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# Developing Case-Based Costs Estimation: A Recursive Approach and Case Study

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# Outline

- Introduction
- Overall Estimation Framework
- Component Level Cost
- System Level Cost
- Properties
- Example – HVAC
- Experience and Conclusion

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# Introduction

- Costs
    - Raw Cost
      - Build from scratch
    - Switching Cost
      - Build from prior products
  - Methods for raw costs may not be suitable for switching costs
    - E.g. Linear regression
- Significant errors!

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# Literature

(Before DARPA AVM 2011)

Most studies were on raw costs

- Manufacturing parts
- Development costs

Switching costs for a generic system: unanswered

AVM: Adaptive Vehicle Make

Switching costs studied for specific domains/systems

- Software-intensive systems  
E.g. (Wang, G., et. al., 2009)
- Tools:  
E.g. SEER-H (hardware systems)  
SEER-SYS, COSYSMO II  
(Systems engineering costs only)

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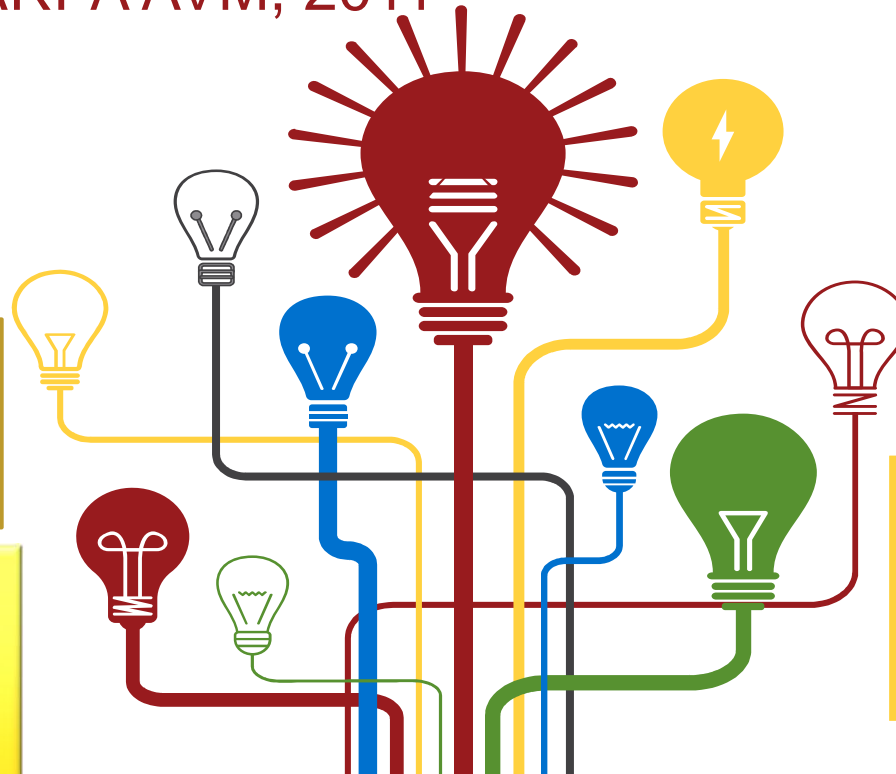
# Our Work

-Performed in DARPA AVM, 2011

Concept and  
Properties of  
Switching Costs

Methods of  
Calculating  
Switching Costs

- Activity-Based Approach;
- Support Early-Stage Estimation



Applicable to  
Systems  
Generated With  
Different Processes

- Minimize manual EJ (Expert Judgment)
- Do not explicitly require data calibration

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# Definitions

- Architecture/Design
  - Components
  - Flows/Connections are special components
- AA (All Activities) Set
  - Include all design activities
- Primitives:
  - SAME(), SWITCHABLE(), etc.

Switching Cost AA  $\hat{C}_{sw}(A, B)$  Raw cost AA  $\hat{C}(A)$

Switching Cost  $C_{sw}(A, B)$  Raw cost  $C(A)$

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# Overall Estimation Framework

Process: Top down, recursion back



Raw Cost:

$$C(A) = f(\hat{C}(A)) = C(\alpha, A) + C(\sigma, A)$$

$$\hat{C}(A) = \hat{C}(\alpha, A) \cup \hat{C}(\sigma, A)$$

Switching Cost:

$$C_{sw}(A, B) = f(\hat{C}_{sw}(A, B))$$

$$= C_{sw}(\alpha, A, B) + C_{sw}(\sigma, A, B)$$

$$\hat{C}_{sw}(A, B) = \hat{C}_{sw}(\alpha, A, B) \cup \hat{C}_{sw}(\sigma, A, B)$$

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# Switching Design Process



Select A

A is prior product

Activities:

- System level:  
Step 1, 2, 4
- Component level  
Step 3



Modification  
Plan

Match each component  
with some prior  
components



Implementation

Implement switch  
designs



Integration

Remaining steps:  
integrate, V&V, etc.

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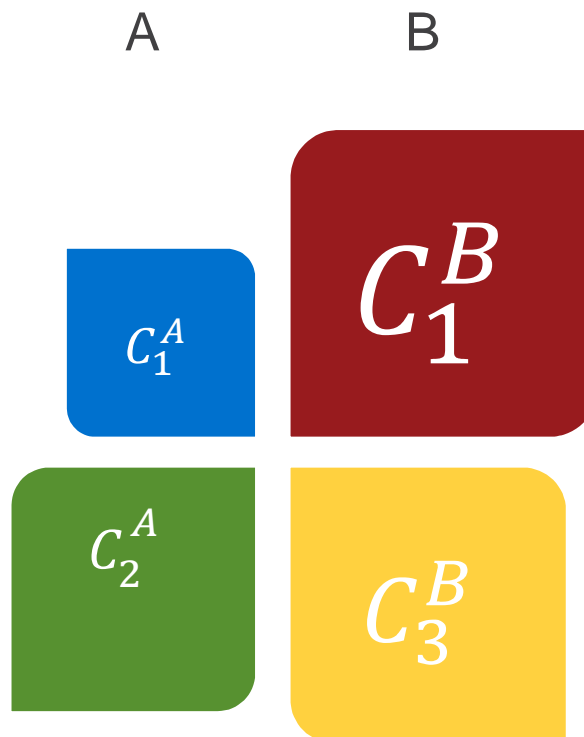


# Component Level

Component Design  
Activities

$$\hat{C}_{sw}(\sigma, A, B) = \bigcup_{n=1}^{|\sigma|} \hat{\Gamma}_{\sigma_n, A, B}$$

Compare by types



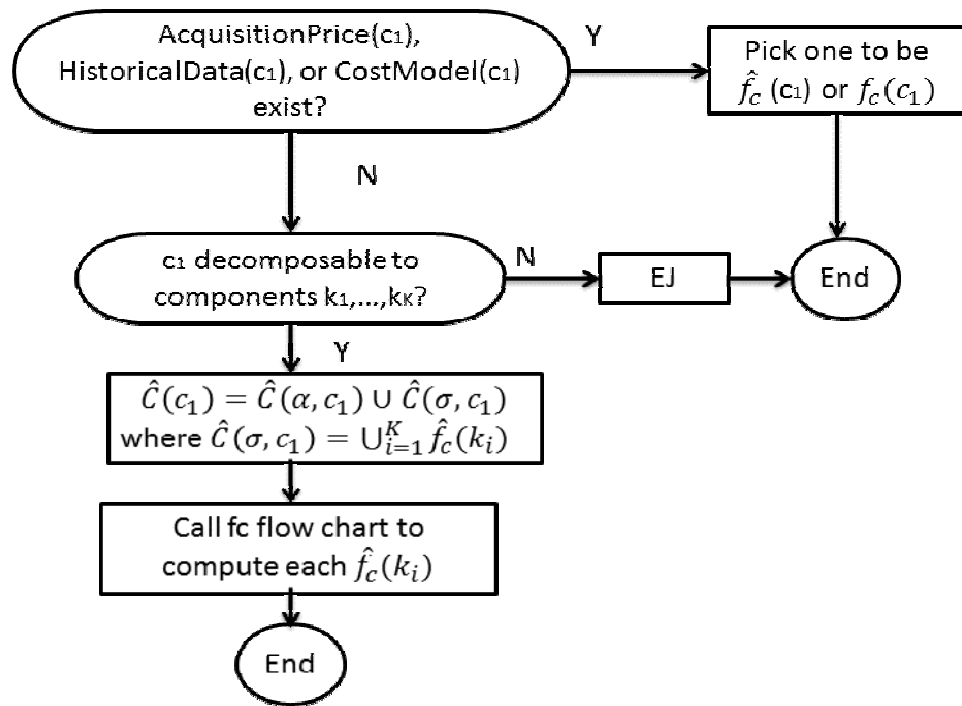
Three types of changes:

$f_c(c_3^B)$ : Add from scratch  
 $f_s(C_1^A, C_1^B)$ : Modify from a prior component  
 $f_r(C_2^A)$ : remove a component

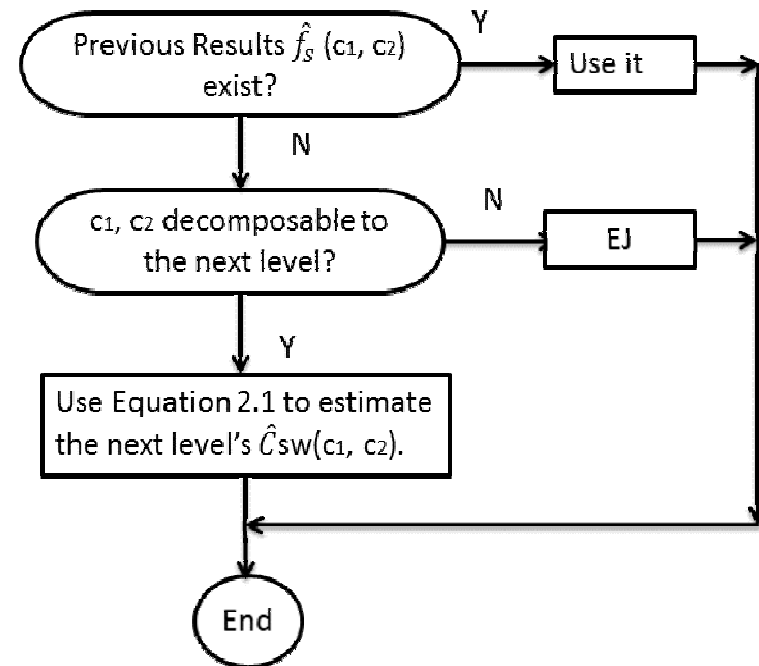
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# Recursions



$fc()$



$fs()$

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# System Level

$$\begin{aligned} C_{sw}(\alpha, A, B) &= f(\hat{C}_{\alpha}(A, B), \hat{C}_{sw}(\alpha_1, B)) \\ &= C_{\alpha}(A, B) + C_{sw}(\alpha_1, B) \end{aligned}$$

$\hat{C}_{\alpha}(A, B)$ : system level activities on analyzing and selecting arrangements

$\hat{C}_{sw}(\alpha_1, B)$ : system level activities on building B besides the costs on B's components

- E.g. designing, integrating and verifying/validating system B




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# Properties

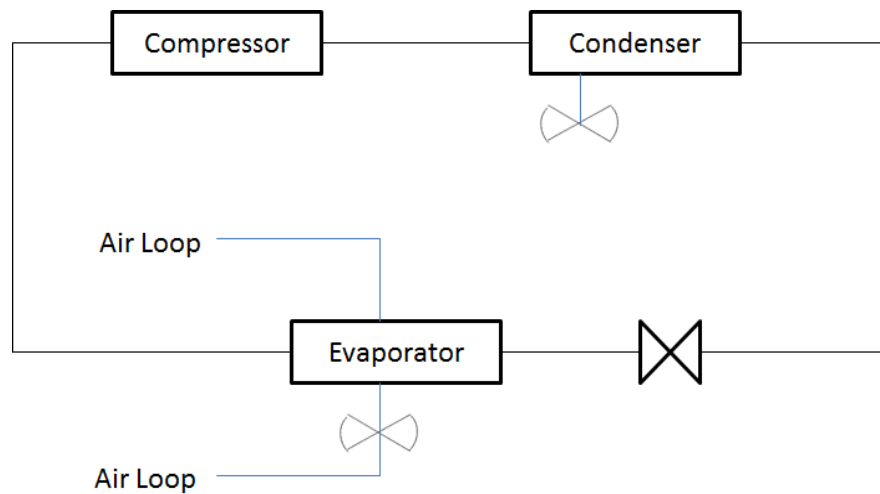


Switching Cost

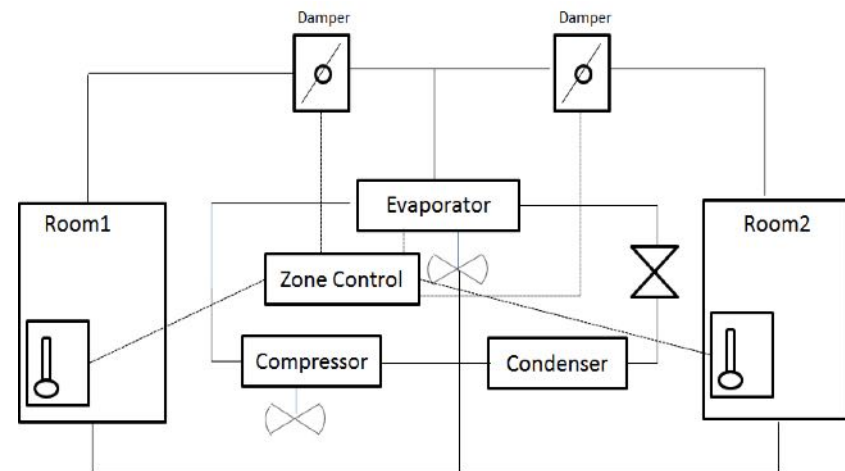
01		Non-Negative Property	Switching cost is always non-negative
02		Triangle Property	$C_{sw}(A, B) \leq C(A) + C(B)$
03		Minimum Property	Minimum switching cost exists
04		...	
05		...	
06		...	
07		...	

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# Example - HVAC



A



———— Mechanical pipe  
- - - - - Electronic links (e.g. IO, Network)

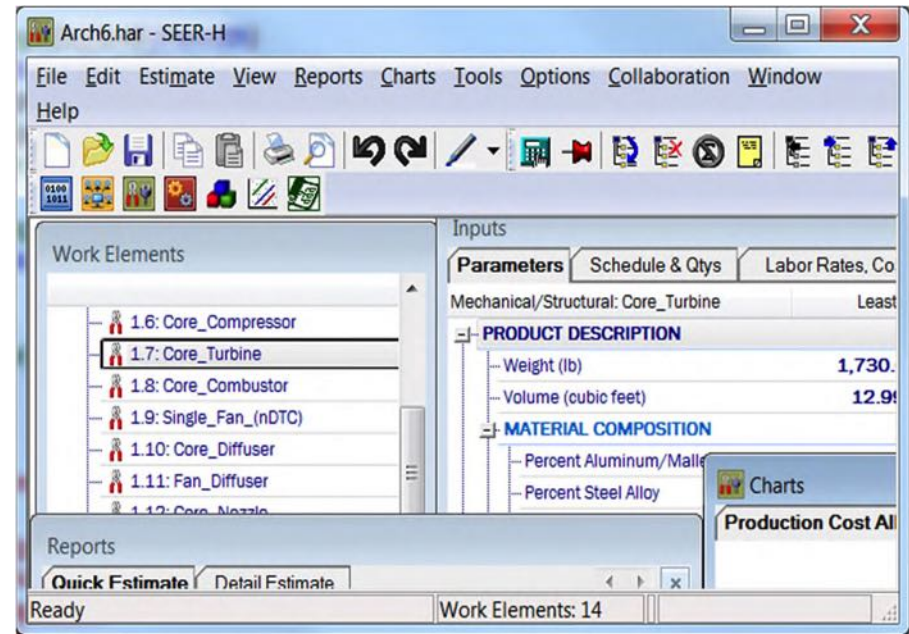
B

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# Process and Tools

$\sigma_1$  = compressor,  $\sigma_{1,A} = \{c_{1,1}\}$ ,  $\sigma_{1,B} = \{c_{1,2}\}$   
 $\sigma_2$  = condenser,  $\sigma_{2,A} = \{c_{2,1}\}$ ,  $\sigma_{2,B} = \{c_{2,2}\}$   
 $\sigma_3$  = vaporizer,  $\sigma_{3,A} = \{c_{3,1}\}$ ,  $\sigma_{3,B} = \{c_{3,2}\}$   
 $\sigma_4$  = damper,  $\sigma_{4,A} = \phi$ ,  $\sigma_{4,B} = \{c_{4,1}, c_{4,2}\}$   
 $\sigma_5$  = controller,  $\sigma_{5,A} = \{c_{5,1}\}$ ,  $\sigma_{5,B} = \{c_{5,2}\}$   
 $\sigma_6$  = user control panel,  $\sigma_{6,A} = \phi$ ,  $\sigma_{6,B} = \{c_{6,1}\}$   
 $\sigma_7$  = software on controller,  $\sigma_{7,A} = \{c_{7,1}\}$ ,  $\sigma_{7,B} = \{c_{7,2}\}$   
 $\sigma_8$  = software on user control panel,  $\sigma_{8,A} = \phi$ ,  $\sigma_{8,B} = \{c_{8,1}\}$   
 $\sigma_9$  = IO link between controller and controlled components (e.g. damper/condenser),  $\sigma_{9,A} = \{c_{9,1}\}$ ,  $\sigma_{9,B} = \{c_{9,2}\}$   
 $\sigma_{10}$  = Network link between user control panel and zone controller,  $\sigma_{10,A} = \phi$ ,  $\sigma_{10,B} = \{c_{10,1}\}$



SEER-H\*

\*courtesy Galorath Inc.

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# Conclusion

- Switching cost
  - Concept, Properties, Methods, Principles
- Our method
  - Automation: Minimize EJ
  - Not parametric
    - Unlike COSYSMO II etc.
    - Do not explicitly require data calibration, thus reduce it
  - Leverage existing tools, models, prices, data
  - First answered the question of switching cost for a complete generic system (AVM)

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