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Architecture Development vs. Cost Estimation

# The Convergence of COSYSMO Parametric Cost Estimation with MBSE



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Cost  
Analyst

System  
Architect

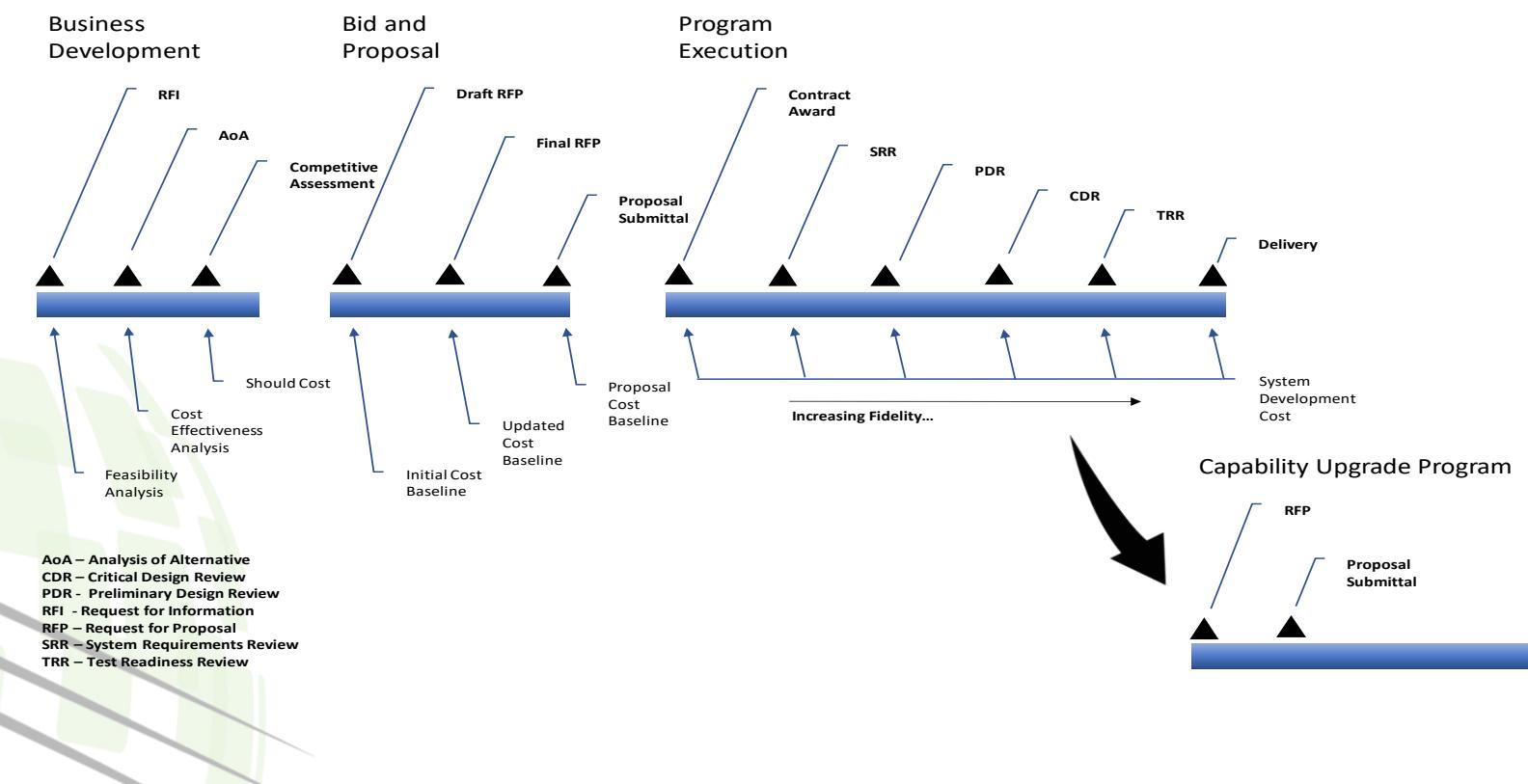


Hey! You've got  
your cost model in  
my architecture  
model!!

No! You've got  
your architecture  
model in my cost  
model!!



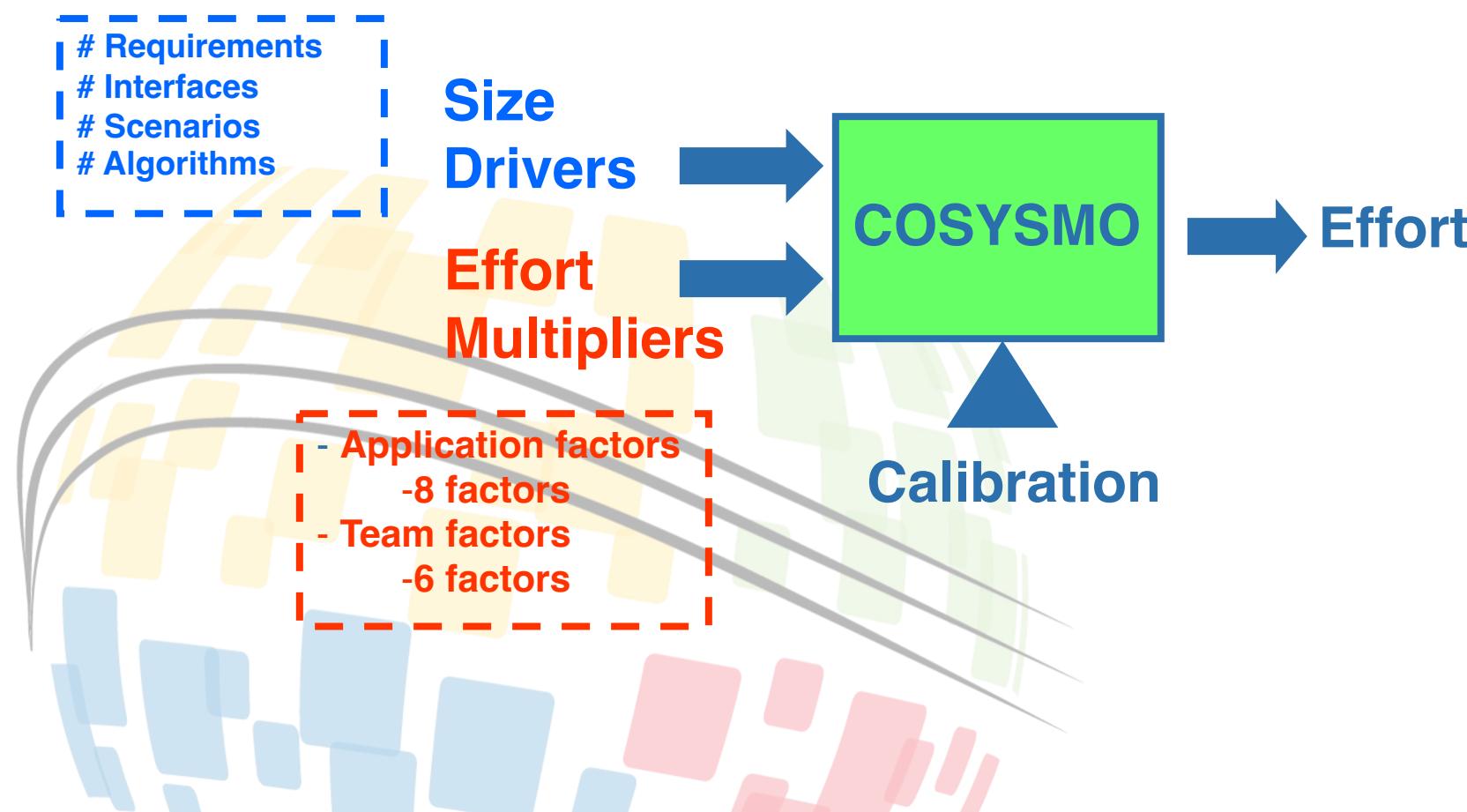
# Why Should Systems Engineers Care About Cost Estimating? Or About COSYSMO?



Cost baseline is part of the technical baseline throughout the project lifecycle!

# A Quick Review of COSYSMO

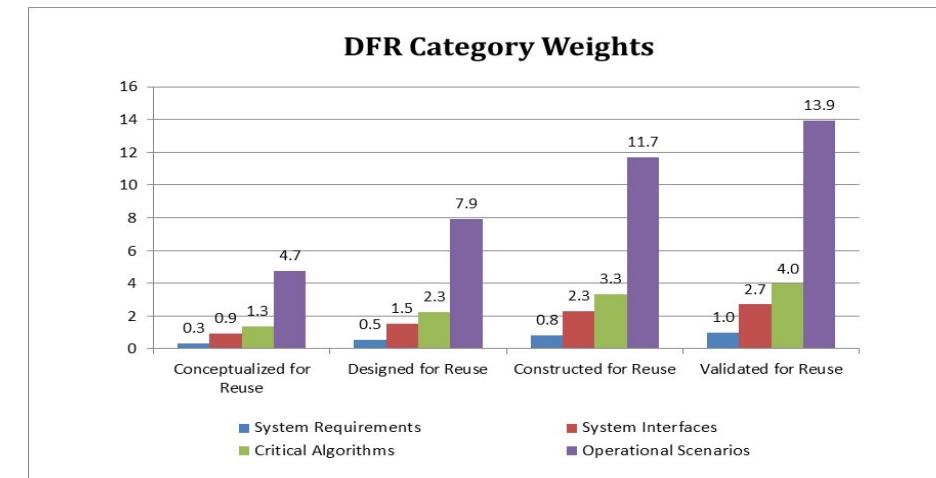
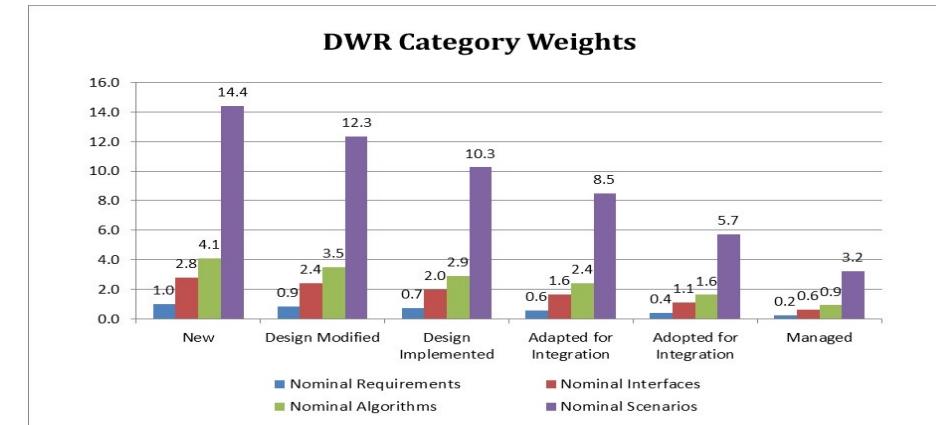
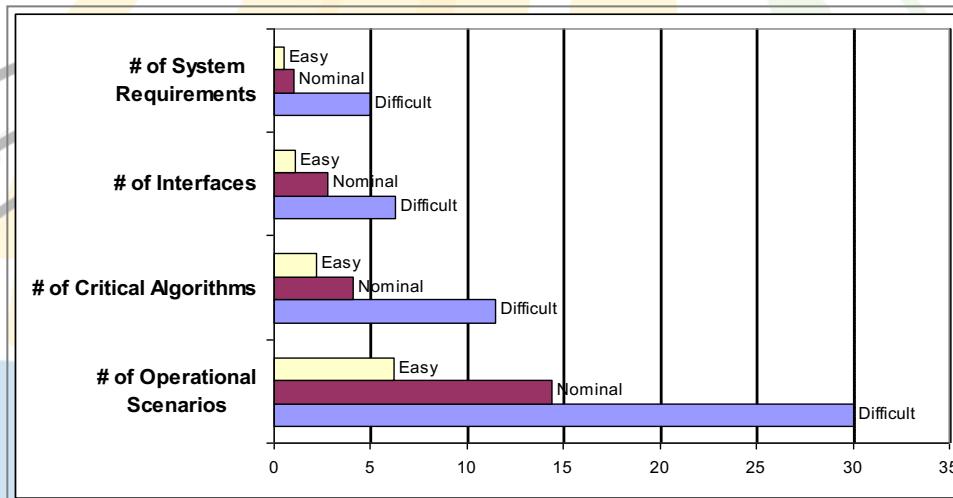
## 4 Size Drivers and 14 Cost Drivers



- History
  - 2000 COCOMO –Boehm
  - 2005 COSYSMO –Valerdi
  - 2007 SysML Standard - OMG
  - 2014 General Reuse Framework - Wang, Roedler, Pena, & Valerdi

# SIZE DRIVERS AND THE GENERAL REUSE FRAMEWORK

- The General Reuse Framework (GRF) extends COSYSMO with the concepts of “Development With Reuse (DWR)” and “Development For Reuse (DFR).”
  - Four Size Drivers
    - Requirements (REQ)
    - System Interfaces (IF)
    - Algorithms (ALG)
    - Operational Scenarios (SCN)
  - Three Difficulty Levels
  - Six DWR Reuse Levels
  - Four DFR Reuse Levels



# REVIEW OF COSYSMO WITH THE GENERAL REUSE FRAMEWORK

## The COSYSMO Cost Estimating Relationship (CER) with the GRF

$$\text{SE Effort} = (A_{DWR} \cdot SS^{E_{DWR}} \cdot CEM_{DWR}) + (A_{DFR} \cdot SS^{E_{DFR}} \cdot CEM_{DFR})$$

Where:

**SE Effort** = total systems engineering effort in person hours

**SS** = System Size (sum of each size driver count for DWR and DFR)

**E** = nonlinearity for the productivity curve, representing a diseconomy of scale

**A** = calibration constant, typically derived from historical project data

**CEM** = composite effort multiplier (cost drivers)

To elaborate the math, we get:

$$\begin{aligned} PH_{Total} = & A_{DWR} \cdot \left[ \sum_k \left( \sum_r w_r (w_{e,k} \Phi_{e,k} + w_{n,k} \Phi_{n,k} + w_{d,k} \Phi_{d,k}) \right) \right]^{E_{DWR}} \cdot CEM_{DWR} \\ & + A_{DFR} \cdot \left[ \sum_k \left( \sum_q w_q (w_{e,k} \Psi_{e,k} + w_{n,k} \Psi_{n,k} + w_{d,k} \Psi_{d,k}) \right) \right]^{E_{DFR}} \cdot CEM_{DFR} \end{aligned}$$

6 DWR Levels x 3 Difficulty Levels x 4 Size Drivers = 72 unique DWR SS Counts

4 DFR Levels x 3 Difficulty Levels x 4 Size Drivers = 48 unique DFR SS Counts

# Background

- In 2017, we developed an approach to implement COSYSMO and the GRF in a SysML model.
- That work demonstrated the feasibility of the approach:
  - Simplified the identification and assignment of size driver properties
  - Automated the counting of size driver elements
  - Made the sizing data a property of the architecture model.
- Size driver counts could be exported to a COSYSMO cost model tool.

# Convergence of COSYSMO with MBSE Today

- **This paper advances the previous work by:**
  - Updating the COSYSMO Size Driver Counting Rules specifically for SysML
  - Further Automating the Counting Process
  - Implementing the complete COSYSMO CER within the modeling tool (allowing full calculation of the system size and the total SE effort from within the model.)
  - Using Advanced Queries to review completeness, correctness, and consistency of the sizing driver assignments
- **The objective was to:**
  - Investigate how much of the COSYSMO cost estimation process could be implemented and automated in a SysML modeling tool
  - Evaluate the usability, benefits and impact
- **Disclaimer**
  - The implementation and the examples shown were developed and demonstrated with CAMEO Systems Model/CATIA Systems Architect:
  - The profile described is a proof of concept, not a product.
  - All features were created using out of the box capabilities of the modeling tool.

## ORIGINALLY A DOCUMENT BASED APPROACH

- Developed before the release of SysML and the widespread adoption of MBSE, the sources for COSYSMO size drivers were document-based systems engineering artifacts:

Counting rules reflected the subjective nature and wide variability of content in the source documents.

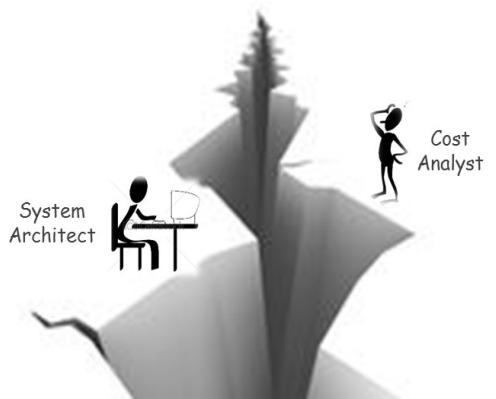
Many of the documents referenced as size driver sources do not exist early in the program when the cost estimation activity is most needed.

Counting and recording the size estimate was a manual process using spreadsheets.

Sizing data was poorly maintained, managed separately from the design artifacts.

Systems engineering continues to view parametric cost estimation as a pricing activity.

Architecture Development vs. Cost Estimation



## Labor Intensive!

# COSYSMO AND THE AGE OF MBSE

- SysML with advanced modeling tools:
  - Open standard systems modeling language
    - Provides a common, consistent set of model elements to represent each of the four size drivers
    - Provides a level of rigor, consistency and repeatability in the counting process.
  - Advanced tool features, such as custom tables that can execute complex queries using structured expressions and custom scripts
    - Can parse the model and automatically count the number of model elements in each of the 72 DWR and 48 DFR size driver categories.
- Wide Adoption of MBSE
  - Models are much more complete, much more rigorous and available much earlier in the project than documents.
  - Modeling tools enable the sizing data to become attributes of the architecture where it belongs!

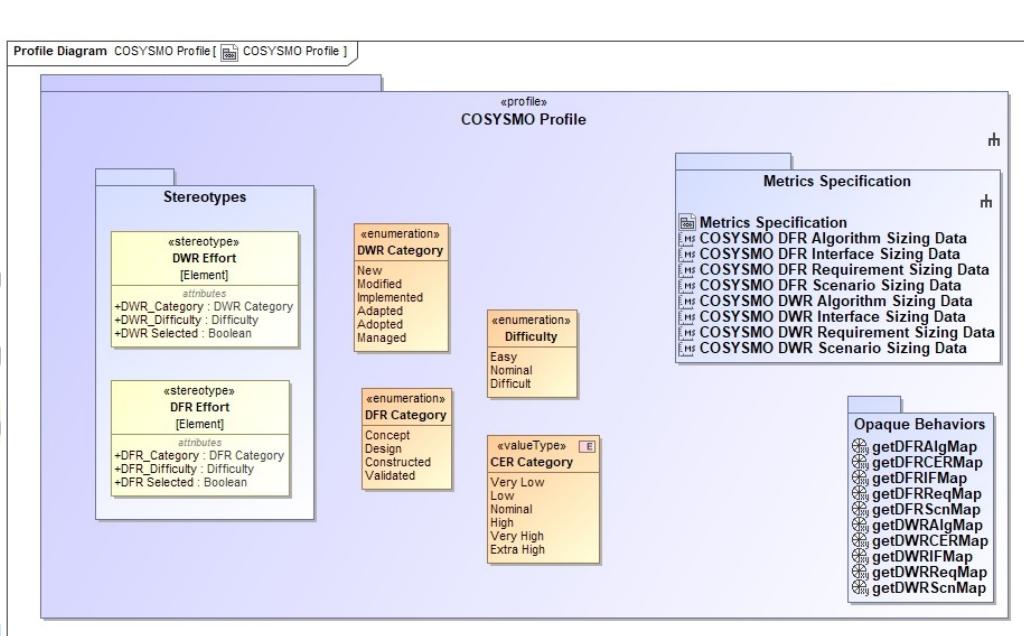
## SysML with Advanced Modeling Tools



## Wide Adoption of MBSE

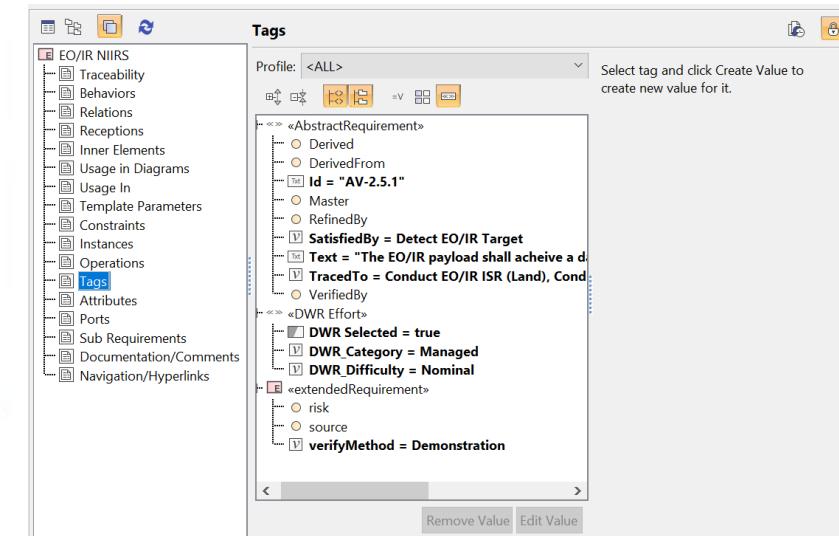
# THE COSYSMO PROFILE

- The COSYSMO profile defines stereotypes for the DWR and DFR reuse levels and Difficulty level.
- When applied to a model element the, DWR, DFR and Complexity properties are implemented as Tag Values.
- The profile also include advanced scripts, structured expressions and Parametric Diagrams the automate the counting and calculation of system size and total SE effort.



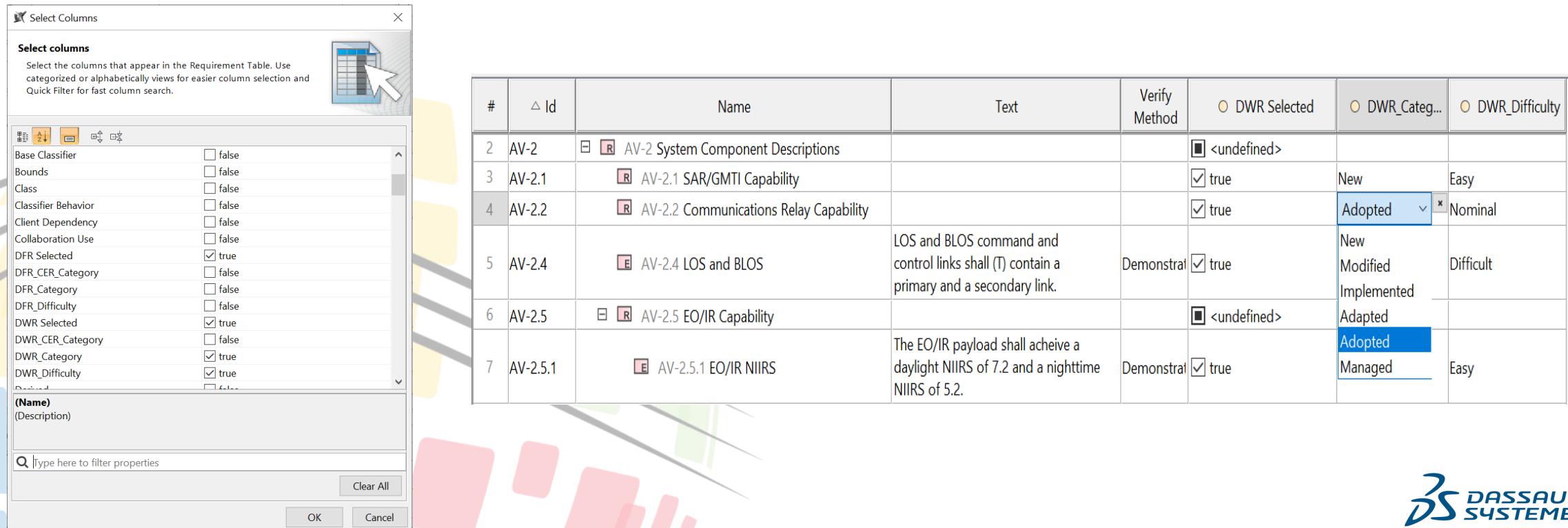
«DWR Effort»  
«extendedRequirement»  
**EO/IR NIIRS**

DWR\_Selected = true  
DWR\_Category = Managed  
DWR\_Difficulty = Nominal  
Id = "AV-2.5.1"  
Text = "The EO/IR payload shall achieve a daylight NIIRS of 7.2 and a nighttime NIIRS of 5.2."  
verifyMethod = Demonstration



# PROFILE FEATURES: SIMPLIFIED ASSIGNMENT OF REUSE CATEGORIES AND DIFFICULTY

- Features of the Generic Table in CAMEO made the assignment of DWR, DFR and Difficulty levels an efficient process.
  - In a Generic Table or a Requirements Table, create a New Custom Column for DWR, DFR and Difficulty Stereotypes.
  - The sizing analyst can first select the model elements to be included in the count and filter the table to show only selected requirements.
  - Clicking in the cell to present the enumerated list of possible values and then click on the value.



The image shows two windows from a software application. On the left is a 'Select Columns' dialog box with a sidebar for filtering properties. On the right is a Requirements Table with columns for ID, Name, Text, Verify Method, and three custom columns for DWR status, category, and difficulty.

**Select Columns Dialog:**

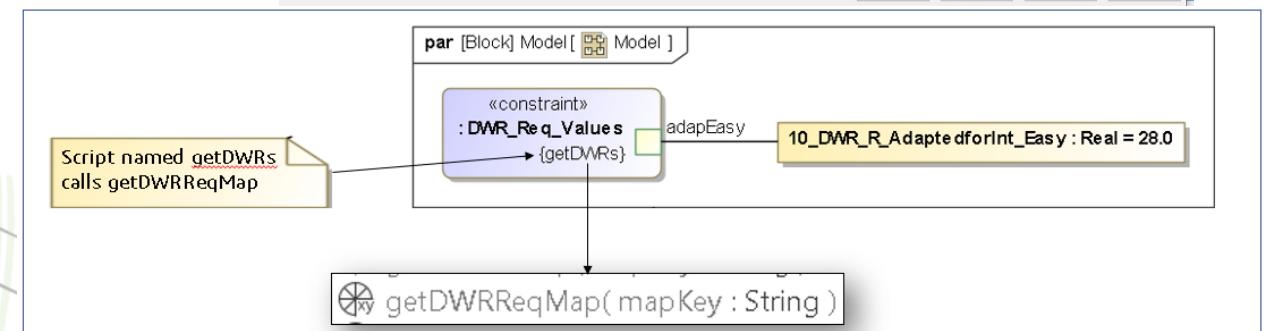
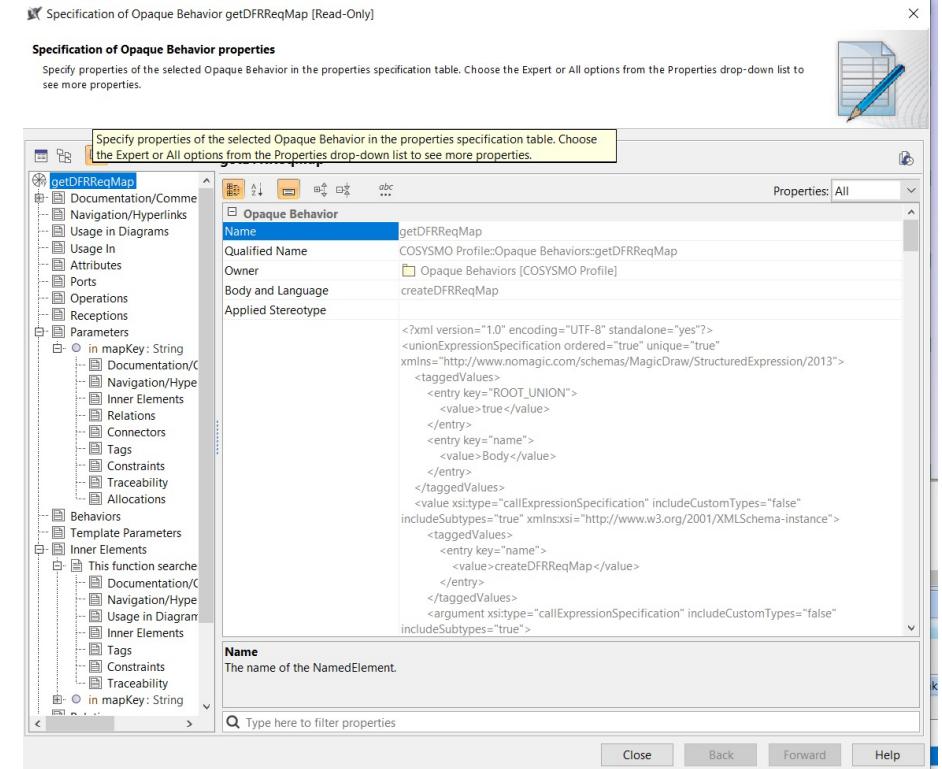
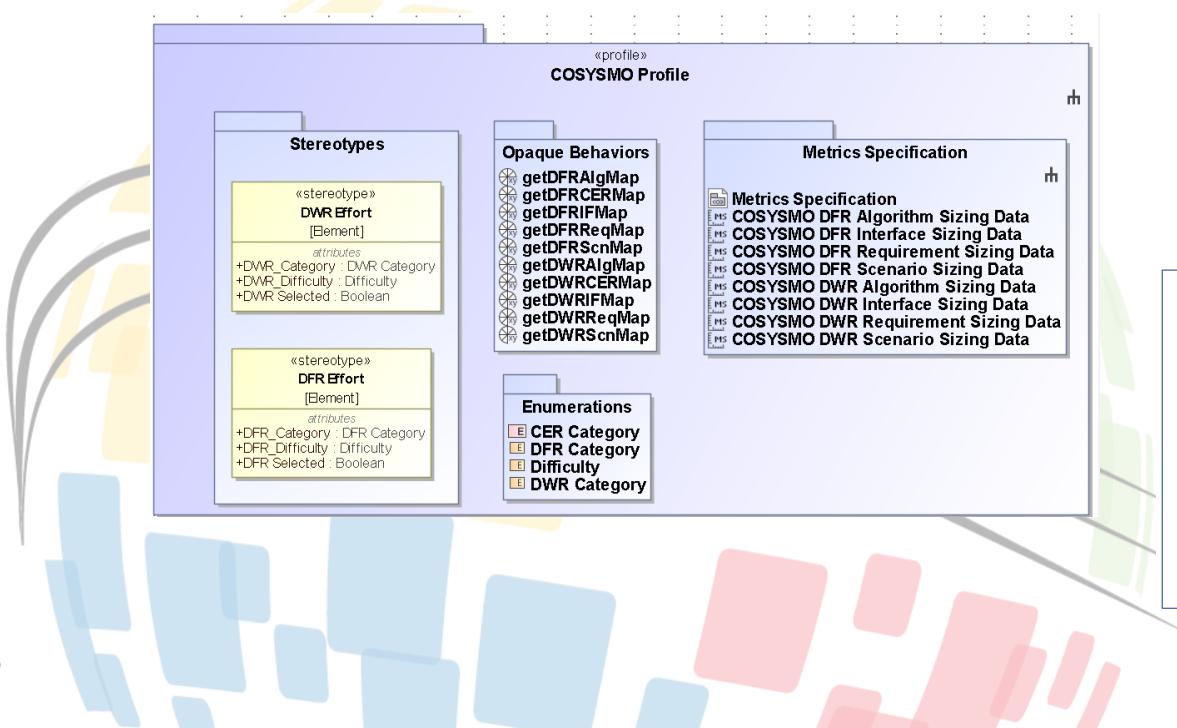
- Header: Select Columns
- Text: Select the columns that appear in the Requirement Table. Use categorized or alphabetically views for easier column selection and Quick Filter for fast column search.
- Toolbar: Includes icons for filter, sort, and search.
- List: Shows a categorized list of columns:
  - Base Classifier: false
  - Bounds: false
  - Class: false
  - Classifier Behavior: false
  - Client Dependency: false
  - Collaboration Use: false
  - DFR Selected: true
  - DFR\_CER\_Category: false
  - DFR\_Category: false
  - DFR\_Difficulty: false
  - DWR Selected: true
  - DWR\_CER\_Category: false
  - DWR\_Category: true
  - DWR\_Difficulty: true
- Buttons: OK and Cancel.

**Requirements Table:**

#	△ Id	Name	Text	Verify Method	DWR Selected	DWR_Categ...	DWR_Difficulty
2	AV-2	AV-2 System Component Descriptions		<undefined>			
3	AV-2.1	AV-2.1 SAR/GMTI Capability		true	New	Easy	
4	AV-2.2	AV-2.2 Communications Relay Capability		true	Adopted	Nominal	
5	AV-2.4	AV-2.4 LOS and BLOS	LOS and BLOS command and control links shall (T) contain a primary and a secondary link.	Demonstrat	true	New	Difficult
6	AV-2.5	AV-2.5 EO/IR Capability		<undefined>	Modified	Implemented	
7	AV-2.5.1	AV-2.5.1 EO/IR NIIRS	The EO/IR payload shall achieve a daylight NIIRS of 7.2 and a nighttime NIIRS of 5.2.	Demonstrat	true	Adapted	

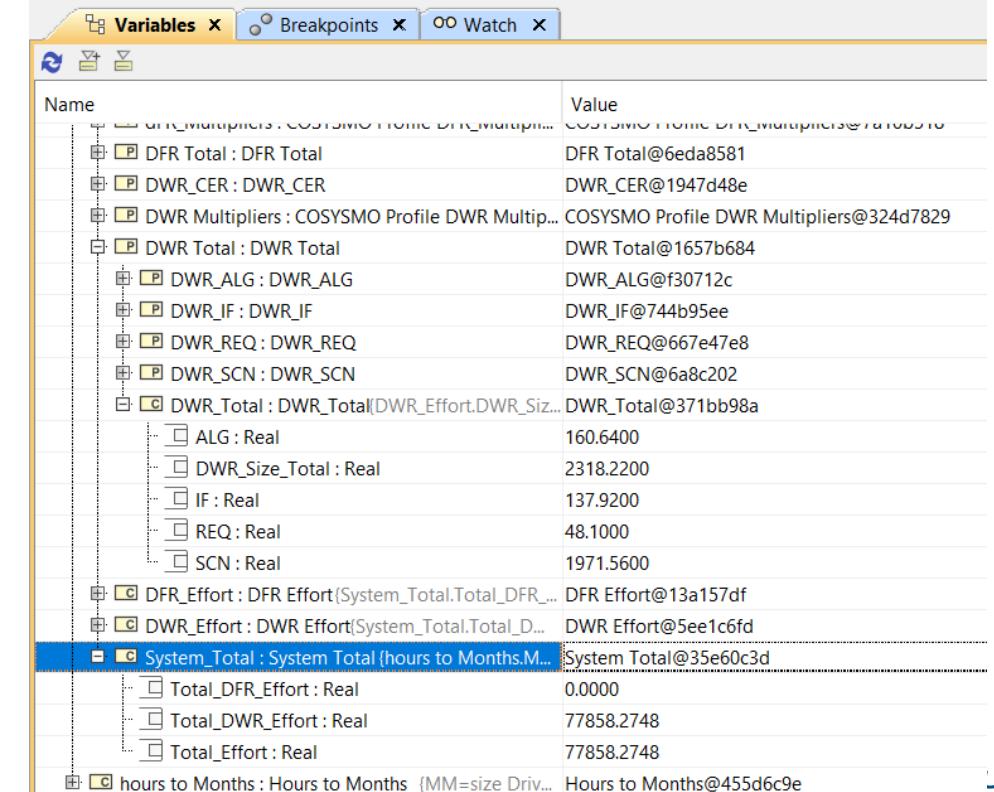
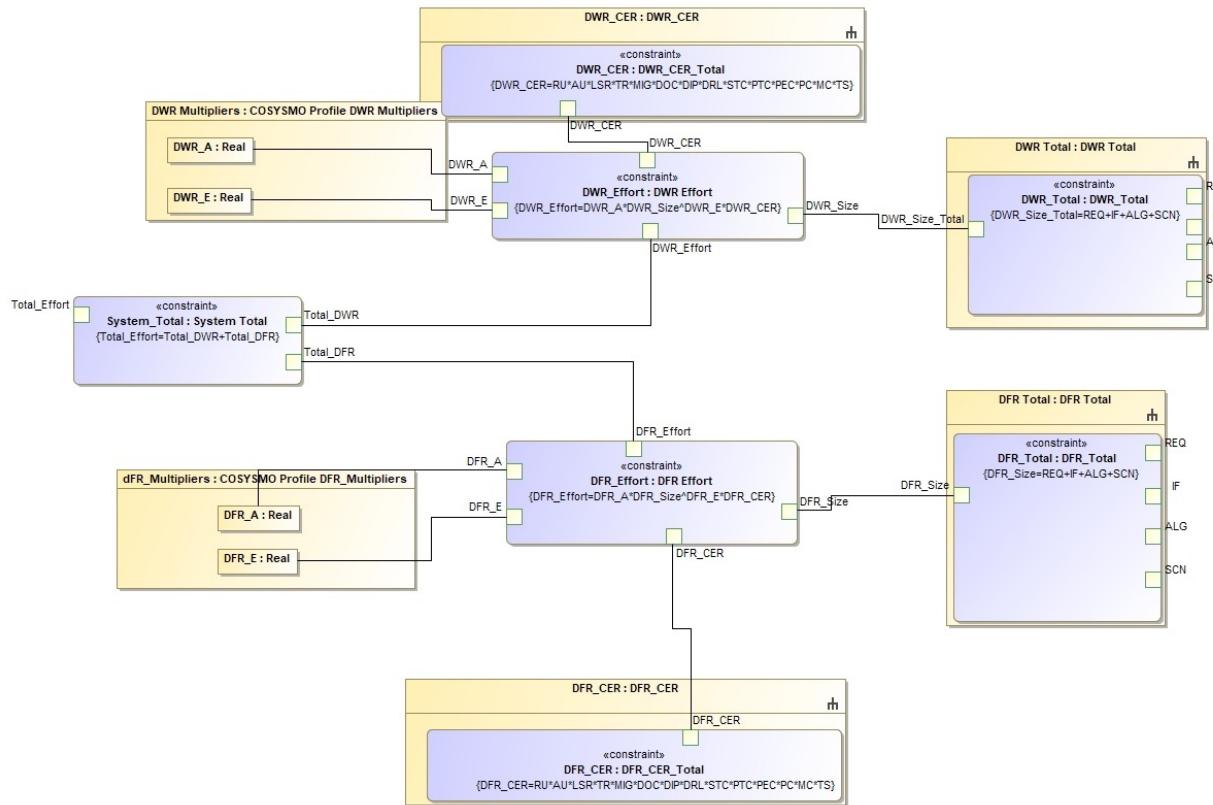
# PROFILE FEATURES: AUTOMATION OF THE COUNTING PROCESS

- When executed, scripts parse the model, count the number of model elements in each of the DWR and DFR size driver categories and write the totals to their respective Size Driver Block Value Properties.
- The scripts are a combination of Stereotypes, Enumerations, and Opaque Behaviors.



# PROFILE FEATURES: AUTOMATIC CALCULATION OF SYSTEM SIZE AND TOTAL SE EFFORT

- The COSYSMO CER is implemented with Constraint Blocks in Parametric Diagrams.
- When the Parametric Diagram is executed, the profile calculates system size and SE effort.
- All properties at each level are displayed in the variables pane of the simulation window and saved as a sizing instance.



# PROFILE FEATURES: THE COMPOSITE EFFORT MULTIPLIER IS IMPLEMENTED AS A BLOCK

- Cost Drivers are represented by a Cost Driver Block with Value Properties for the fourteen cost drivers.
- A Cost Driver stereotype allows the rating level to be applied to each cost driver value property.
- A custom script translates the rating level (Very Low to Extra High) into the numerical values that determine the Cost Effort Multiplier.

«block» COSYSMO Profile Cost Drivers	
values	
Requirements Understanding : Real	
Architecture Understanding : Real	
Level of Service Requirements : Real	
Migration Complexity : Real	
Technology Risk : Real	
Documentation : Real	
# and diversity of installations/platforms : Real	
# of recursive levels in the design : Real	
Stakeholder team cohesion : Real	
Personnel/team capability : Real	
Personnel experience/continuity : Real	
Process capability : Real	
Multisite coordination : Real	
Tool support : Real	

#	Name	DWR_CER_Category
1	# and diversity of installations/platforms	Very Low
2	# of recursive levels in the design	Low
3	Architecture Understanding	Nominal
4	Documentation	Nominal
5	Level of Service Requirements	Nominal
6	Migration Complexity	Nominal
7	Multisite coordination	Low
8	Personnel experience/continuity	Very High
9	Personnel/team capability	High
10	Process capability	High
11	Requirements Understanding	Very High
12	Stakeholder team cohesion	Nominal
13	Technology Risk	Nominal
14	Tool support	Extra High

Cost Diver	Very Low	Low	Nominal	High	Very High	Extra High
1 Requirements Understanding	1.85	1.36	1.00	0.77	0.60	
2 Architecture Understanding	1.62	1.27	1.00	0.81	0.65	
3 Level of Service Requirements	0.62	0.79	1.00	1.32	1.74	
4 Migration Complexity			1.00	1.24	1.54	2.10
5 Technology Risk	0.70	0.84	1.00	1.32	1.74	
6 Documentation	0.82	0.91	1.00	1.13	1.28	
7 # and diversity of installations/platforms			1.00	1.23	1.51	2.00
8 # of recursive levels in the design	0.80	0.89	1.00	1.21	1.46	
9 Stakeholder team cohesion	1.50	1.22	1.00	0.81	0.66	
10 Personnel/team capability	1.48	1.22	1.00	0.81	0.66	
11 Personnel experience/continuity	1.46	1.21	1.00	0.82	0.67	
12 Process capability	1.46	1.21	1.00	0.88	0.77	
13 Multisite coordination	1.33	1.15	1.00	0.90	0.80	
14 Tool support	1.34	1.16	1.00	0.85	0.73	

SO, WE MADE APPLYING SIZE DRIVER PROPERTIES EASY AND WE  
AUTOMATED THE COUNTING PROCESS!

BUT WHAT DO YOU COUNT?



# UPDATING COSYSMO SIZE DRIVER COUNTING RULES FOR SYSML

- While the mechanics of counting size drivers in a SysML model proved almost trivial, the question remains “which ones do you count?”
- In collaboration with Dr. Ricardo Valerdi and Dr. Gan Wang, we revised the size driver counting rules to be specific for counting in a SysML model.
- We selected the model elements that most closely corresponded to the original COSYSMO size driver definitions.

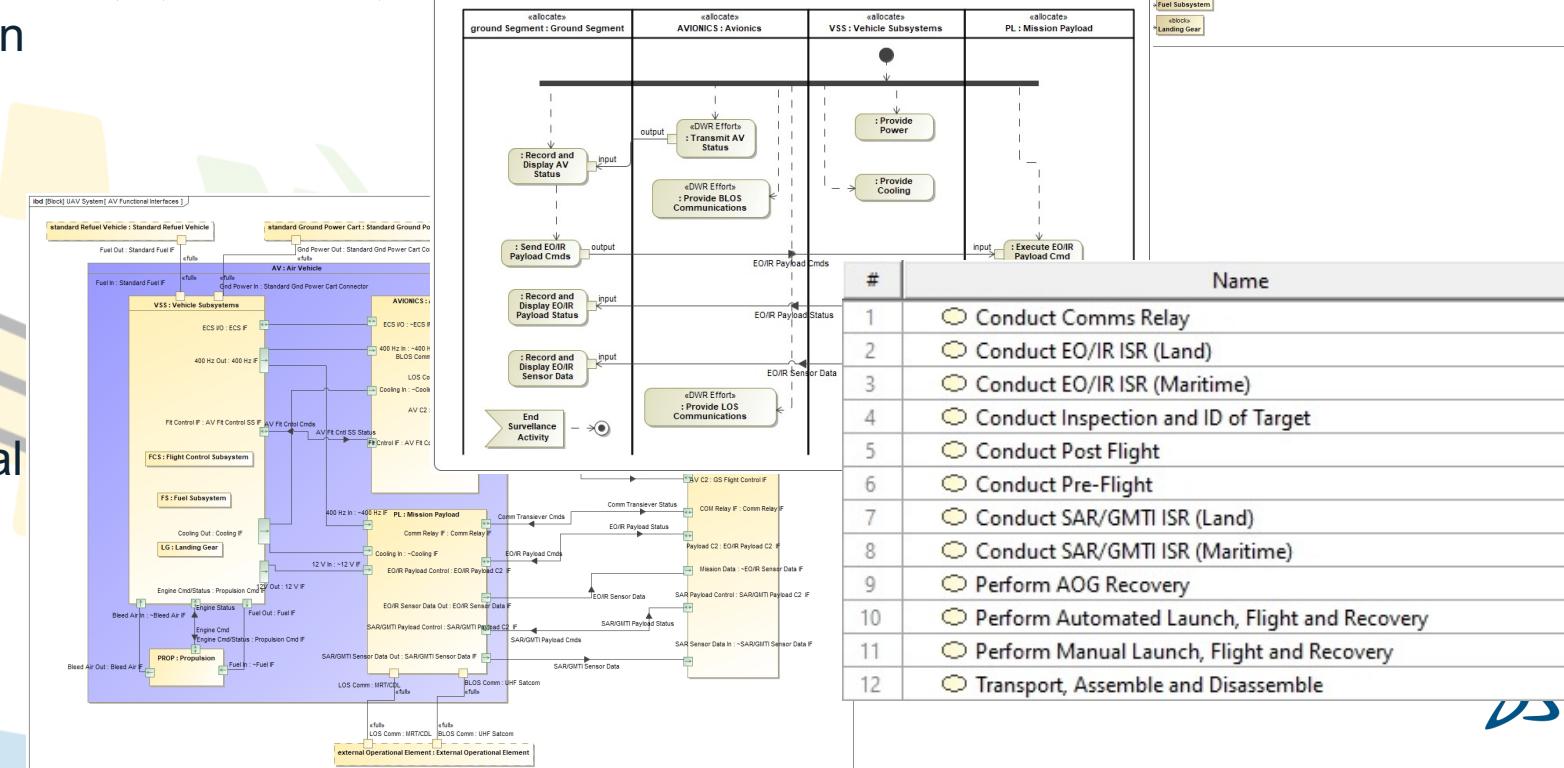
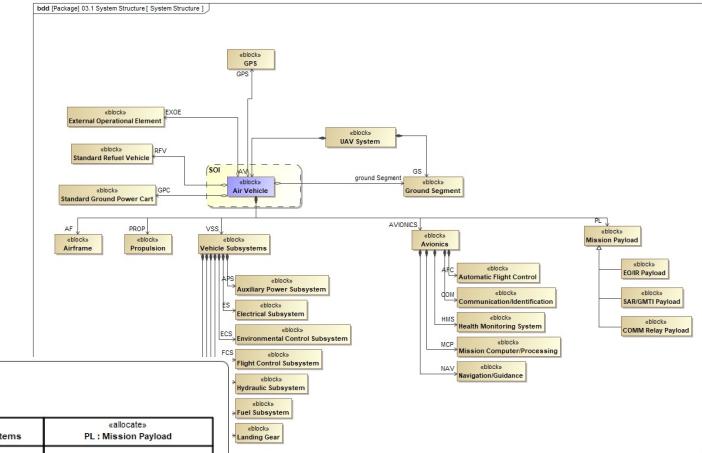
Criteria

Scope (optional): 1.1 Air Vehicle Spec

Context (optional):  Drag elements from the diagram

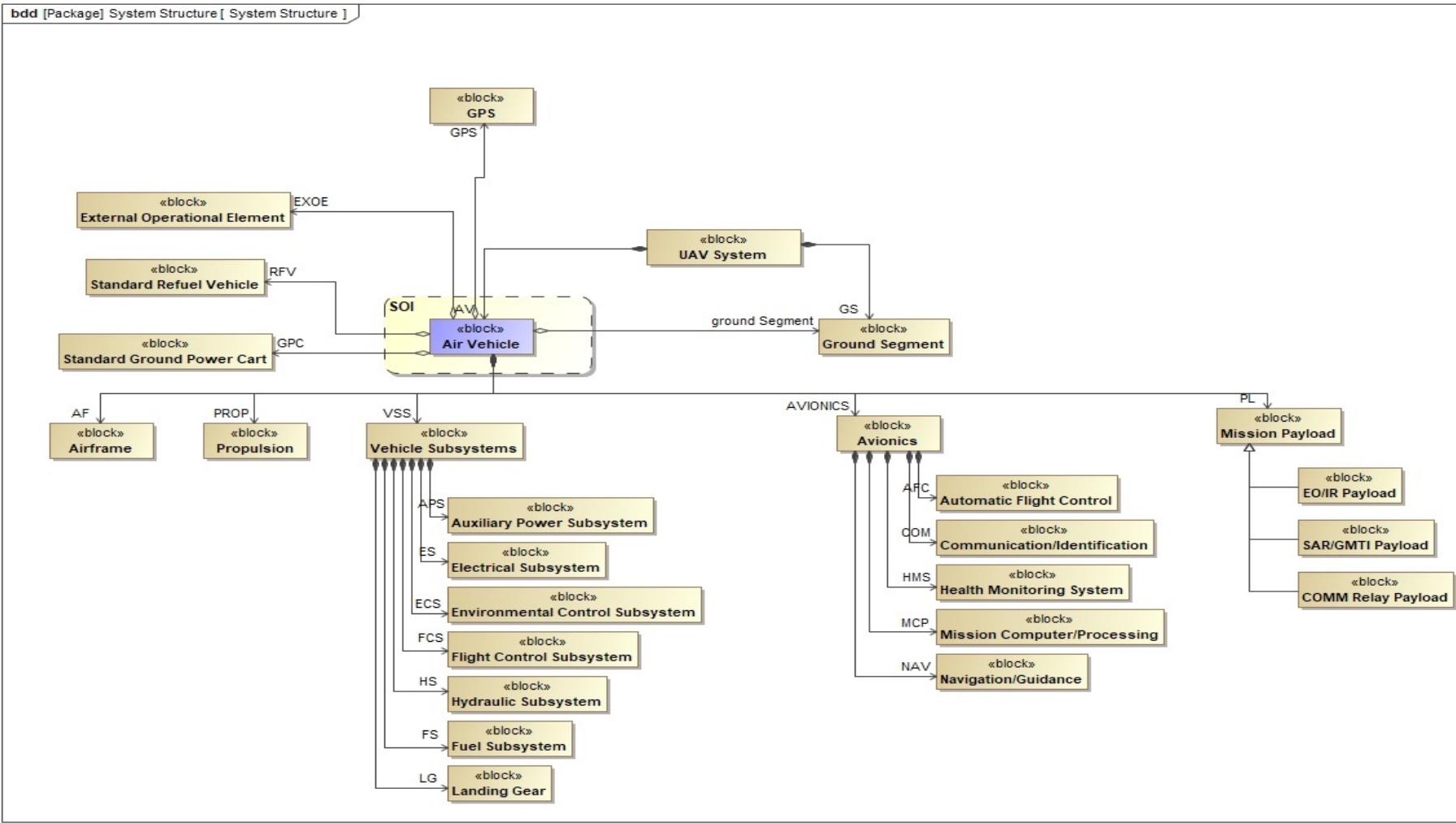
Filter:

#	△ Id	Name	Text	Verify Method	<input type="radio"/> DWR Selected	<input type="radio"/> DWR_Categ...	<input type="radio"/> DWR_Difficulty
1	AV-1	AV-1 System Requirements		<input type="checkbox"/> undefined			
2	AV-2	AV-2 System Component Descriptions		<input type="checkbox"/> undefined			
3	AV-2.1	AV-2.1 SAR/GMTI Capability		<input checked="" type="checkbox"/> true	Adapted	Difficult	
4	AV-2.2	AV-2.2 Communications Relay Capability	LOS and BLOS command and control links shall (1) contain a primary and a secondary link.	<input checked="" type="checkbox"/> true	Adopted	Nominal	
5	AV-2.4	AV-2.4 LOS and BLOS		<input type="checkbox"/> undefined	Managed	Nominal	
6	AV-2.5	AV-2.5 EO/IR Capability	The EO/IR payload shall achieve a daylight NIIRS of 7.2 and a nighttime NIIRS of 5.2.	<input type="checkbox"/> undefined			
7	AV-2.5.1	AV-2.5.1 EO/IR NIIRS	The EO/IR payload shall be able to detect a target location to the users with a Target Location Error (TLE) of less than or equal to 25 meters (m) Circular Error Probable (CEP) at 3-5 km slant range.	<input type="checkbox"/> undefined			
8	AV-2.5.2	AV-2.5.2 EO/IR Geolocation	Analysis	<input checked="" type="checkbox"/> true	Managed	Nominal	
9	AV-2.5.3	AV-2.5.3 EO/IR Search	The EO/IR payload shall be able to detect a 10 m object at a range of 5 km.	<input checked="" type="checkbox"/> true	Managed	Nominal	
10	AV-2.5.4	AV-2.5.4 EO/IR Track	The EO/IR payload shall be capable of automatic tracking of a selected target.	<input checked="" type="checkbox"/> true	Managed	Nominal	
11	AV-2.5.5	AV-2.5.5 EO/IR Manual Control	The EO/IR payload shall provide manual zoom azimuth control.	<input type="checkbox"/> undefined			
12	AV-2.5.6	AV-2.5.6 EO/IR Laser Illumination and Ranging	The EO/IR payload shall provide illumination and ranging.	<input type="checkbox"/> undefined			



# SAMPLE SYSTEM MODEL

The system of interest is the Air Vehicle segment of a larger UAV system.



# COUNTING SIZE DRIVERS IN SYSML

- The paper provides full description of SysML size driver counting rules and required model content:
  - Requirements - Requirements in the Systems Specification Package of the SOI.
  - System Interfaces - Connectors between the SOI and External Systems and between the Level 1 Subsystems in the System Internal Block Diagram.
  - Algorithms - Activities in Level 1 Subsystem Functions that will require development or modification of algorithms.
  - Operational Scenarios - Operational scenarios in CONOPS documents, enterprise architecture operational views, etc. (Create Use Cases as proxies for the operational scenarios.)

Criteria

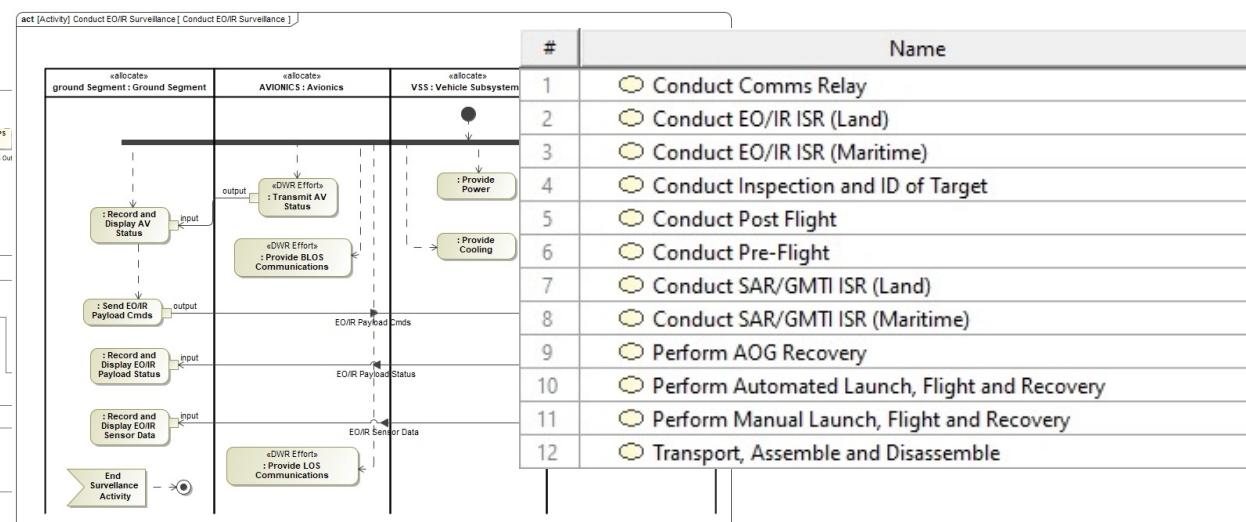
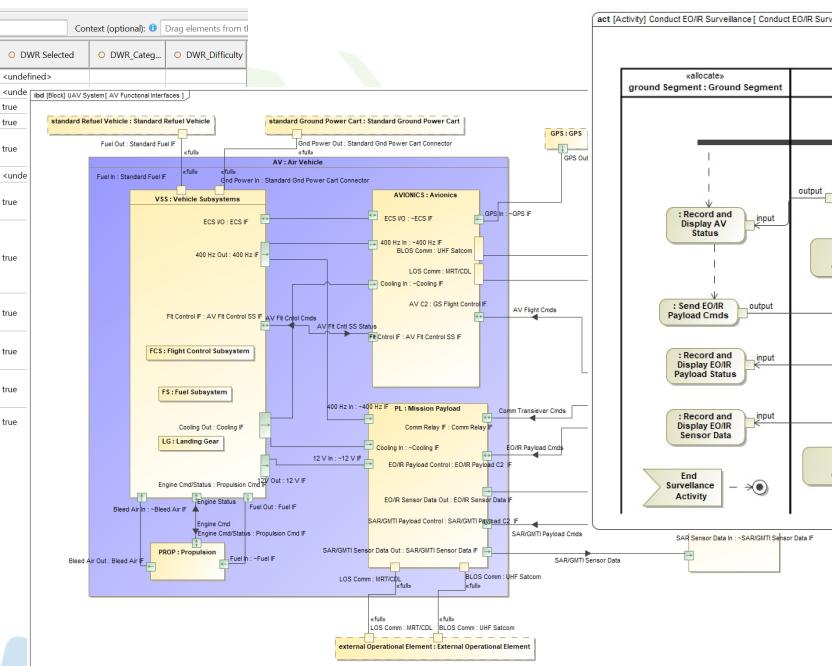
Scope (optional): 1.1 Air Vehicle Spec

Context (optional):

Verify Method: DWR Selected, DWR\_Categ., DWR\_Difficulty

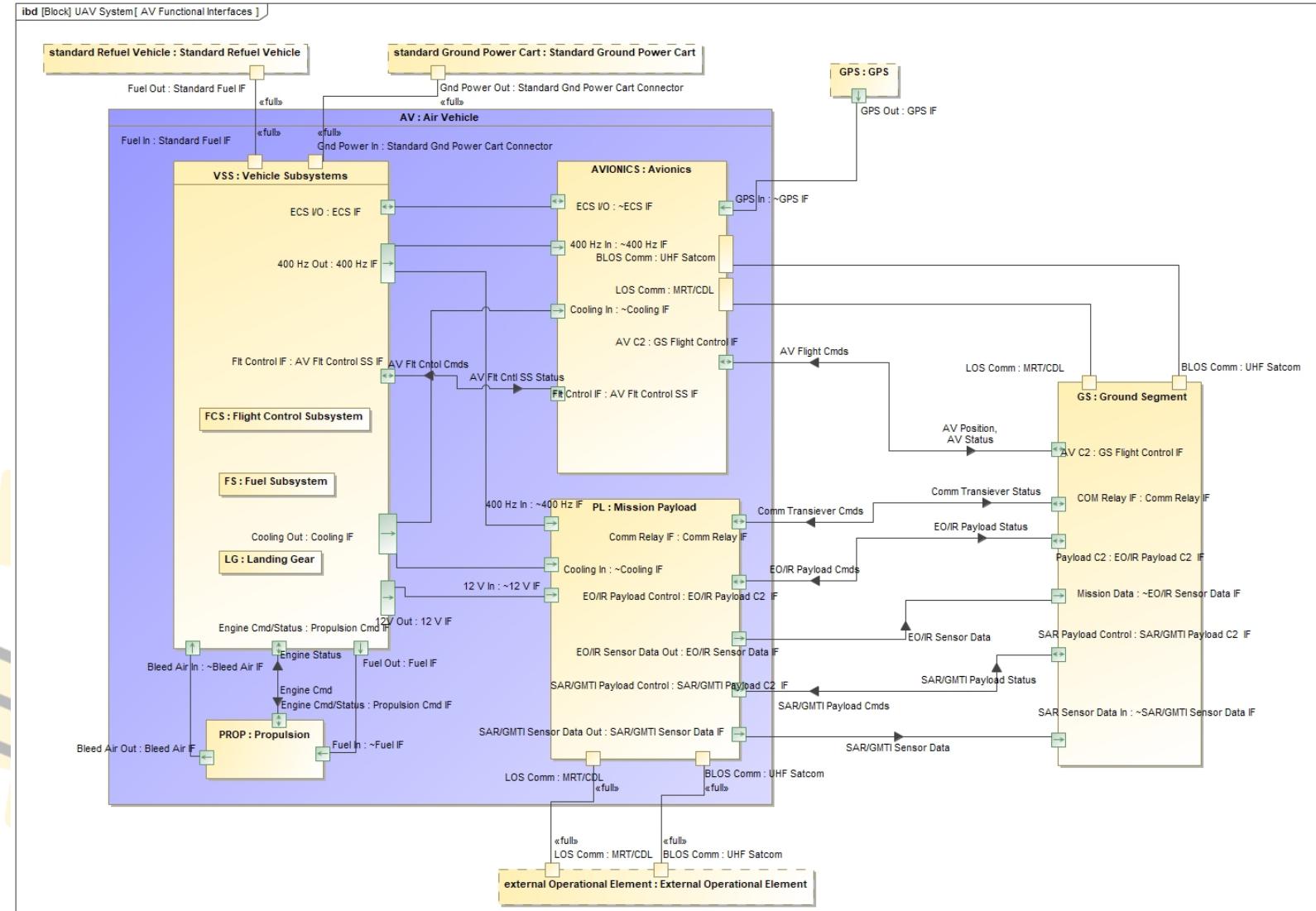
Criteria Table:

#	△ Id	Name	Text	Verify Method
1	AV-1	AV-1 System Requirements		▪ undefined
2	AV-2	AV-2 System Component Descriptions		▪ undefined
3	AV-2.1	AV-2.1 SAR/GMTI Capability		✓ true
4	AV-2.2	AV-2.2 Communications Relay Capability		✓ true
5	AV-2.4	AV-2.4 LOS and BLOS	LOS and BLOS command and control links shall (T) contain a primary and a secondary link.	Demonstrat✓ true
6	AV-2.5	AV-2.5 EO/IR Capability		▪ unde
7	AV-2.5.1	AV-2.5.1 EO/IR NIIRS	The EO/IR payload shall achieve a daylight NIIRS of 7.2 and a nighttime NIIRS of 5.2.	Demonstrat✓ true
8	AV-2.5.2	AV-2.5.2 EO/IR Geolocation	The EO/IR payload shall (T) provide a target location error (TLE) with a target location error (TLE) of less than or equal to 25 meters (m) Circular Error Probable (CEP) at 3-5 km slant range.	Analysis ✓ true
9	AV-2.5.3	AV-2.5.3 EO/IR Search	The EO/IR payload shall be able to detect a 10 m object at a range of 5 km.	Demonstrat✓ true
10	AV-2.5.4	AV-2.5.4 EO/IR Track	The EO/IR payload shall be capable of automatic tracking of a selected target.	Demonstrat✓ true
11	AV-2.5.5	AV-2.5.5 EO/IR Manual Control	The EO/IR payload shall provide manual zoom, elevation and azimuth control.	Demonstrat✓ true
12	AV-2.5.6	AV-2.5.6 EO/IR Laser Illumination and Ranging	The EO/IR payload shall provide laser illumination and laser rangefinding.	Demonstrat✓ true



# EXAMPLE: COUNTING SYSTEM INTERFACE (IF) IN SYSML

- Model all Level 1 internal and systems external interfaces with Ports, Interface Blocks and Connectors in the System Internal Block Diagram.
- Include Items Flows.



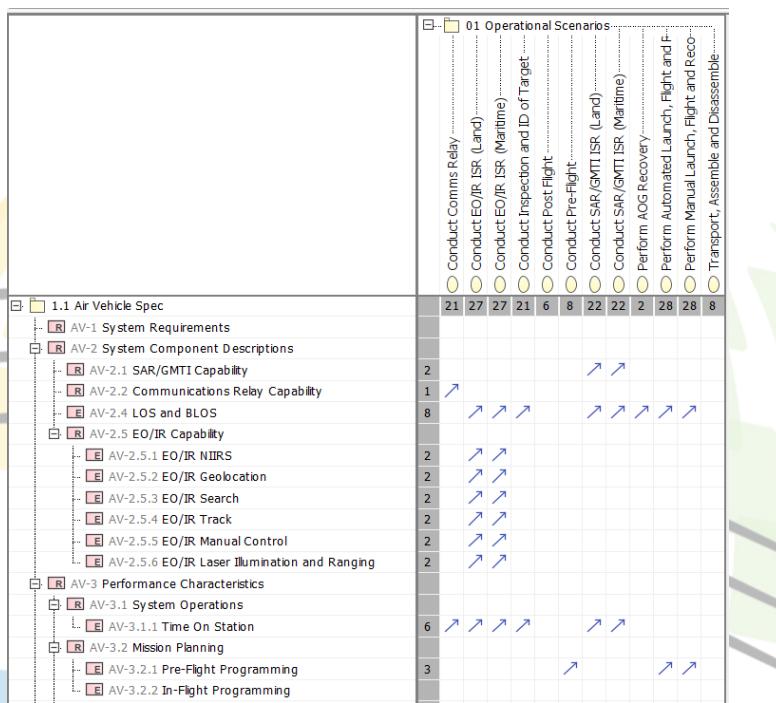
# EXAMPLE: COUNTING SYSTEM INTERFACE (IF) IN SYSML

- In CAMEO, create a White Box ICD Table for the SOI.
- Each row in the table represents a Connector.
- The Port Features column shows the properties of the Interface Block that types the Port at each end of the connector.
- Add New Custom Columns for the DWR, DFR and Difficulty stereotypes.
- Reuse Levels and Difficulty are derived from the Port Features (i.e. Interface Blocks).

#	Part A	Port A	△ Port A Features	Item Flow	Port B	Port B Features	Part B	○ DWR Selected	○ DWR_Category	○ DWR_Difficulty
1	AF : Airframe	Engine Mount: Engine Mounti...			Engine Mount: ~Engine Moun...		PROP : Propul...	<input type="checkbox"/> <undefined>		
2	PL : Mission Payload	Payload Mount : ~Payload Mo...			Payload Mount : Payload Mou...		PROP : Propul...	<input type="checkbox"/> <undefined>		
3	VSS : Vehicle Subsystems	VSS Mount : ~VSS Mounting P...			VSS Mount : VSS Mounting Pr...		AF : Airframe	<input type="checkbox"/> <undefined>		
4	VSS : Vehicle Subsystems	inout ECS I/O : ECS IF	<input type="checkbox"/> F in ECS Status <input type="checkbox"/> F out ECS Cmd		inout ECS I/O : ~ECS IF	<input type="checkbox"/> F out ECS Status : AV Flt Cntl SS St <input type="checkbox"/> F in ECS Cmds : Flight Control Cm	AVIONICS : A...	<input checked="" type="checkbox"/> true	Modified	Nominal
5	VSS : Vehicle Subsystems	inout Flt Control IF : AV Flt Con...	<input type="checkbox"/> F inout AV Flt	<input checked="" type="checkbox"/> AV Flt Cn <input checked="" type="checkbox"/> AV Flt Cn	inout Flt Cntrol IF : AV Flt Cont...	<input type="checkbox"/> F inout AV Flight Cmds and Status	AVIONICS : A...	<input checked="" type="checkbox"/> true	Modified	Difficult
6	VSS : Vehicle Subsystems	inout Engine Cmd/Status : Pro...	<input type="checkbox"/> F inout Engin	<input checked="" type="checkbox"/> Engine Cn <input checked="" type="checkbox"/> Engine St	inout Engine Cmd/Status : Pro...	<input type="checkbox"/> F inout Engine Commands: Engin	PROP : Propul...	<input checked="" type="checkbox"/> true	Implemented	Nominal
7	VSS : Vehicle Subsystems	out 12V Out : 12 V IF	<input type="checkbox"/> F out 12 V Cu		in 12 V In : ~12 V IF	<input type="checkbox"/> F in 12 V Current : 12 V DC Current	PL: Mission P...	<input type="checkbox"/> false		
8	VSS : Vehicle Subsystems	out 400 Hz Out : 400 Hz IF	<input type="checkbox"/> F out 400 Hz I		in 400 Hz In : ~400 Hz IF	<input type="checkbox"/> F in 400 Hz Current : 400 Hz AC Cu	AVIONICS : A...	<input checked="" type="checkbox"/> true	Adopted	Easy
9	VSS : Vehicle Subsystems	out 400 Hz Out : 400 Hz IF	<input type="checkbox"/> F out 400 Hz I		in 400 Hz In : ~400 Hz IF	<input type="checkbox"/> F in 400 Hz Current : 400 Hz AC C	PL: Mission P...	<input checked="" type="checkbox"/> true	Adopted	Easy
10	PROP : Propulsion	out Bleed Air Out : Bleed Air IF	<input type="checkbox"/> F out Cooling		in Bleed Air In : ~Bleed Air IF	<input type="checkbox"/> F in Cooling Air : Bleed Air	VSS : Vehicle ...	<input type="checkbox"/> <undefined>		
11	VSS : Vehicle Subsystems	out Cooling Out : Cooling IF	<input type="checkbox"/> F out Cooling		in Cooling In : ~Cooling IF	<input type="checkbox"/> F in Cooling Air : Bleed Air	AVIONICS : A...	<input type="checkbox"/> <undefined>		
12	VSS : Vehicle Subsystems	out Cooling Out : Cooling IF	<input type="checkbox"/> F out Cooling		in Cooling In : ~Cooling IF	<input type="checkbox"/> F in Cooling Air : Bleed Air	PL: Mission P...	<input type="checkbox"/> <undefined>		
13	VSS : Vehicle Subsystems	out Fuel Out : Fuel IF	<input type="checkbox"/> F out Fuel : JP		in Fuel In : ~Fuel IF	<input type="checkbox"/> F in Fuel : JP4	PROP : Propul...	<input type="checkbox"/> <undefined>		

# USING ADVANCED QUERIES TO ENSURE ESTIMATE QUALITY

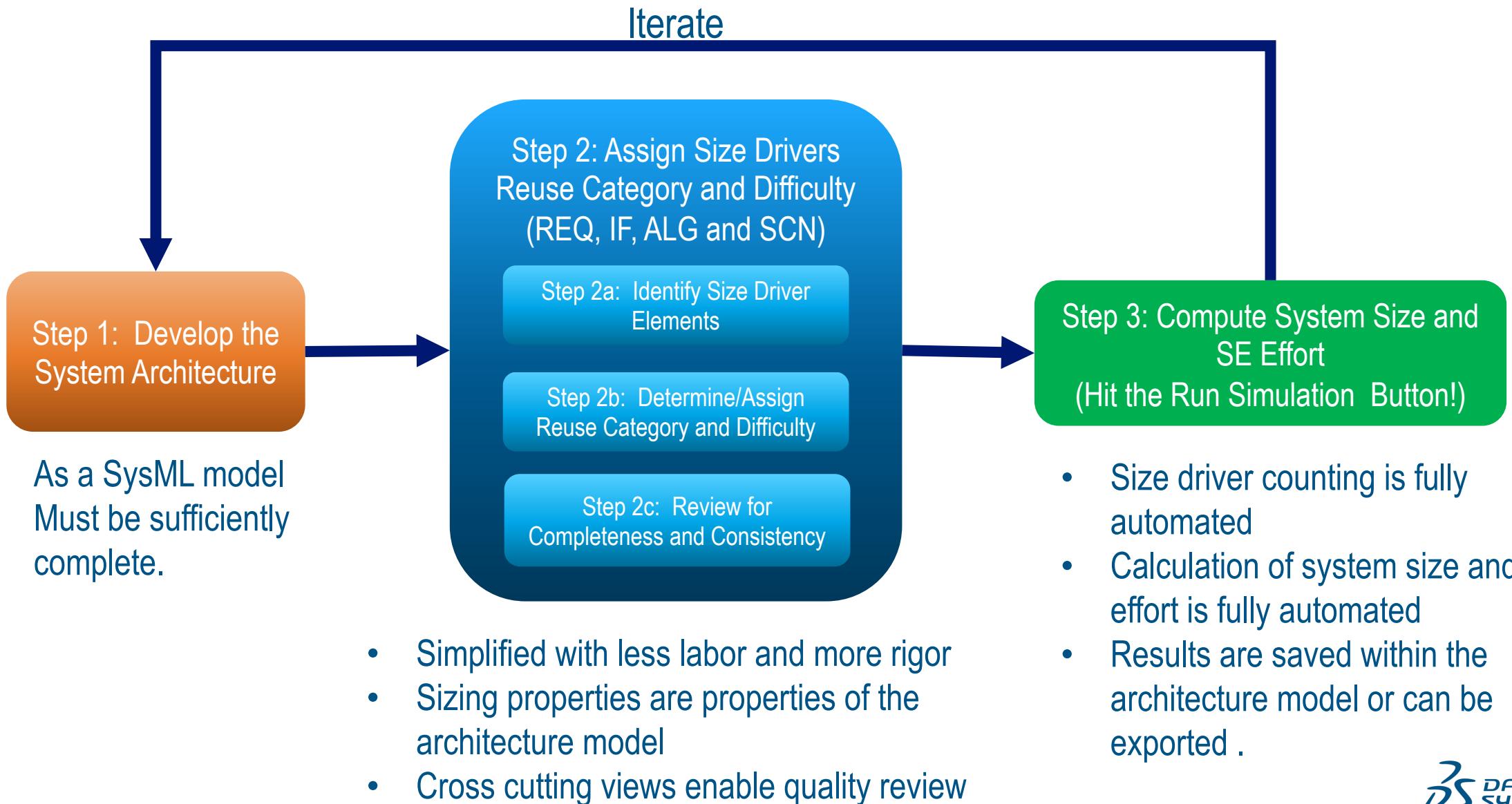
- While not part of the original COSYSMO counting rules, there are clear relationships between each of the size drivers.
- There are two fundamental relationships to review:
  - Traceability (Completeness and Correctness)
  - Consistency of DWR, DFR, and Difficulty assignments



Criteria		Element Type: Activity	Scope (optional): 03.2 Activities				
#	Name	Satisfies	ALG DWR Category	Req DWR Category	ALG DWR Difficulty	Req DWR Difficulty	
4	Conduct Pre-Flight						
5	Conduct SAR Surveillance						
6	Detect EO/IR Target	AV-2.5.3 EO/IR Search AV-2.5.1 EO/IR NIIRS AV-19 Payload Options	Implemented	Managed New	Nominal Nominal	Nominal Difficult	
7	Detect GMTI Target	AV-2.1 SAR/GMTI Capability AV-19 Payload Options		Adapted New	Difficult	Difficult	
8	Determine GMTI Target Velocity and Direction	AV-2.1 SAR/GMTI Capability AV-19 Payload Options		Adapted New	Difficult	Difficult	
9	Execute EO/IR Payload Cmd	AV-19 Payload Options AV-2.5.5 EO/IR Manual Control		New Managed	Difficult Nominal	Difficult Nominal	
10	Execute GCS Flight Commands	AV-3.3.2 Takeoff Abort AV-19 Payload Options	Adopted	New	Difficult	Difficult	
11	Execute GMTI PL Cmds	AV-19 Payload Options		New	Difficult	Difficult	

The table above shows DWR and Difficulty of Algorithms compared to the Requirements they Satisfy.

# COSYSMO COST ESTIMATION PROCESS WITH MBSE



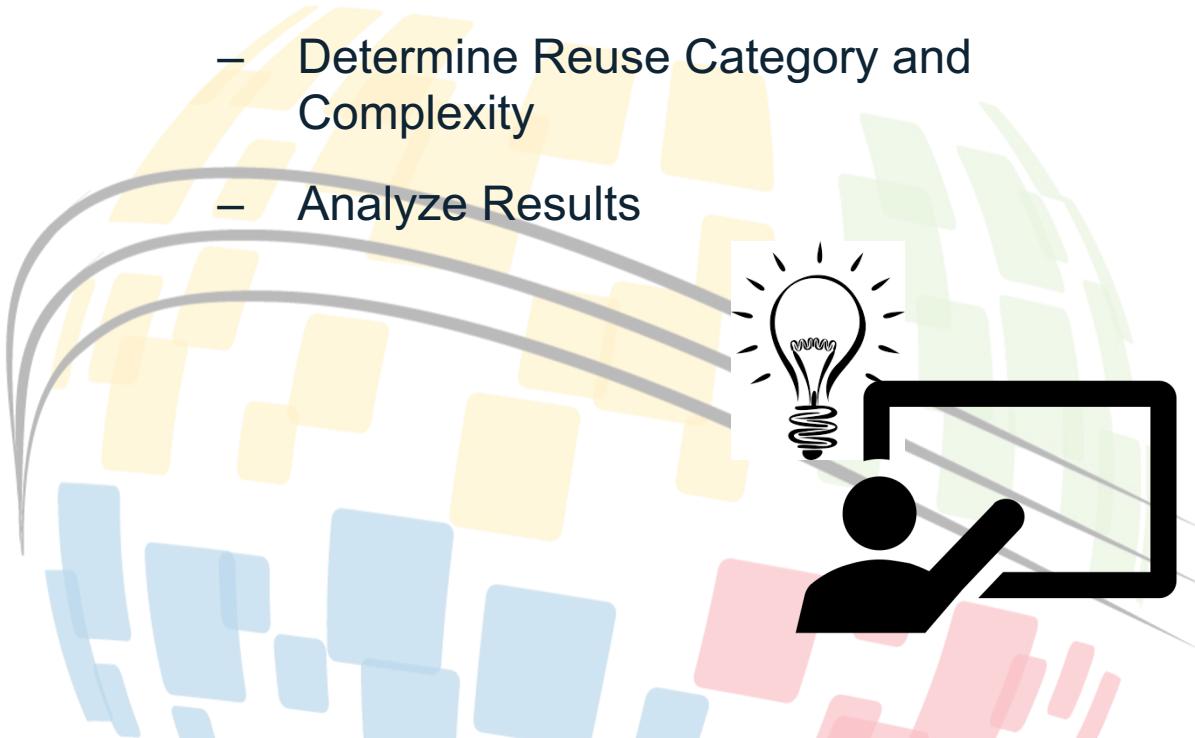
# COSYSMO with MBSE simplifies the labor intensive tasks and lets the Systems Engineer focus on the important things!

- **Tasks for the Systems Engineer**

- Design the System
- Identify Sizing Elements
- Determine Reuse Category and Complexity
- Analyze Results

- **Tasks for MSBE Toolset**

- Maintain Sizing Data as part of the System Architecture
- Provide efficient User Interface to apply Sizing Parameters
- Automates Counting
- Calculates System Size and SE Effort
- Provide Cross Cutting Views for Analysis



# SUMMARY, CONCLUSION AND NEXT STEPS

- The Tool and the Method
  - The COSYSMO profile simplifies the assignment of size driver properties and automates the counting and calculations.
  - The rigor and structure of SysML, along with sound modeling practices, enable a more repeatable counting process.
  - The semantic relationships between model elements provides strong traceability between size driver elements.
  - Advanced queries in tables and matrices enable a review of completeness, correctness and consistency of size driver assignments.
- The SE Process
  - The convergence of COSYSMO with MBSE makes the sizing activity a responsibility of the system engineer/architect.
  - The size driver properties become properties of the architecture model as opposed to data maintained separately and disconnected from the system architecture.
  - Requires sufficient model content and fidelity and some specific modeling patterns.
  - Enables the project to perform quick cost trades earlier in the lifecycle.
  - The ability to access the sizing data for each size driver, for each DWR/DFR category, allows the cost analyst to review and validate the size estimate.
- Next Steps
  - Developing cost model calibration data for SysML Models
  - Industry use and feedback to validate new counting rules
  - Case Study with an Actual SOI

# Questions?



# About the Authors



Barry Papke. Barry is the MBSE Special Project Lead for CATIA Magic. He has thirty-five years of systems engineering and operations analysis experience in the aerospace and defense industry across the entire systems engineering life cycle from concept development through integration, test and post-delivery support. Throughout his career, he has been actively involved in application of model-based methods including requirements management, enterprise architecture, cost estimation, system design, and operations analysis. He is a member of the INCOSE Agile and Security Working Groups and the MBSE Initiative.



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