

Integrating an Upgraded Constituent System in a System of Systems: A SysML case study

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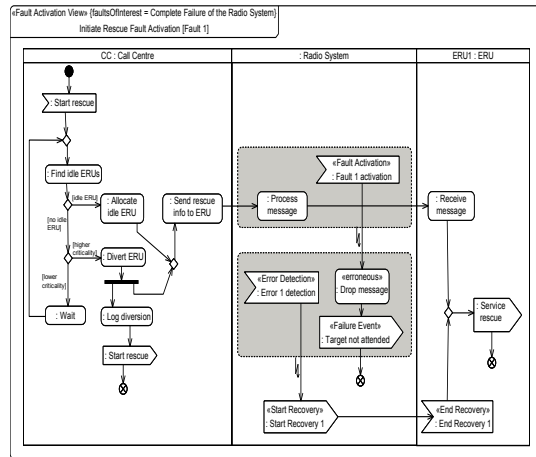
Nico Plat, West Consulting, Netherlands

Introduction



- SoSs are comprised of elements that are themselves independent systems
- Often exhibit:
 - Operational & managerial independence
 - Distribution
 - Reliance placed on emergence
 - Evolution
- Challenging aspects include:
 - Operational & Managerial Independence of Constituent Systems
 - Complexity of confirming/refuting SoS-level properties
 - Semantic heterogeneity



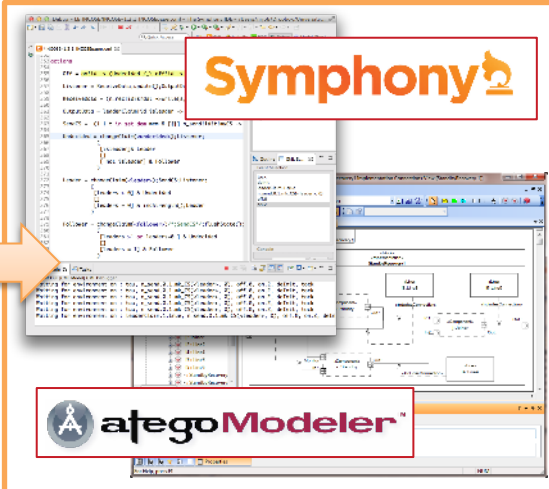


**process CallCentreProc = begin
actions**

```

MERGE1(r) =
(dcl e: set of ERUId @ e := findIdleERUs();
(do e = {} -> DECISION2(r) |
e <> {} -> (dcl e1: ERUId @
e1 := allocateIdleERU(e, r);
MERGE2(e1, r))
end)) ...
    
```

process InitiateRescue =
CallCentreProc [| SEND_CHANNELS |]
RadioSystemProc [| RCV_CHANNELS |] **ERUsProc**



Architectural Modelling

- SoS Modelling Frameworks
- ... instantiated to domains
- **SoS Modelling patterns & profiles, e.g. Fault-Error-Failure**
- Guidelines on negotiation, requirements, integration, test, etc.

Underpinning Formalisms

- Behavioural semantics of SoS
- Tight link to modelling frameworks
- Cope with multiple paradigms.
- **Compositional Design**
- **Dynamic response to adaptation & evolution**
- **Covering cyber elements, physical, human, economic, social, ...**

Tool-supported V&V:

- Exploration of Design Space
- Efficient verification by model-checking and proof
- **Test generation**
- **Simulation**
- **Tools Robustness**
- **Conformance during evolution, and emergence**

Outline



1. Integration in an SoS
2. Introduction to the case study
3. Application of the Integration Framework
 - Constituent system identification process
 - Integration process
 - Validation process
4. Conclusions

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Integration in an SoS



- An SoS is a system comprising components which are each independent systems themselves
 - Constituent parts operated and managed separately
 - Large-scale, distributed
 - Emergent behaviour
 - Continually evolving

Integration in an SoS



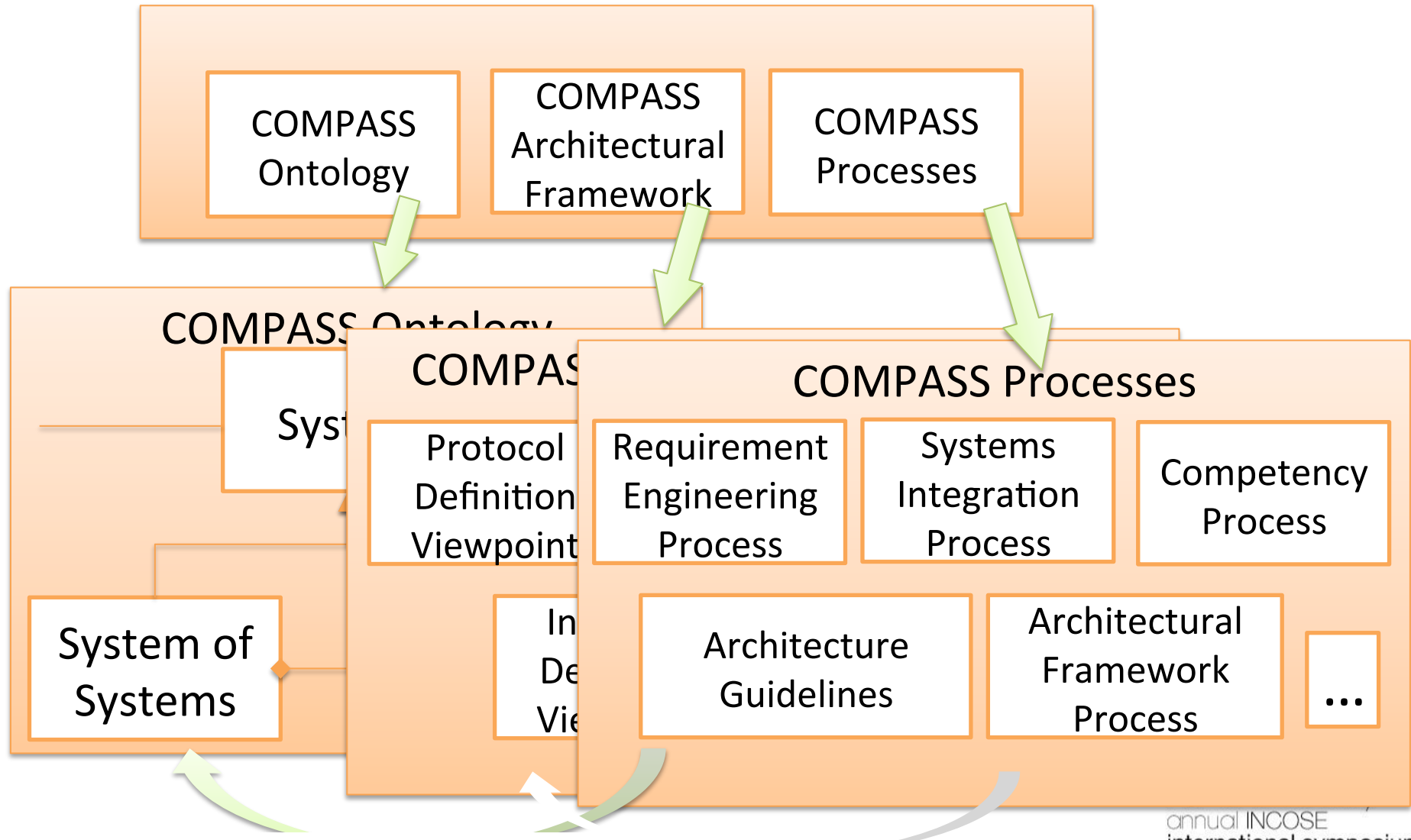
- Integration a key challenge for an SoS
 - SoSs are continually changing
- Several activities covered by “integration”
 - e.g. ensuring no negative effects felt after a changed/new constituent is integrated
- Modelling is important for SoSs
 - Scale and SoS operating environment difficult to replicate in a lab
 - Testing accurately difficult/expensive

Architectural Modelling



- We follow **COMPASS** architectural approach
 - patterns and guidelines
- Use collections of *modelling patterns* to define SoS structure and behaviour
- COMPASS architectural modelling approach also includes *guidelines* for SoS integration and development lifecycles

COMPASS Approach



Viewpoints use mc Processes use viewpoints from architectural framework

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Case Study: Road Traffic Management



- Traffic Management System (TMS) collects information about conditions and traffic flow
- Takes actions to achieve traffic behaviour goals:
 - improving efficiency of the road network
 - ensuring road safety
 - reducing the impact accidents, blockages etc
 - reducing environmental impact
- Inter-urban road network in the Netherlands

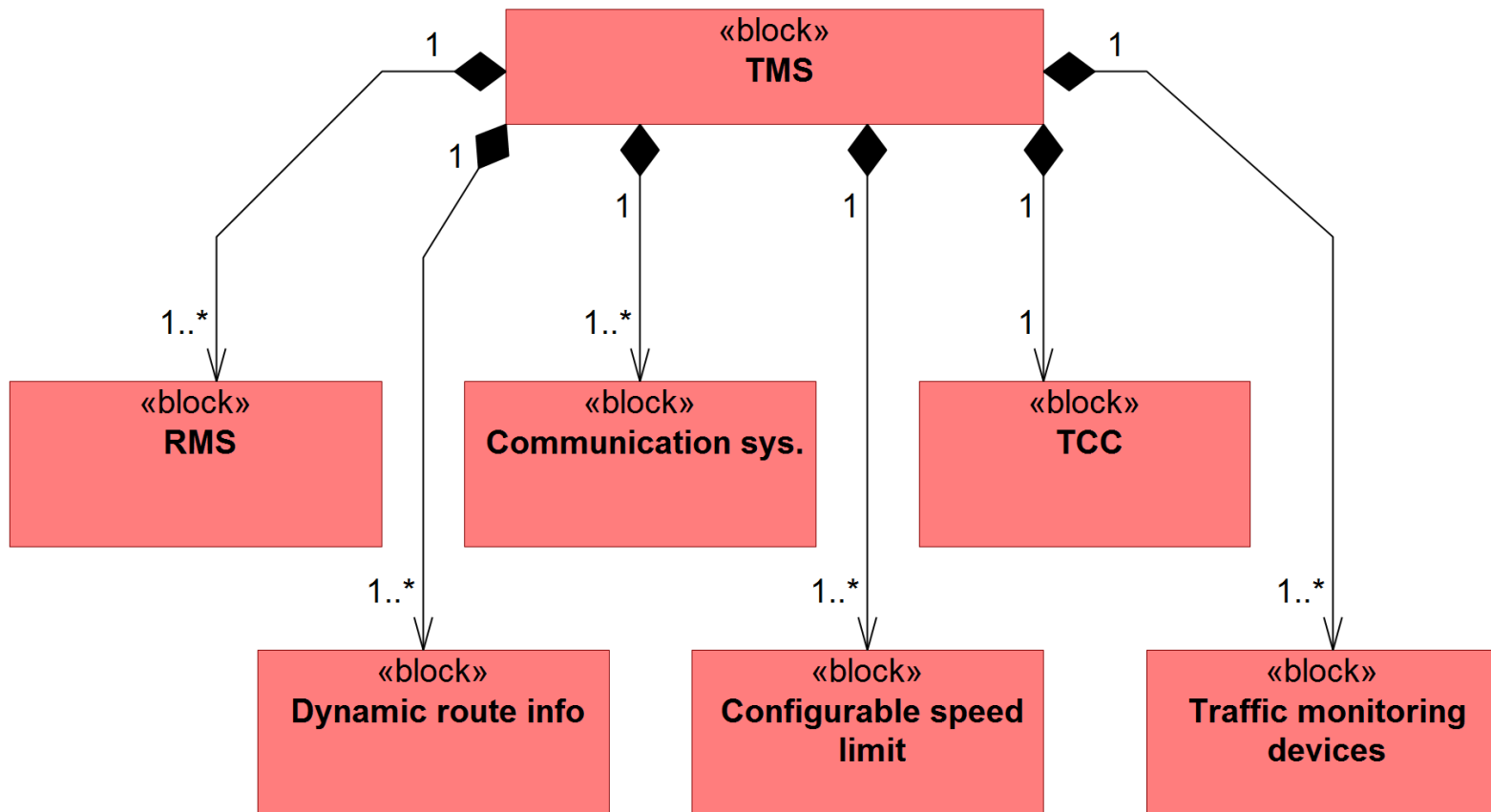
Case Study: Road Traffic Management



- Wide variety of CSs
 - Traffic monitoring systems
 - Systems for influencing traffic flow
 - Control rooms
- Interact with TMSs operated by third parties in adjacent regions

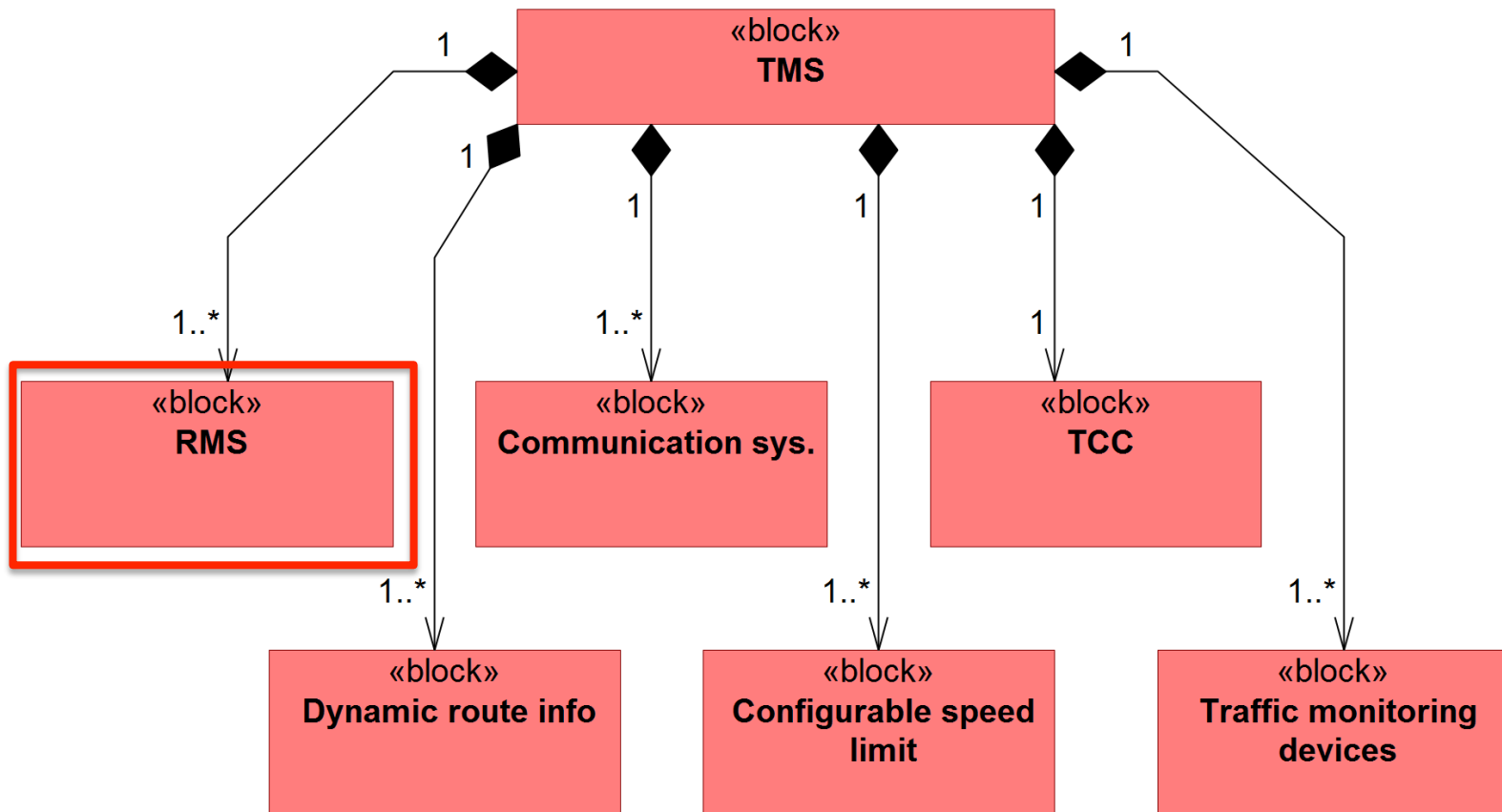
Road Traffic Management

bdd Nominal SoS Composition



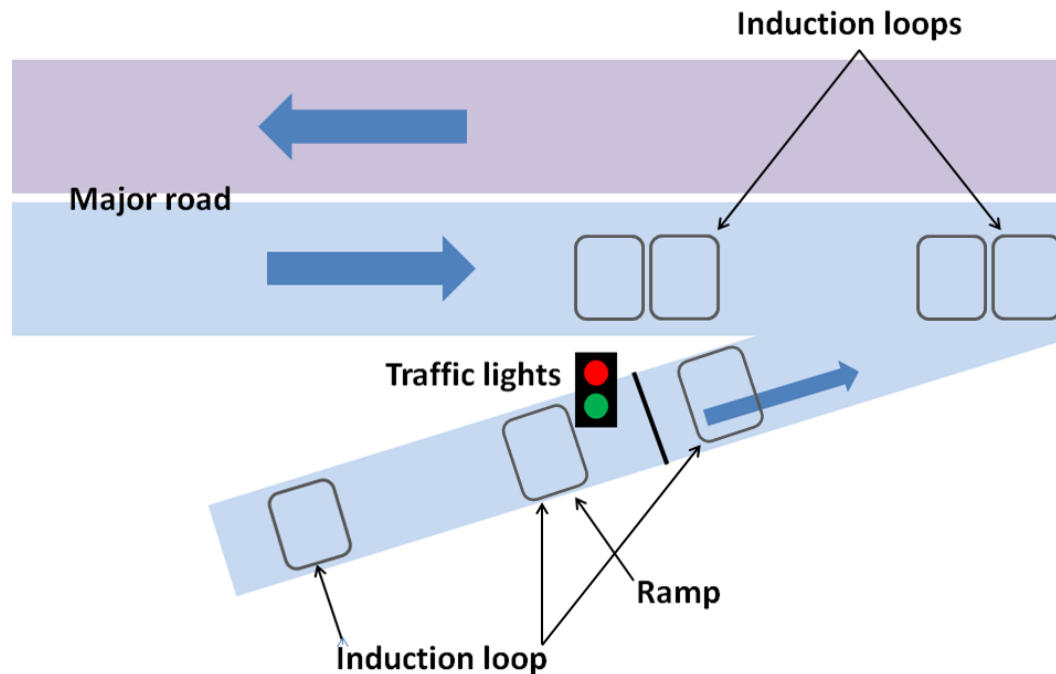
Road Traffic Management

bdd Nominal SoS Composition



Case Study: Road Traffic Management

- Ramp meter system (RMS)
 - Two-phase traffic lights control vehicle rate
 - Prevents bottlenecks and improves vehicle distribution
 - Can reduce accidents caused by high speed merges.





Case Study: Road Traffic Management

- An RMS typically has access to data about traffic in its immediate vicinity
- The RMS operates in one of several modes:
 - Fixed-time mode
 - Responsive mode – responds to current traffic conditions:
 - Responsive/Isolated mode
 - Collaborative mode

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Scenario



- We assume that we are adding a newly evolved version of a single RMS
- There are already RMSs in the SoS
- We use the COMPASS Integration Framework to model this scenario
- We use a requirements process designed for SoSs, SoS-ACRE, to capture requirements

COMPASS Integration Framework



CIF provides a coherent set of views & concepts to:

- Identify a number of Viewpoints required for the integration of SoSs
- Describe sequences of activities that should be carried out
- Provide guidance on how the activities should be implemented

COMPASS Integration Framework



Modelling a change in a single RMS:

1. Constituent system identification.

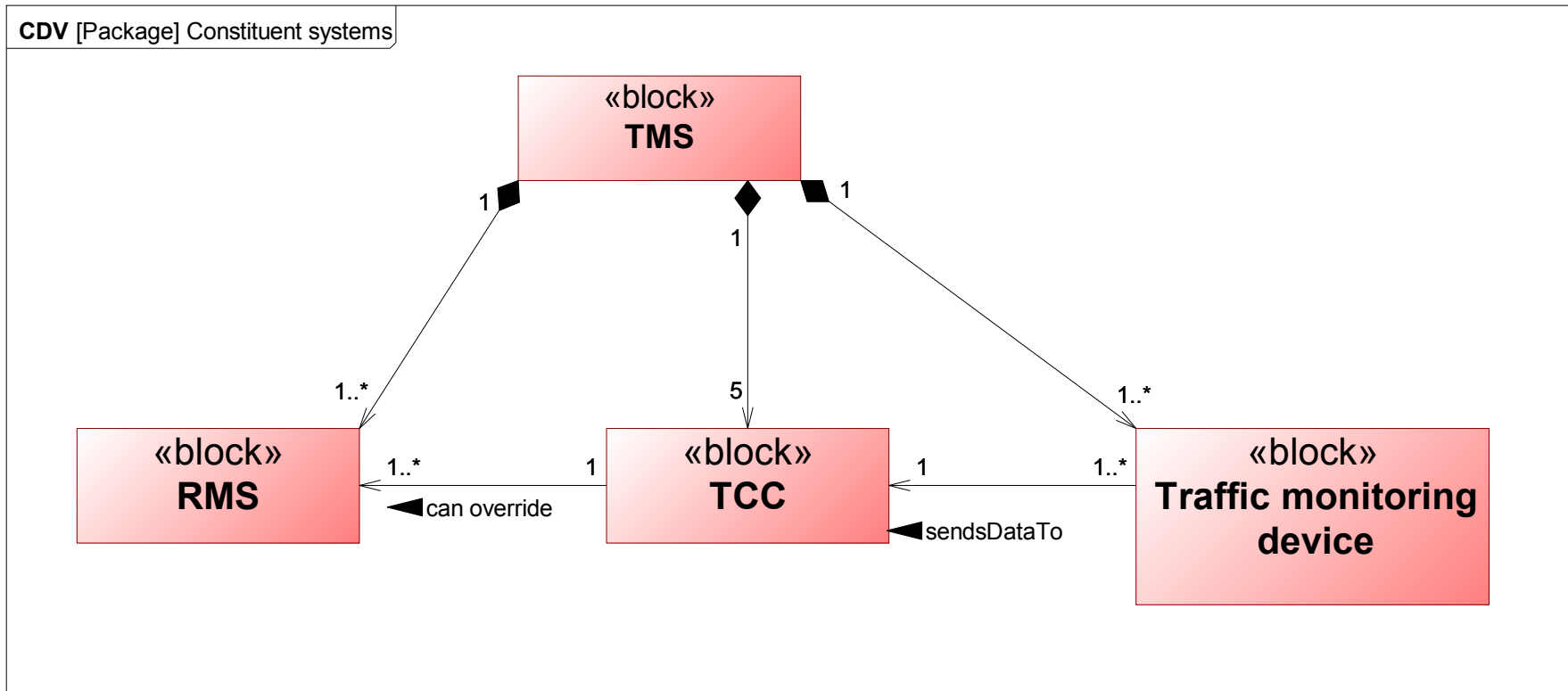
Captures and models requirements and CSs.

2. Integration. Captures and models interfaces and how they connect.

3. Validation. Identifies scenarios for validating the models.

Repeat the process twice: once for existing RMS (RMSv1), once for new version (RMSv2).

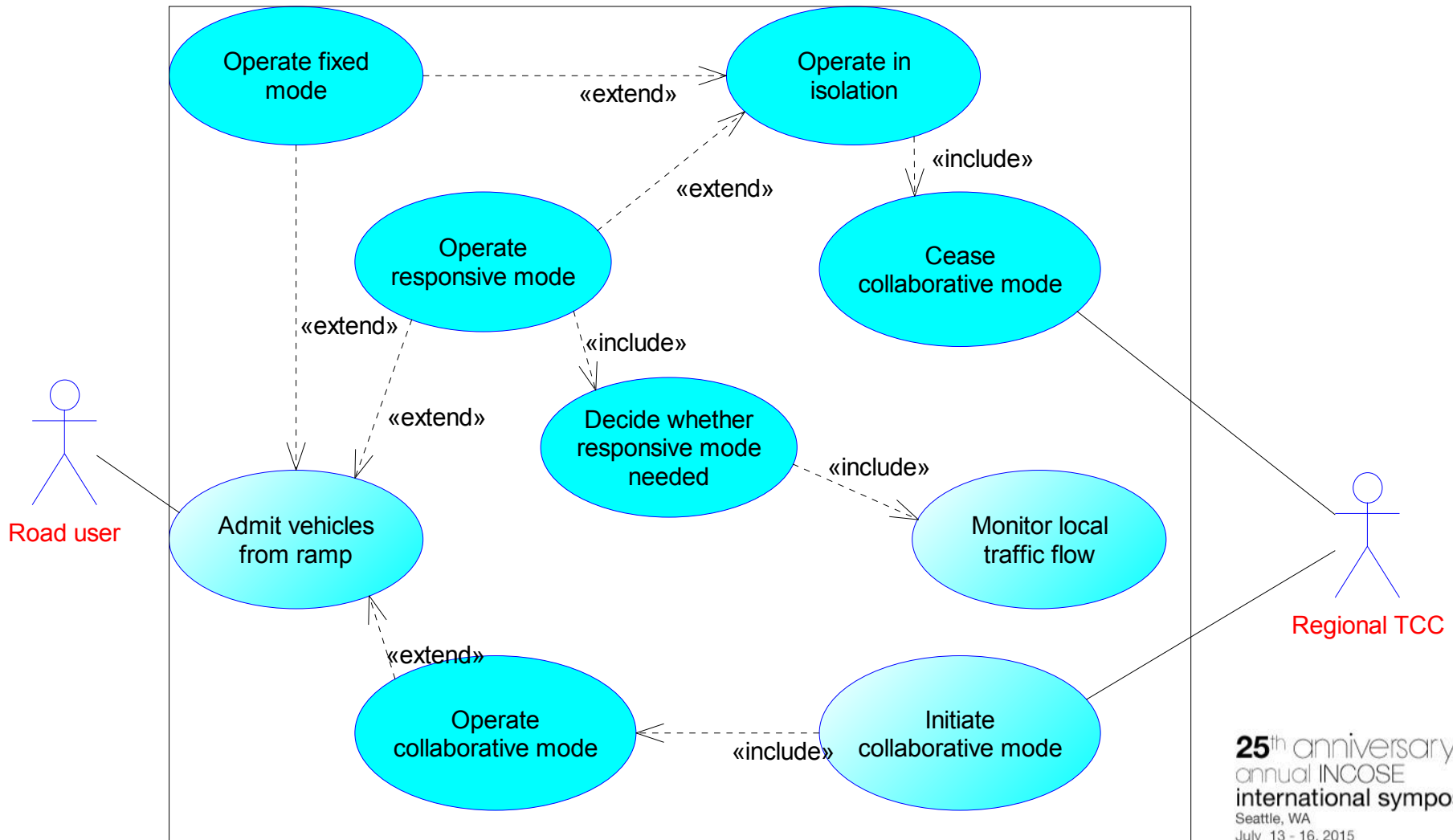
Context Definition Viewpoint



Constituent System Identification



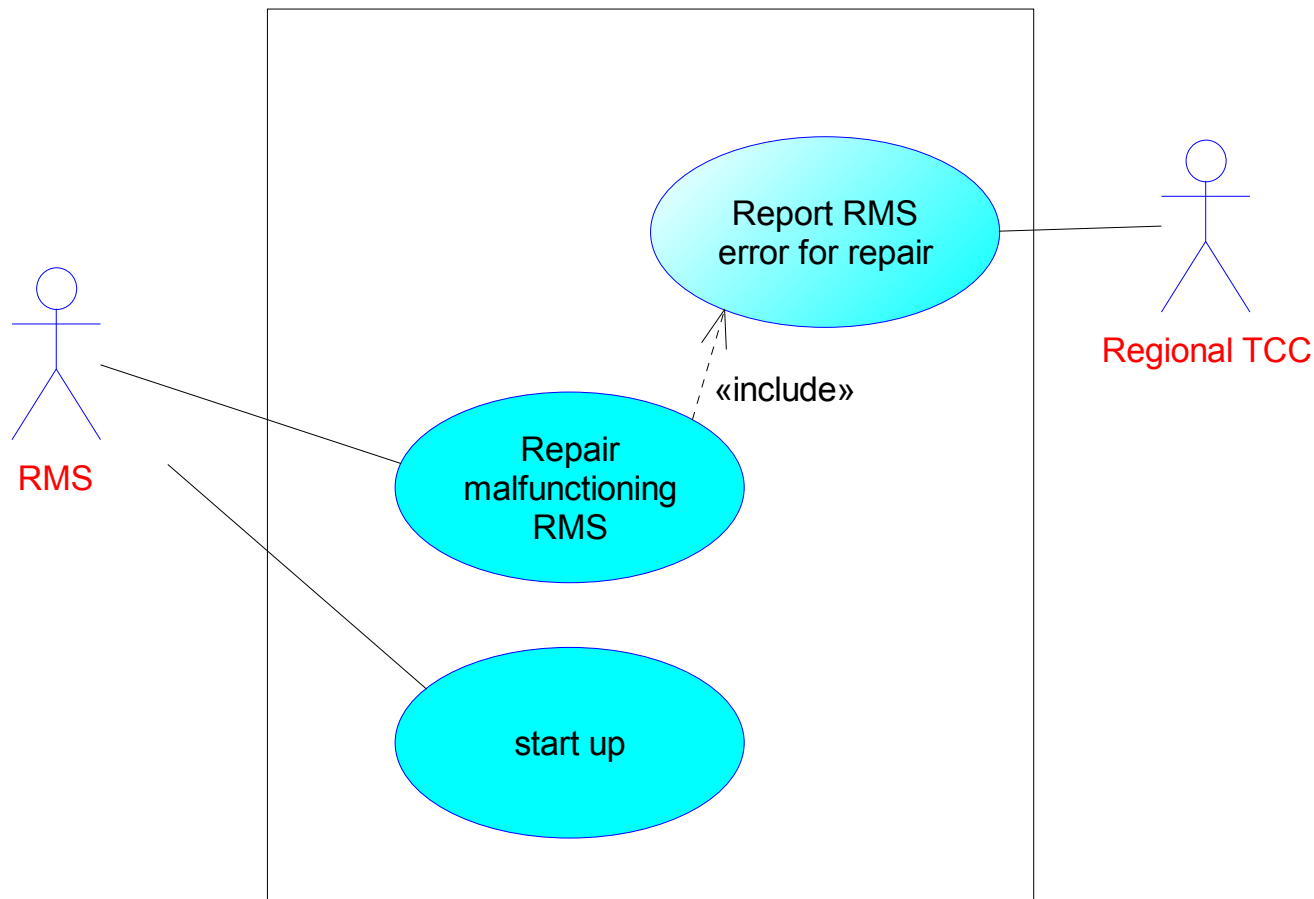
Requirement Context Viewpoint: RMS POV



Constituent System Identification



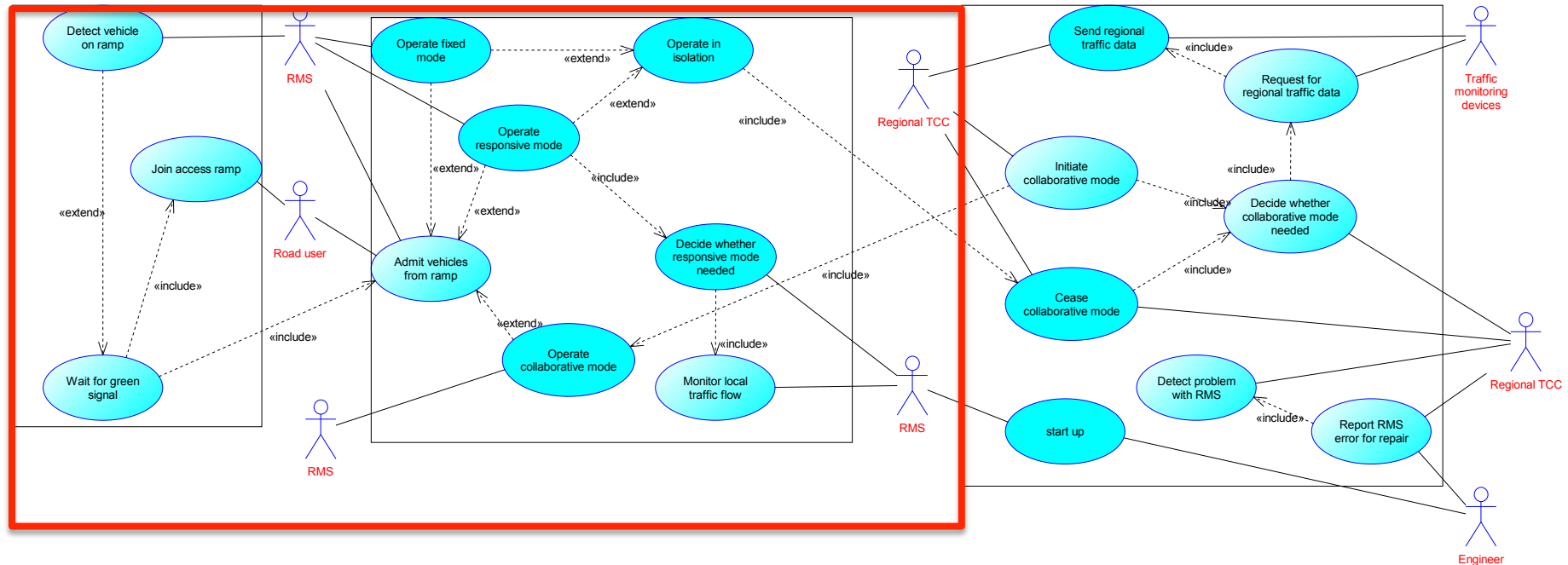
Requirements Context Viewpoint: engineer POV



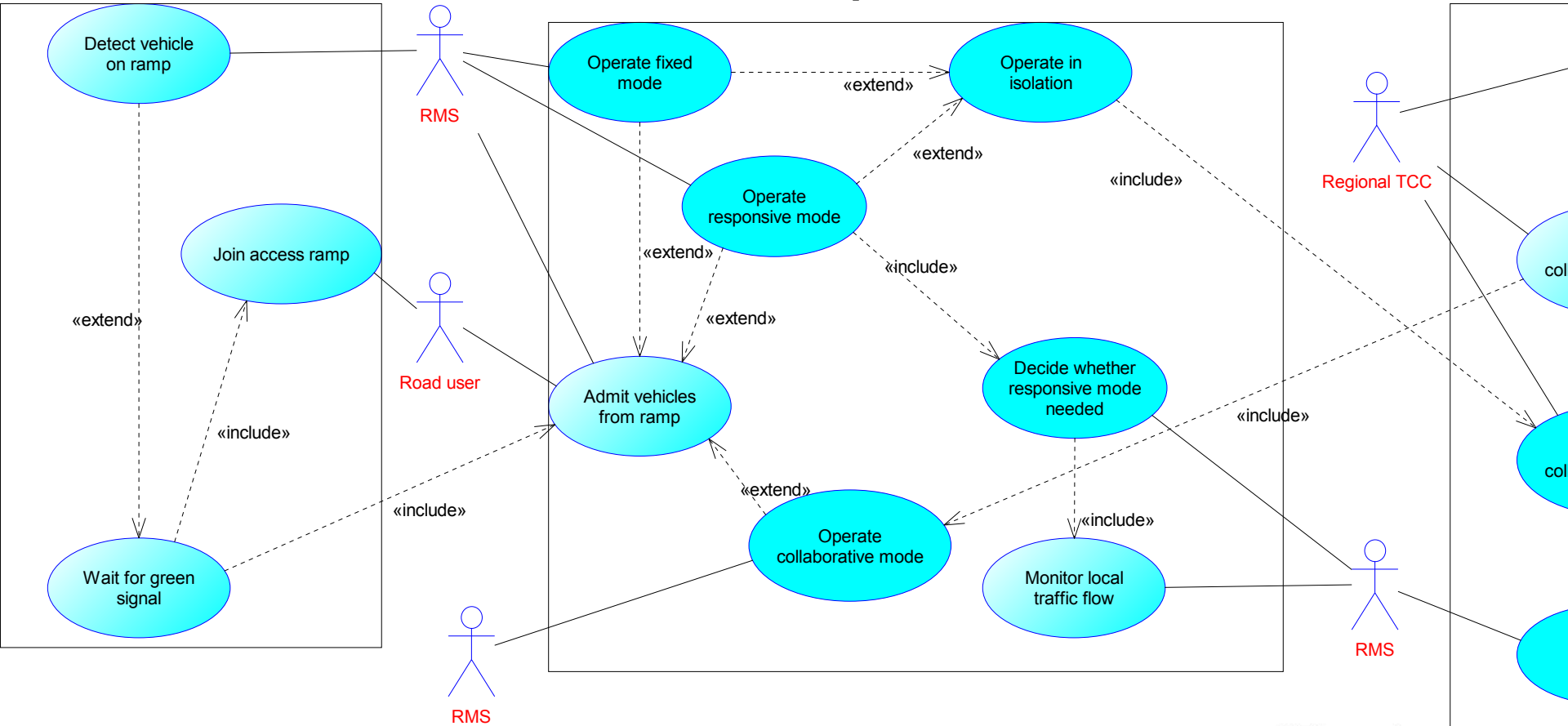
Constituent System Identification



Context Interaction Viewpoint



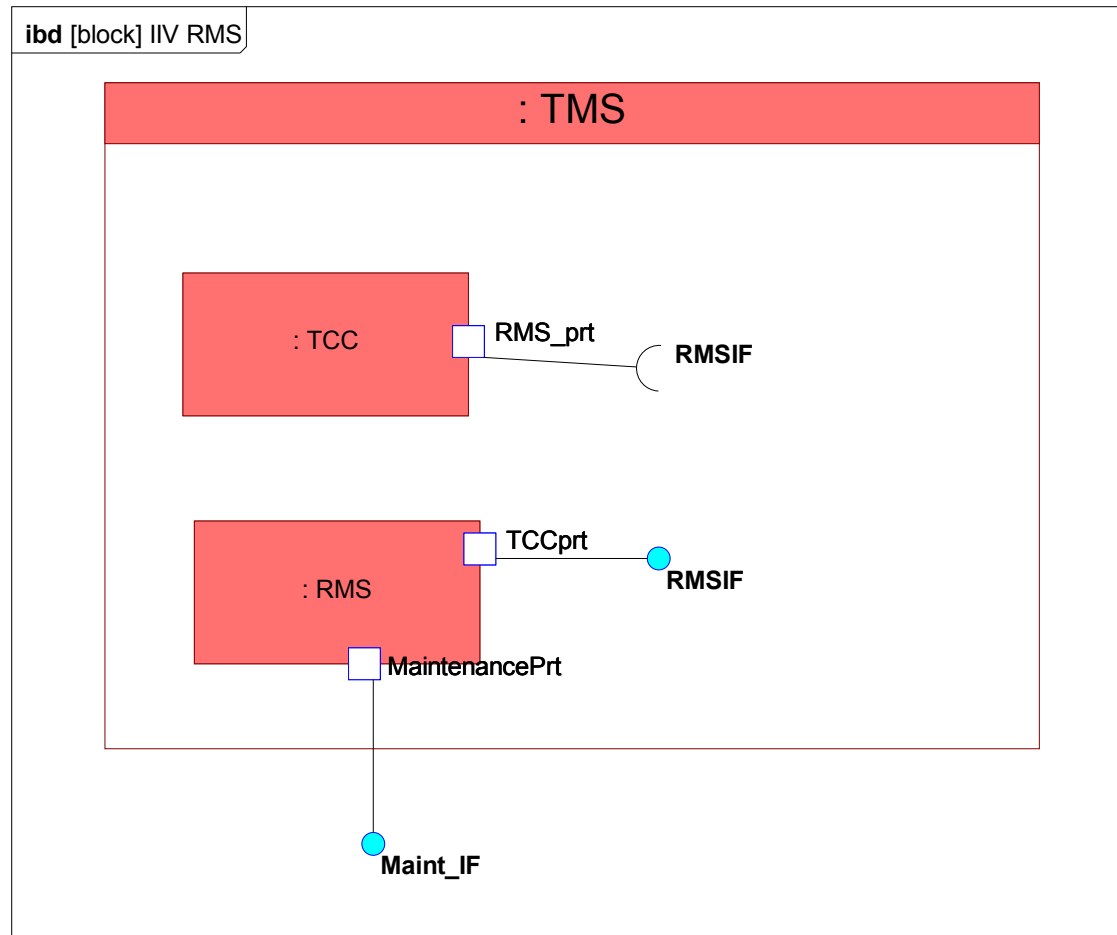
Context Interaction Viewpoint



Constituent System Identification



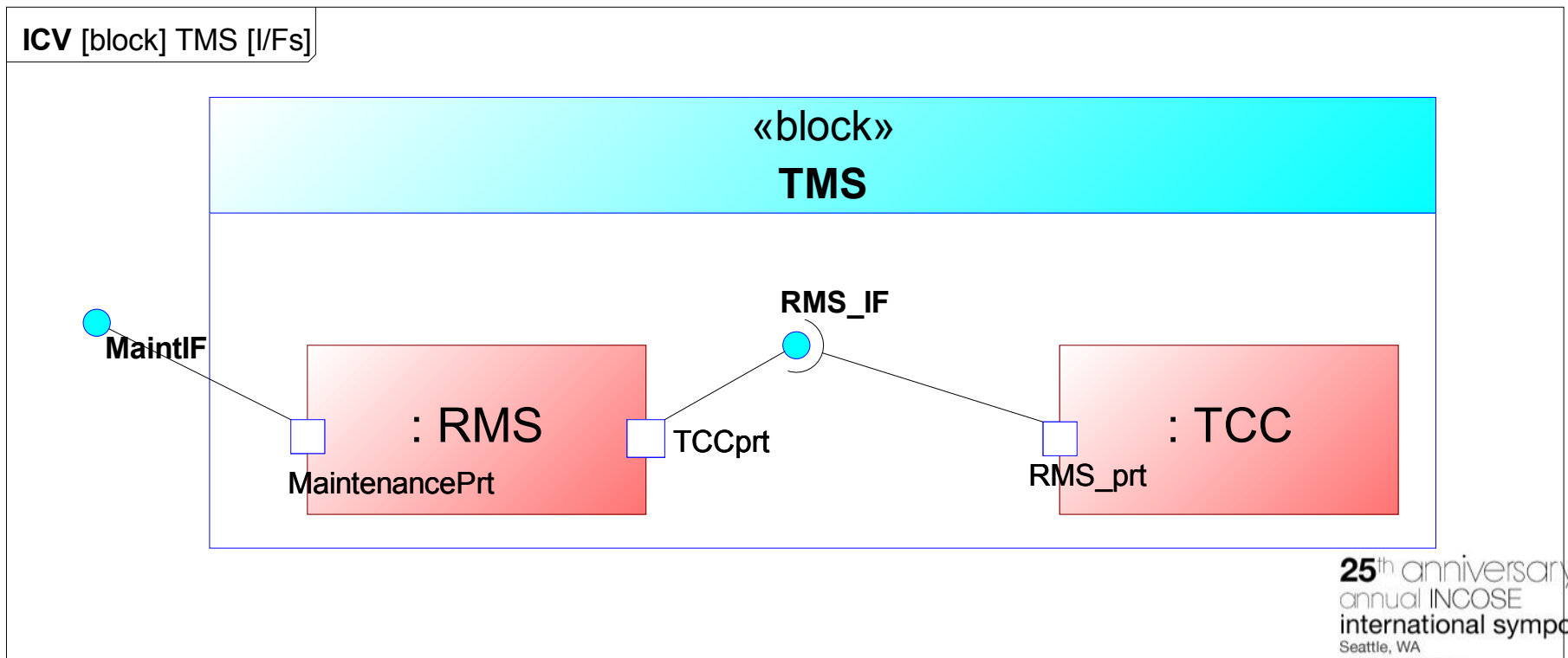
Interface Identification Viewpoint



Integration Process

Interface Connectivity Viewpoint

- defines how the interfaces in the IIV are connected



Integration Process

Interface Definition Viewpoint

- Defines structure of each interface in IIV

IDV [Package] [Interface definition of RMSIF]

```

«interface»
TMS::Connections::RMSIF

goCollaborative (in vehiclesPerMin : Nat) : Boolean
goResponsive () : Boolean
goFixed () : Boolean
reset () : Boolean
shutdown (in delay : secs) : Boolean
    
```

```

{Pre-conditions
goCollaborative::vehiclesPerMin<=100
shutdown:: delay >= 30}
    
```

Integration Process



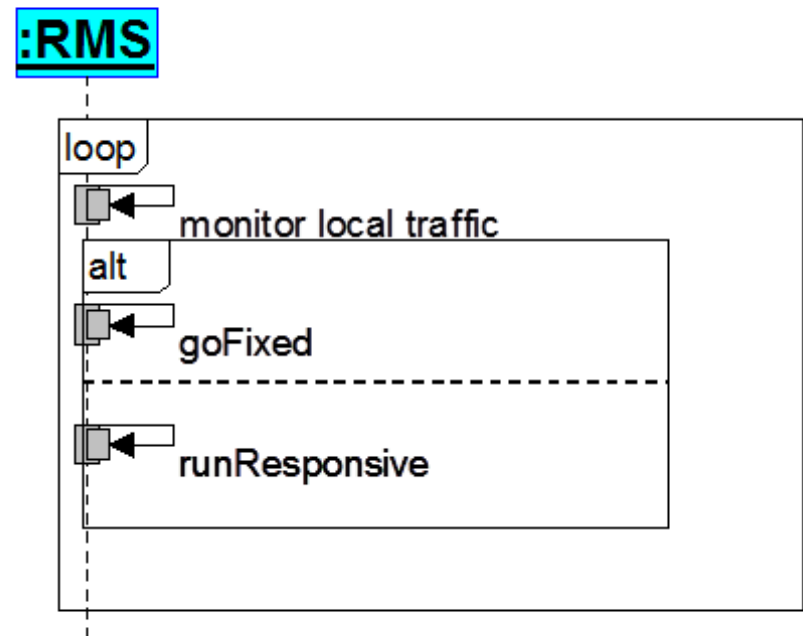
Interface Behaviour Viewpoint

- IBV defines interactions between interfaces we have already identified
- Implemented as a selection of sequence diagrams
- Model both acceptable and unacceptable sequences
- Five scenarios are developed and one IBV developed for each

Integration Process

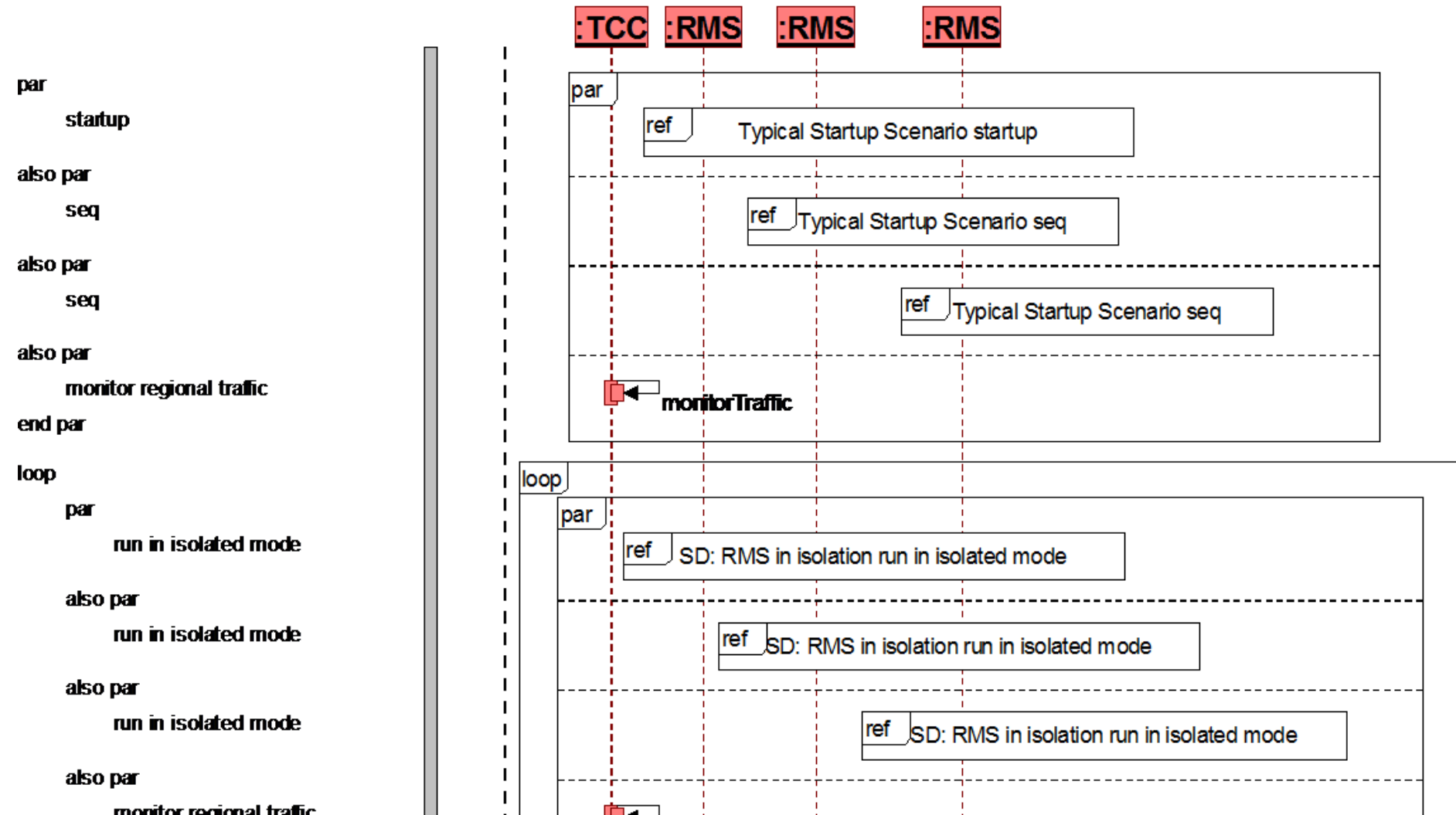
Interface Behaviour Viewpoint: an RMS operates in isolated mode

```
loop
  monitor traffic
  alt
    fixed time mode
  else alt
    responsive mode needed
  end alt
end loop
```



Integration Process

Interface Behaviour Viewpoint: acceptable behaviour



```

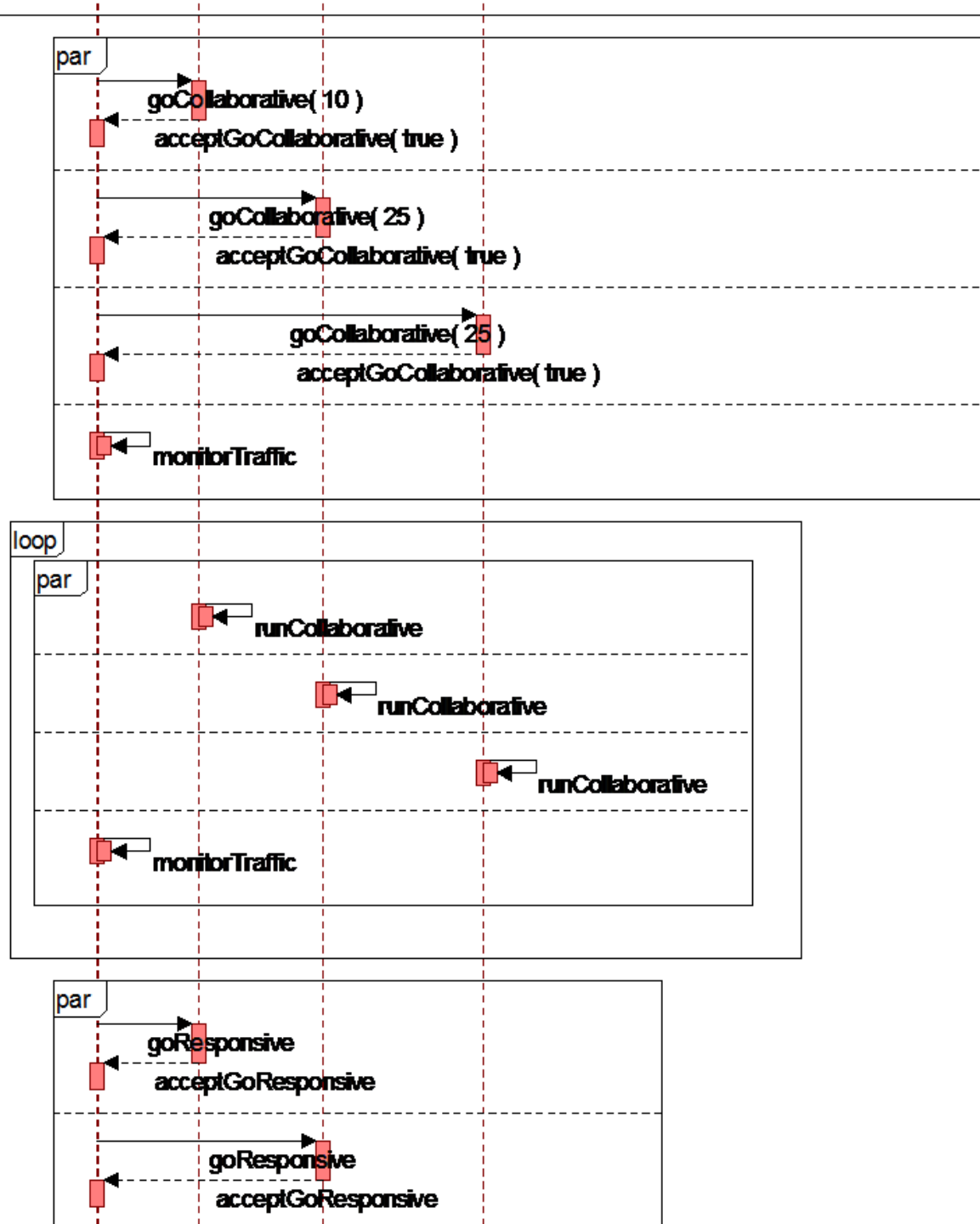
end loop

par
    go to collaborative mode
    accept collaborative mode
also par
    go to collaborative mode
    accept collaborative mode
also par
    go to collaborative mode
    accept collaborative mode
also par
    monitor regional traffic
end par

loop
    par
        run collaborative
    also par
        run collaborative mode
    also par
        run collaborative mode
    also par
        monitor regional traffic
    end par
end loop

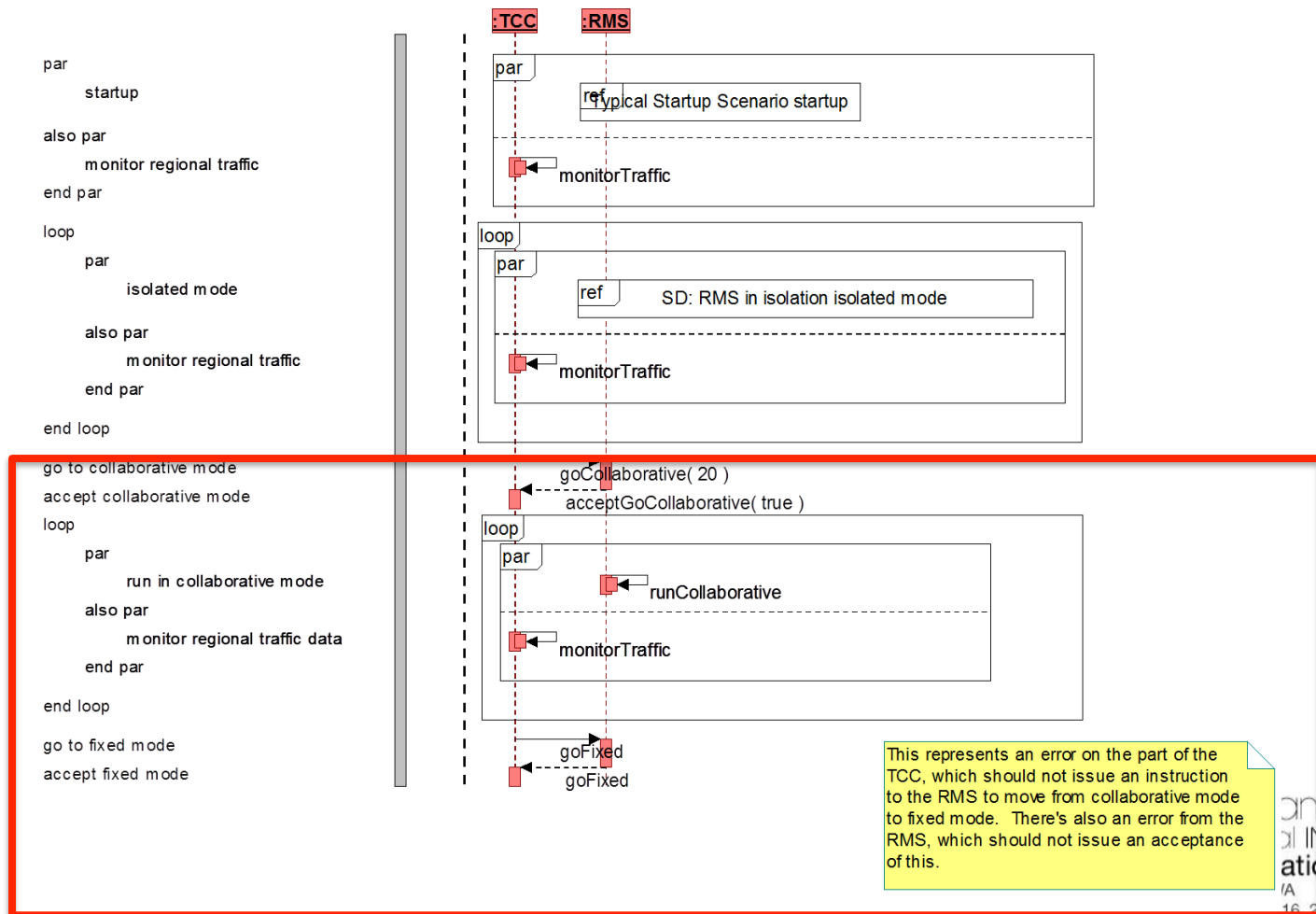
par
    go to responsive mode
    accept responsive mode
also par
    go to responsive mode
    accept responsive mode
also par

```



Integration Process

Interface Behaviour Viewpoint: unacceptable behaviour



Integration Process

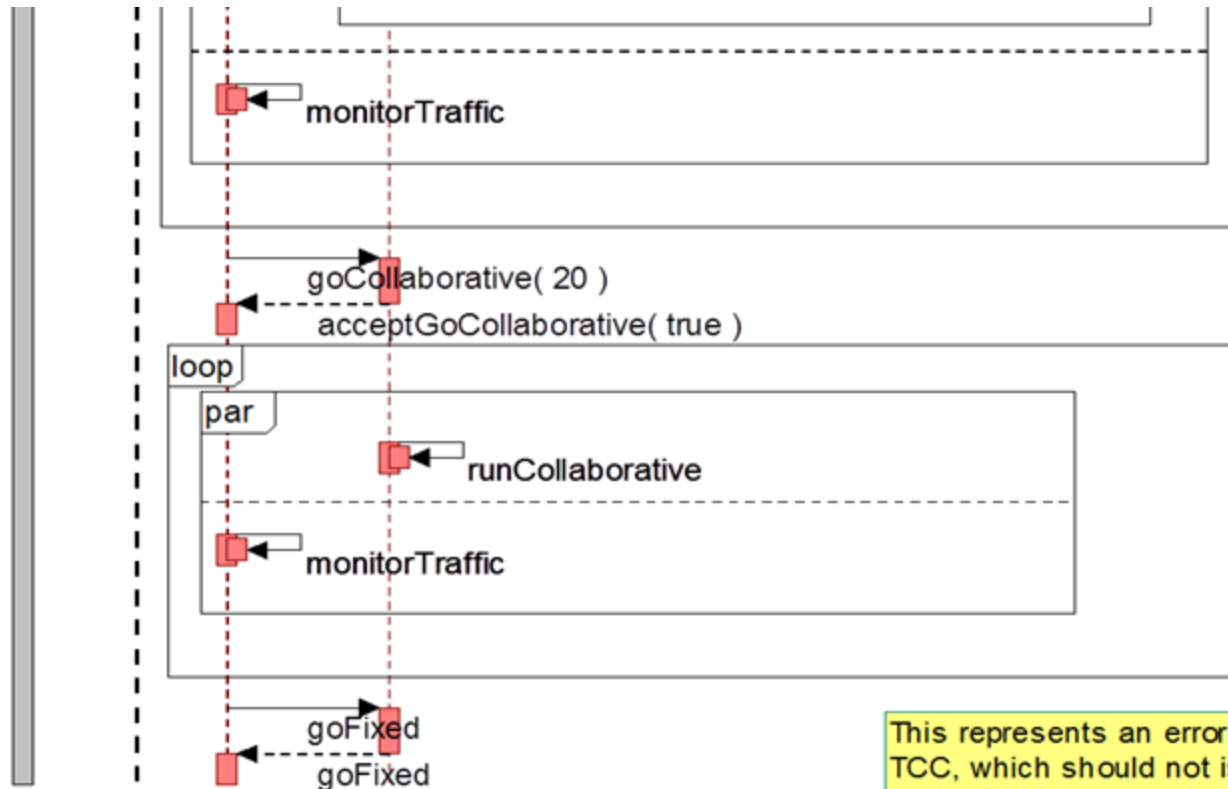
```

also par
    monitor regional traffic
end par

end loop

go to collaborative mode
accept collaborative mode
loop
    par
        run in collaborative mode
    also par
        monitor regional traffic data
    end par
end loop

go to fixed mode
accept fixed mode
    
```



This represents an error of TCC, which should not be sent to the RMS to move from collaborative to fixed mode. There's already a message from the RMS, which should not be part of this.

Integration Process

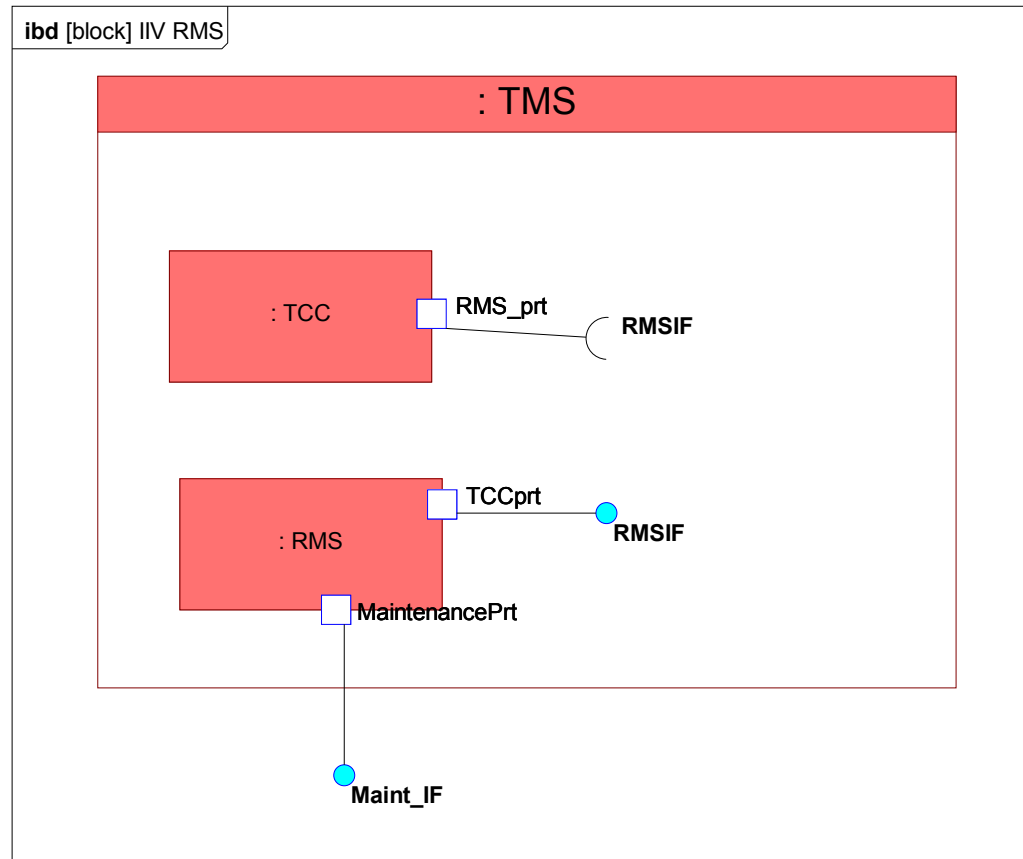


Interface Connectivity Viewpoint

- Defines how the interfaces in the IIV are connected

Integration Process

Interface Identification Viewpoint



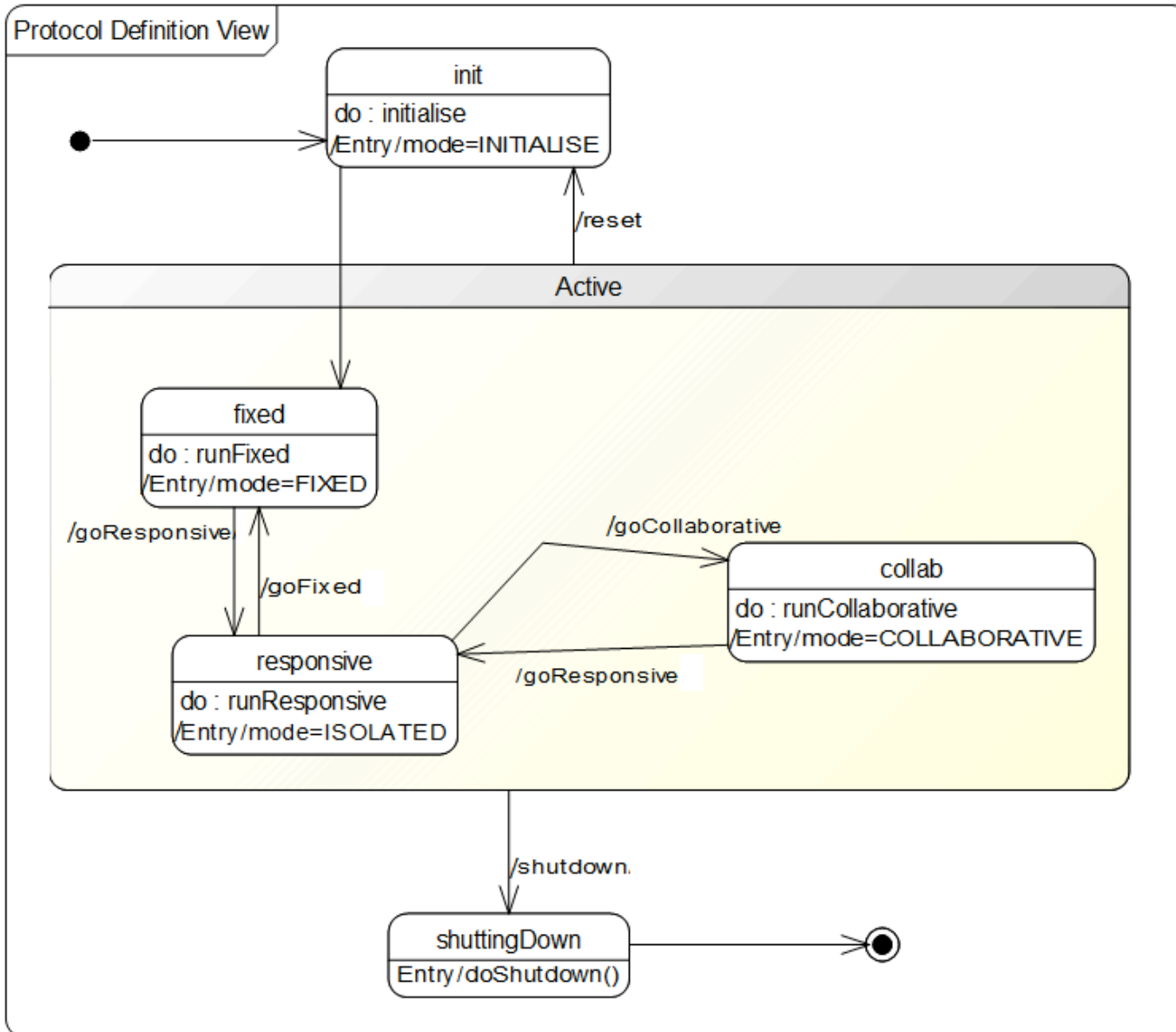
Integration Process



Protocols Definition Viewpoint

- Defines protocols for each interface identified during previous modelling efforts

Protocol Definition



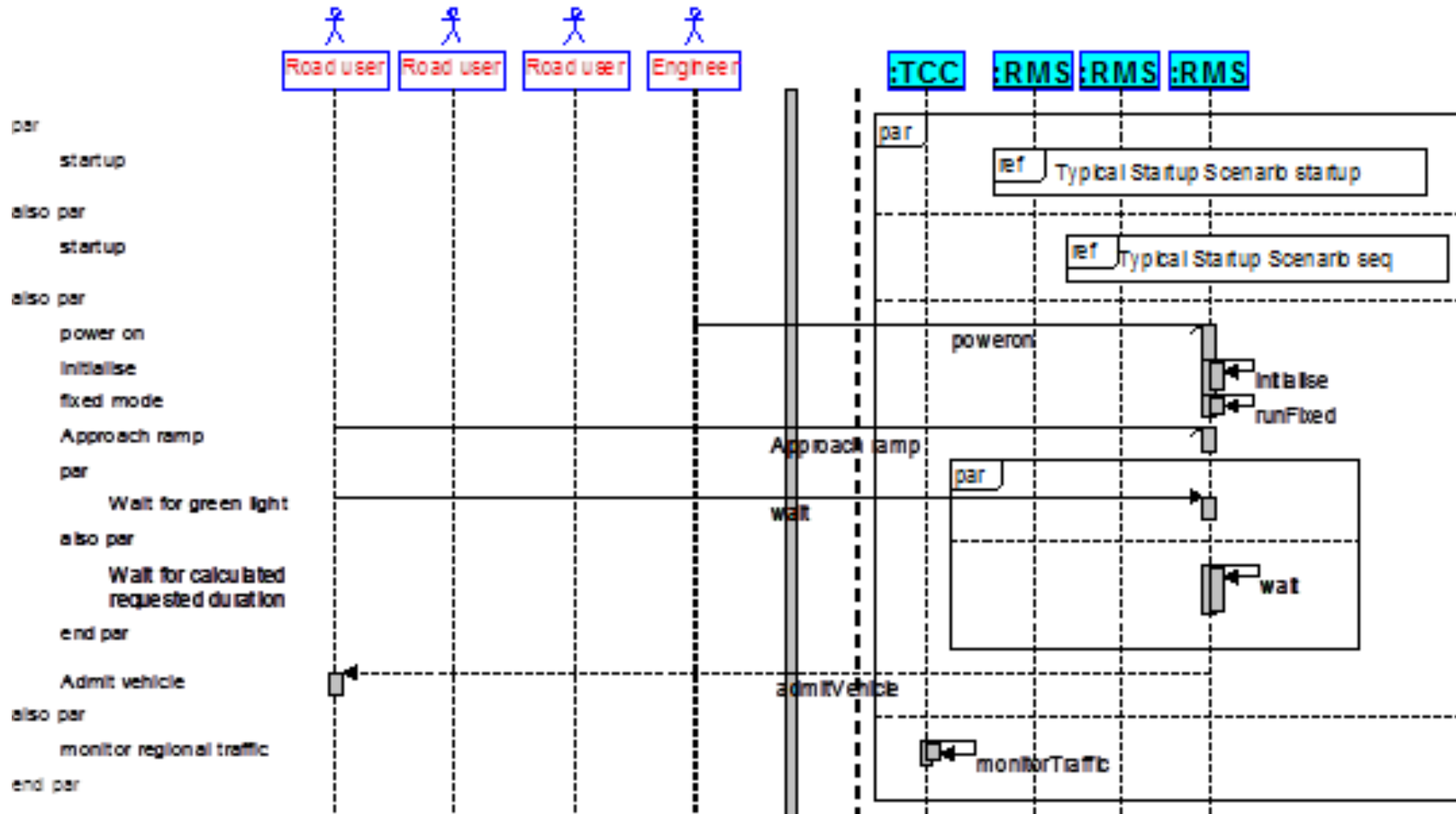
Validation



- Integration Framework also includes validation phase
- We validate our SoS-level use cases using Interface Behaviour Viewpoints (already presented)
- CIF recommends further validation, in the form of a Validation Interaction Viewpoint
 - integrates the previous sequence diagrams all onto one view
 - Identify inconsistencies or duplication

Validation

Validation Interaction Viewpoint

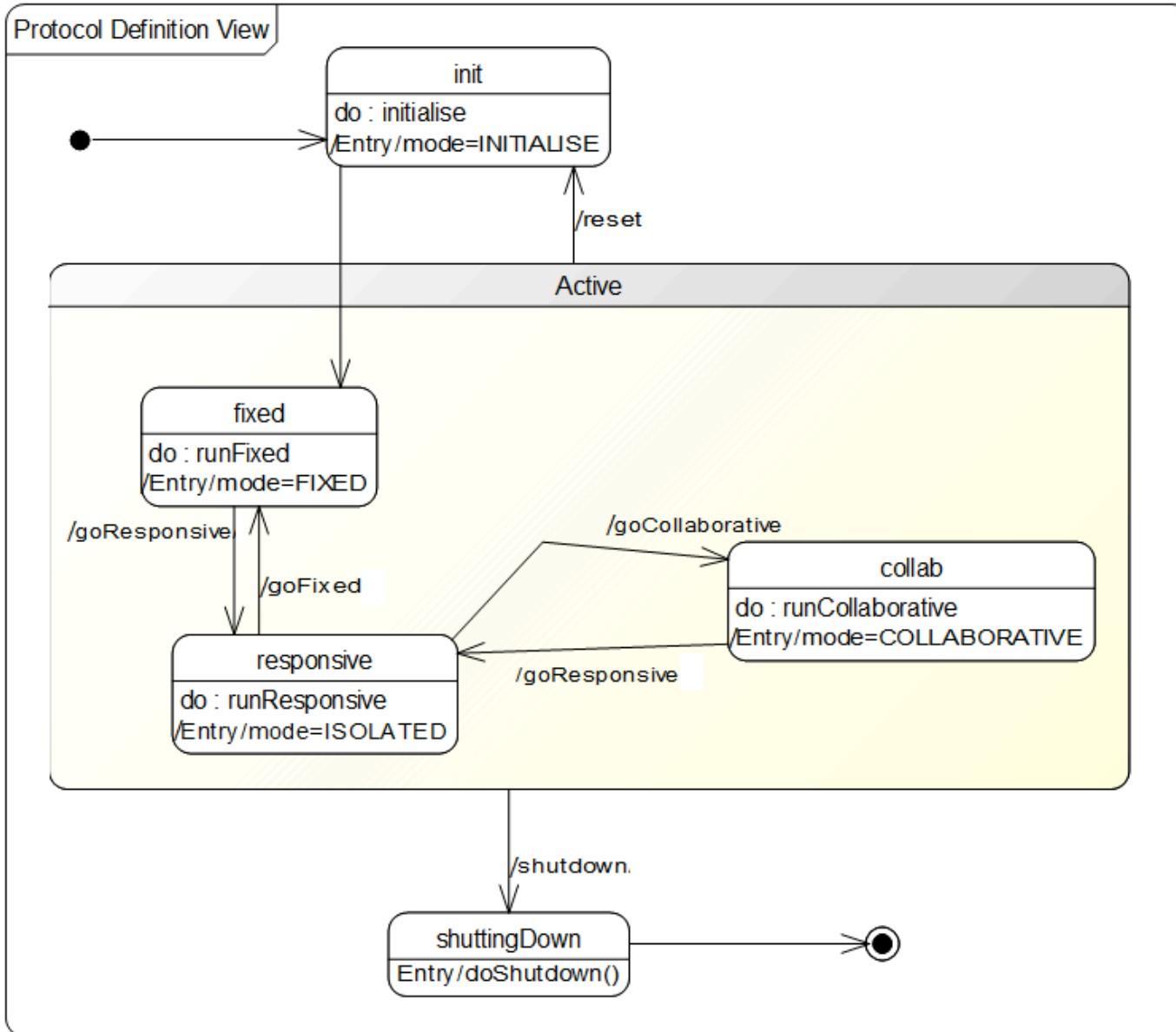


COMPASS Integration Framework

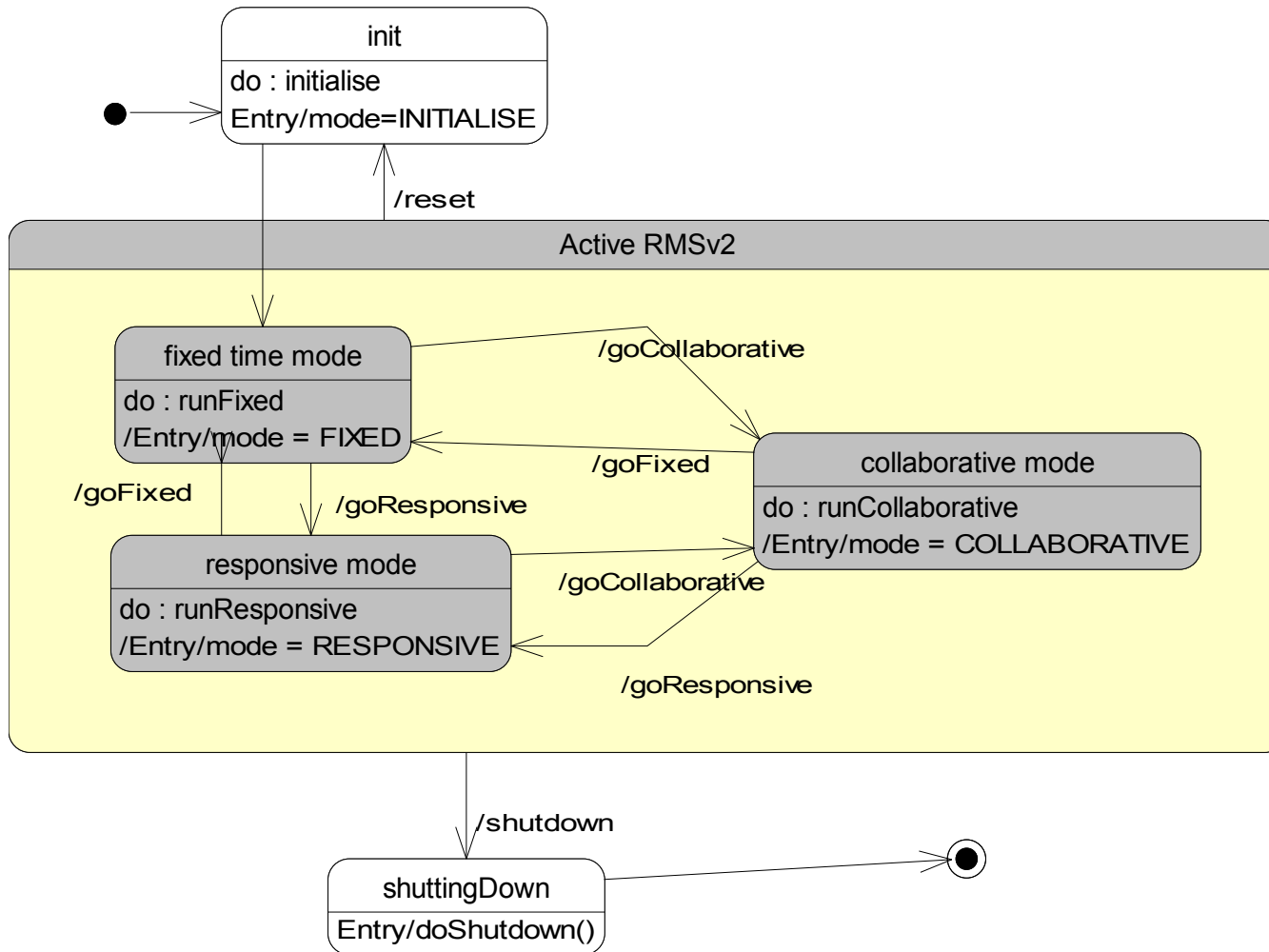


- The result is a set of models describing our existing RMS, which we call **RMSv1**
- Next: we repeat the same complete process, to generate a set of similar models for a new version of the RMS, which we call **RMSv2**
- Only one model differs for RMSv2 - Protocols Definition Viewpoint

RMSv1



Protocol Definition View



RMSv2

COMPASS Integration Framework



CIF process:

1. Architectural models, as prescribed
2. Translate to a formal modelling notation
3. Analysis and validation with automated or semi-automated support

Outline

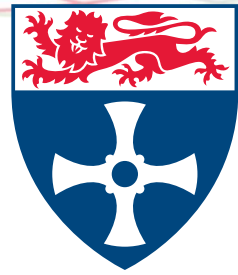


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Conclusions



- CIF offers a structured, guided process for modelling various integration scenarios
- SoSs have long life-spans; CIF can help to plan regression testing
- Our approach here is a good introductory step for formal modelling of the SoS
- More work to be done – including further work to integrate with automated testing and formal modelling techniques where possible



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This work is part of the COMPASS project: research into model-based techniques for developing, maintaining and analysing SoSs

C O M P A S S

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25th anniversary
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