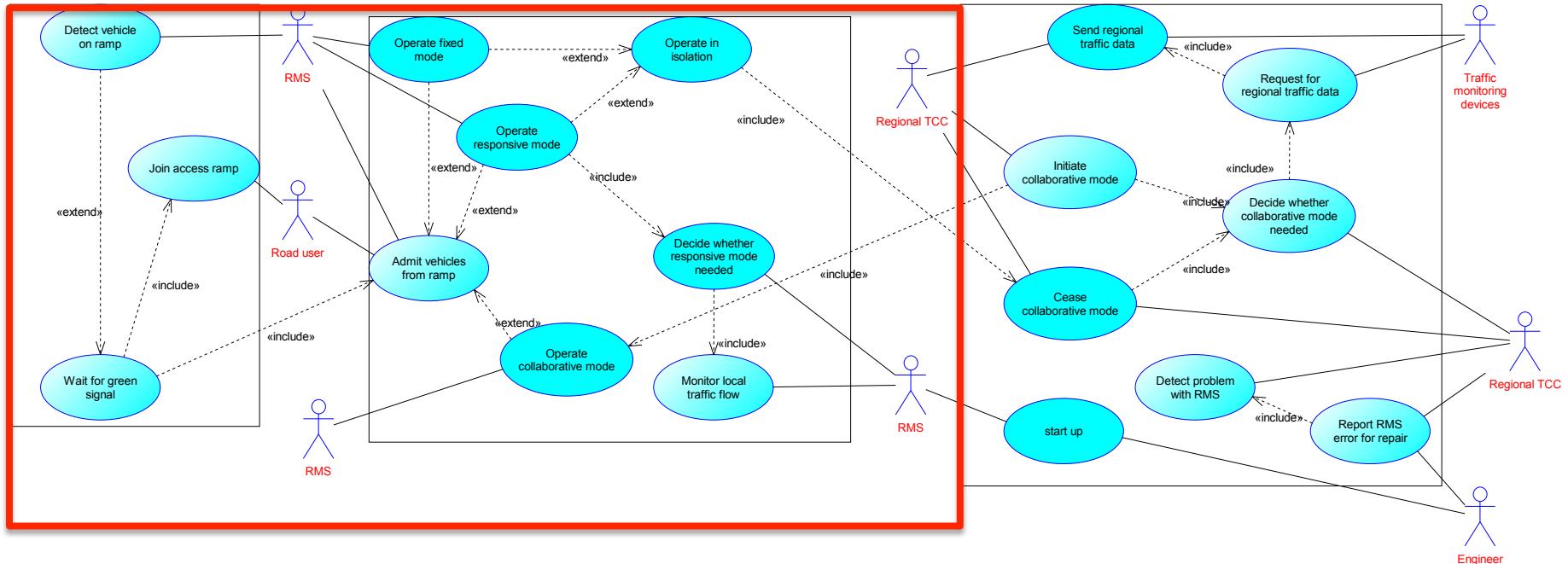
## Requirements Context Viewpoint: engineer POV



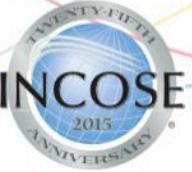
# Constituent System Identification



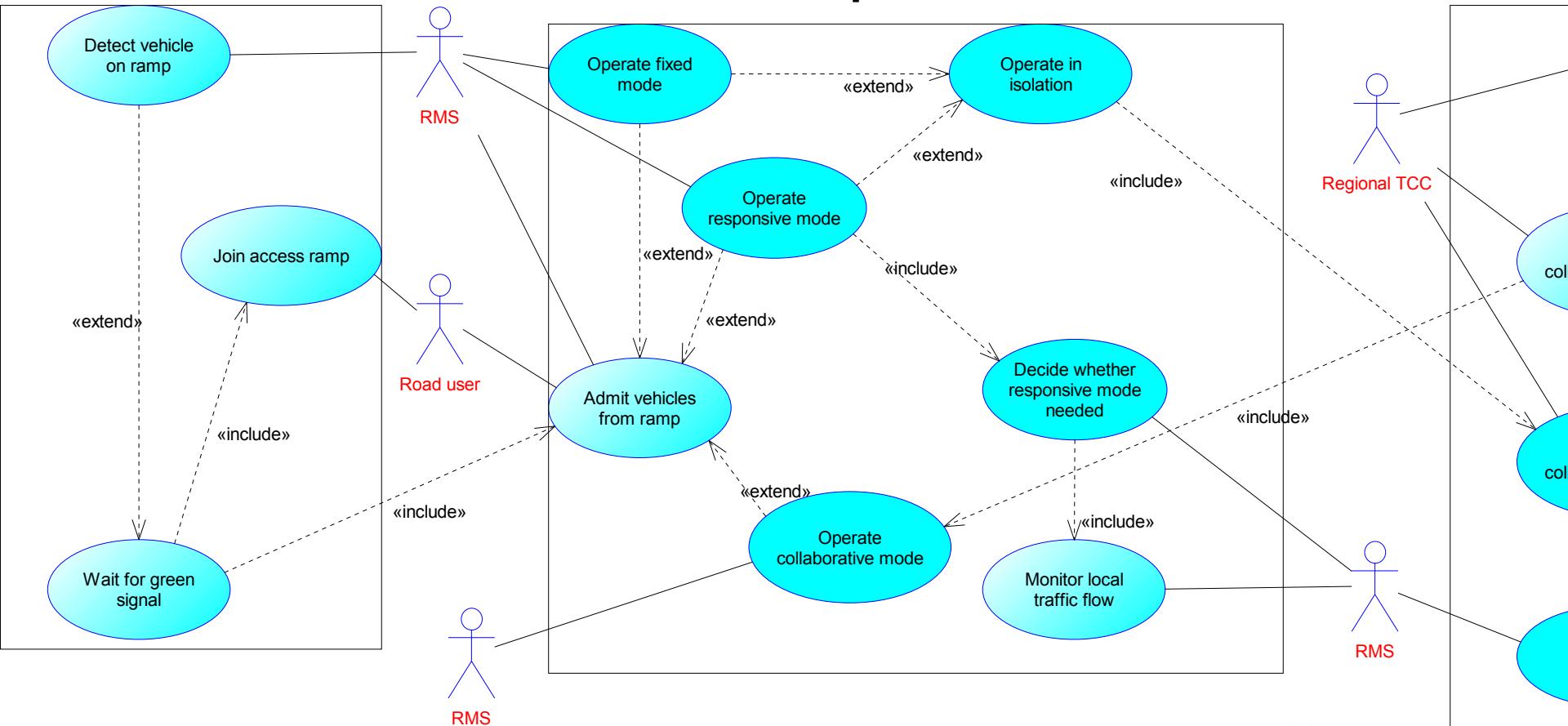
## Context Interaction Viewpoint



# Constituent System Identification



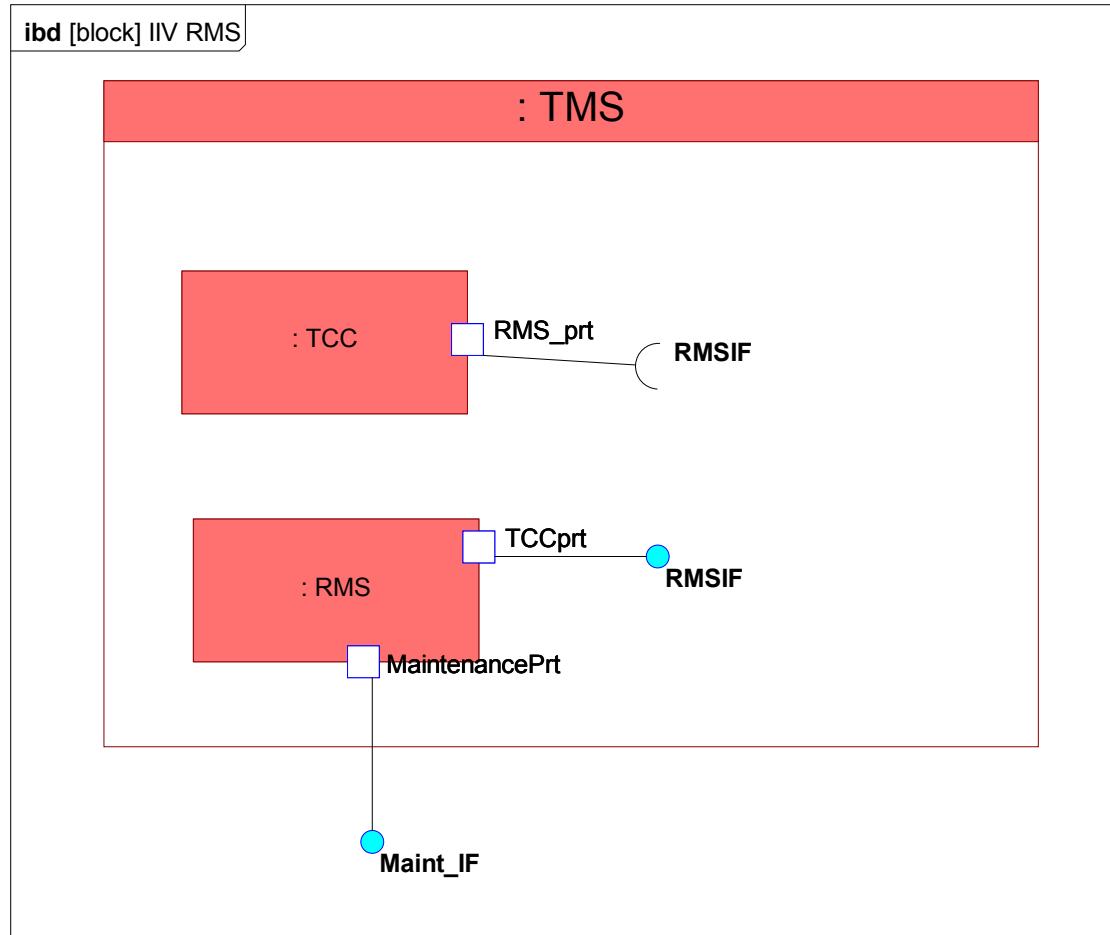
## Context Interaction Viewpoint



# Constituent System Identification



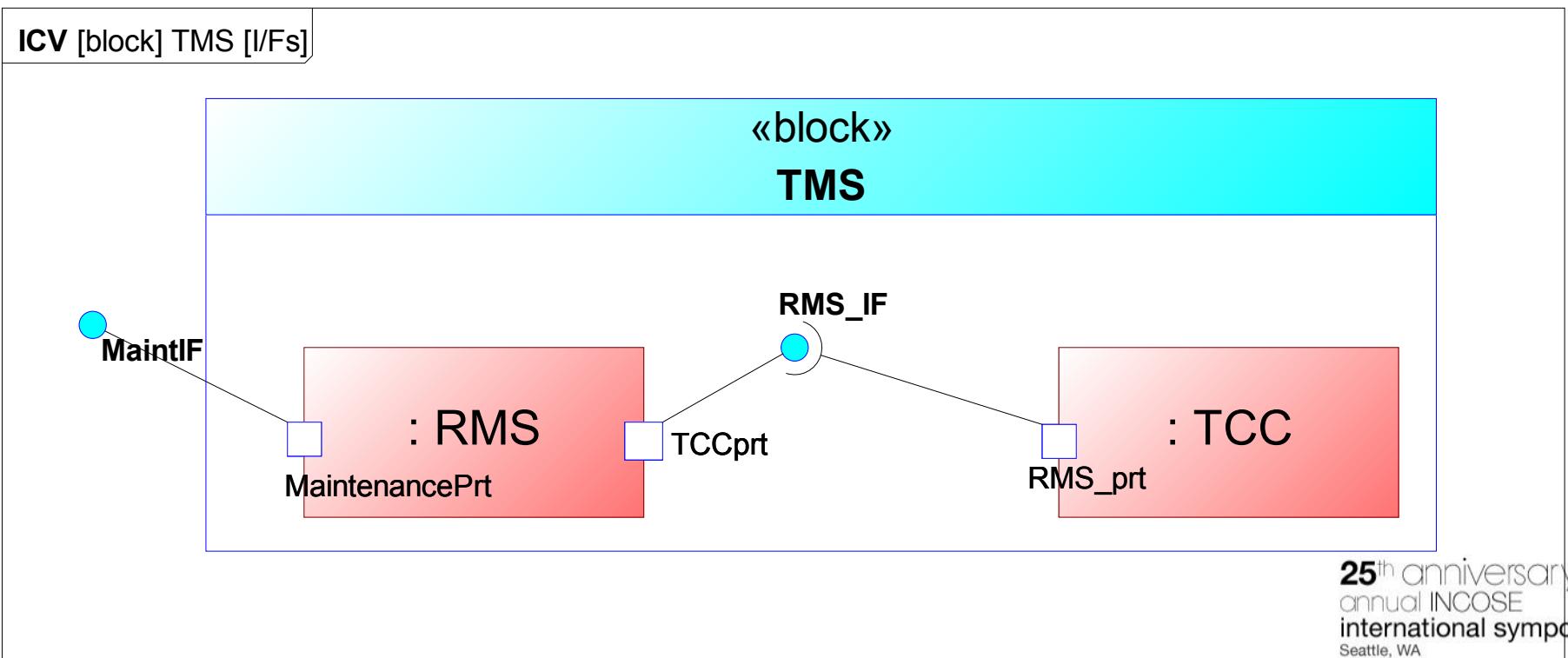
## Interface Identification Viewpoint



# Integration Process

## Interface Connectivity Viewpoint

- defines how the interfaces in the IIV are connected



# Integration Process

## Interface Definition Viewpoint

- Defines structure of each interface in IIV

**IDV** [Package] [Interface definition of RMSIF]

«interface»  
**TMS::Connections::RMSIF**

*goCollaborative (in vehiclesPerMin : Nat) : Boolean*  
*goResponsive () : Boolean*  
*goFixed () : Boolean*  
*reset () : Boolean*  
*shutdown (in delay : secs) : Boolean*

{Pre-conditions  
*goCollaborative::vehiclesPerMin<=100*  
*shutdown:: delay >= 30}*

# Integration Process

## Interface Behaviour Viewpoint

- IBV defines interactions between interfaces we have already identified
- Implemented as a selection of sequence diagrams
- Model both acceptable and unacceptable sequences
- Five scenarios are developed and one IBV developed for each

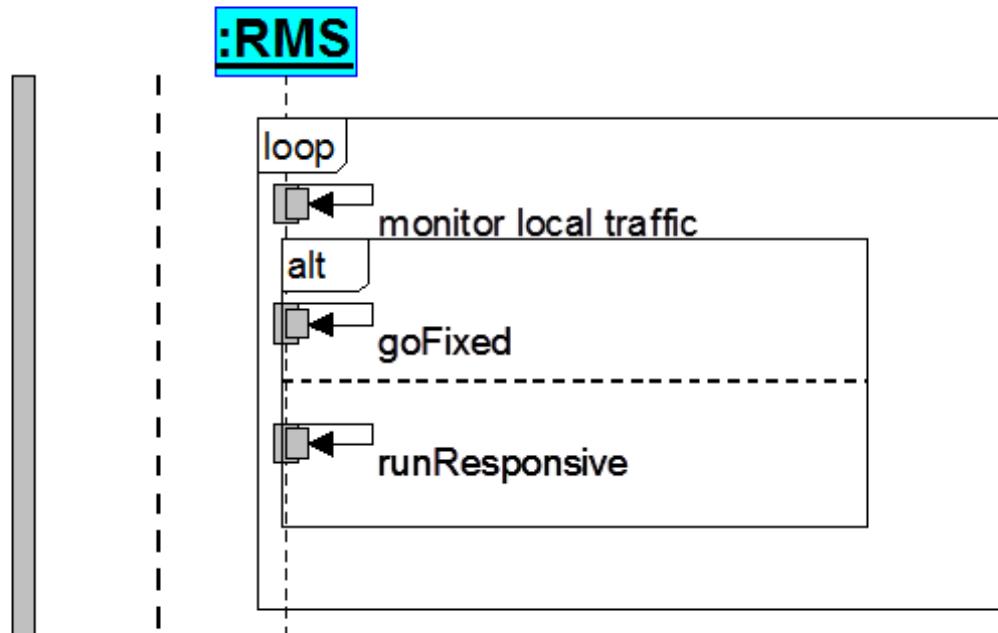
# Integration Process

## Interface Behaviour Viewpoint: an RMS operates in isolated mode

```

loop
  monitor traffic
  alt
    fixed time mode
    else alt
      responsive mode needed
    end alt
  end loop

```



# Integration Process

## Interface Behaviour Viewpoint: acceptable behaviour

par

  startup

also par

  seq

also par

  seq

also par

  monitor regional traffic

end par

loop

  par

    run in isolated mode

  also par

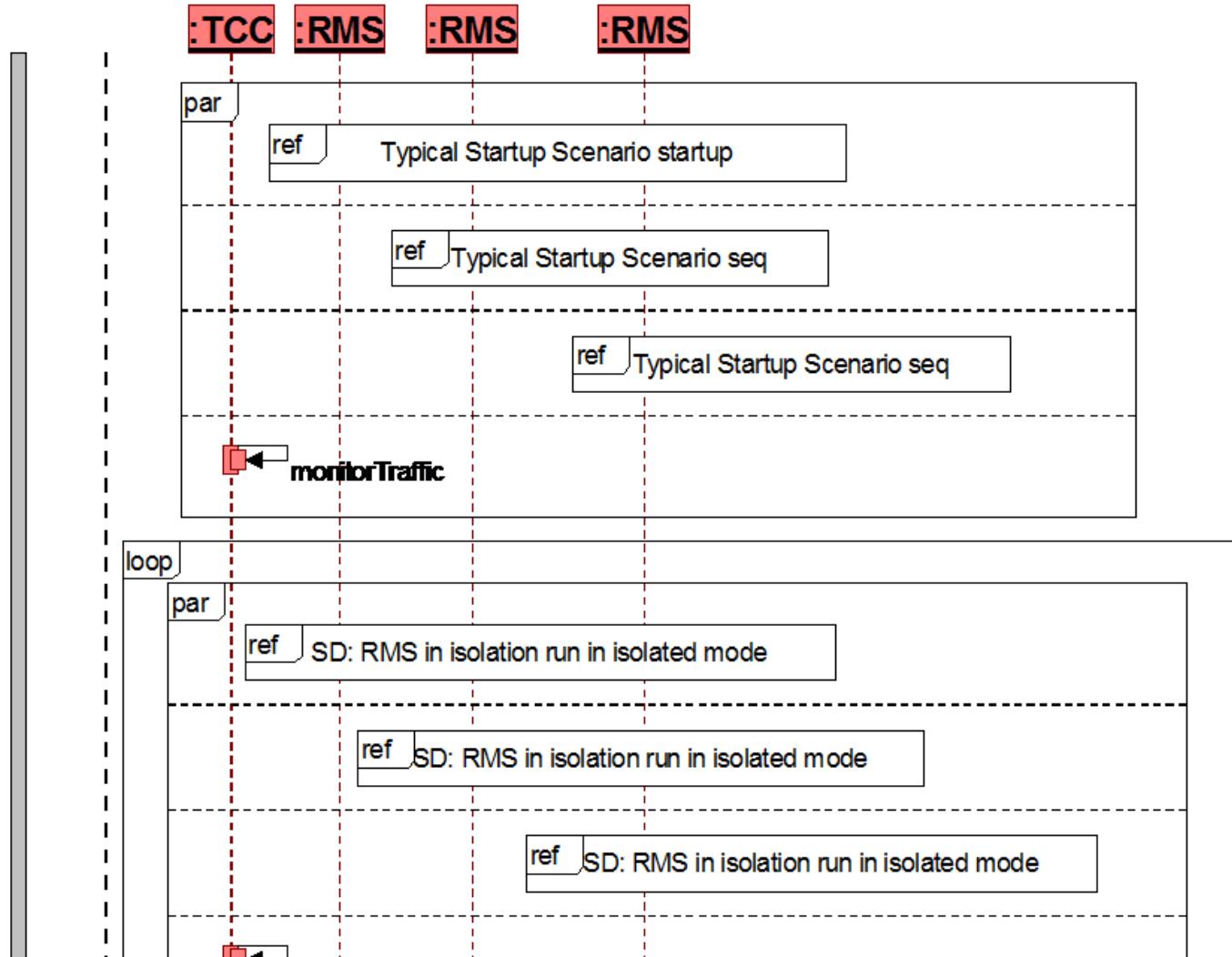
    run in isolated mode

  also par

    run in isolated mode

  also par

    monitor regional traffic



end loop

par

    go to collaborative mode  
    accept collaborative mode

also par

    go to collaborative mode  
    accept collaborative mode

also par

    go to collaborative mode  
    accept collaborative mode

also par

    monitor regional traffic

end par

loop

    par

        run collaborative

    also par

        run collaborative mode

    also par

        run collaborative mode

    also par

        monitor regional traffic

    end par

end loop

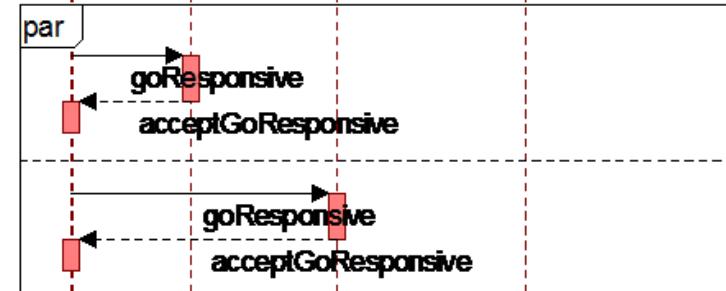
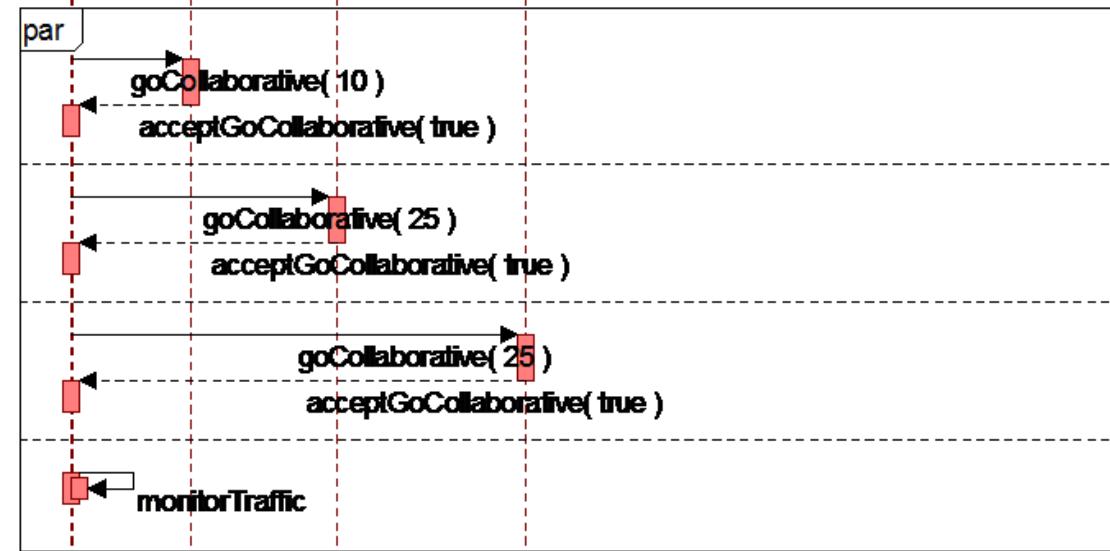
par

    go to responsive mode  
    accept responsive mode

also par

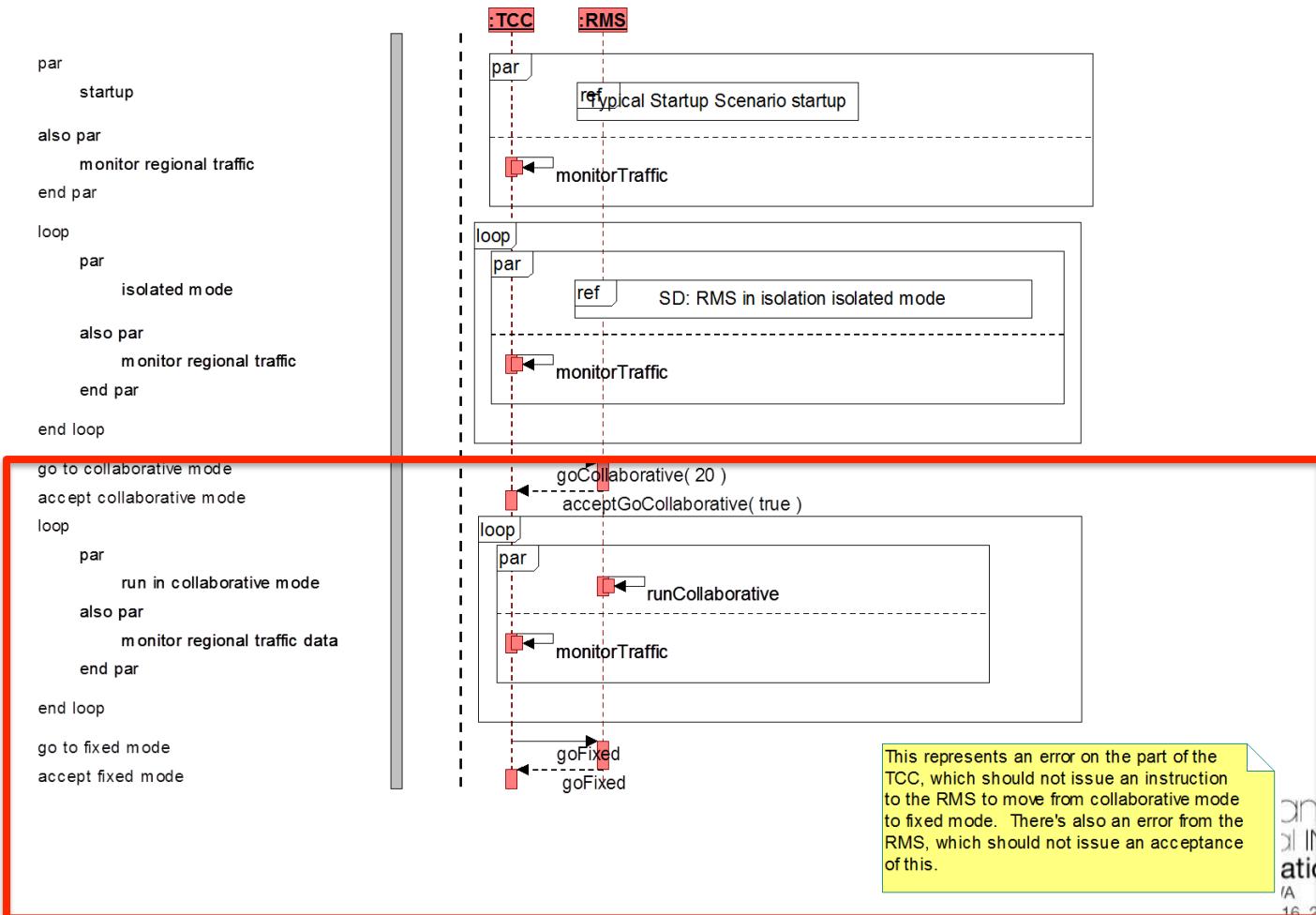
    go to responsive mode  
    accept responsive mode

also par



# Integration Process

## Interface Behaviour Viewpoint: unacceptable behaviour



# Integration Process

```

also par
  monitor regional traffic
end par

end loop

go to collaborative mode
accept collaborative mode
loop
  par
    run in collaborative mode
  also par
    monitor regional traffic data
  end par
end loop

go to fixed mode
accept fixed mode
  
```



This represents an error or TCC, which should not issue to the RMS to move from collaborative to fixed mode. There's also an RMS, which should not issue this.



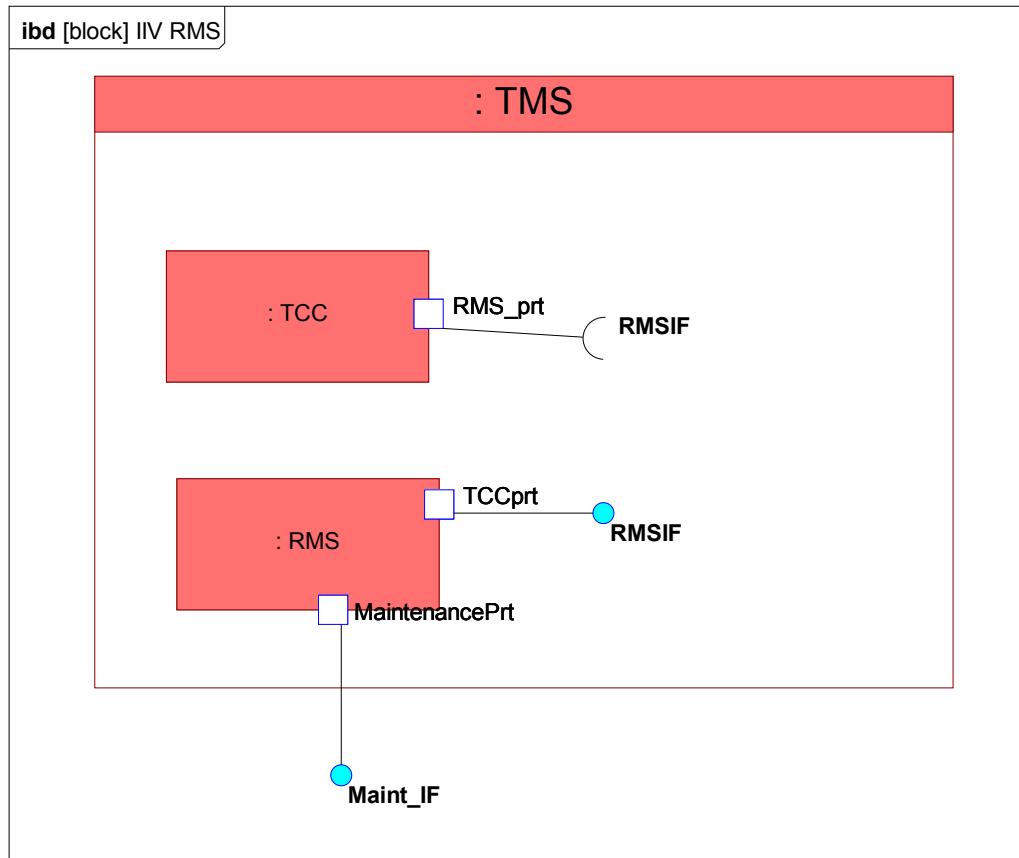
# Integration Process

## Interface Connectivity Viewpoint

- Defines how the interfaces in the IIV are connected

# Integration Process

## Interface Identification Viewpoint

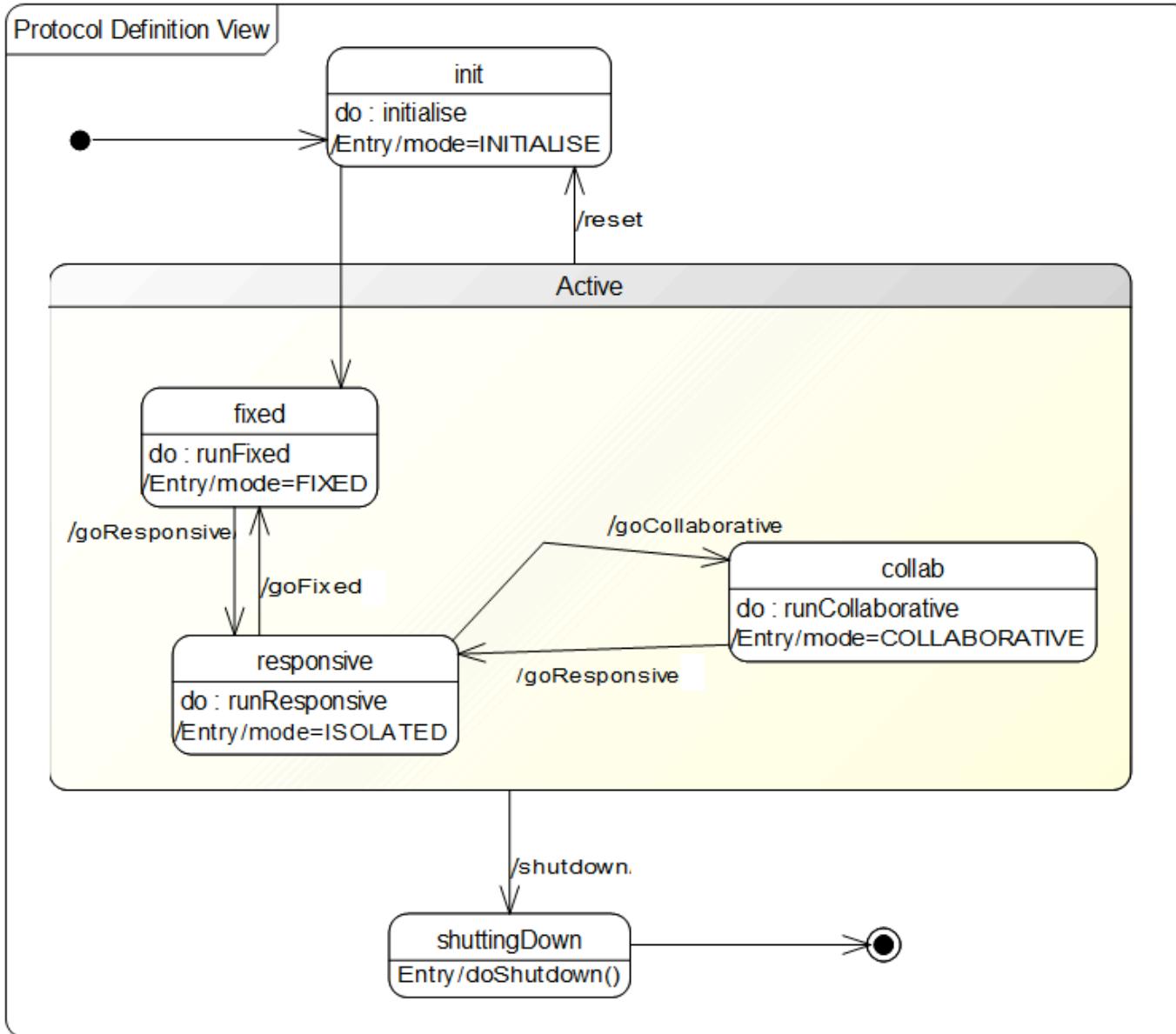


# Integration Process

## Protocols Definition Viewpoint

- Defines protocols for each interface identified during previous modelling efforts

# Protocol Definition

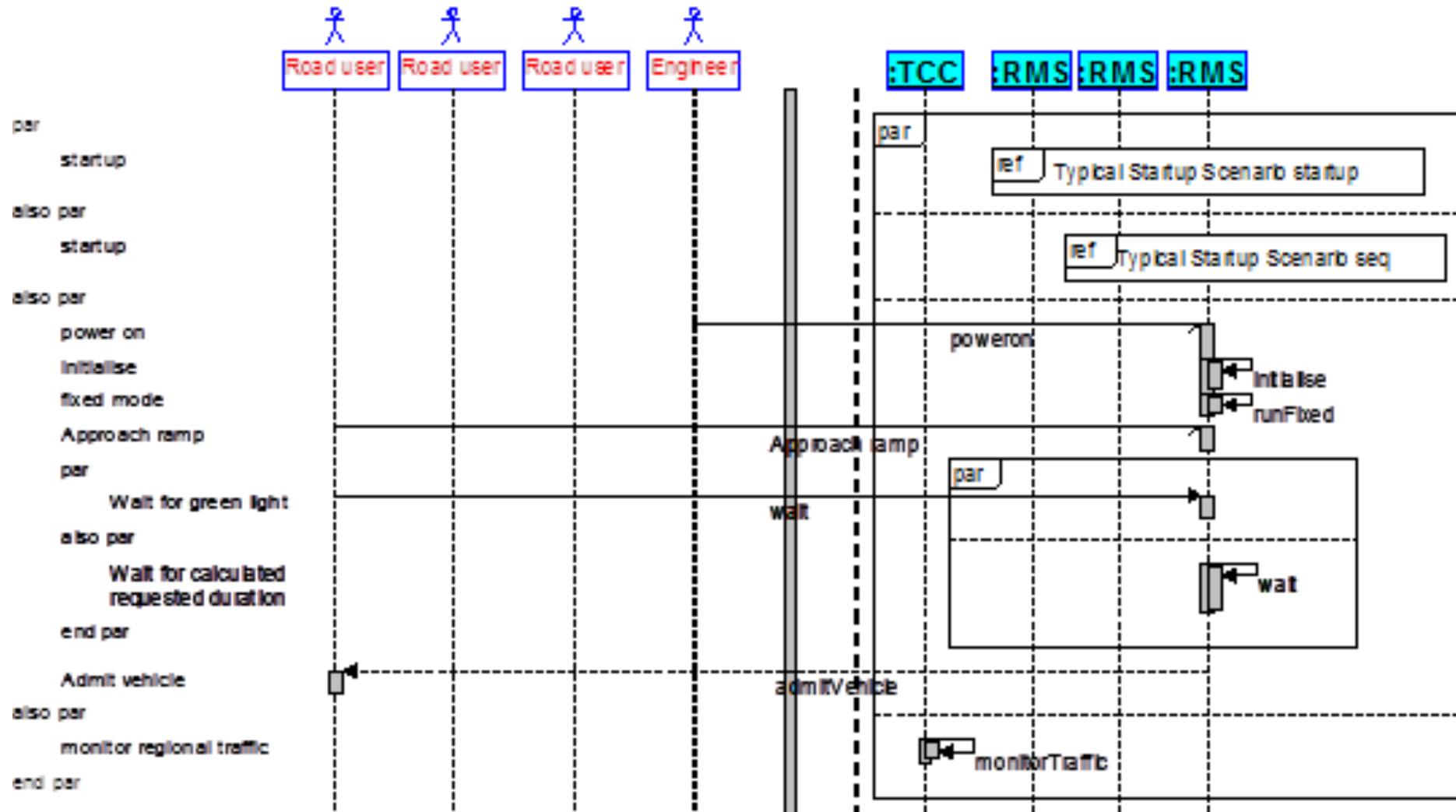


# Validation

- Integration Framework also includes validation phase
- We validate our SoS-level use cases using Interface Behaviour Viewpoints (already presented)
- CIF recommends further validation, in the form of a Validation Interaction Viewpoint
  - integrates the previous sequence diagrams all onto one view
  - Identify inconsistencies or duplication

# Validation

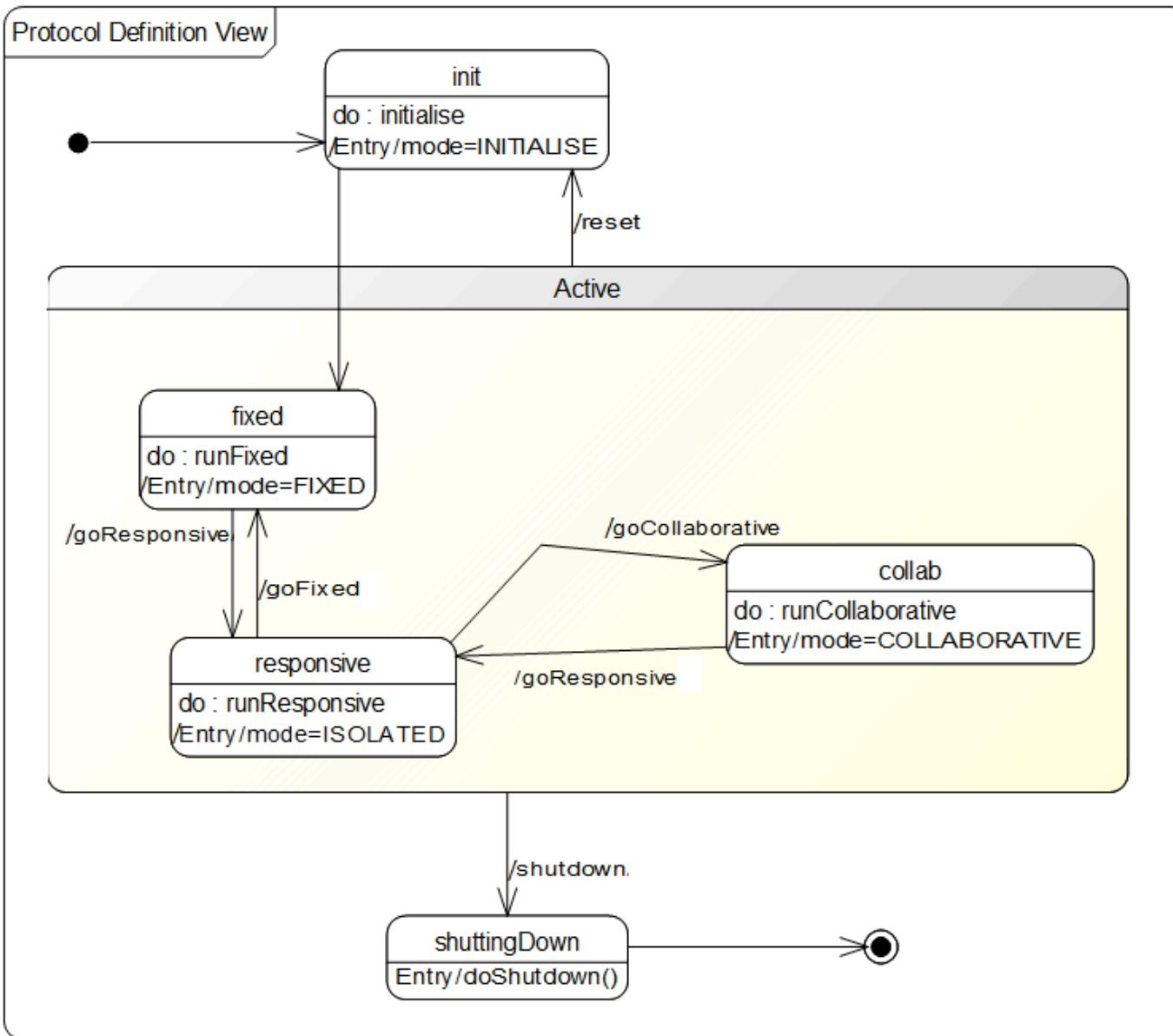
# Validation Interaction Viewpoint



# COMPASS Integration Framework

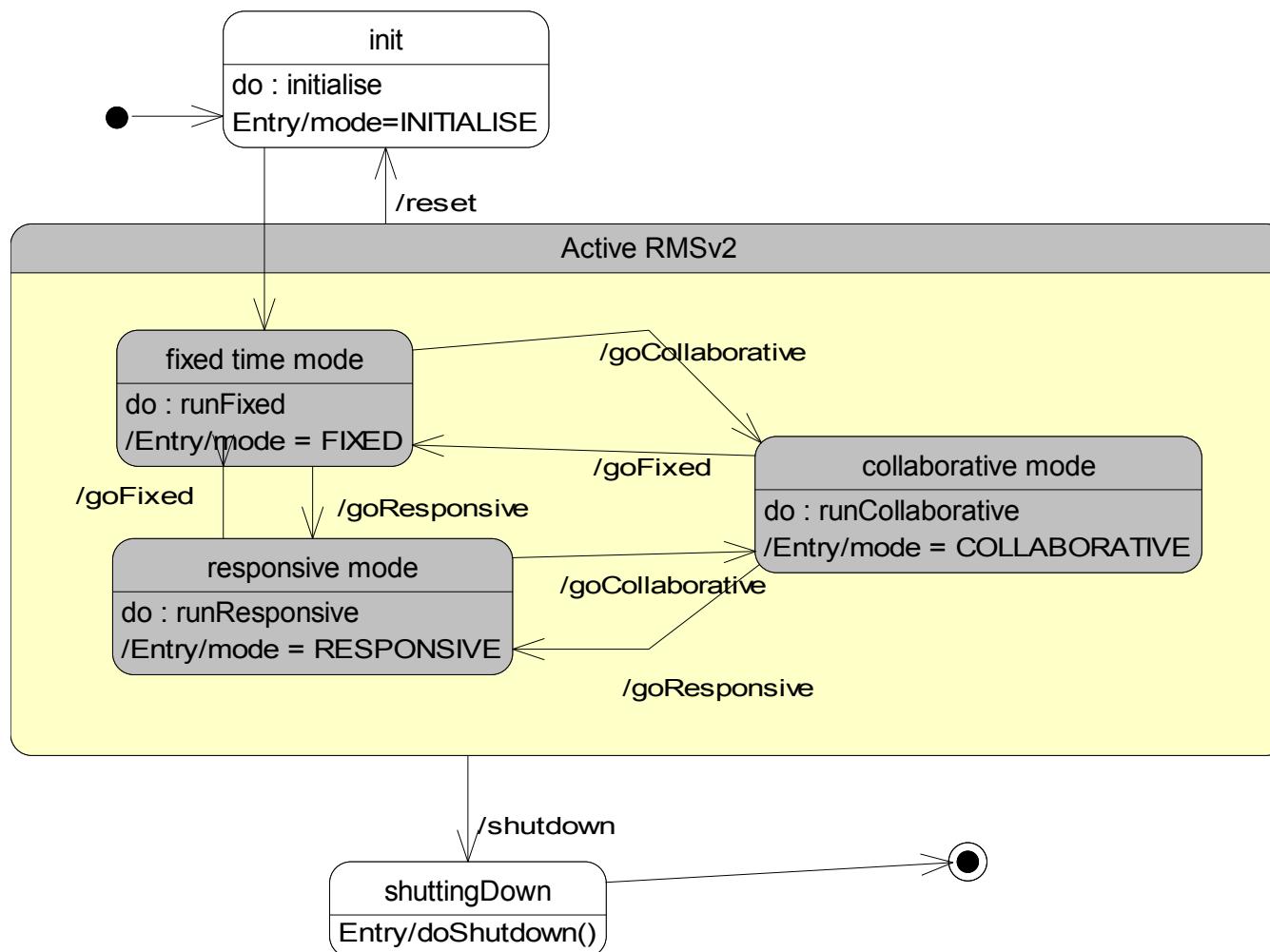
- The result is a set of models describing our existing RMS, which we call **RMSv1**
- Next: we repeat the same complete process, to generate a set of similar models for a new version of the RMS, which we call **RMSv2**
- Only one model differs for RMSv2 - Protocols Definition Viewpoint

RMSv1



# RMSv2

## Protocol Definition View



# COMPASS Integration Framework



## CIF process:

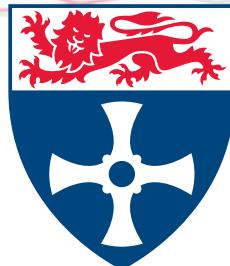
1. Architectural models, as prescribed
2. Translate to a formal modelling notation
3. Analysis and validation with automated or semi-automated support

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# Conclusions

- CIF offers a structured, guided process for modelling various integration scenarios
- SoSs have long life-spans; CIF can help to plan regression testing
- Our approach here is a good introductory step for formal modelling of the SoS
- More work to be done – including further work to integrate with automated testing and formal modelling techniques where possible



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This work is part of the COMPASS project: research into model-based techniques for developing, maintaining and analysing SoSs

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