

ESEM: Automated Systems Analysis using Executable SysML Modeling Patterns

July 18, 2016, Nerijus Jankevičius
No Magic Europe

Outline

- Current State of Practice and Need for MBSE
- TMT Application
- Executable System Engineering Method (ESEM)
- Demo video
- Summary



- Nerijus Jankevičius, nerijus@nomagic.com
- Product Manager @ No Magic Europe
- Leads the development of MBSE tools and solutions since 1997
- OMG member, co-author of UML and SysML languages



Robert Karban is a senior systems architect at the Jet Propulsion lab in the Systems Engineering and Formulation Division. Robert works in the domain of Model Based Systems Engineering (MBSE) as the task lead on providing a Model Based Engineering Environment (MBEE) for projects and applies modeling in the Thirty Meter Telescope project.

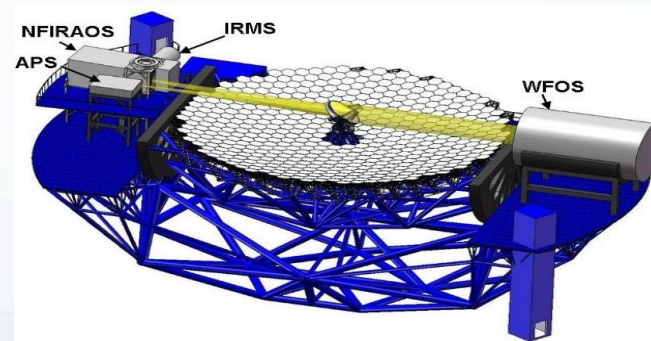


Maged Elaasar is a senior software architect at the Jet Propulsion Laboratory in the Systems Engineering and Formulation Division.

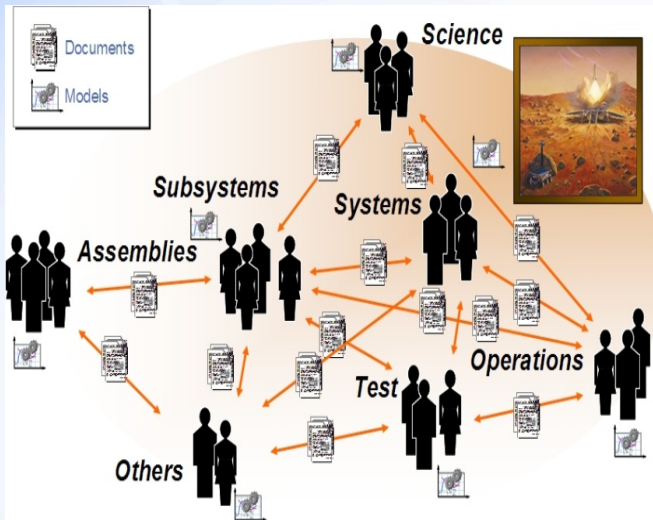
Thirty Meter Telescope (TMT)

www.tmt.org

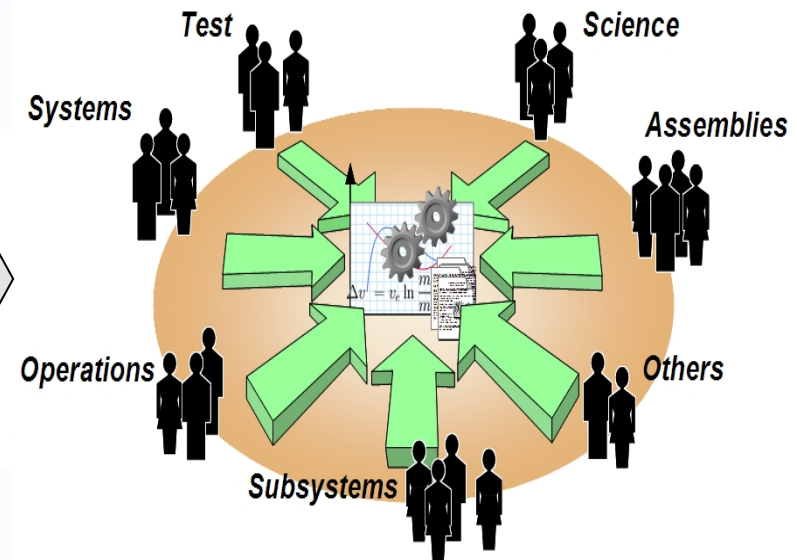
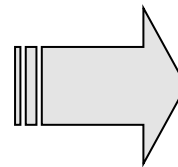
- Developed by TMT International Observatory (TIO)
 - ◊ JPL participates in several subsystems of TMT
 - ◊ APS (and AO) team uses MBSE to analyze requirements, produce design, and perform analysis
- Alignment and Phasing System (APS)
 - ◊ Sensor responsible for measuring the pre-adaptive optics wavefront quality



Current Practice to Future Practice



Today: Standalone models related through documents



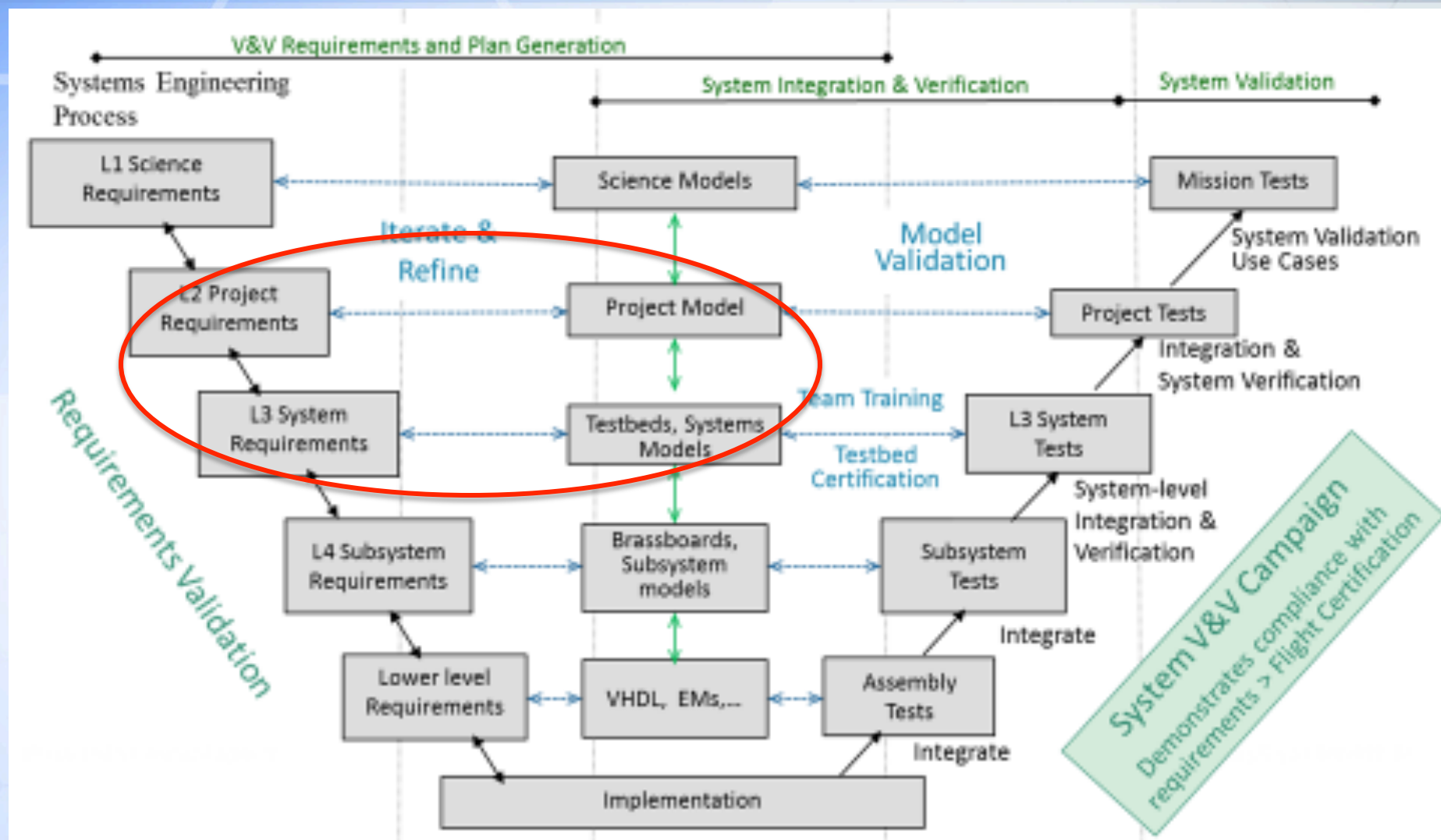
Future: Shared system model with multiple views, and connected to discipline models

Source : MBSE 101 by Elyse Fosse

Model Based Systems Engineering

- MBSE is the formalized application of modeling techniques to support system requirements, design, analysis, verification, validation and documentation activities
- MBSE expresses a system using a Systems Modeling Language (SysML), a profile of UML
- MBSE is often applied with a method like Object Oriented System Engineering Method (OOSEM)
- OOSEM maps onto the ISO systems engineering process and integrates top-down (**functional decomposition**) approach with **model-based** approach

Model-based V-Process at JPL



- Provides a platform for modeling that integrates JPL's mission environment OpenCAE, by incorporating a model repository that can be accessed for example with a rich SysML desktop client (MagicDraw) and a light-weight web-based client (ViewEditor)
- The model repository provides the following features:
 - ◊ Basic Infrastructure for Version, Workflow, Access Control
 - ◊ Flexibility of content
 - ◊ Support for Web Applications and Web-based API access
 - ◊ Multi-tool and multi-repository integration across engineering and management disciplines

Systems Analysis

- Carry out quantitative assessments of systems in order to select and/or update the most efficient system architecture and to generate derived engineering data.
- System analysis provides a rigorous approach to technical decision-making. It is used to perform trade-off studies, and includes modeling and simulation, cost analysis, technical risks analysis, and effectiveness analysis.

Requirements Verification

- A kind of systems analysis that assesses whether a system design meets the objectives and satisfies the constraints that are implied by the system requirements

Proposed Approach

- Next phase of system modeling emphasizes executable models to enhance understanding , precision, and verification of requirements
- Executable Systems Engineering Method (**ESEM**) augments the OOSEM activities by enabling executable models
 - ◊ ESEM produces executable SysML models that verify requirements
 - ◊ Includes a set of analysis patterns that are specified with various SysML structural, behavioral and parametric diagrams
 - ◊ Also enables integration of supplier/customer models

TMT MBSE Objectives

- Use MBSE to define **executable SysML model** that captures requirements, operational scenarios (use cases), system decomposition, relationships and between subsystems, etc.
- Use the model to **analyze the system design** for
 - ◊ power consumption, mass, and duration
- Produce **engineering documents**
 - ◊ Requirement Flow Down Document
 - ◊ Operational Scenario Document
 - ◊ Design Description Document
 - ◊ Interface Control Documents
- Uses **standard languages and techniques where practical** to avoid custom software development

Typical Analysis Activities Using ESEM

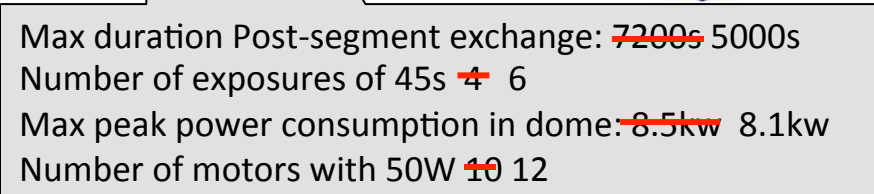
- Capture **operational use cases** with estimated durations of actions, e.g.
 - ◊ Post segment-exchange alignment: requirement: 2h; CBE 1h19m
- Capture **power and mass characteristics** of components
- Identify **involved subsystems**, e.g. Telescope Control System (TCS), M1 Control System (M1CS)
- Identify **interfaces and interactions** among subsystems
- **Analyze** associated scenarios
- Automatically **verify system requirements** are met
- Derive requirements for TMT subsystems
- Develop/refine timing requirements for algorithms, internal and external interface commands

MagicDraw

Cameo Simulation Toolkit

- Model execution framework and infrastructure:
 - ◊ Model debugging and animation environment
 - ◊ Pluggable engines, languages and evaluators
 - ◊ User Interface prototyping support
 - ◊ Model driven configs and test cases
- The standard based model execution of:
 - ◊ Activities (OMG fUML standard)
 - ◊ Composite structures (OMG PSCS)
 - ◊ Statemachines (W3C SCXML standard)
 - ◊ Actions/scripts (JSR223 standard)
 - ◊ Parametrics (OMG SysML standard)
 - ◊ Sequence diagrams (OMG UML Testing Profile)





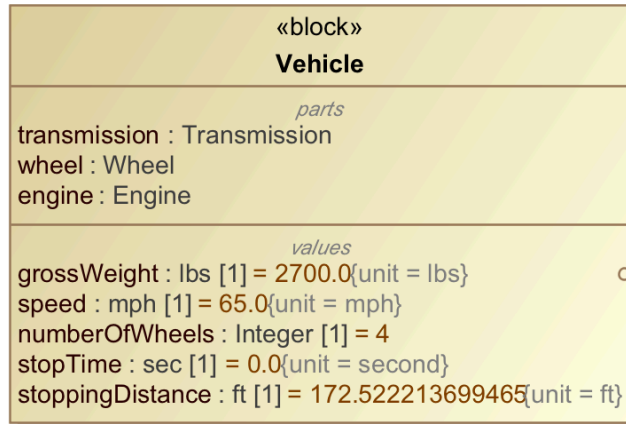
Executable System Engineering Method (ESEM)

- Step 1: Formalize Requirements
- Step 2: Specify Design
- Step 3: Characterize Components
- Step 4: Specify Analysis Context
- Step 5: Specify Operational Scenarios
- Step 6: Specify Analysis Configurations
- Step 7: Run Analysis

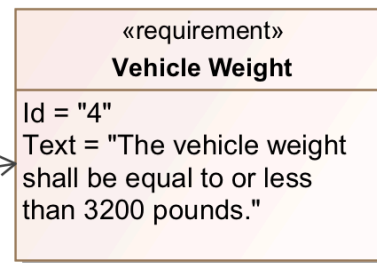
Step 1: Formalize Requirements

- Requirement Pattern
 - ◊ Customer Side
 - Define the textual requirement with a Requirement
 - Optionally define a design black box specification with a Block with relevant value properties
 - Optionally refine the Requirement with a Constraint Block on the black box design Block
 - ◊ Supplier Side
 - Define a design black box specification with a Block (that refines the customer's black box Block if any and provides tighter property values)
 - Refine the textual Requirement by a Constraint Block (if not already defined by the customer)

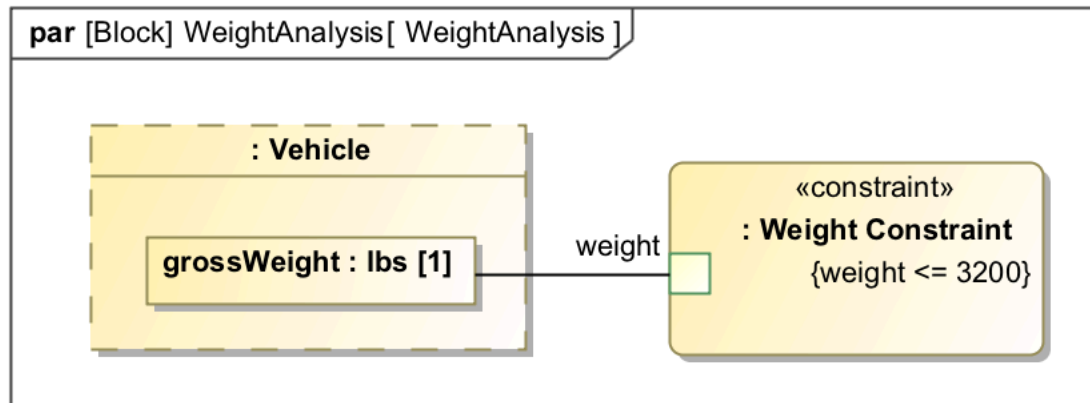
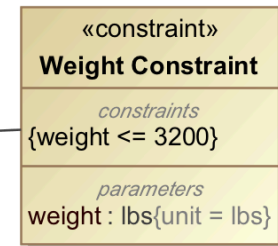
Satisfy, refine, bind



«satisfy»



«refine»

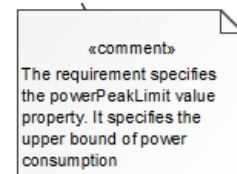
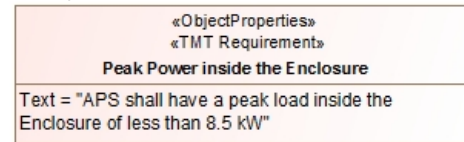
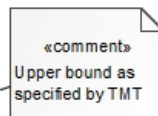
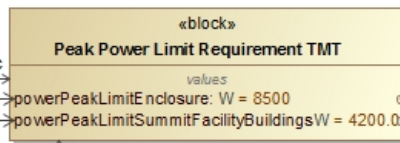
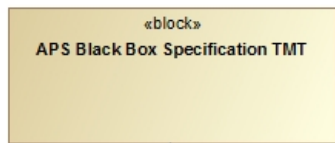


Step 1: Formalize Requirements

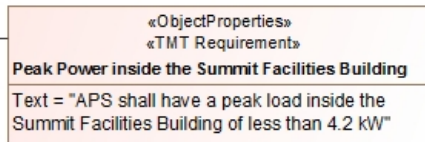
req [Package] 01 Requirements [Requirements Specification]

TMT

«Specifies»

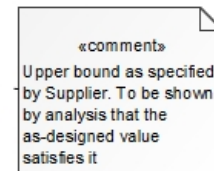
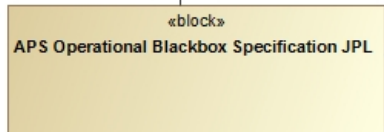


«Specifies»

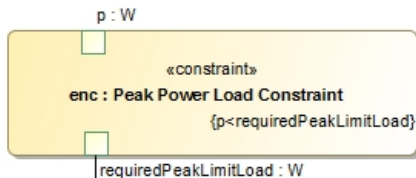


«refine»

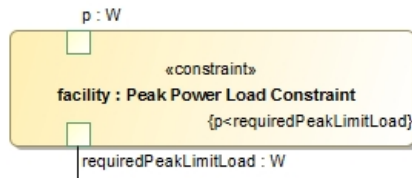
JPL



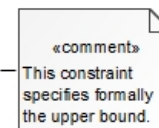
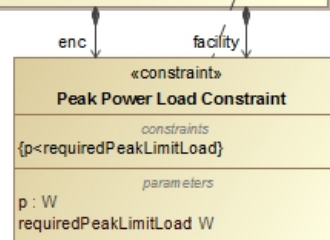
par [Block] Peak Power Limit Requirement JPL Peak Power Limit Requirement JPL



powerPeakLimitEnclosure : W = 8100



powerPeakLimitSummitFacilityBuildings : W = 4100.0

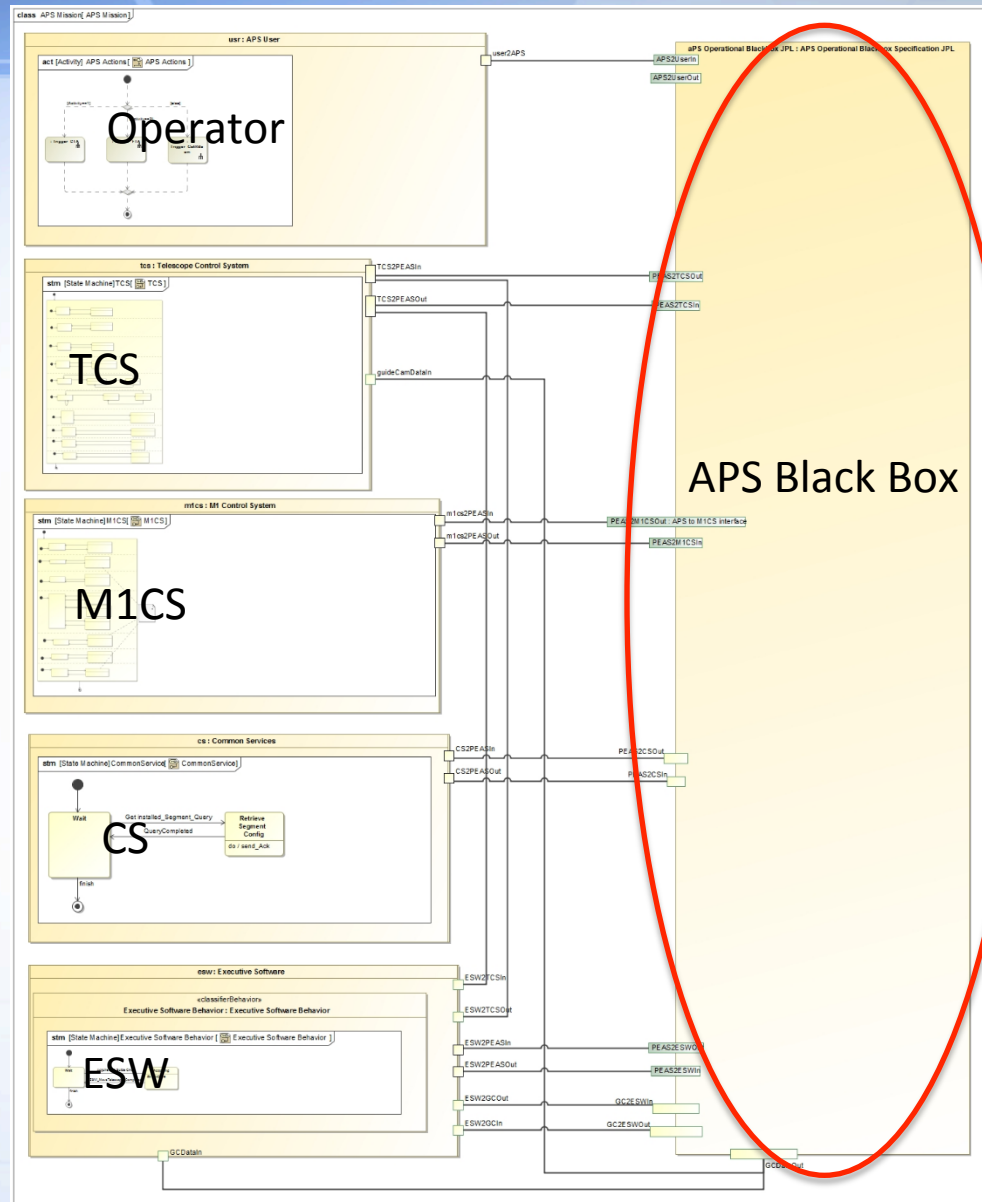


Step 2: Specify Design

- Follow OOSEM to define two white box specifications that specialize the black box specification
 - ◊ Conceptual Specification
 - ◊ Realization Specification
- Decompose the white box designs into Blocks representing the subsystems

Black Box Level

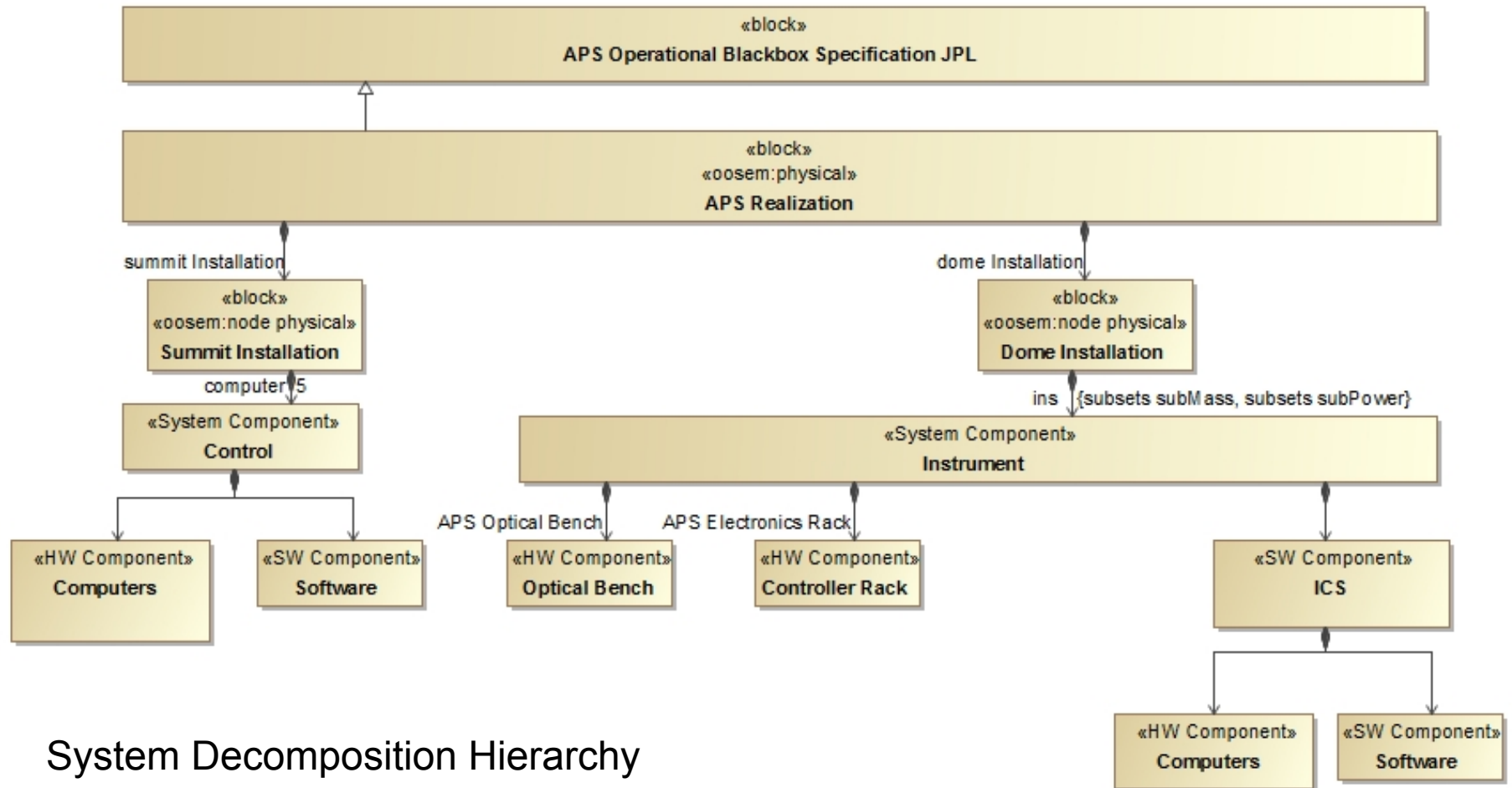
Project level components communicate with APS black box block



Step 2: Realization

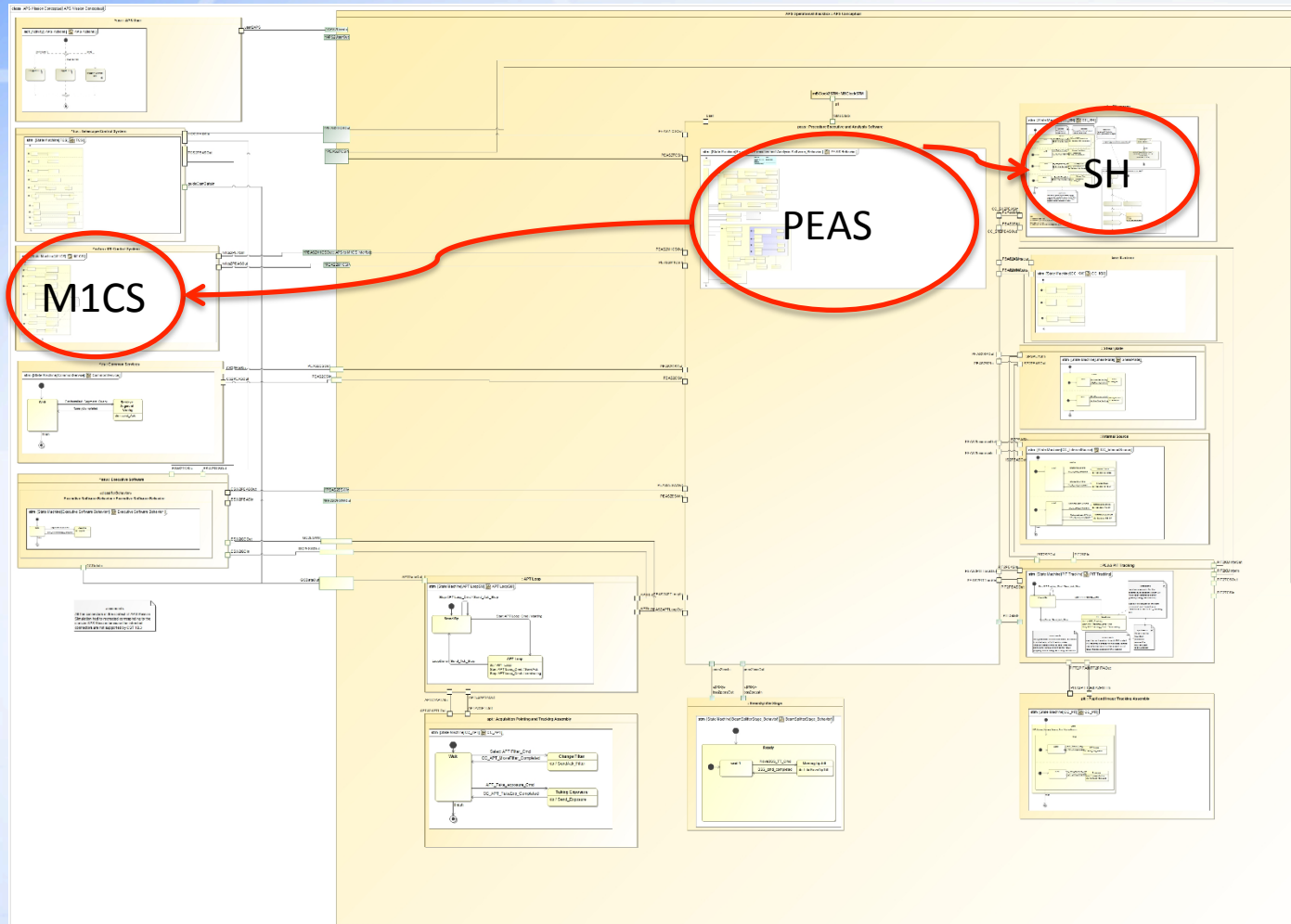
«Diagram Description»

bdd [Package] Realization Design[APS Realization Structure]



System Decomposition Hierarchy

Step 2: Conceptual Model




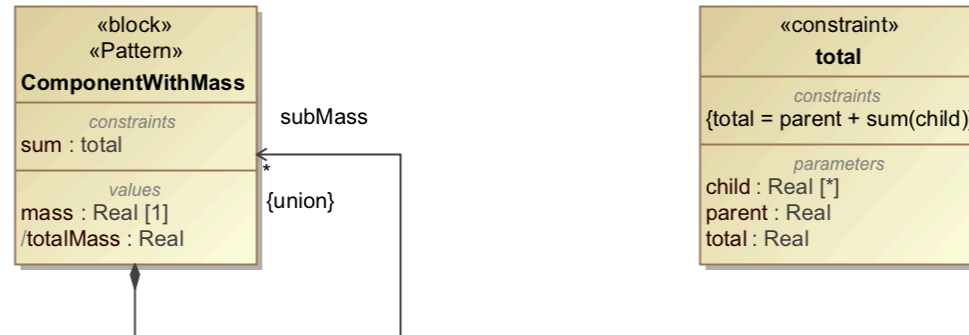
Communication between state machine specified components over ports


Step 3: Characterize Components

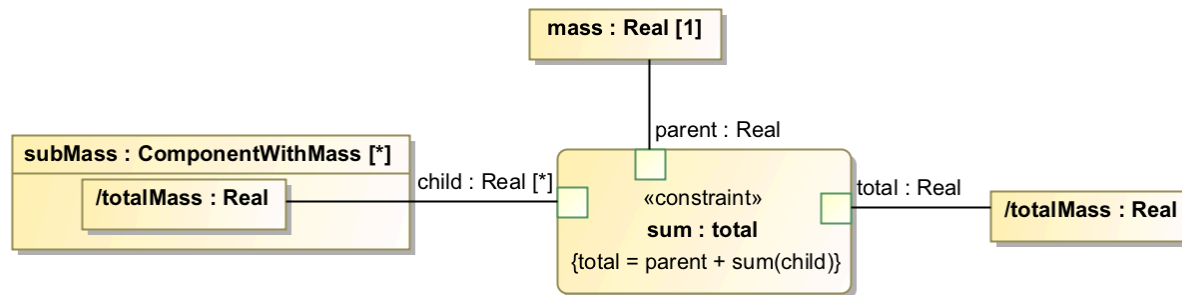
- Add relevant patterns to the design Block to make it executable
- Example: Roll-up Pattern
 - ◊ Constrained value represents an aggregate value that is propagating up a hierarchy of subcomponents
 - ◊ Static roll-up (e.g., mass roll-up)
 - ◊ Dynamic roll-up (e.g., power roll-up)

Parametric Rollup Pattern

bdd [Package] rollup patterns[ Rollup pattern]

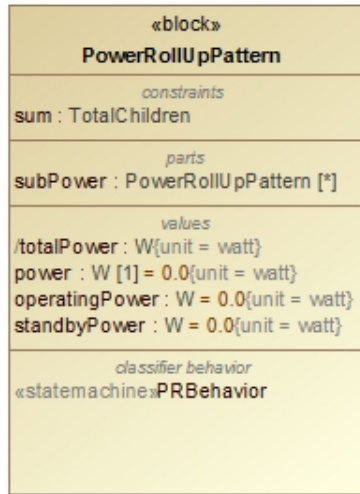


par [Block] ComponentWithMass[ ComponentWithMass]

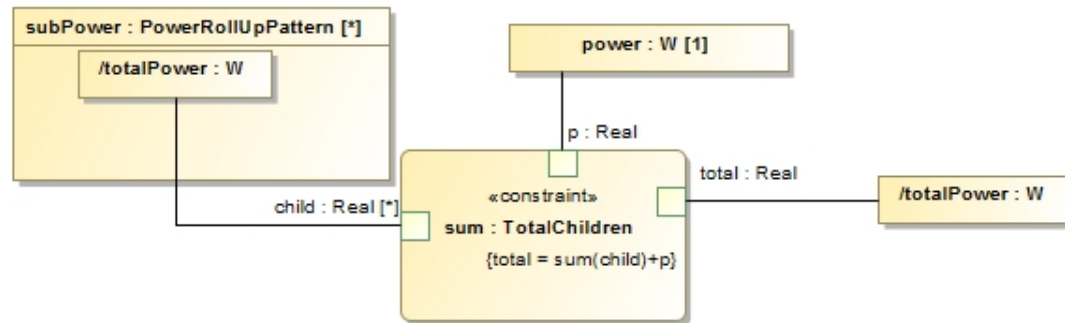


Step 3: Characterize Components

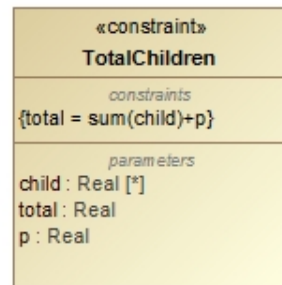
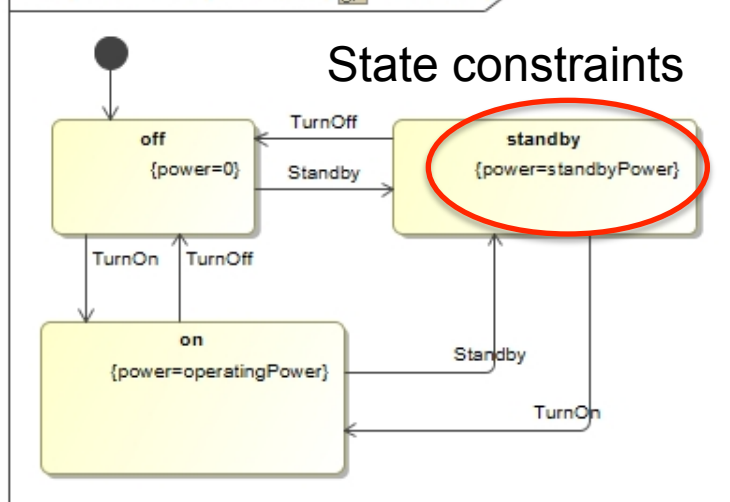
bdd [Package] Roll-up Pattern [Power Roll-up Pattern]



par [Block] PowerRollUpPattern [PowerRollUpPattern]



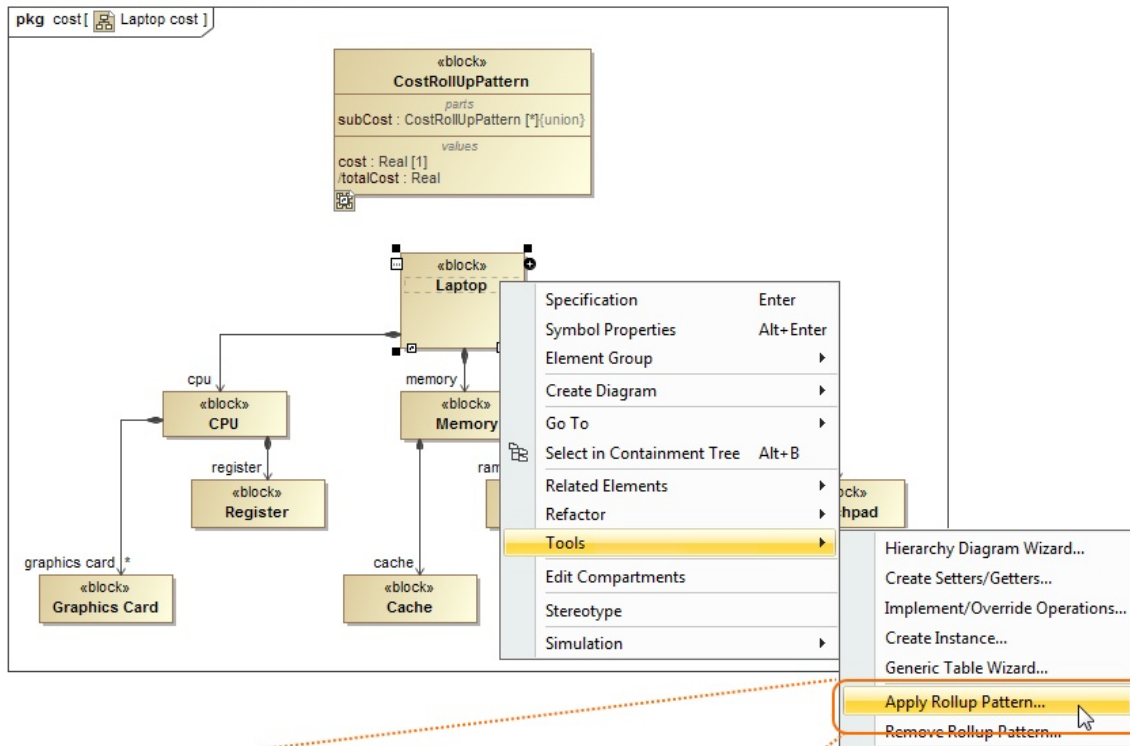
stm [State Machine] PRBehavior [PRBehavior]



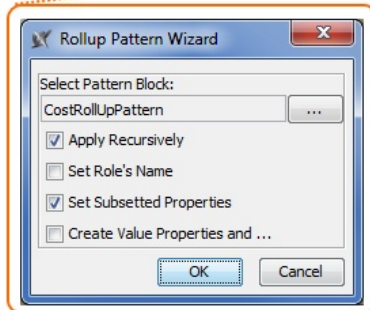
Power Rollup Pattern

Automation

1. Before applying Rollup Pattern

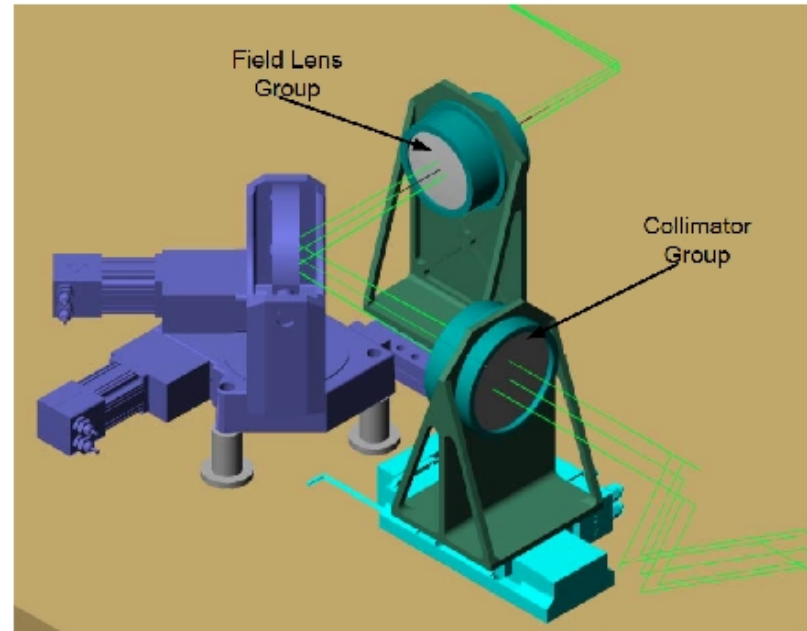
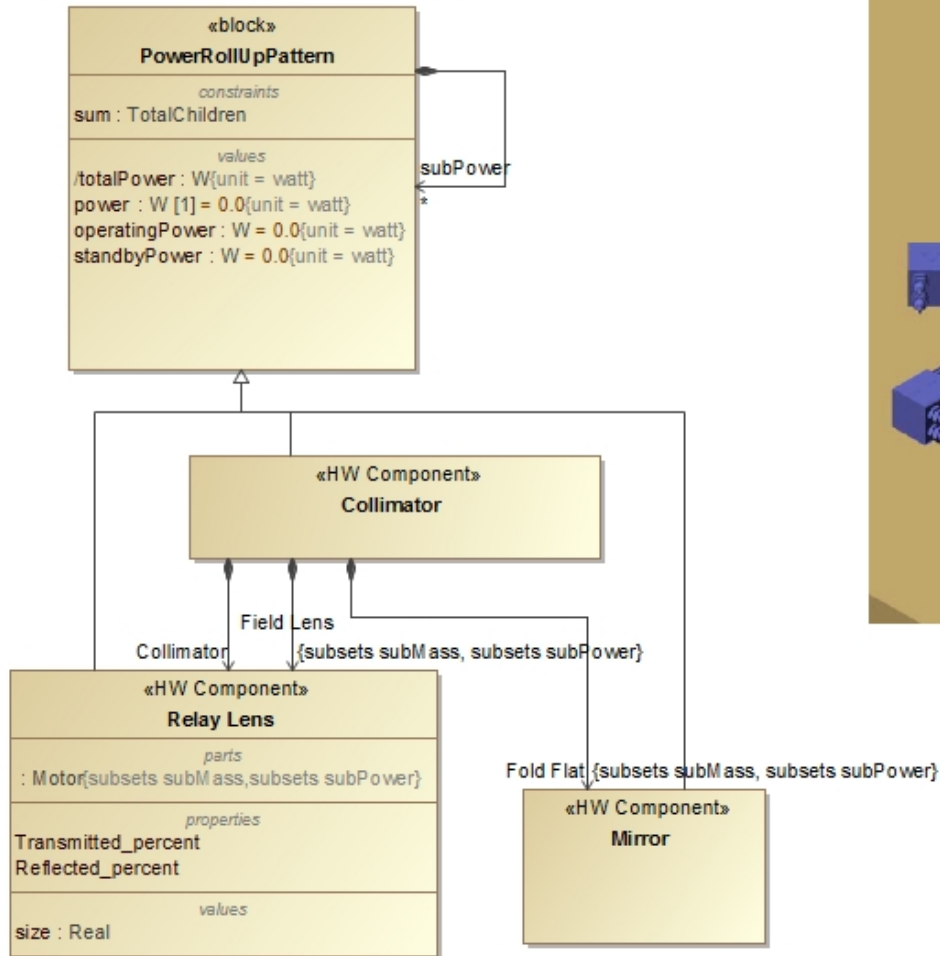


2. Applying Rollup Pattern using Rollup Pattern Wizard



Step 3: Characterize Components

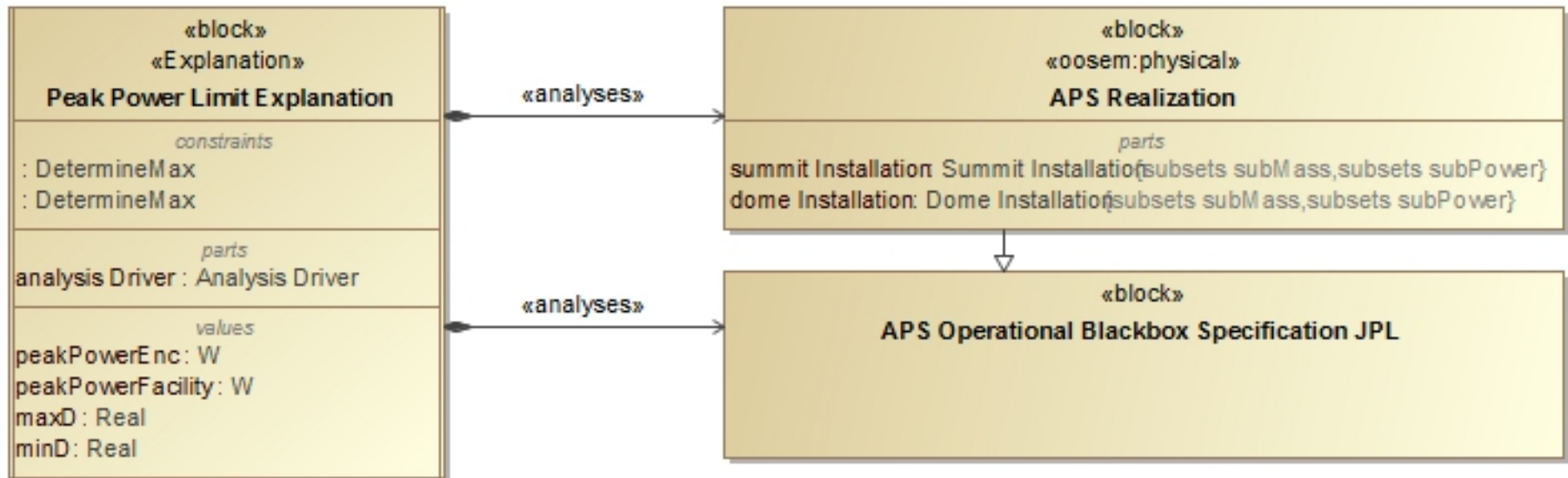
bdd [HW Component]Collimator[Collimator Assembly Roll-up]



Step 4: Specify Analysis Context

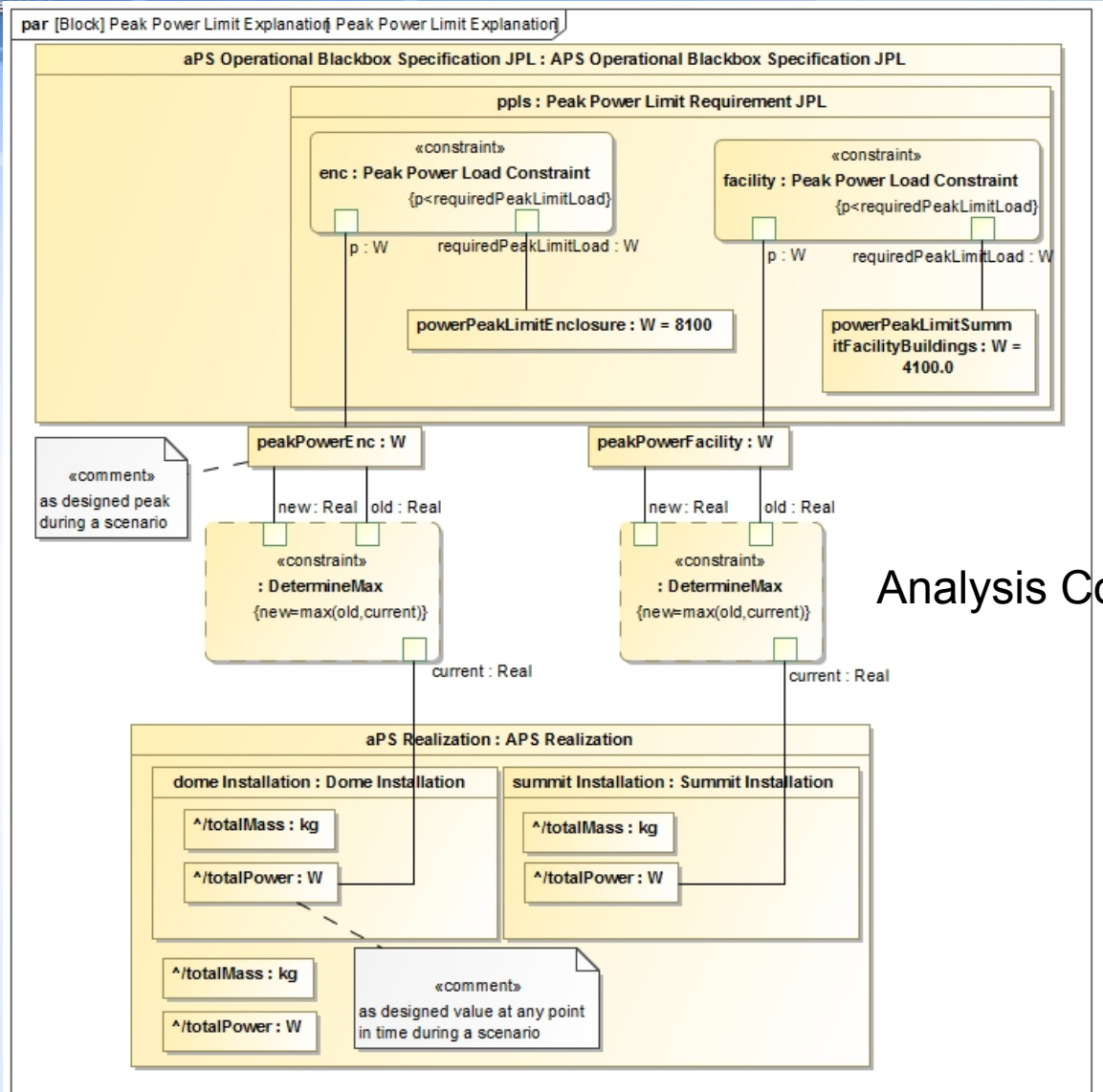
- Analysis Context Pattern
 - ◊ Abstract analysis context Block composes both the design black box Block and white box Block
 - ◊ Analysis properties defined on the analysis context Block (e.g., peak power, power margin)
 - ◊ Analysis parametric model on the analysis context that computes and binds analysis values

Step 4: Specify Analysis Context



Analysis Context Pattern

Step 4: Specify Analysis Context



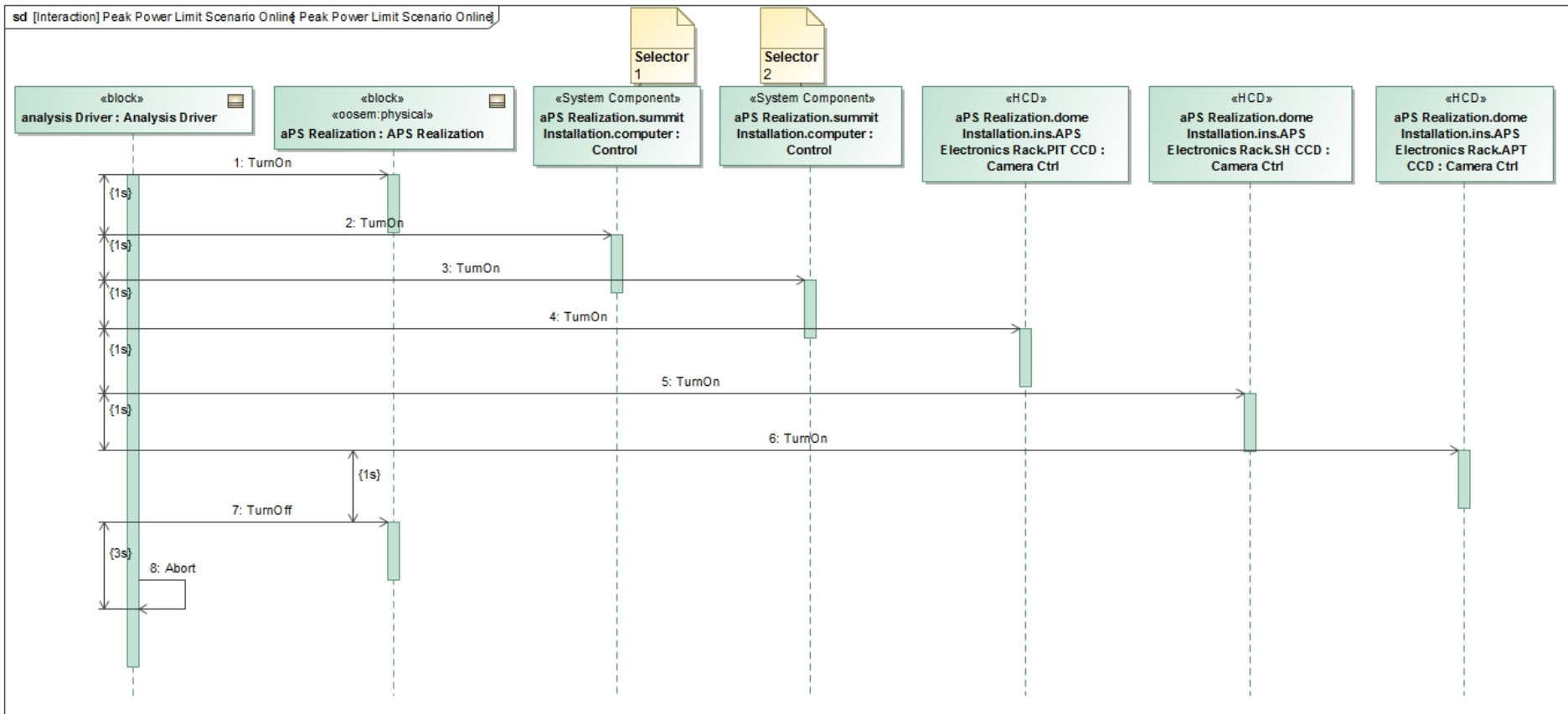
Analysis Context Parametric Model

Step 5: Specify Operational Scenarios

- Operational Scenario Pattern
 - Concrete analysis context Block that
 - ◊ Represents one operational scenario (e.g., power configuration)
 - ◊ Specializes the abstract analysis context Block
 - ◊ Redefines context's properties with scenario-specific values
 - ◊ Defines an owned behavior (sequence diagram) as scenario driver
 - Changes the states of the different components, by sending them signals, causing the rolling-up to occur automatically
 - Can specify duration constraints to time the injection of signals thus controlling time spent in a certain state
 - Can use state constraints (on components) to verify during execution if a component is actually in expected state

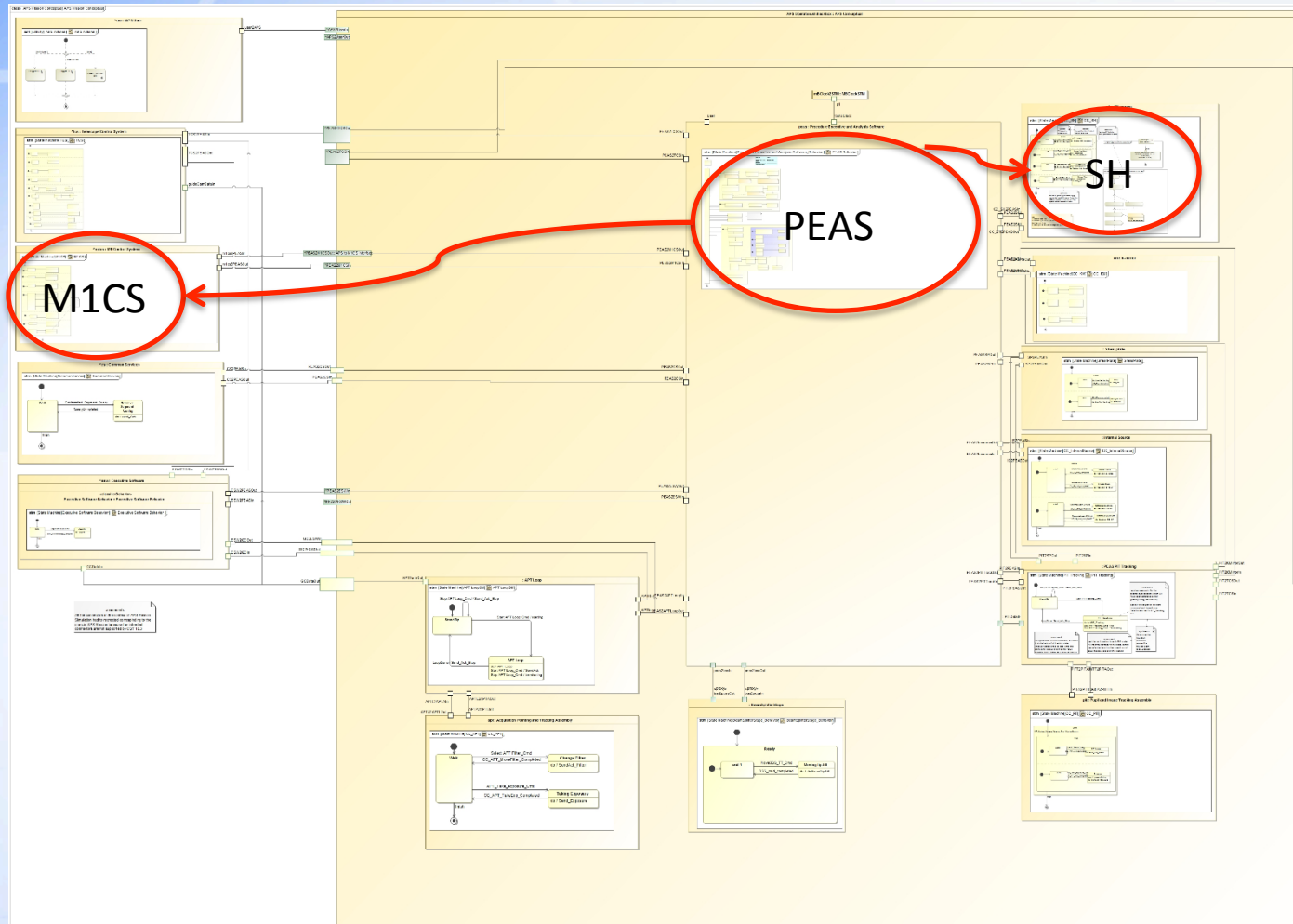
TMT Step 5: Specify Operational Scenarios

Thirty Meter Telescope



Operational Scenario Driver

Step 2: Conceptual Model



Communication between state machine specified components over ports

Step 6: Specify Scenario Configurations

- Scenario Condition Pattern
 - ◊ A decomposition tree of instance specifications representing the state of the scenario
 - ◆ Can be presented in tabular form
 - ◊ Rows represent the instance specifications (e.g., component)
 - ◊ Columns represent values (e.g., operating power) from the instance specifications
- Issues
 - ◊ Hard to keep instance specifications in sync with Block hierarchy
 - ◆ Mitigation: tool automation
 - ◊ Instance specifications cannot be displayed in IBDs
 - ◆ Mitigation: use full specialization tree of singleton Blocks for each scenario

TMT Step 6: Specify Analysis Configurations

Thirty Meter Telescope

#	Name	Classifier	Operating Power : W	Standby Power : W
1	peak Power Limit Scenario Online.aPS Realization	APS Realization	0.0	0.0
2	peak Power Limit Scenario Online.aPS Realization.dome Installation	Dome Installation	0.0	0.0
3	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins	Instrument	0.0	0.0
4	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack	Controller Rack	0.0	0.0
5	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr bs	Motor Ctrl	0.0	0.0
6	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr bs.subMass[1]	MassRollUpPattern		
7	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr bs.subPower[1]	PowerRollUpPattern		
8	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr ccd	Camera Ctrl	150.0	200.0
9	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr ccd.subMass[1]	MassRollUpPattern		
10	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr ccd.subPower[1]	PowerRollUpPattern		
11	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr filter 1	Slide Wheel Ctrl	0.0	0.0
12	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr filter 1.subMass[1]	MassRollUpPattern		
13	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr filter 1.subPower[1]	PowerRollUpPattern		
14	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr filter 2	Slide Wheel Ctrl		
15	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.apr filter 3	Slide Wheel Ctrl		
16	peak Power Limit Scenario Online.aPS Realization.dome Installation.ins.aps electronics rack.pit ccd	Camera Ctrl	150.0	100.0

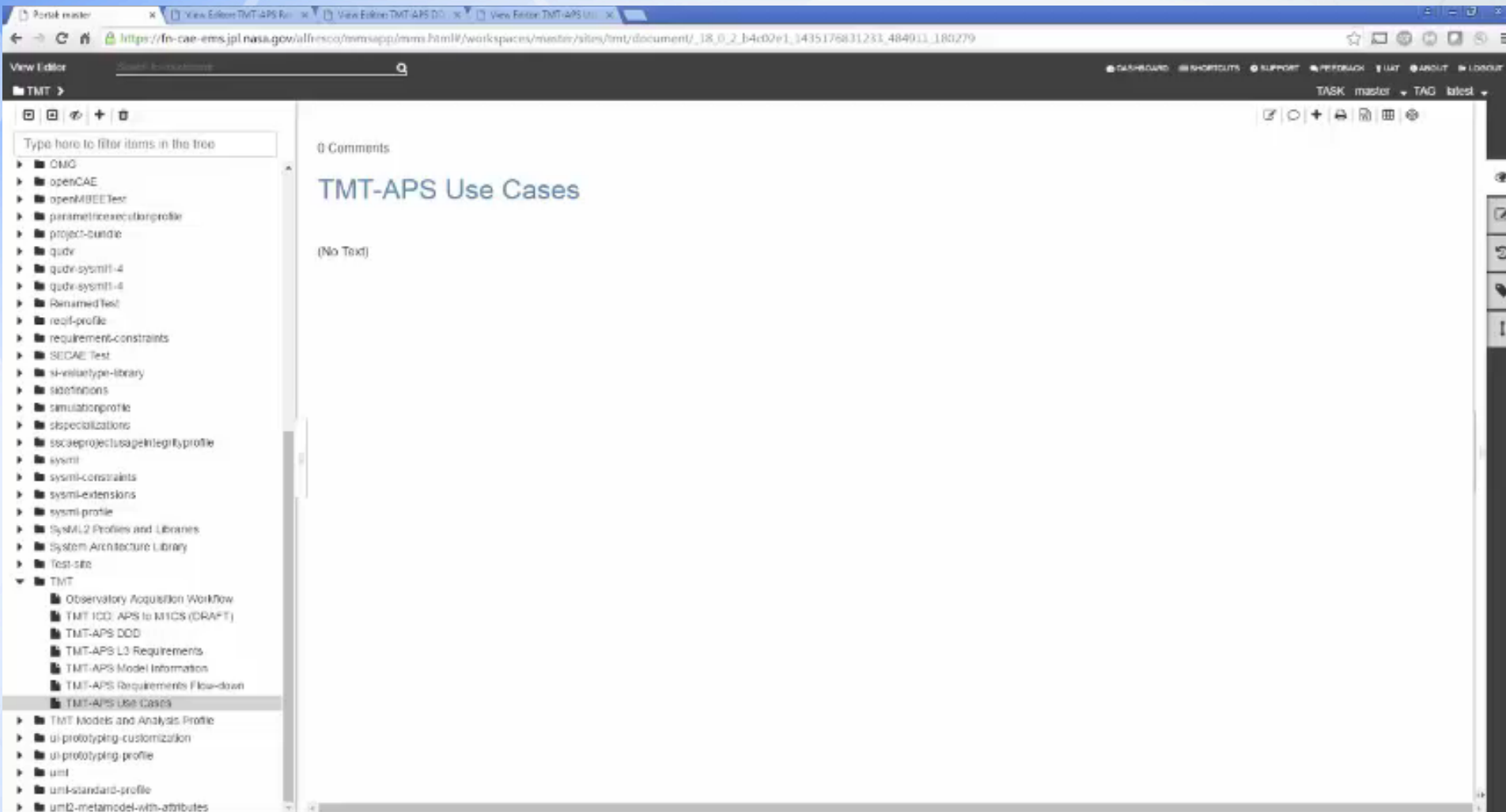
Scenario Initial Condition Pattern

177	peak Power Limit Scenario Online.aPS Realization.summit Installation.computer rack.ctrl [4]	PowerRollUpPattern			
178	peak Power Limit Scenario Online.aPS Realization.summit Installation.subMass[1]	MassRollUpPattern			
179	peak Power Limit Scenario Online.aPS Realization.summit Installation.subPower[1]	PowerRollUpPattern			
180	peak Power Limit Scenario Online.aPS Operational Blackbox Specification JPL.pplc	Peak Power Limit Requirem			8500.0
181	peak Power Limit Scenario Online.aPS Operational Blackbox Specification JPL.ppls	Peak Power Limit Requirem			8100.0
182	peak Power Limit Scenario Online.aPS Realization.pplc	Peak Power Limit Requirem			
183	peak Power Limit Scenario Online.aPS Realization.ppls	Peak Power Limit Requirem			
184	peak Power Limit Scenario Online.aPS Realization.summit Installation.computer 1	Control	500.0	100.0	0.0

Step 7: Run Analysis

- Run the configured analysis with a simulation engine on the initial conditions to get the final conditions:
- Produce the following views on final conditions
 - ◊ Table showing final analysis values (e.g., peak power) and the constraint's pass/fail status for each scenario
 - ◊ Timelines: state changes for components over time
 - ◊ Value profiles: total rolled up values over time

System Level Analysis



Portal master

View Editor TMT-APS Use Cases

View Editor TMT-APS Use Cases

View Editor TMT-APS Use Cases

https://tn-cae-ems.jpl.nasa.gov/alfresco/mmsapp/mms.html#/workspaces/munster/sites/tmt/document/_18_0_2_b4c02e1_1435176831231_484911_180279

View Editor

TMT

Type here to filter items in the tree

- CMIO
- openCAE
- openMBEETest
- parametricaccdlogprofile
- project-bundle
- qudr
- qudr-sysml-4
- qudr-sysml-4
- Renamed Test
- reqif-profile
- requirement-constraints
- SECAD Test
- si-initiate-type-library
- satisfactions
- simulationprofile
- specializations
- sscaeprojectusageintegrityprofile
- sysml
- sysml-constraints
- sysml-extensions
- sysml-profile
- SysML2 Profiles and Libraries
- System Architecture Library
- Test-site
- TMT
 - Observatory Acquisition Workflow
 - TMT ICQ: APS to MICS (DRAFT)
 - TMT-APS DOD
 - TMT-APS L3 Requirements
 - TMT-APS Model Information
 - TMT-APS Requirements Flow-down
 - TMT-APS Use Cases
- TMT Models and Analysis Profile
- ui-prototyping-customization
- ui-prototyping-profile
- uml
- uml-standard-profile
- uml2-metamodel-with-attributes

0 Comments

TMT-APS Use Cases

(No Text)

TMT Model

- Customer and supplier model in same SysML project, APS and Adaptive Optics
- Project level (customer) conceptual elements re-used for simulation in downstream design
- Analysis: Duration, Power and Mass

<https://github.com/Open-MBEE/TMT-SysML-Model>

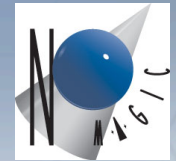
Summary & Outlook

- It is possible to automate requirements verification in SysML models
- Introduced a new Executable System Engineering Method that consists of a set of pure SysML analysis patterns
- The method can be executed using an Off the shelf simulation engine for SysML
- big interest in other projects at JPL
- Trigger Analysis from Web interface and auto-generate documents
- Integrate analysis engine (solver)
- Integrate FMI units

Thank You !

Visit No Magic booth at H1-H2

Acknowledgments



The research was carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract with the National Aeronautics and Space Administration and No Magic Inc.

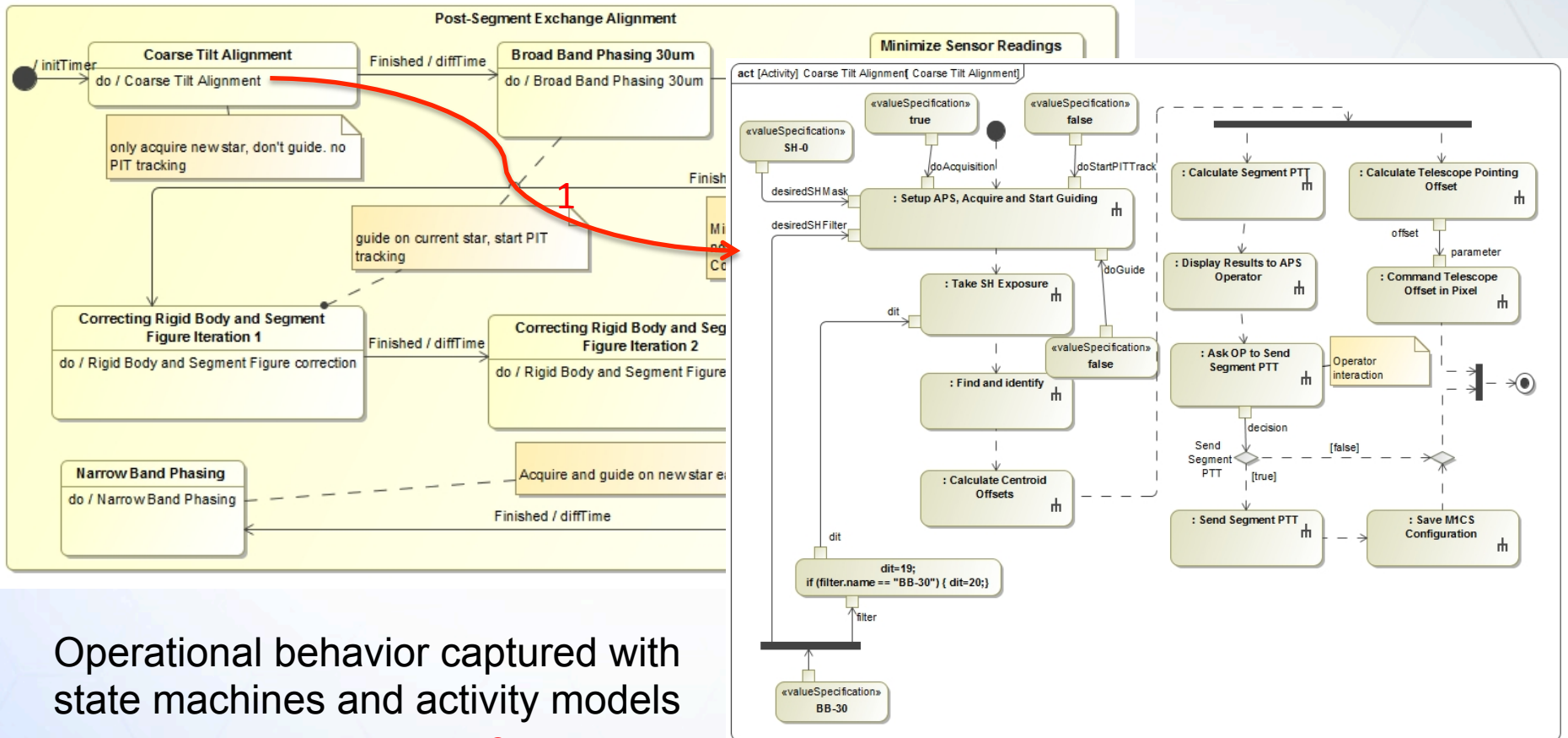
The TMT Project gratefully acknowledges the support of the TMT collaborating institutions. They are the Association of Canadian Universities for Research in Astronomy (ACURA), the California Institute of Technology, the University of California, the National Astronomical Observatory of Japan, the National Astronomical Observatories of China and their consortium partners, and the Department of Science and Technology of India and their supported institutes. This work was supported as well by the Gordon and Betty Moore Foundation, the Canada Foundation for Innovation, the Ontario Ministry of Research and Innovation, the National Research Council of Canada, the Natural Sciences and Engineering Research Council of Canada, the British Columbia Knowledge Development Fund, the Association of Universities for Research in Astronomy (AURA) and the U.S. National Science Foundation.

Reference

- Karban, R., Jankevičius, N., Elaasar, M. “ESEM: Automated Systems Analysis using Executable SysML Modeling Patterns”, (to appear in the proceedings of INCOSE International Symposium (IS), Edinburgh, Scotland, 2016.)
- Karban, R., “Using Executable SysML Models to Generate Systems Engineering Products”, NoMagic World Symposium, Allen, TX, 2016
- Open Source TMT model:
<https://github.com/Open-MBEE/TMT-SysML-Model>
- Open Source Engineering Environment: <https://github.com/Open-MBEE>
- A Practical Guide to SysML, 3rd Edition, Chapter 17 by Friedenthal, Moore, and Steiner
- Zwemer, D., “Connecting SysML with PLM/ALM, CAD, Simulation, Requirements, and Project Management Tools”, May 2016

Backup

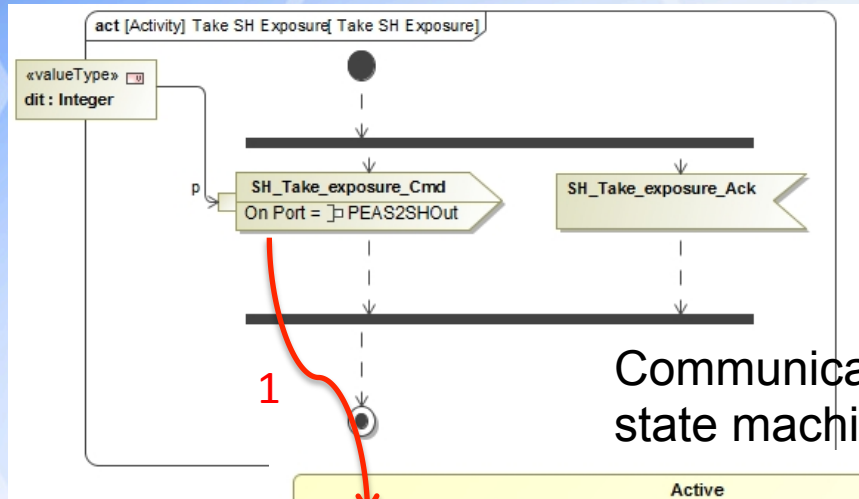
Conceptual Design



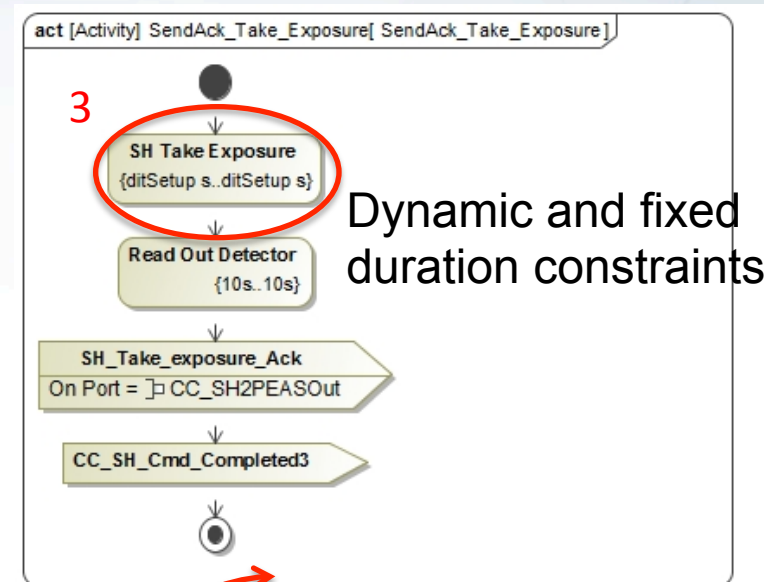
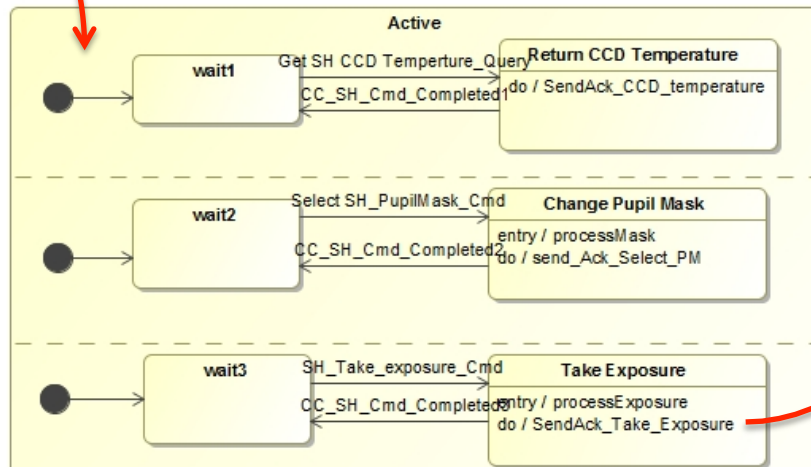
Operational behavior captured with state machines and activity models

#	Name	Specification	Constrained Element	Owner Of Constrained Element
1	dAPTMoving	10s..10s	Moving	SendAck_Filter
2	dAPTTakeExposure	ditSetup s..ditSetup s	APT Take Exposure	Send_Exposure
3	dCalcCentroidOffsets	0s..1s	Execute Centroid Offset Calculation	Calculate Centroid Offsets
4	dCalcPupilRegistrationOffset	0.5s..1s	Calculate Pupil Registration Offset	Calculate Pupil Registration and Image Offset
5	dCalcRMSForM2AndSegmentPTT	1s..3s	Calculate RMS for M2 and Segment PTT Cmds	Calculate RMS for M2 and Segment PTT cmds

Conceptual behavior model



Communicating
state machines



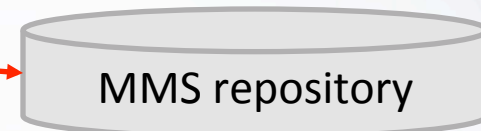
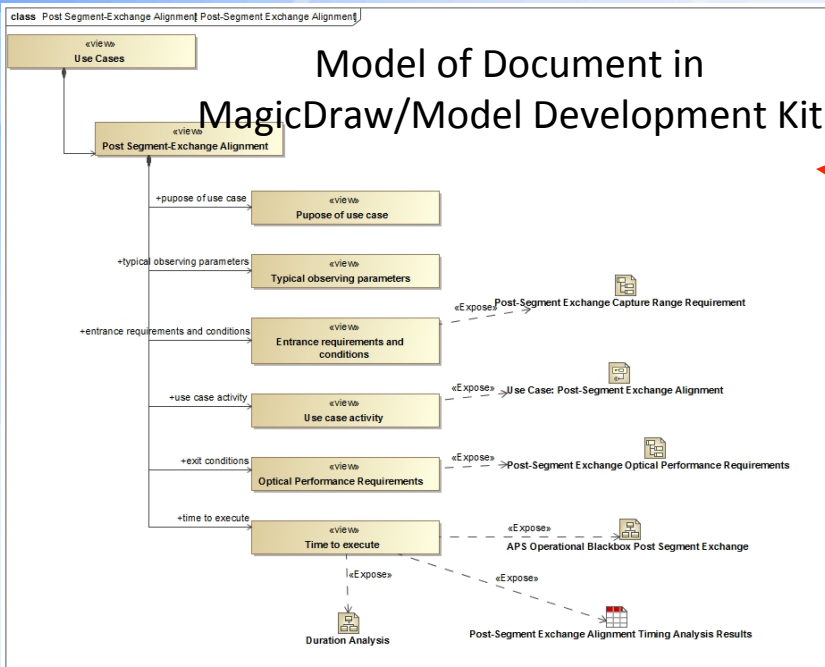
Dynamic and fixed
duration constraints

Duration analysis results verified
against requirement for a particular
configuration

4

#	Name	T Final : Real	Post Seg Xchg Time Limit : Second	Post Segment Exchange : Post Segment Exchange Time Constraint	Off Axis Measurement Steps : Integer	Off Axis Map Points : Integer	RB Dit : Integer	Phasing Dit : Integer
1	maintenance Alignment Duration Scenario.aps mission conceptual.aps co		7200.0	pass				
2	maintenance Alignment Duration Scenario.aps mission conceptual.aps co	1517.0			6	7	45	20

OpenMBEE Core Integration



Rendered and editable document in Web interface View Editor

2.1.6 Time to execute

The table below shows our current bottom-up time estimate for each of the activities that make up this use case. The total time estimate is ~96 (TBR) minutes, which is to be compared with our requirement of 120 min (as shown in the figure below).

At Keck, we routinely perform post-segment exchange alignment in 120 minutes or less. However, at Keck the segment shapes are measured in a separate test, with each segment measured separately, but adjustment of the segment warping harnesses is manual and occurs the next day. We will measure the TMT segment shapes in parallel as part of the rigid body and segment figure activity and immediately adjust the segment shapes during the night via the motorized warping harnesses and iterate the control at least once. Given our bottom up estimate and our Keck experience we have a high degree of confidence we can meet the 120 minute requirement.

#	Name	Classifier	Post Seg Exch Time Limit - Second	T Final - Real	Post Segment Exchange Time - Integer	Post Segment Exchange Time - Integer	Normalized Filter Steps - Integer	Rigid Body Steps - Integer	RR D1 - Integer	Phasing D1 - Integer	TCT1 - Real	TMR01 - Real	TMR1 - Real	TMR2 - Real	TMR3 - Real	TMR4 - Real	TMR5 - Real	TMR6 - Real	TMR7 - Real	TMR8 - Real
1	Post Segment Exchange Duration Set	Procedure Executive and Anal	360.0		11	2	3	45	20		135.0	797.0	36.0	468.0	465.0	613.0	827.0	108.0		
2	Post Segment Exchange Duration Set	Post Segment Exchange Dual																		
3	Post Segment Exchange Duration Set	Post Segment Exchange Maximum 1200.0																		

Post-Segment Exchange Alignment Timing Analysis Results

This table shows the results for the post segment exchange duration analysis.

