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Dublin, Ireland
July 2 - 6, 2024



Jul 5, 2024: 09:00-09:40 AM (Session 10.5.1: Modular Open Systems Approach [MOSA])

Towards a Reusable Model-Based Systems Integration [MBSI] Framework

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2-6 July 2024

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AGENDA

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration [MBSI] Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

MOTIVATION

IS2020 PAPER: CONSIDERATIONS FOR FUTURE WORK



30th Annual INCOS
International Symposium
Virtual Event
July 20 - 22, 2020

Case Study: Achieving System Integration through Interoperability in a large System of Systems (SoS)

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Abstract. This paper provides a case study on system of systems engineering (SoSE) performed in a multi-billion-dollar program – the California High-Speed Rail System – viewed from the systems integration perspective. The paper discusses why the subject program of project (PoP) can be viewed as a system of systems (SoS), identifies the SoSE challenges faced, describes the SoSE activities performed, and summarizes the achieved outcomes and conclusions as of today.

Specific SoSE challenges discussed include SoS authority, leadership, architecting, collaborative integration, and emergence. The paper reviews how decision-making in independently operated and managed constituent systems (projects) resulted in unanticipated SoS emergent behavior which is one of the key challenges in the engineering of SoS.

The paper further discusses the performed SoSE activities, including an international best practice review, the tailoring of SoSE to the specific SoSE challenges, and provides examples where SoS principles are being applied to perform successful SoS integration.

Brief Introduction: System of Systems

A system of systems is a system-of-interest (SOI) whose elements are themselves systems. A SoS brings together a set of systems for a task that none of the systems can accomplish on its own. Each constituent system (CS) retains its own management, goals, and resources while coordinating within the SoS and adapting to meet SoS goals (ISO/IEC/IEEE 15288, 2015).

SoS Characteristics: SoS are characterized by **managerial and operational independence** of the constituent systems, which in many cases were developed and continue to support original identified users of the constituent concurrently with users of the overall SoS. In other contexts, the constituent systems are developed and operated to support the overall SoS.

interface standards (Figure 14) into early civil works contracts, thereby interoperable constituent systems / contracts.

- **SoS Autonomy, Emergence & Constituent Systems:** Considered the design-build project delivery methods that encourages innovation within constituent systems (contracts), but may result in unanticipated and/or undesirable SoS behavior. The clear communication of the interoperable interfaces (Figure 15) compliant implementation of interoperable interface standards (Figure 16 & 17) numerous changes by contractors during design and construction.
- **SoS Integration:** CHSRS systems integration is anticipated to benefit significant interoperable interfaces and contracts (Figure 18), avoiding the late discovery of interfaces and the non-compatibility of existing interfaces many programs suffer when relying on the traditional systems integration approach.

Conclusion

As mentioned in the SoS introduction, identifying and addressing unanticipated and/or unemergent behavior is a frequent challenge in the engineering of SoS.

In summary, the prevailing design-build project delivery methods encourages innovation (changes or emergent behavior) within a constituent system. As contracts are issued independently, there are no incentives to consider their roles in the SoS. Additionally, the traditional integration approach relies on coordinating active contracts once they have been issued, the provision of specific interface definitions, leading potentially to late integration challenges.

In conclusion, it can be confidently stated that the tailored CHSRS systems integration approach addresses the challenges described above. Key interfaces are proactively identified and using industry accepted interoperable standards. Contractors can take full advantage of innovative solutions as long as they can demonstrate conformance to the identified interoperable interface standards. The tailored CHSRS systems integration approach creates modern interoperable constituent systems that can be efficiently integrated into a SoS, such as achieving system integration through interoperability.

Considerations for Future Work

Based on valuable peer review feedback, the following topics are being considered in INCOSE papers and publications:

- **Lessons Learned:** As of today, only CHSRS Civil Works contracts have been completed. Lessons learned from the trainset, and the discussion on the integration approach.
- **System Integration Framework:** Use this case study to define a System Integration Framework that other projects could follow. The use of agile processes as well as

SYSTEMS INTEGRATION FRAMEWORK THAT OTHERS COULD FOLLOW

CHSRS External: Figure 2 presents the CHSRS as a constituent system within a larger SoS. Other interfacing constituent systems and organizations included, but are not limited to adjacent railroads and highways requiring intrusion detection and protection, utilities providing high-voltage power, potential interfaces with U.S. Geological Survey (USGS) for the earthquake hazards program, shared track operation in existing rail corridors in the San Francisco area (Caltrain) and Los Angeles (Metrolink), irrigation canals, local counties, cities, businesses, property owners, and many more.



Figure 2. CHSRS as a Constituent System within a Larger SoS

CHSRS Program: Figure 3 presents a simplified life cycle view. The CHSRS program will be procured (acquired) in form of several projects (supplied). Each project is managed and operated independently by a design-build-operate-maintain (DBOM) contractor. Additionally, each contractor is managed by a construction manager (CM) and operated project and program engineers (ICE/ISE), reporting both to a local and program level.

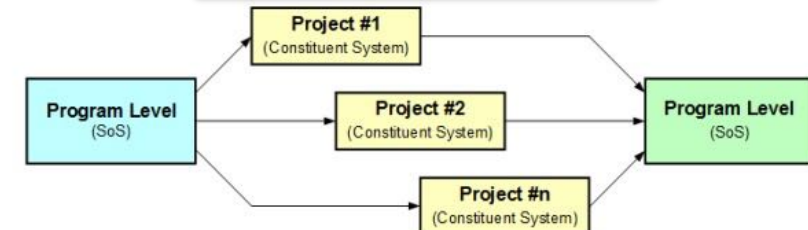


Figure 3. CHSRS as a Program (SoS) of Projects (Constituent Systems)

CHSRS Program Organization: The California High-Speed Rail Authority organization can be characterized as a matrix organization, with three main vertical **program delivery pillars** (strategic delivery, infrastructure delivery, rail systems delivery), supported by horizontal **functional support groups** and **executive support functions**, as presented in Figure 4 below. The **network integration** section, part of the rail systems delivery branch, is led by the deputy director of network integration and program compliance responsible for managing the process for integrating all aspects of the rail system and for developing and retaining documentation related to systems engineering, including requirements management, configuration management, interface management, RAM (reliability, availability, maintainability), and system certification (CHSRS, 2018). The **systems integration** lead position reports to deputy director of network integration and program compliance (CHSRS, 2018).

MOTIVATION

IS2020 PAPER: CONSIDERATIONS FOR FUTURE WORK (CONT'D)

SYSTEM OF SYSTEMS (SoS) CHALLENGES

deliverables include interface coordination work (e.g., interface agreements), coordination of interface demarcation drawings)

Description of the Challenges Facing the CHSRS

Using the background information provided above, this section provides a description of the systems integration challenges the CHSRS has faced, provided from the perspective of the program manager.

SoS Authority: While the CHSRS as a whole could be classified as a system of systems, the CHSRS has a rather limited power and authority to coordinate the three active CHSRS civil works contracts (constituent systems) and the infrastructure delivery branch, not the rail systems branch which oversees the three design and construction managers (PCM).

SoS Architecture & Leadership: There is a lack of recognition in the industry that the program manager becomes the de-facto SoS architect. Figure 5. By decomposing a program into contract/procurement packages, the program manager effectively creates large-scale constituent systems with numerous interfaces that require careful management throughout the life cycle as a pre-requisite for (program) integration at a later stage.

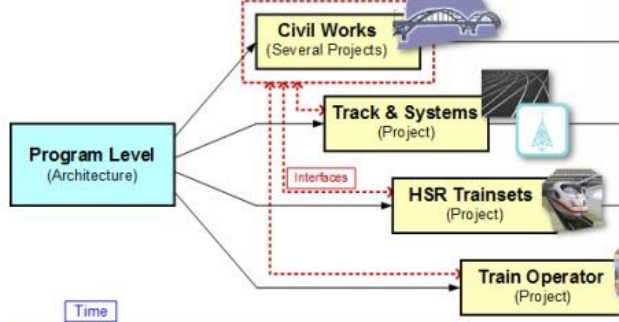


Figure 5. Program Manager as the SoS Architect

SoS Collaboration & Integration: While the traditional U.S. infrastructure approach to systems integration may work in a single project, all interfacing parties present and available for coordination, the same approach is not available in a SoS/program environment such as the CHSRS, if one of the projects/contracts are not available for coordination. For example, the CHSRS tunnel cross-section, highlighting several key interfaces between the infrastructure and the rolling stock.

takes a long time, a tunnel contract would be issued years before the rolling stock is delivered, creating a significant challenge in identifying the applicable requirements, and interface implementation in the early civil works phase.

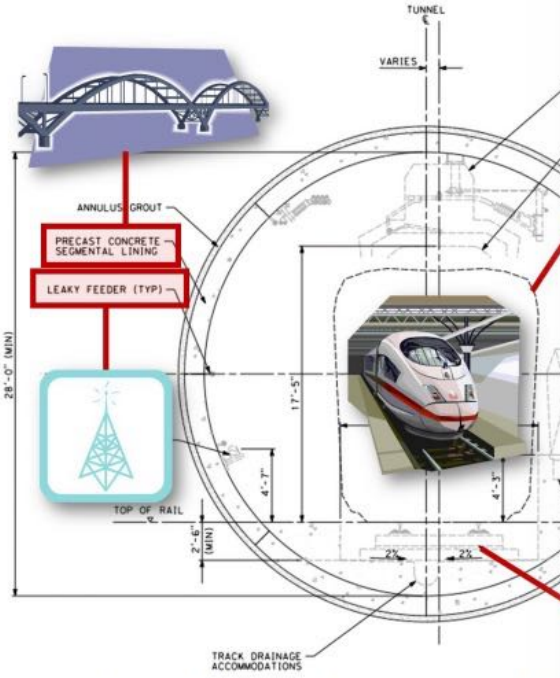


Figure 6. SoS Interface Requirements for Civil Works

The problem is exacerbated due to the fact that owners have not provided implementation (here interface) details out of concern of providing inconsistent information to the contractors, possibly resulting in conflicting orders. Consequently, contracts often lack interface specifics such as dimensions and/or interface requirements. As contracts are commonly fixed-price contracts, there is also a significant risk that any changes during the project may be claimed as additional out-of-scope work.

SoS Autonomy & Emergence: As CHSRS contracts are implemented, there are no contractual relationships between each project delivery method, contractors are deliberately encouraged to meet the contract requirements. For example, the CHSRS civil works contract (bridge) for a specific track/guideway area, and the infrastructure contract (tunnel) for a specific track/guideway area, and the rolling stock contract (train) for a specific track/guideway area.

INTEROPERABLE INTERFACE SPECIFICATIONS

Technical specifications for interoperability (TSI) with the objective of providing a framework of mandatory TSIs, and of voluntary or (where necessary) standards with the purpose of ensuring interoperability on the European network.

For the purposes of the directive, the high-speed rail system was defined as a system of structural and operational HSR subsystems:

- **Structural subsystems:** (1) Infrastructure, (2) Energy, (3) Command & Control, (4) Signaling, and (5) Rolling stock (trainsets);
- **Operational subsystems:** (1) Maintenance, (2) Environment, and (3) Users.

Each TSI subsystem followed the same document structure/outline. The infrastructure subsystem, including the functional and technical specification provides an example of an interface between the infrastructure (INF) subsystems. The specific interface ensures that HSR trainsets can operate under bridges, and stay clear of any wayside structures. The infrastructure subsystem perspective (shown in red). Each subsystem interface requirements and implementation details (shown in blue). Reference to the interoperable interface standard (shown in green). The same interoperable interface standard applies to all types of interfaces, including data interfaces such as functional interfaces between the command, control and signaling (CCS) TSI and Rolling stock (RST) TSI.

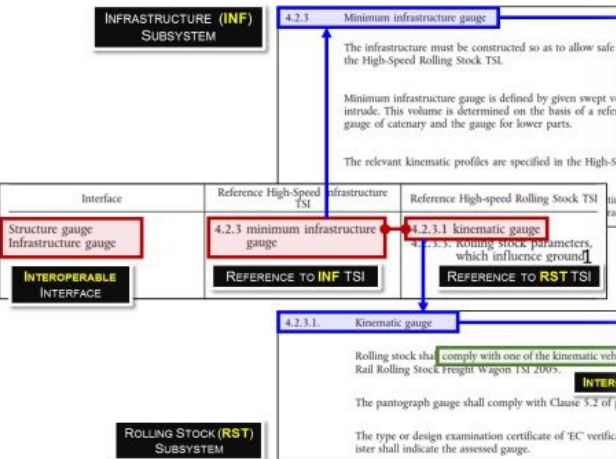


Figure 8. Technical Specifications for Interoperability (TSI)

CREATING INTEROPERABLE CONSTITUENT SYSTEMS

- **Step 1:** CHSRS program manager (SoS Architect) identifies key interfaces between the constituent systems.
- **Step 2:** HSR trainset subject matter expert (SME) identifies candidate interfaces.
- **Step 3:** HSR trainset SME determines interoperable interface requirements.
- **Step 4:** Civil works SME develops corresponding interoperable interface requirements.
- **Step 5:** Civil works contractor implements interoperable civil works interfaces.
- **Step 6:** HSR trainset contractor implements interoperable HSR trainset interfaces.
- **Step 7:** SoS system integrator (track & systems contractor) integrates the constituent systems (taking into service) the interoperable contracts.

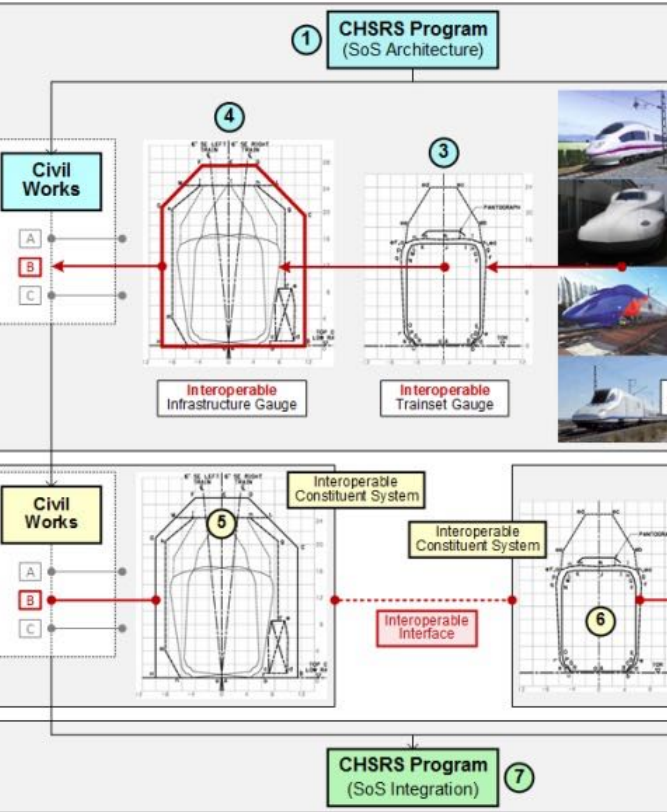


Figure 10. Creating Interoperable Constituent Systems

PROGRESS

❖ Motivation

❖ Background, Challenges & Objectives

- Large Scale Projects
- Common Contract Breakdown Structures
- Interface & Integration Challenges

❖ Model-Based Systems Integration Framework

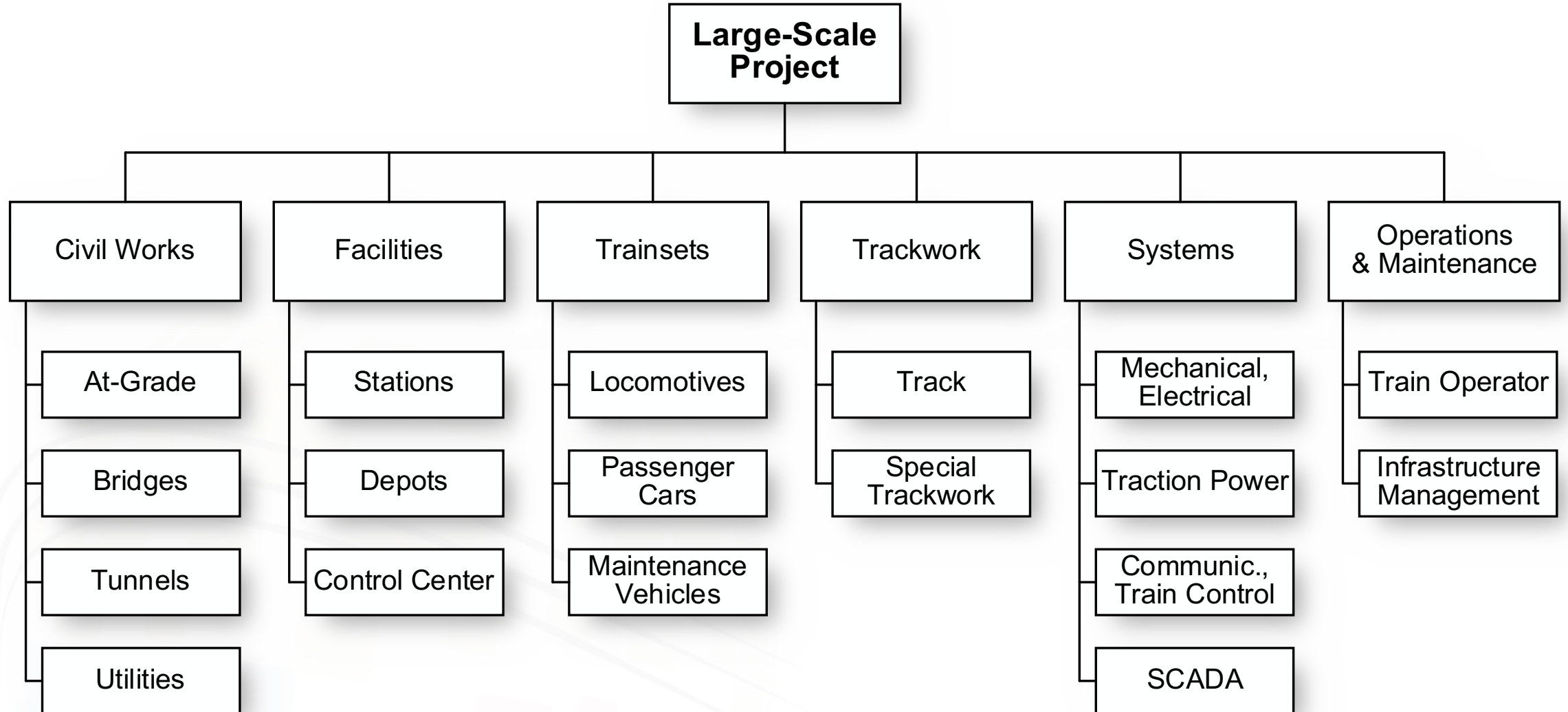
❖ MBSI Framework Development

❖ MBSI Framework Use

❖ Summary & Conclusion

BACKGROUND, CHALLENGES & OBJECTIVES

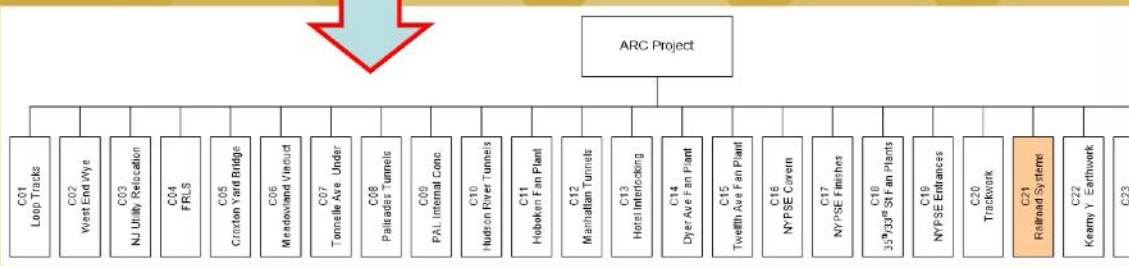
LARGE-SCALE PROJECTS: INDUSTRY TYPICAL **CONTRACT BREAKDOWN STRUCTURE**



BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: EXAMPLE – ARC TUNNEL PROJECT

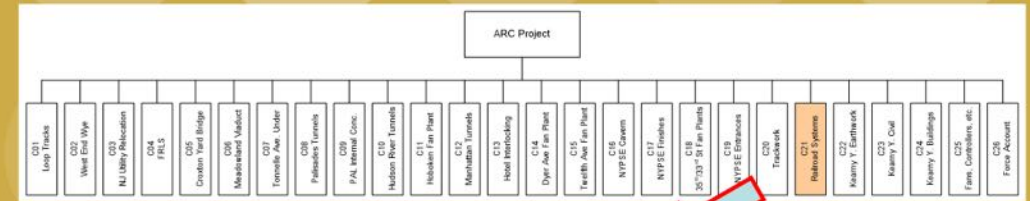
System Engineering ARC Project – Contract Packages



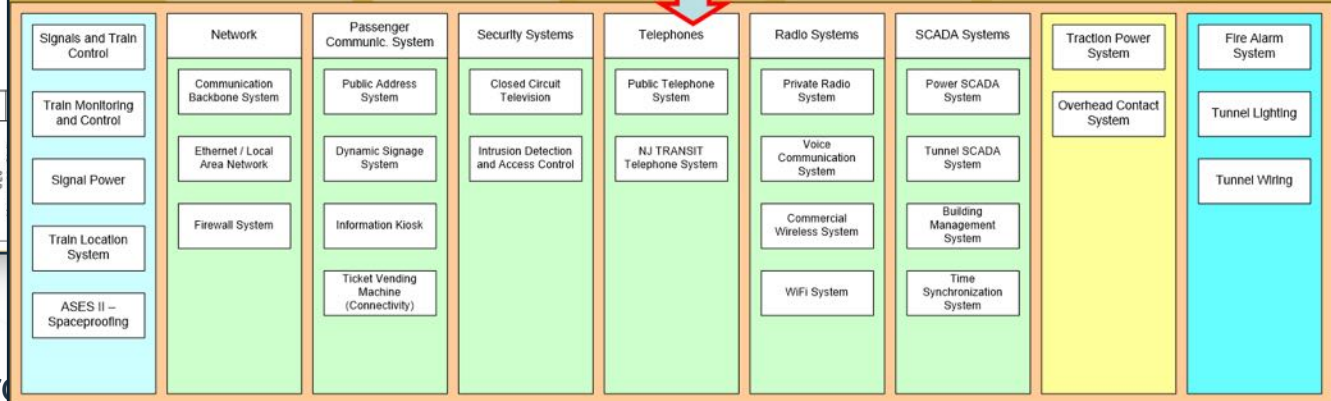
25 PROCUREMENT CONTRACTS

Source: Hoehne, O., 2009, "Access to the Region's Core (ARC) Tunnel, Scaling Systems Engineering to Transit Challenges", 2009 APTA Rail Conference, Chicago, IL, 2009

System Engineering Railroad Systems Contract

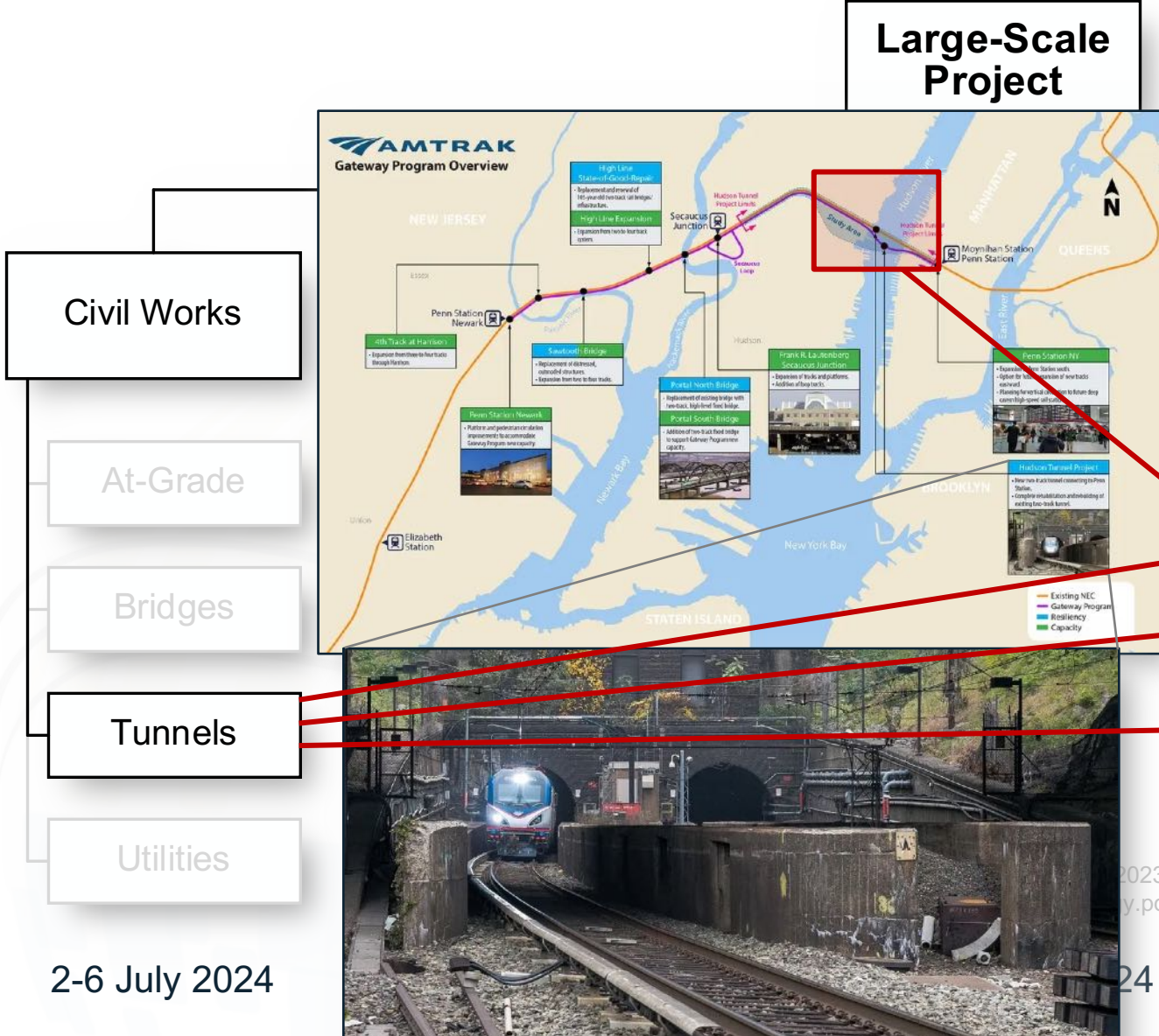


Thirty (30) RRS sub-systems



BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: **EXAMPLE – GATEWAY PROGRAM (NY/NJ)**



GATEWAY DEVELOPMENT COMMISSION ANNOUNCES IMPROVED CONTRACTING STRATEGY FOR HUDSON TUNNEL PROJECT TO ENSURE COMPETITIVE BIDDING POOL AND ADVANCE EARLY WORK

Approach Divides Tunneling Component of Hudson Tunnel Project into Four Packages, Including “Hudson River Ground Stabilization” Early Work

Newark/New York – The Gateway Development Commission today announced that it has revised its procurement strategy to build the Hudson Tunnel Project, dividing the “Civil Works” construction of the new tunnel from the one package previously contemplated, to ensure there is a robust and competitive bidding pool for the project.

The Civil Works is the largest portion of the Hudson Tunnel Project. It encompasses the excavation and construction of a new tunnel under the Palisades in New Jersey and the Hudson River and connecting to Penn Station in Manhattan. This portion of the project alone consists of 2 tubes, each 2.4 miles long.

The Civil Works portion of the Hudson Tunnel Project will now be divided into four contract packages, rather than the one package previously contemplated, to ensure there is a robust and competitive bidding pool for the project.

Package 1A, the portion of the tunnel through the Palisades to the construction shaft in Hoboken, New Jersey, which will be delivered via Design-Bid-Build.

Package 1B, the section of the tunnel going through the Hudson River Park and connecting to the new construction shaft in Manhattan, which will be delivered via Design-Build;

and Package 1C, which includes the tunneling under the Hudson River from the new construction shaft in Hoboken to the new construction shaft in Manhattan, which will be delivered via Design-Bid-Build.

THREE DIFFERENT TUNNEL CONTRACTS

Packages 1A and 1B are scheduled to commence work in 2024 after a Full Funding Grant Agreement with the U.S. Department of Transportation’s Capital Investment Grants Program is signed by the FTA and GDC. Package 1C is scheduled to commence work in 2025.

In addition, the fourth contract package, **Contract Package EA1**, is an early work project which is expected to commence prior to the project’s full construction. This “Hudson River Ground Stabilization” package will reduce the risk of the full project by fortifying and stabilizing the river bottom on the New York side of the Hudson River. The work will create an improved condition in which to bore the new tunnel through the eastern portion of the Hudson River section of the project. The work will also comply with all environmental regulations to ensure the protection of the Hudson River.

BACKGROUND, CHALLENGES & OBJECTIVES

SoS COLLABORATION & INTEGRATION (EARLY INTERFACE NEEDS)

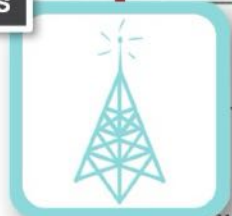


CIVIL WORKS



CURRENT NORTH RIVER TUNNELS

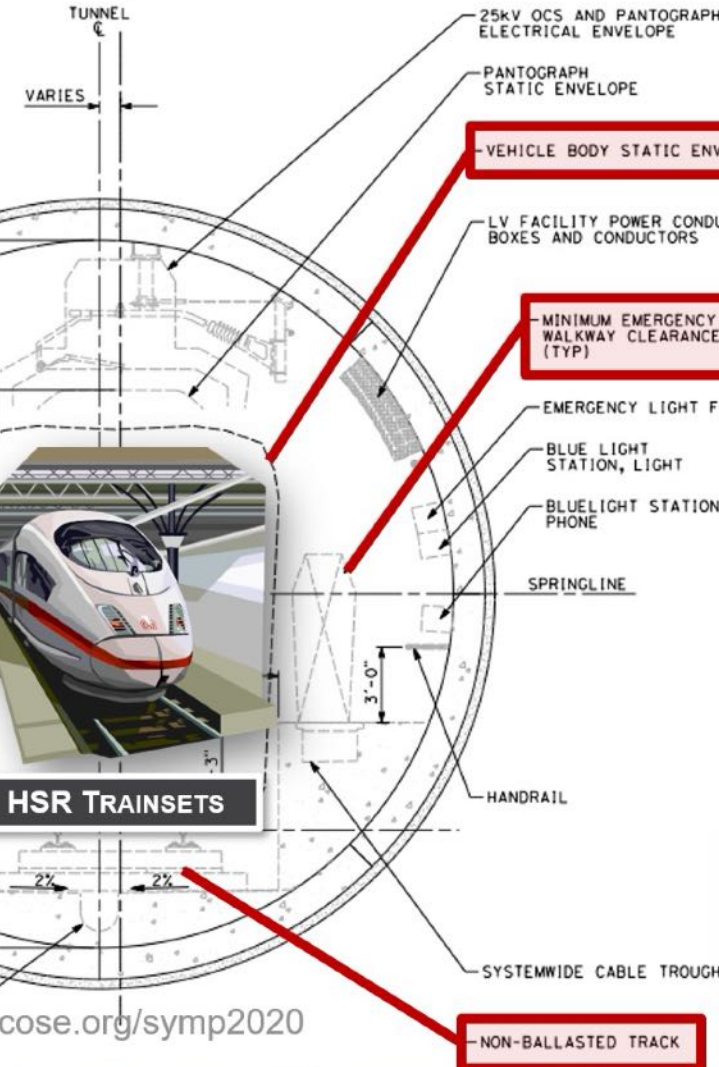
TRACK & SYSTEMS



INTERFACE REQUIREMENTS NEEDED FROM CONTRACTS NOT ISSUED YET

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TRACK DRAINAGE ACCOMMODATIONS



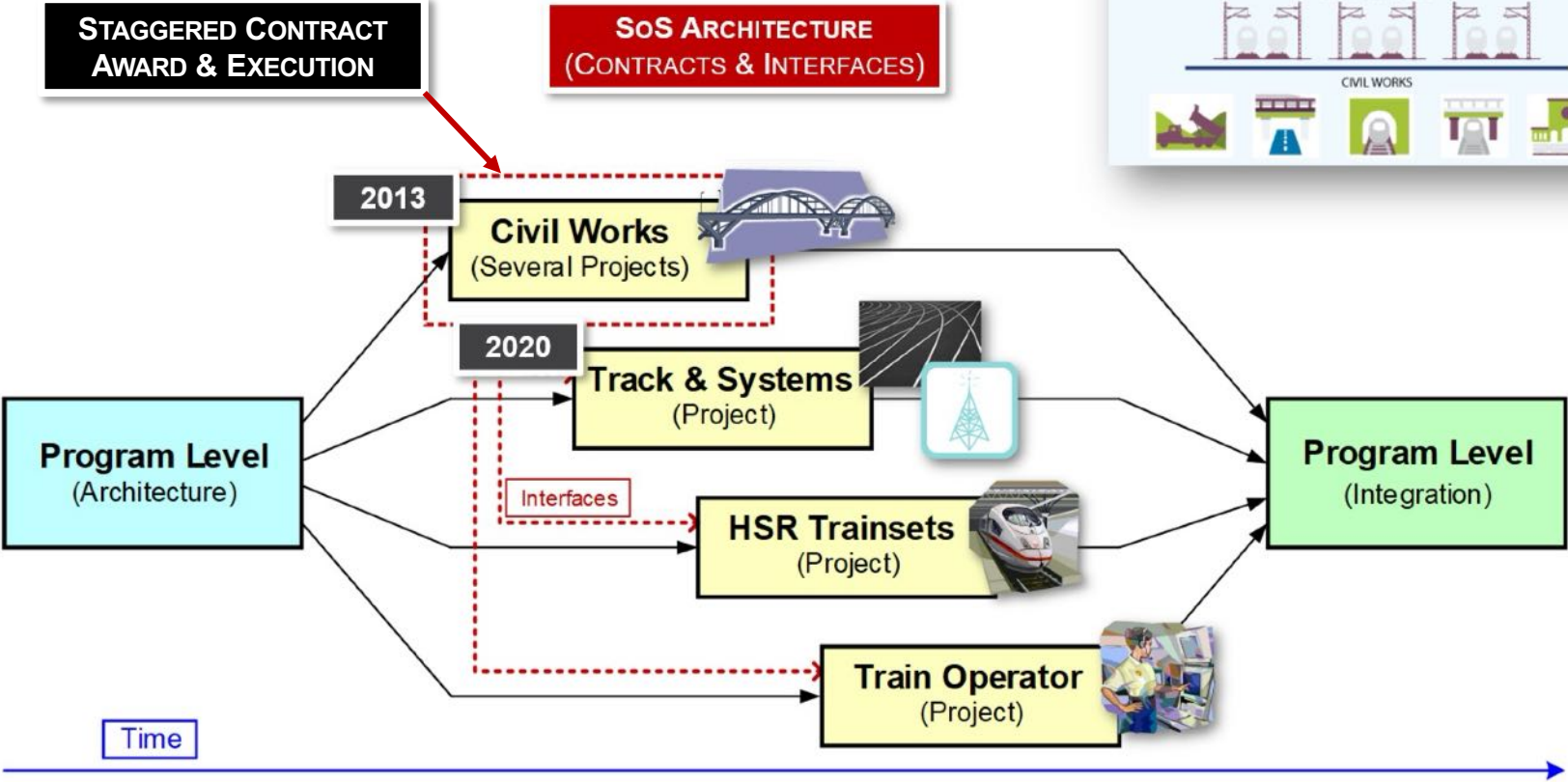
TRAIN OPERATOR

TRACK & SYSTEMS



BACKGROUND, CHALLENGES & OBJECTIVES

SoSE CHALLENGES FACED SoS ARCHITECTURE & LEADERSHIP (CONT'D)



TRAIN OPERATOR

HSR TRAINSETS

TRACK & SYSTEMS

CIVIL WORKS



PROGRAM INTERFACE & INTEGRATION CHALLENGES

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20

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: **INDUSTRY TYPICAL INTERFACE MANAGEMENT APPROACH**

❖ **Interface Management Working Group(s):** (Interface Management “As You Go”)

- **Purpose:**
 - Regularly meet to “liaise” and “cooperate”, and “coordinate” interfaces
- **Attendees:**
 - Contractor(s)
 - Interfacing contractors
 - Project Oversight
 - Client
- **Scope:**
 - Develop interface management program
 - Coordinate schedule development (including site access, handovers)
 - Identify interfaces
 - Develop interface requirements
 - Coordinate design development, including information exchange
 - Address, manage and resolve interface issues as they arise
 - Manage interface status



Sources/Credits:
<https://www.clker.com/clipart-617868.html>
https://de.freepik.com/vektoren-kostenlos/glueckliche-kinder-halten-haende-um-regenbogen-kreis_1250832.htm

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INTERFACE MANAGEMENT REALITIES

How a French rail company spent £12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you



TRAINS

STATIONS

Source/Credit: <https://www.theguardian.com/world/shortcuts/2014/may/21/french-rail-company-sncf-trains-too-wide>

'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



OPERATORS

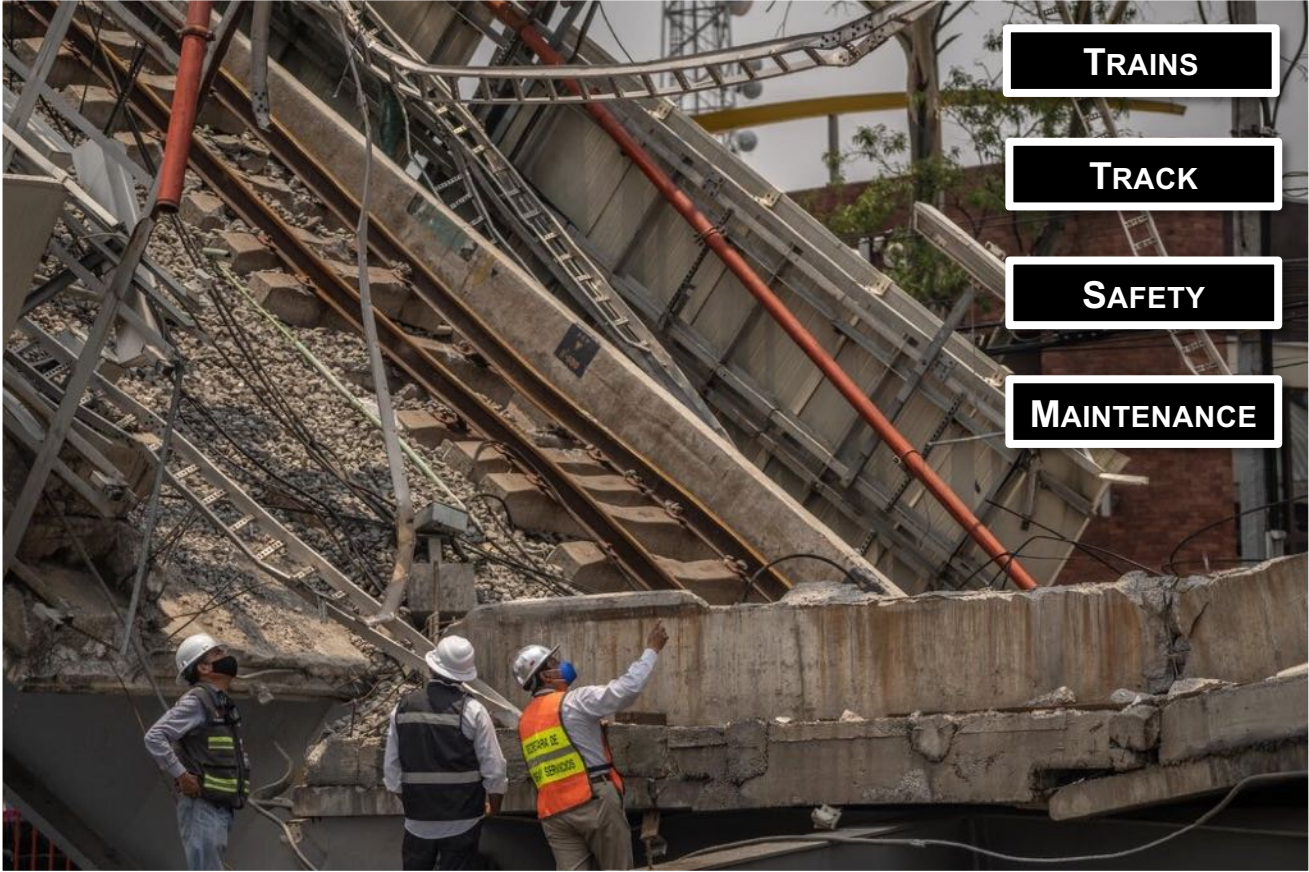
TUNNELS

Source/Credit: <https://www.euronews.com/travel/2023/02/21/unspeakable-botch-spain-spends-258-million-on-trains-that-are-too-big-for-its-tunnels>

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INTERFACE MANAGEMENT REALITIES (CONT'D)

MEXICO CITY METRO



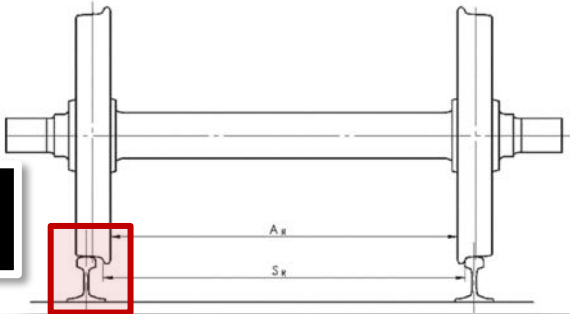
Source/Credit: <https://www.nytimes.com/interactive/2021/06/12/world/americas/mexico-city-train-crash.html?searchResultPosition=3>

The problem that drew the most public attention was the purchase of trains, which didn't fit tightly enough on the tracks.

The mismatch stemmed from another timesaving decision. The rails were designed for American standards according to testimony in the 2014 investigation by the city legislature. But the government ended up choosing a Spanish supplier, CAF, that provided trains designed for European specifications. The reason: CAF had promised to deliver the trains about a year ahead of its competitor, Canada-based Bombardier.

“Bombardier gave us a longer timeline,” said Francisco Bojorquez, metro director at the time, in 2014 testimony. “It was a question of time and of opportunity.”

The incompatibility caused so much wear that the city had to replace a half mile of rail weeks before the metro even started carrying passengers.



RAIL-WHEEL
INTERFACE

BACKGROUND, CHALLENGES & OBJECTIVES

OBJECTIVES: PREDICTABLE, REPEATABLE PROCESS, CONVENIENT, INTEROPERABLE

CMMI Level 1: Initial

- Unpredictable Processes, relying on SME Expertise (or Lack Thereof)

CMMI Level 2: Managed

- Repeatable Processes w/in Project

CMMI Level 3: Defined

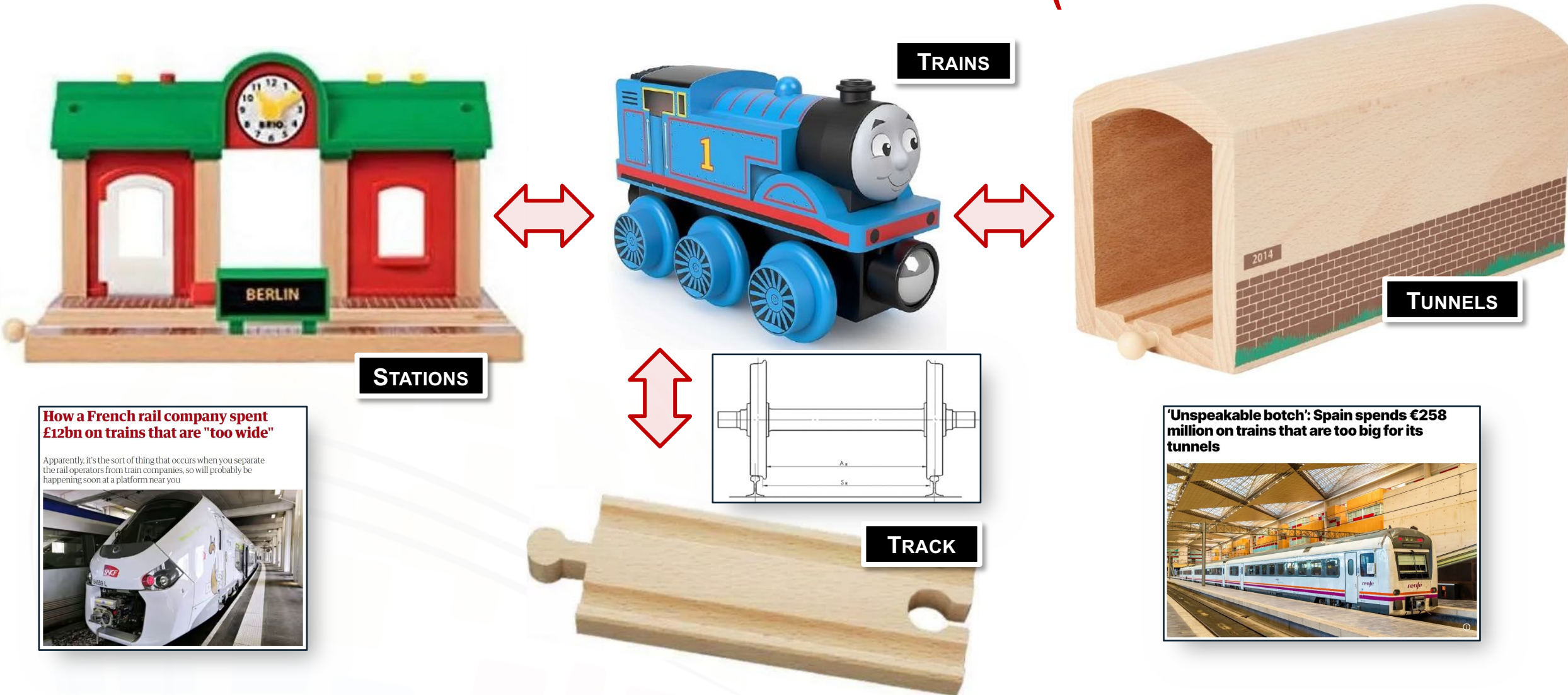
- Repeatable Processes w/in Organization
- Project Tailors Processes from Organizational Standards

Additional Objectives

- Convenience: Ready (Easy) to Use
- Interoperable: Compatible w/ Future Contracts

BACKGROUND, CHALLENGES & OBJECTIVES

OBJECTIVES: INTEROPERABLE CONSTITUENT SUBSYSTEM(S)



PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
 - Modular Open Systems Approach
 - Interoperability
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MODULAR OPEN SYSTEMS APPROACH (MOSA)

MODULAR OPEN SYSTEMS APPROACH THE TRANS-EUROPEAN HIGH SPEED-RAIL SYSTEM



Source: Hoehne, O., 2016, "Implementing an Effective Modular Open Systems Approach [MOSA] Framework Insights into the Application of MOSA to Non-Defense Industries", 19th Annual Systems Engineering Conference, Springfield, VA, 2016



MODULAR OPEN SYSTEMS APPROACH APPLICATION OF MOSA PRINCIPLES TO HSR



“Modular Open Systems Approach or MOSA” is the DoD’s implementation of Open Systems. Within the MOSA context, programs should design their system based on adherence to the following five MOSA principles:

Establish an Enabling Environment;
Employ Modular Design;
Designate Key Interfaces;
Use Open Standards; and
Certify Conformance.



[A Modular Open Systems Approach (MOSA) to Acquisition, OSJTF]



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MOSA APPLIED TO LARGE RAIL PROJECTS – ENABLING ENVIRONMENT, MODULARITY

MODULAR OPEN SYSTEMS APPROACH PRINCIPLE #1: ENABLING ENVIRONMENT



Source: Hoehne, O., 2016, "Implementing an Effective Modular Open Systems Approach [MOSA] Framework Insights into the Application of MOSA to Non-Defense Industries ", 19th Annual Systems Engineering Conference, Springfield, VA, 2016

THE TRANS-EUROPEAN HIGH-SPEED RAIL SYSTEM

Guide for the application of the high-speed TSIs of Council Directive 96/48/EC

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI)

Preface by Loyola de Palacio
Vice-President of the European Commission
Commissioner in charge of transport and energy

The railway sector is constrained by barriers within from competing effectively with other modes of transport. The establishment of an internal market for rail depends, on the one hand, on the opening of access and, on the other hand, on the progressive alignment in order to ensure their interoperability.

Our challenge is to move towards a single European a fully-fledged internal market for railway services; it will play a key role in this and the wider success cost-effective, reliable and safe transport alternative

Harmonisation of technical and operational specific rail system is vital for free movement of trains and related equipment in the EU

The interoperability directives, together with European legislation opening up competition, are key factors in increasing the rail sector's productivity and in competitive

The directives... system, company of the leading players in the transport system in the enlarged Europe. The lack of the provisions for... 48/EC and the

Technical and operational barriers work in favour of incumbent companies a players... railway network

The railway... removal of barriers to trade in trains and to their interoperability — that is, their ability to run on the network of the... on these difficulties

This has... competing transport have, instead of... construction of... a multi-domain contribution to resolving these problems for the high-speed rail system.

INTEROPERABILITY

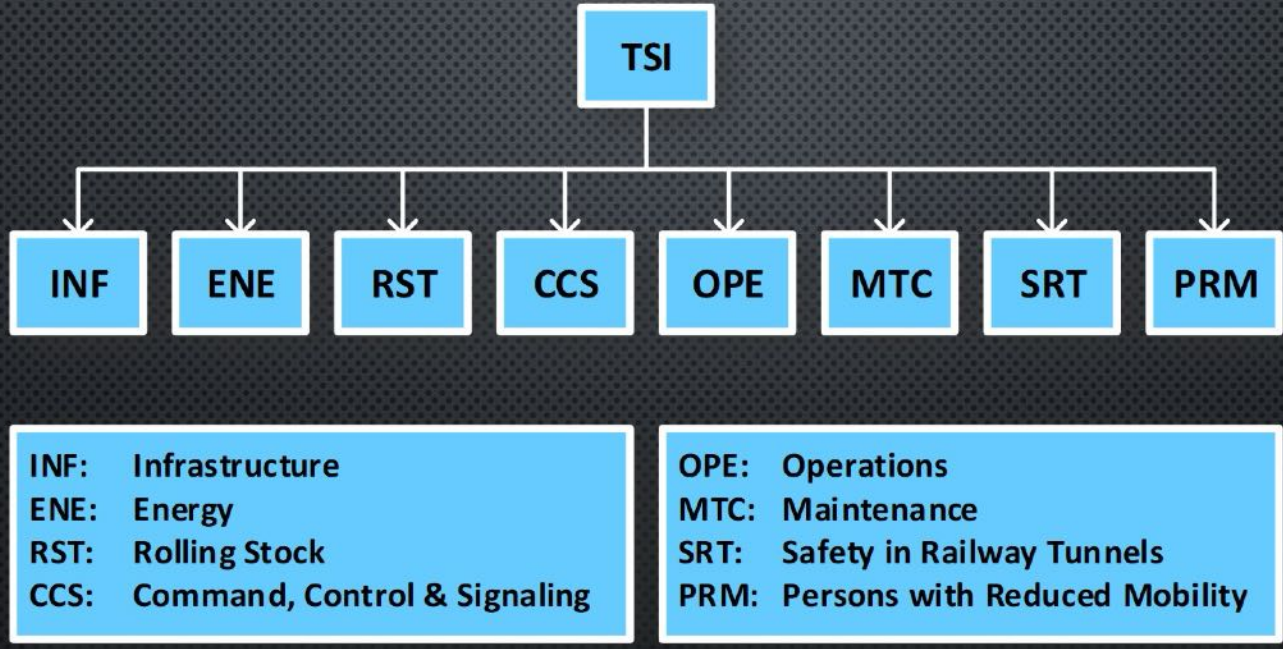
OPEN MARKET

COMPETITION

COST-EFFECTIVENESS

SAFE & RELIABLE

MODULAR OPEN SYSTEMS APPROACH PRINCIPLE #2: MODULAR DESIGN



TSI 'SUBSYSTEMS'

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI) – KEY INTERFACES

TSI INFRASTRUCTURE

02014R1299 — EN — 28.09.2023

TSI ROLLING STOCK

02014R1302 — 1

02014R1302 — EN — 28.09.2023 — 005.001 — 137

▼ M5

▼ M5

Reference TSI LOC & PAS		Reference TSI Energy	
Parameter	Point	Parameter	Point
Energy consumption measuring function	4.2.8.2.8	On-ground energy data collecting system	4.2.17
Height of pantograph	4.2.8.2.9.1	Geometry of the overhead contact line	4.2.9
Pantograph head geometry	4.2.8.2.9.2		
Contact strip material	4.2.8.2.9.4	Contact wire material	4.2.14
Pantograph static contact force	4.2.8.2.9.5	Mean contact force	4.2.11
Pantograph contact force and dynamic behaviour	4.2.8.2.9.6	Dynamic behaviour and quality of current collection	4.2.12
Arrangements of pantographs	4.2.8.2.9.7	Pantograph spacing	4.2.13
Running through phase or system separation section	4.2.8.2.9.8	Separation sections: — phase	4.2.15
			4.2.16
Electrical protection			4.2.7
Harmonics and for AC systems			4.2.8

'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



4.3.2.

Interface with It

Reference TSI LOC & PAS		Reference TSI Infrastructure	
Parameter	Point	Parameter	Point
Rolling stock kinematic gauge	4.2.3.1.	Structure gauge	4.2.3.1
		Distance between track centres	4.2.3.2
		Minimum radius of vertical curve	4.2.3.5
Axle load parameter	4.2.3.2.1	Track resistance to vertical loads	4.2.6.1

▼ M1
▼ M2
▼ M1

4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

Table 15

Interface: INTERFACING SYSTEMS

Interface	► M2 Reference in TSI INF ◀	► M2 Reference in TSI LOC&PAS ◀
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging

How a French rail company spent £12bn on trains that are "too wide"

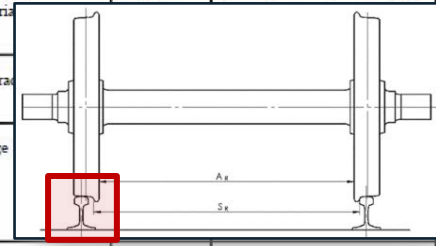
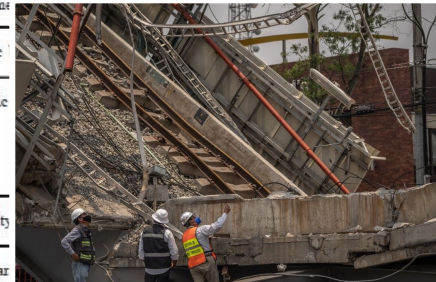
Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you



10 Load conditions
weighed mass
2.1 Axle load
meter
4.2.1 Limit values for
ing safely
4.2.2 Track loading
values

Ride stability 4.2.4.4 Equivalent conicity 4.2.3.4.3 Equivalent

Reference TSI LOC & PAS		Reference TSI Infrastructure	
Parameter	Point	Parameter	Point
Running dynamic	4.2.4.3		
Running dynamic for track loading	4.2.6.1		
	4.2.6.3		
Equivalent conicity	4.2.4.5		
Geometrical characteristics of char wheelset	4.2.4.1		
Geometrical characteristics of wheels	4.2.3.5.2.2	Rail head profile for plain line	4.2.4.6
Automatic vari systems	4.2.5.3		
Minimum curve ra	4.2.3.4		
Maximum average	4.2.6.2		
	4.2.7.1.5		
Slipstream effects	4.2.6.2.1	Resistance of new structures over or adjacent to tracks	4.2.7.3
Head pressure pulse	4.2.6.2.2	Maximum pressure variations in tunnels	4.2.10.1
Maximum pressure variations in tunnels	4.2.6.2.3	Distance between track centres	4.2.3.2
Crosswind	4.2.6.2.4	Effect of crosswinds	4.2.10.2
Aerodynamic effect on ballasted track	4.2.6.2.5	Ballast pick-up	4.2.10.3
Toilet discharge system	4.2.11.3	Toilet discharge	4.2.12.2
Exterior cleaning through a	4.2.11.2.2	Train external cleaning facilities	4.2.12.3



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI) – OPEN STANDARDS

TSI CONTROL-COMMAND & SIGNALLING

4.2.7.5. Euroloop/LEU

This is the interface between Euroloop and the LEU. The requirements are specified in Appendix A, Table A 1, 4.2.7.5 a.

This interface contributes to this Basic Parameter only when Euroloop and LEU are supplied as constituents (see point 5.2.2, Grouping of interoperability constituents).

4.2.8. Key Management

This basic parameter specifies requirements for the management of cryptographic keys used to protect the transmission of data transmitted via radio.

The requirements are specified in Appendix A, Table A 1, 4.2.8 a. Only requirements related to the management of cryptographic keys for Command and Signalling equipment fall within the scope of this TSI.

4.2.9. ETCS-ID Management

This basic parameter concerns the ETCS-identities (ETCS-IDs) for equipment in Control-Command and On-board Subsystems.

The requirements are specified in Appendix A 4.2.9 a.

4.2.10. Trackside Train Detection Systems

This basic parameter specifies the interface requirements between the trackside train detection systems and the train detection system related to vehicle design and operation.

The interface requirements to be respected by the train detection systems are specified in Appendix A, Table A 1, 4.2.10 a.

4.2.11. Electromagnetic Compatibility between Rolling Stock and Control-Command and Signalling

This basic parameter specifies the interface requirements for electromagnetic compatibility between rolling stock and control-command and signalling equipment. The requirements are specified in Appendix A, Table A 1, 4.2.11 a.

TRAIN CONTROL TO DRIVER INTERFACE

4.2.12. ETCS DMI (Driver-Machine Interface)

This basic parameter describes the information provided from ETCS and ATO to the driver and by the driver. See Appendix A, Table A 1, 4.2.12 a.

It includes:

- (1) ergonomics (including visibility);
- (2) ETCS and ATO functions to be displayed;
- (3) ETCS and ATO functions triggered by driver input.

4.2.13. RMR DMI (Driver-Machine Interface)

L 222/480		EN	Official Journal of the European Union	
4.2.8				
4.2.8 a			10d, 11, 79, 83	
4.2.9				
4.2.9 a			23	
4.2.10				
4.2.10 a			77 (point 3.1)	
4.2.11				
4.2.11 a			77 (point 3.2)	
4.2.12				
4.2.12 a			6	
4.2.13				
4.2.13 a			32, 33	
4.2.13 b			93, 94	
4.2.14				
4.2.14 a			5	
4.2.15				
4.2.15 a			38	
4.2.15 b			101	
4.2.17				
4.2.17 a			103	
4.2.18				
4.2.18 a			84, 85	
4.2.18 b			98	
4.2.18 c			88	
4.2.18 d			87	
4.2.19				
4.2.19 a			84, 85	
4.2.19 b			98	

Specifications

When a document listed in Table A 2 incorporates, by copying or by reference to, a clearly identified

8.9.2023

EN

Official Journal of the European Union

L 222/481

Table A 2

List of mandatory specifications

Index No	ETCS Baseline 4 Release 1; RMR: GSM-R Baseline 1 Maintenance Release 1 + FRMCS Baseline 0; ATO Baseline 1 Release 1			
	Reference	Name of Specification	Version	Notes
1	Intentionally deleted			
2	Intentionally deleted			
3	SUBSET-023	Glossary of Terms and Abbreviations	4.0.0	
4	OPEN INTERFACE STANDARDS		ification	4.0.0
5			4.0.0	
6	ERA_ERTMS_015560	ETCS Driver Machine interface	4.0.0	
7	SUBSET-034	Train Interface FIS	4.0.0	
8	SUBSET-035	Specific Transmission Module FFFIS	4.0.0	
9	SUBSET-036	FFFIS for Eurobalise	4.0.0	
10a	SUBSET-037-1	EuroRadio FIS GSM-R – Part 1 [Communication layer and coordination function]	4.0.0	
10b	SUBSET-037-2	EuroRadio FIS – Part 2 [Safety layer]	4.0.0	
10c	SUBSET-037-3	EuroRadio FIS – Part 3 [FRMCS interface]	4.0.0	
10d	SUBSET-146	ERTMS End-to-End Security	4.0.0	
11	SUBSET-038	Offline key management FIS	4.0.0	
12	SUBSET-039	FIS for the RBC/RBC handover	4.0.0	
13	SUBSET-040	Dimensioning and Engineering rules	4.0.0	
14	SUBSET-041	Performance Requirements for Interoperability	4.0.0	
15	Intentionally deleted			

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY – OPEN STANDARDS (CONT'D)

1. CCS TSI Appendix A – Mandat				
era.europa.eu/era-folder/1-ccs-tsi-appendix-mandatory-specifications-etcs-b4-r1-rmr-gsm-r-b1-mr1-frmcs-b0-ato-b1				
Index	Reference	Title	Approved	Note
000	-	readme_file_-_mandatory_specs.docx	-	-
003	SUBSET-023	Glossary of Terms and Abbreviations	4.0.0	-
004	SUBSET-026	System Requirements Specification	4.0.0	-
005	SUBSET-027	FIS Juridical Recording	4.0.0	-
006	ERA_ERTMS_015560	ETCS Driver Machine interface	4.0.0	-
007	SUBSET-034	Train Interface FIS	4.0.0	-
008	SUBSET-035	Specific Transmission Module FFFIS	4.0.0	-
009	SUBSET-036	FFFIS for Eurobalise	4.0.0	-
010a	SUBSET-037-1	EuroRadio FIS – Part 1 [Communication layer and coordination function]	4.0.0	-
010b	SUBSET-037-2	EuroRadio FIS – Part 2 [Safety layer]	4.0.0	-
010c	SUBSET-037-3	EuroRadio FIS – Part 3 [FRMCS interface]	4.0.0	-
010d	SUBSET-146	ERTMS End-to-End Security	4.0.0	-
011	SUBSET-038	Offline key management FIS	4.0.0	-
012	SUBSET-039	FIS for the RBC/RBC handover	4.0.0	-
013	SUBSET-040	Dimensioning and Engineering rules	4.0.0	-

PROGRESS

















- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
 - Design Terms, Nomenclature
 - Requirements
 - Structure
 - Interfaces
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – DESIGN TERMS, NOMENCLATURE

Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg 454/2011/EU TAP TSI								x
Reg (EU) 321/2013 WAG TSI					x		x	
Reg (EU) 1299/2014 INF TSI	x						x	
Reg (EU) 1300/2014 PRM TSI	x				x	x		
Reg (EU) 1301/2014 ENE TSI		x					x	
Reg (EU) 1302/2014 LOC & PAS TSI					x		x	
Reg (EU) 1303/2014 SRT TSI	x	x	x	x	x	x		
Reg (EU) 1304/2014 RST Noise TSI					x		x	
Reg (EU) 1305/2014 TAF TSI								x
Reg (EU) 2016/919 CCS TSI			x	x			x	
Com. Impl. Reg (EU) 2019/773 OPE TSI						x		

Table 6 – Applicability of TSIs to subsystems

#	△ Term	Description
1	 CCS	Command Control and Signalling (TSI)
2	 ENE	Energy (TSI)
3	 INF	Infrastructure (TSI)
4	 LOC & PAS	Locomotive and passenger rolling stock (TSI)
5	 MTC	Maintenance (Subsystem)
6	 OB	(CCS) Onboard (Subsystem)
7	 OPE	Operation and Traffic Management
8	 PRM	Person with Disabilities or Person with Reduced Mobility (TSI)
9	 RST	Rolling Stock (Subsystem)
10	 SRT	Safety in Railway Tunnels (TSI)
11	 TAF	Telematics Applications for Freight Service (TSI)
12	 TAP	Telematics Applications for Freight Service (TSI)
13	 TAx	Telematics Application (Subsystem)
14	 TS	(CCS) Trackside (Subsystem)
15	 TSI	Technical Specification for Interoperability
16	 WAG	Freight wagon (TSI)

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – REQUIREMENTS

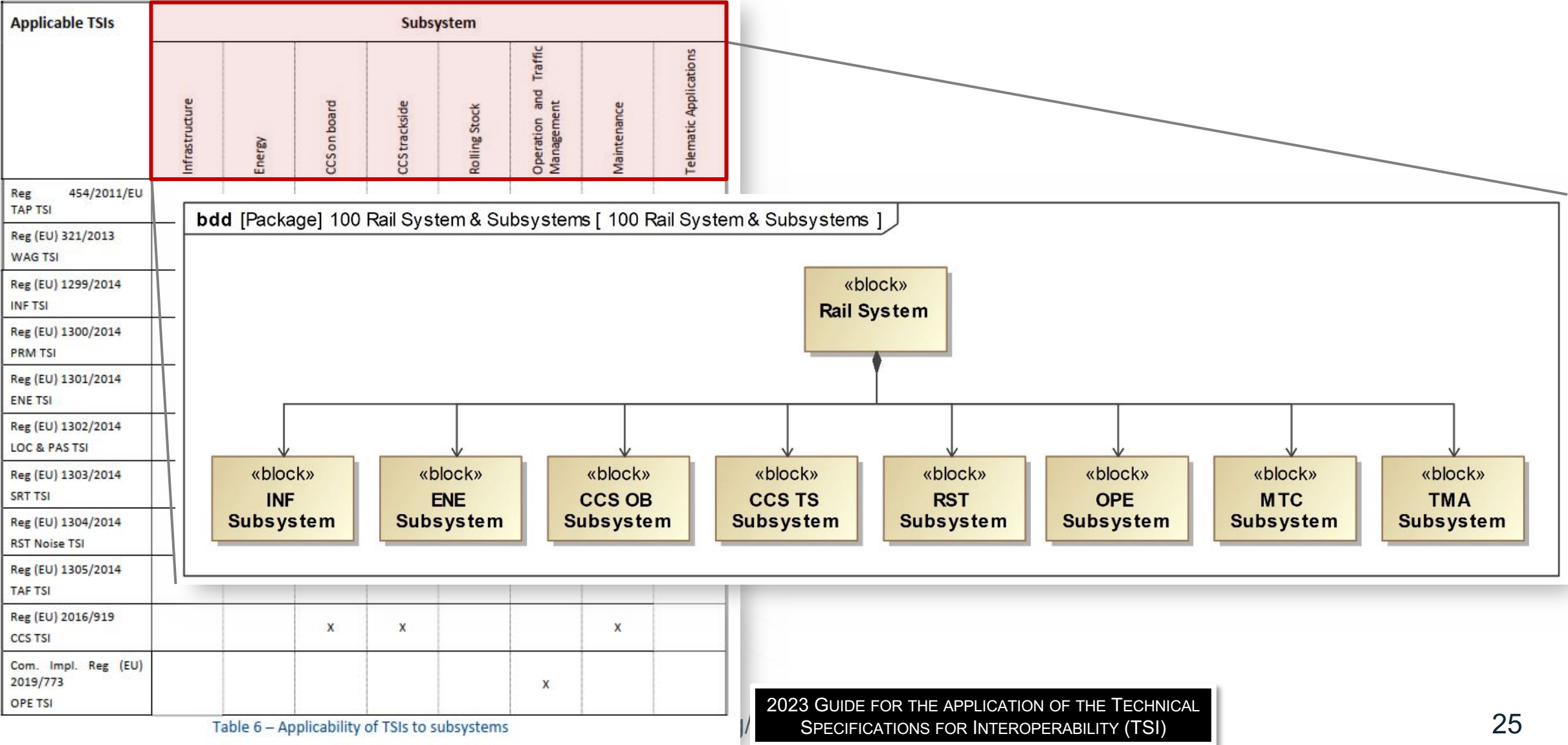
Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg 454/2011/EU TAP TSI								X
Reg (EU) 321/2013 WAG TSI					X		X	
Reg (EU) 1299/2014 INF TSI	X						X	
Reg (EU) 1300/2014 PRM TSI	X				X	X		
Reg (EU) 1301/2014 ENE TSI		X					X	
Reg (EU) 1302/2014 LOC & PAS TSI					X		X	
Reg (EU) 1303/2014 SRT TSI	X	X	X	X	X	X		
Reg (EU) 1304/2014 RST Noise TSI					X		X	
Reg (EU) 1305/2014 TAF TSI								X
Reg (EU) 2016/919 CCS TSI			X	X			X	
Com. Impl. Reg (EU) 2019/773 OPE TSI						X		

Table 6 – Applicability of TSIs to subsystems

#	△ Id	Name
1	TSI-INF-1	TSI-INF-1 INF TSI
2	TSI-INF-1.1	TSI-INF-1.1 1. Introduction
6	TSI-INF-1.2	TSI-INF-1.2 2. Definition and scope of subsystem
17	TSI-INF-1.3	TSI-INF-1.3 3. Essential requirements
18	TSI-INF-1.4	TSI-INF-1.4 4. Description of the infrastructure subsystem
19	TSI-INF-1.4.1	TSI-INF-1.4.1 4.1. Introduction
20	TSI-INF-1.4.2	TSI-INF-1.4.2 4.2. Functional and technical specifications of subsystem
81	TSI-INF-1.4.3	TSI-INF-1.4.3 4.3. Functional and technical specification of the interfaces
105	TSI-INF-1.4.4	TSI-INF-1.4.4 4.4. Operating rules
106	TSI-INF-1.4.5	TSI-INF-1.4.5 4.5. Maintenance rules
109	TSI-INF-1.4.6	TSI-INF-1.4.6 4.6. Professional qualifications
110	TSI-INF-1.4.7	TSI-INF-1.4.7 4.7. Health and safety conditions
111	TSI-INF-1.5	TSI-INF-1.5 5. Interoperability constituents
128	TSI-INF-1.6	TSI-INF-1.6 6. Assessment of conformity of interoperability constituents and EC verification of the subsystems
151	TSI-INF-1.7	TSI-INF-1.7 7. Implementation of the infrastructure TSI
182	TSI-INF-1.8	TSI-INF-1.8 Appendix A — Assessment of interoperability constituents
183	TSI-INF-1.9	TSI-INF-1.9 Appendix B — Assessment of the infrastructure subsystem
184	TSI-INF-1.10	TSI-INF-1.10 Appendix C — Technical characteristics of track design and switches and crossings design
185	TSI-INF-1.11	TSI-INF-1.11 Appendix D — Conditions of use of track design and switches and crossings design
186	TSI-INF-1.12	TSI-INF-1.12 Appendix E — Capability requirements for structures according to traffic code
187	TSI-INF-1.13	TSI-INF-1.13 Appendix F — Capability requirements for structures according to traffic code in the United Kingdom of Great Britain and Northern Ireland
188	TSI-INF-1.14	TSI-INF-1.14 Appendix G — Speed conversion to miles per hour for Ireland and the United Kingdom of Great Britain and Northern Ireland
189	TSI-INF-1.15	TSI-INF-1.15 Appendix H — Structure gauge for the 1 520 mm track gauge system
190	TSI-INF-1.16	TSI-INF-1.16 Appendix I — Reverse curves with radii in the range from 150 m up to 300 m
191	TSI-INF-1.17	TSI-INF-1.17 Appendix J — Safety assurance over fixed obtuse crossings
192	TSI-INF-1.18	TSI-INF-1.18 Appendix K — Basis of minimum requirements for structures for passenger coaches and multiple units
193	TSI-INF-1.19	TSI-INF-1.19 Appendix M — Specific case on the Estonian network
194	TSI-INF-1.20	TSI-INF-1.20 Appendix N — Specific cases of the Hellenic network
195	TSI-INF-1.21	TSI-INF-1.21 Appendix O — Specific case on the Ireland and United Kingdom of Northern Ireland networks
196	TSI-INF-1.22	TSI-INF-1.22 Appendix P — Structure gauge for the lower parts for the 1 668 mm track gauge on the Spanish network
197	TSI-INF-1.23	TSI-INF-1.23 Appendix Q — National technical rules for UK-GB Specific Cases
198	TSI-INF-1.24	TSI-INF-1.24 Appendix R — List of open points
199	TSI-INF-1.25	TSI-INF-1.25 Appendix S — Glossary
200	TSI-INF-1.26	TSI-INF-1.26 Appendix T — List of referenced standards

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – STRUCTURE



MBSI REFERENCE ARCHITECTURE – SATISFY REQUIREMENTS MATRIX

Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg 454/2011/EU TAP TSI								X
Reg (EU) 321/2013 WAG TSI					X		X	
Reg (EU) 1299/2014 INF TSI	X						X	
Reg (EU) 1300/2014 PRM TSI	X				X	X		
Reg (EU) 1301/2014 ENE TSI		X					X	
Reg (EU) 1302/2014 LOC & PAS TSI					X		X	
Reg (EU) 1303/2014 SRT TSI	X	X	X	X	X	X		
Reg (EU) 1304/2014 RST Noise TSI					X		X	
Reg (EU) 1305/2014 TAF TSI								X
Reg (EU) 2016/919 CCS TSI			X	X			X	
Com. Impl. Reg (EU) 2019/773 OPE TSI						X		

Table 6 – Applicability of TSIs to subsystems

Legend			010 Rail System & Subsystems	INF Subsystem	ENE Subsystem	CCS OB Subsystem	CCS TS Subsystem	RST Subsystem	OPE Subsystem	MTC Subsystem	TMA Subsystem
	Satisfy										
020 Requirements			3	2	2	2	7	3	6	2	
	TAP-TSI-1 TAP TSI	1									
	WAG-INF-1 WAG TSI	2									
	INF-TSI-1 INF TSI	2									
	PRM-TSI-1 PRM TSI	3									
	ENE-TSI-1 ENE TSI	2									
	LOC&PAS-TSI-1 LOC & PAS TSI	2									
	SRT-TSI-1 SRT TSI	6									
	RST-NOISE-TSI-1 RST NOISE TSI	2									
	TAF-TSI-1 TAF TSI	1									
	CCS-TSI-1 CCS TSI	3									
	OPE-TSI-1 OPE TSI	1									

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

SUBSYSTEM ELEMENTS – INTEROPERABILITY CONSTITUENTS (INF – RAIL)

02014R1299 — EN — 28.09.2023 — 002.001 — 47

▼B

TSI INFRASTRUCTURE

5. INTEROPERABILITY CONSTITUENTS

5.1. Basis on which interoperability constituents have been selected

- (1) The requirements of point 5.3 are based on a traditional design of ballasted track with Vignole (flat-bottom) rail on concrete or wooden sleepers and fastening providing resistance to longitudinal slip by bearing on the rail foot.
- (2) Components and subassemblies used for the construction of other designs of track are not considered to be interoperability constituents.

5.2. List of constituents

- (1) For the purposes of this technical specification for interoperability, only the following elements, whether individual components or subassemblies of the track are declared to be 'interoperability constituents':
 - (a) the rail (5.3.1),
 - (b) the rail fastening systems (5.3.2),
 - (c) track sleepers (5.3.3).
- (2) The following points describe the specifications applicable to each of these constituents.
- (3) Rails, fastenings and sleepers used for short length of track for specific purposes, for example in switches and crossings, at expansion devices, transition slabs and special structures, are not considered to be interoperability constituents.

5.3. Constituents performances and specifications

5.3.1. The rail

The specifications of the 'rail' interoperability constituent concern the following parameters:

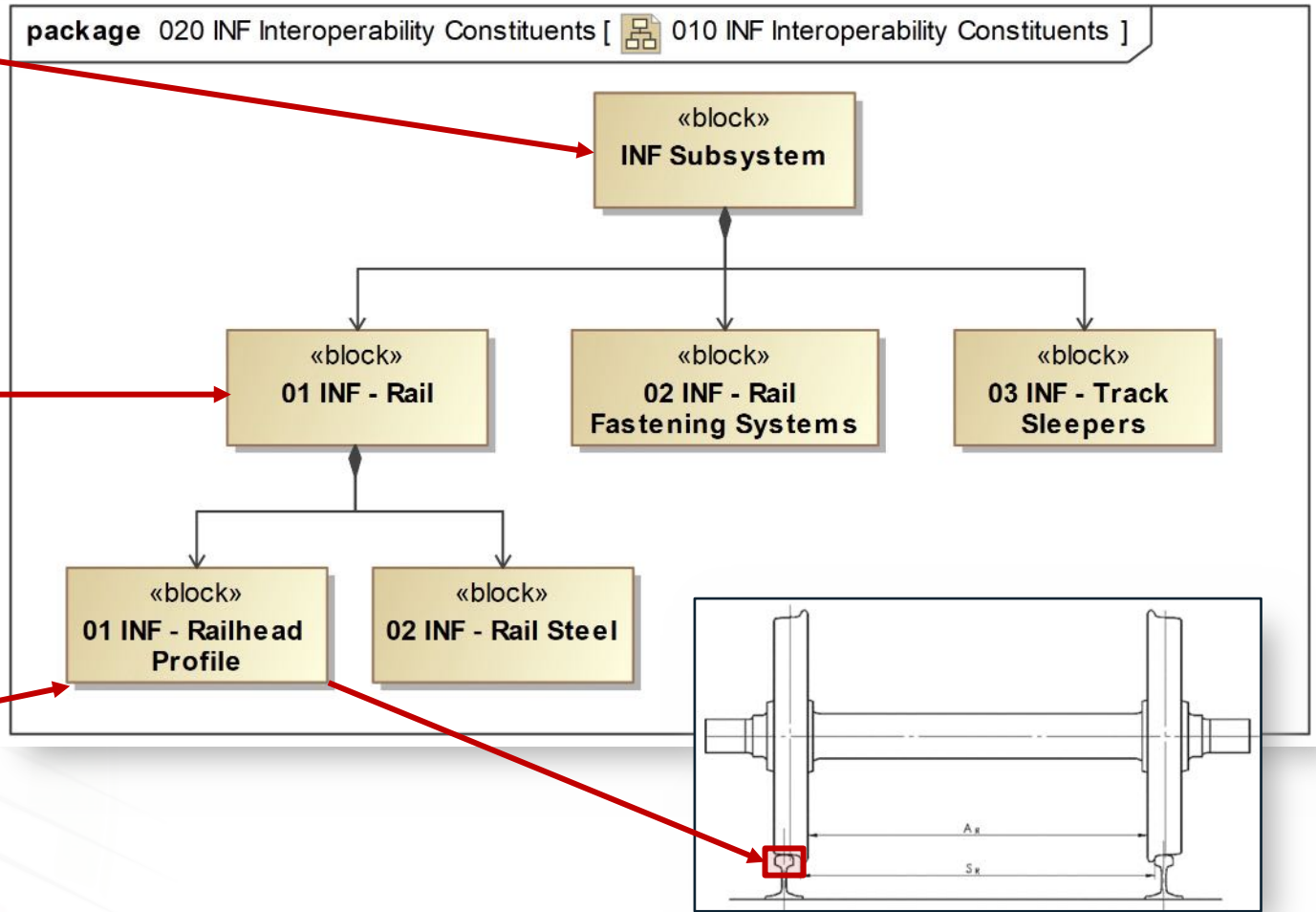
- (a) railhead profile,
- (b) rail steel.

5.3.1.1. Railhead profile

The rail head profile shall fulfil the requirements of point 4.2.4.6 'Railhead profile for plain line'.

5.3.1.2. Rail steel

- (1) The rail steel is relevant to the requirements of point 4.2.6 'Track resistance to applied loads'.



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

SUBSYSTEM ELEMENTS – INTEROPERABILITY CONSTITUENTS REQUIREMENTS

02014R1299 — EN — 28.09.2023 — 002.001 — 47

02014R1299 — EN — 28.09.2023 — 002.001 — 29

▼B

5. INTEROPERABILITY CONSTITUENTS
- 5.1. Basis on which interoperability constituents have been selected
- (1) The requirements of point 5.3 are based on a traditional design of ballasted track with Vignole (flat-bottom) rail on concrete or wooden sleepers and fastening providing resistance to longitudinal slip by bearing on the rail foot.
- (2) Components and subassemblies used for the construction of other designs of track are not considered to be interoperability constituents.
- 5.2. List of constituents
- (1) For the purposes of this technical specification for interoperability, only the following elements, whether individual components or subassemblies of the track are declared to be 'interoperability constituents':
- (a) the rail (5.3.1),
- (b) the rail fastening systems (5.3.2),
- (c) track sleepers (5.3.3).
- (2) The following points describe the specifications applicable to each of these constituents.
- (3) Rails, fastenings and sleepers used for short length of track for specific purposes, for example in switches and crossings, at expansion devices, transition slabs and special structures, are not considered to be interoperability constituents.
- 5.3. Constituents performances and specifications
- 5.3.1. The rail
- The specifications of the 'rail' interoperability constituent concern the following parameters:
- (a) railhead profile,
- (b) rail steel.
- 5.3.1.1. Railhead profile
- The rail head profile shall fulfil the requirements of point 4.2.4.6 'Railhead profile for plain line'.
- 5.3.1.2. Rail steel
- (1) The rail steel is relevant to the requirements of point 4.2.6 'Track resistance to applied loads'.

STRUCTURE

TSI INFRASTRUCTURE

▼M2

▼B

▼M1

▼B

(5) Instead of points (1) to (4), for the 1 520 mm track gauge system, no assessment of equivalent conicity is required

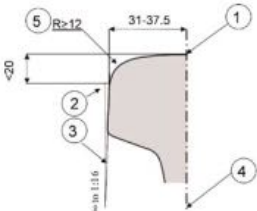
4.2.4.6. Railhead profile for plain line

REQUIREMENTS

- (1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).
- (2) The design of railhead profiles for plain line shall comprise:
- (a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;
- (b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;
- (c) a radius of at least 12 mm at the gauge corner;
- (d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.

Figure 1

Railhead profile



- 1 crown of rail
2 tangent point
3 lateral slope
4 vertical axis of rail head
5 gauge corner

(3) These requirements are not applicable to expansion devices.

4.2.4.7. Rail inclination

4.2.4.7.1. Plain line

Legend

✓ Satisfy

020 INF Interoperability		01 INF - Railhead Profile...	
TSI-INF-1.4.2.4.6	4.2.4.6 Railhead profile f	7	
TSI-INF-1.4.2.4.6.1		1	✓
TSI-INF-1.4.2.4.6.2		1	✓
TSI-INF-1.4.2.4.6.3		1	✓
TSI-INF-1.4.2.4.6.4		1	✓
TSI-INF-1.4.2.4.6.5		1	✓
TSI-INF-1.4.2.4.6.6		1	✓
TSI-INF-1.4.2.4.6.7		1	✓

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

SUBSYSTEM ELEMENTS – INTEROPERABILITY CONSTITUENTS REQUIREMENTS (CONT'D)

#	△ Id	Name	Text	Satisfied By
1	TSI-INF-1.4	<div>TSI-INF-1.4 4. Description of the infrastructure subsystem</div>		
3	TSI-INF-1.4.2	<div>TSI-INF-1.4.2 4.2. Functional and technical specifications of subsystem</div>		
17	TSI-INF-1.4.2.4	<div>TSI-INF-1.4.2.4 4.2.4. Track parameters</div>		
23	TSI-INF-1.4.2.4.6	<div>TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line</div>		
24	TSI-INF-1.4.2.4.6.1	<div>TSI-INF-1.4.2.4.6.1</div>	(1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).	01 INF - Railhead Profile
25	TSI-INF-1.4.2.4.6.2	<div>TSI-INF-1.4.2.4.6.2</div>	(2) The design of railhead profiles for plain line shall comprise:	01 INF - Railhead Profile
26	TSI-INF-1.4.2.4.6.3	<div>TSI-INF-1.4.2.4.6.3</div>	(a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;	01 INF - Railhead Profile
27	TSI-INF-1.4.2.4.6.4	<div>TSI-INF-1.4.2.4.6.4</div>	(b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;	01 INF - Railhead Profile
28	TSI-INF-1.4.2.4.6.5	<div>TSI-INF-1.4.2.4.6.5</div>	(c) a radius of at least 12 mm at the gauge corner;	01 INF - Railhead Profile
29	TSI-INF-1.4.2.4.6.6	<div>TSI-INF-1.4.2.4.6.6</div>	(d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.	01 INF - Railhead Profile
30	TSI-INF-1.4.2.4.6.7	<div>TSI-INF-1.4.2.4.6.7</div>	<div><p>Figure 1</p><p>Railhead profile</p><p>1 crown of rail 2 tangent point 3 lateral slope 4 vertical axis of rail head 5 gauge corner</p></div>	<div><div><div>Legend</div><div><div>Satisfy</div></div></div><div><div>020 INF Interoperability</div><div>01 INF - Railhead Profile</div></div><div><div>TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile f</div><div><div>TSI-INF-1.4.2.4.6.1</div><div>1</div><div>✓</div></div><div><div>TSI-INF-1.4.2.4.6.2</div><div>1</div><div>✓</div></div><div><div>TSI-INF-1.4.2.4.6.3</div><div>1</div><div>✓</div></div><div><div>TSI-INF-1.4.2.4.6.4</div><div>1</div><div>✓</div></div><div><div>TSI-INF-1.4.2.4.6.5</div><div>1</div><div>✓</div></div><div><div>TSI-INF-1.4.2.4.6.6</div><div>1</div><div>✓</div></div><div><div>TSI-INF-1.4.2.4.6.7</div><div>1</div><div>✓</div></div></div></div>
31	TSI-INF-1.4.2.4.6.8	<div>TSI-INF-1.4.2.4.6.8</div>	(3) These requirements are not applicable to expansion devices.	

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION

02014R1299 — EN — 28.09.2023 — 002.001 — 29

▼B

(5) Instead of points (1) to (4), for the 1520 mm track gauge system, no assessment of equivalent conicity is required.

4.2.4.6. Railhead profile for plain line

▼M2

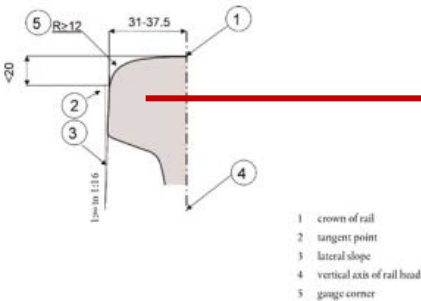
(1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).

▼B

- (2) The design of railhead profiles for plain line shall comprise:
- (a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;
 - (b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;
 - (c) a radius of at least 12 mm at the gauge corner;
 - (d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.

▼M1

Figure 1
Railhead profile



▼B

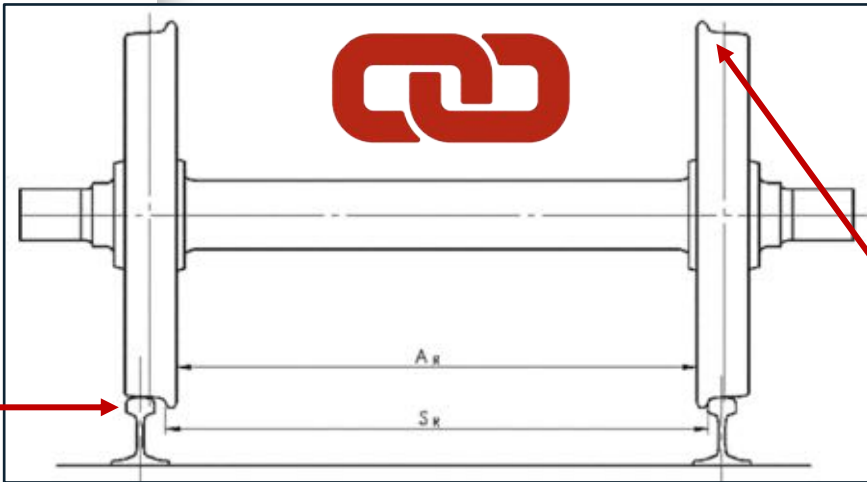
(3) These requirements are not applicable to expansion devices.

4.2.4.7. Rail inclination

4.2.4.7.1. Plain line

TSI INFRASTRUCTURE

INTERFACE BETWEEN INF RAILHEAD PROFILE & RST WHEEL CHARACTERISTICS



TSI ROLLING STOCK (Loc&Pas)

02014R1302 — EN — 28.09.2023 — 005.001 — 50

4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

Mechanical behaviour of wheels

- (1) The characteristics of the wheels shall ensure the safe movement of rolling stock and contribute to the guidance of the rolling stock.

The conformity assessment procedure is described in ►M5 point ◄ 6.1.3.1 of this TSI.

Geometrical dimensions of wheels

- (2) The geometrical dimensions of the wheels (as defined in Figure 2) shall be compliant with limit values specified in Table 2. These limit values shall be taken as design values (new wheel) and as in-service limit values (to be used for maintenance purposes; see also ►M5 point ◄ 4.5).

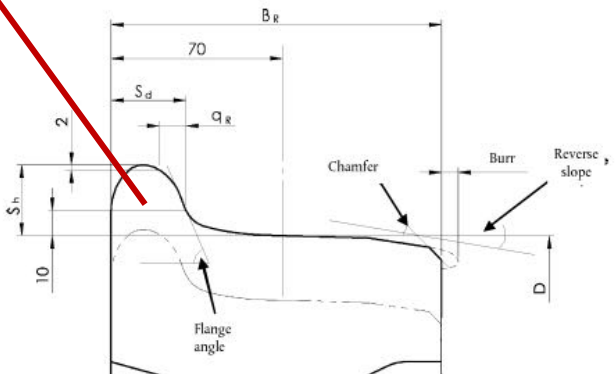
Table 2

In-service limits of the geometric dimensions of wheel

Designation	Wheel diameter D (mm)	Minimum value (mm)	Maximum value (mm)
Width of the rim (B _R + Burr)	D ≥ 330	133	145
Thickness of the flange (S _d)	D > 840	22	33
	760 < D ≤ 840	25	
	330 ≤ D ≤ 760	27,5	
Height of the flange (S _h)	D > 760	27,5	36
	630 < D ≤ 760	29,5	
	330 ≤ D ≤ 630	31,5	
Face of flange (q _R)	≥ 330	6,5	

Figure 2

Symbols for wheels



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: TSI INTERFACE TABLES

02014R1299 — EN — 28.09.2023 — 002.001 — 42

▼ B

4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

▼ M1

▼ M2

▼ M1

Table 15

Interfaces with the

TSI INF

TSI Loc&PAS

Interface	► M2 Reference in TSI INF ◀	► M2 Reference in TSI LOC&PAS ◀
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging

Ride stability

4.2.4.4 Equivalent conicity

4.2.4.6 Railhead profile for plain line

4.2.11.2 Equivalent conicity in service

4.2.3.4.3 Equivalent conicity

4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

Running characteristics	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1.4 Nosing forces	4.2.3.4.2.1 Limit values for running safely 4.2.3.4.2.2 Track loading limit values
Ride stability	4.2.4.4 Equivalent conicity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent conicity in service	4.2.3.4.3 Equivalent conicity 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
Longitudinal actions	4.2.6.2 Longitudinal track resistance 4.2.7.1.5 Actions due to traction	4.2.4.5 Braking performance

02014R1299 — EN — 28.09.2023 — 002.001 — 29

TSI INFRASTRUCTURE

(5) Instead of points (1) to (4), for the 1 520 mm track gauge system, no assessment of equivalent conicity is required.

4.2.4.6. Railhead profile for plain line

▼ M2

▼ M1

▼ M1

Figure 1

Railhead profile

(1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).

(2) The design of railhead profiles for plain line shall comprise:

(a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;

(b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;

(c) a radius of at least 12 mm at the gauge corner;

(d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.

(3) These requirements are not applicable to expansion devices.

4.2.4.7. Rail inclination

4.2.4.7.1. Plain line

(1) The rail shall be inclined towards the centre of the track.

(2) For tracks intended to be operated at speeds greater than 60 km/h the rail inclination for a given gauge shall be related

▼ B

▼ M1

28.09.2023 — 005.001 — 50

TSI ROLLING STOCK (Loc&PAS)

4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

▼ B

Mechanical behaviour of wheels

(1) The characteristics of the wheels shall ensure the safe movement of rolling stock and contribute to the guidance of the rolling stock.

The conformity assessment procedure is described in ► M5 point ◀ 6.1.3.1 of this TSI.

Geometrical dimensions of wheels

(2) The geometrical dimensions of the wheels (as defined in Figure 2) shall be compliant with limit values specified in Table 2. These limit values shall be taken as design values (new wheel) and as in-service limit values (to be used for maintenance purposes; see also ► M5 point ◀ 4.5).

Table 2

In-service limits of the geometric dimensions of wheel

Designation	Wheel diameter D (mm)	Minimum value (mm)	Maximum value (mm)
Width of the rim (B_R + Burr)	$D \geq 330$	133	145
Thickness of the flange (S_d)	$D > 840$	22	33
	$760 < D \leq 840$	25	
	$330 \leq D \leq 760$	27,5	
Height of the flange (S_h)	$D > 760$	27,5	36
	$630 < D \leq 760$	29,5	
	$330 \leq D \leq 630$	31,5	
Face of flange (q_u)	≥ 330	6,5	

Figure 2

Symbols for wheels

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: CREATING INTERFACE TABLES IN MBSI FRAMEWORK

02014R1299 — EN — 28.09.2023 — 002.001 — 42

▼ B
4.3. Functional and technical specification of the interfaces
From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

▼ M1
4.3.1. Interfaces with the rolling stock subsystem

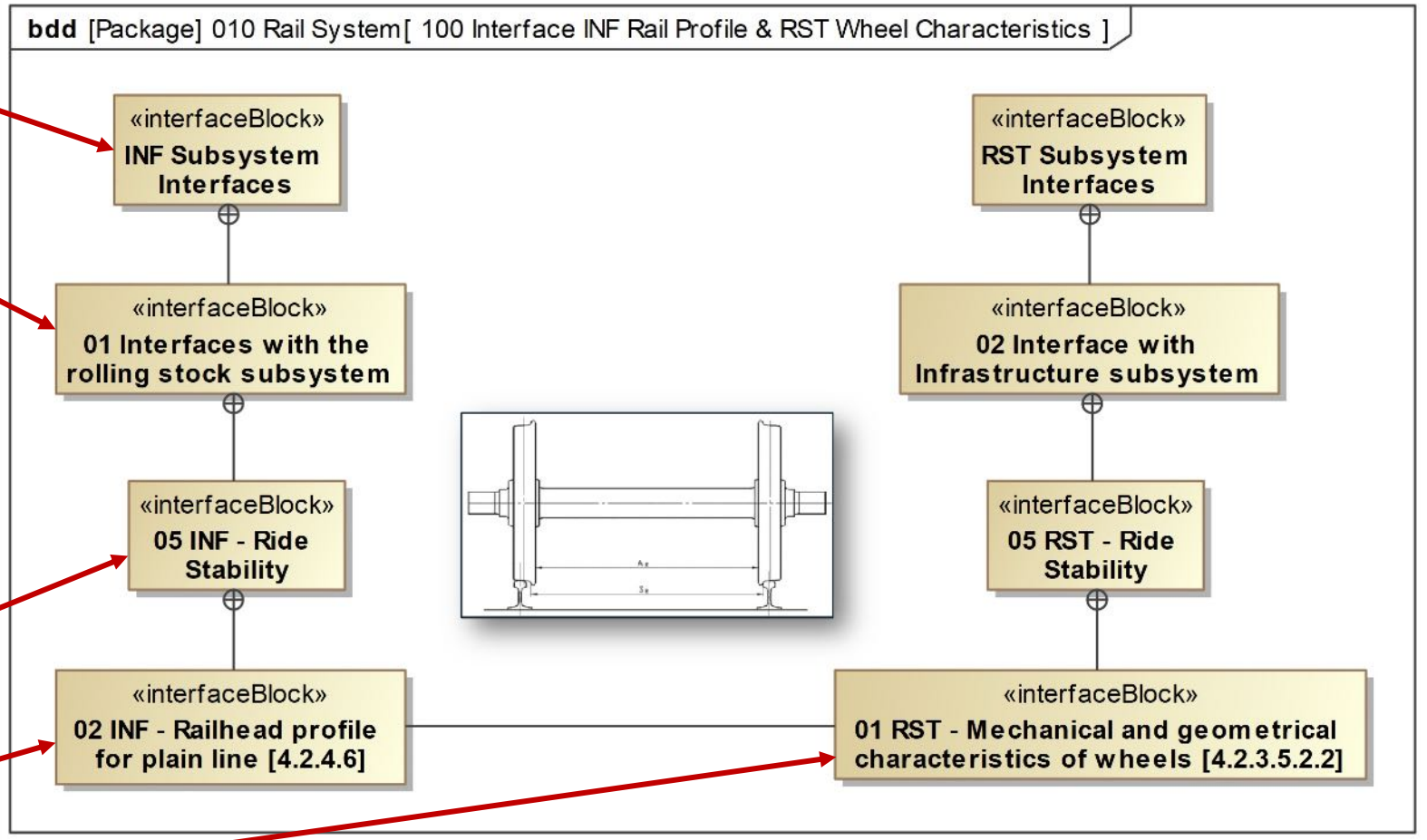
▼ M1

▼ M2

▼ M1

Table 15
Interfaces with the subsystem 'Rolling stock – locomotives and passenger rolling stock'

Interface	► M2 Reference in TSI INF ◀	► M2 Reference in TSI LOC&PAS ◀
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging
Axle load and axle spacing	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1 Resistance of new bridges to traffic loads 4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures 4.2.7.4 Resistance of existing bridges and earthworks to traffic loads	4.2.2.10 Load conditions and weighed mass 4.2.3.2.1 Axle load parameter
Running characteristics	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1.4 Moving forces	4.2.3.4.2.1 Limit values for running safely 4.2.3.4.2.2 Track loading limit values
Ride stability	4.2.4.4 Equivalent conicity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent conicity in service	4.2.3.4.3 Equivalent conicity 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
Longitudinal actions	4.2.6.2 Longitudinal track resistance 4.2.7.1.5 Actions due to traction	4.2.4.5 Braking performance



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: TABLE VIEW (INTERFACE REGISTER VIEW)

02014R1299 — EN — 28.09.2023 — 002.001 — 42

▼ B

4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

▼ M1

▼ M2

▼ M1

Table 15

Interfaces with the subsystem 'Rolling stock – locomotives'

Interface	► M2 Reference in TSI INF ◀
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset
Axle load and axle spacing	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1 Resistance of new bridges to traffic loads 4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures 4.2.7.4 Resistance of existing bridges and earthworks to traffic loads
Running characteristics	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1.4 Nosing forces
Ride stability	4.2.4.4 Equivalent concity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent concity in service
Longitudinal actions	4.2.6.2 Longitudinal track resistance 4.2.7.1.5 Actions due to traction

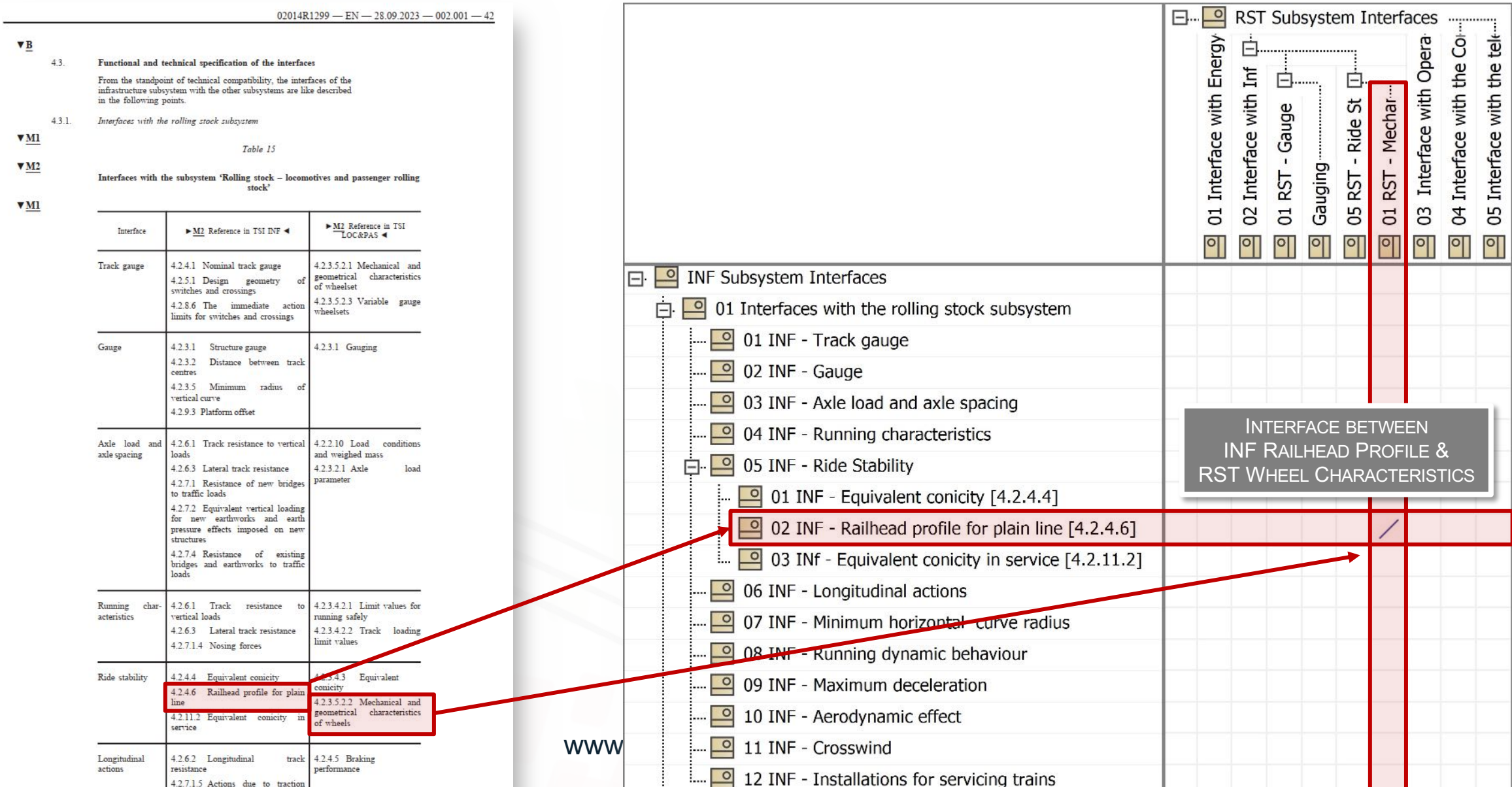
#	△ Name	TSI INF	Interfacing Subsystem	TSI RST (LOC&PAS)
1	INF Subsystem Interfaces			
2	01 Interfaces with the rolling stock subsystem			
3	01 INF - Track gauge			
4	02 INF - Gauge			
5	03 INF - Axle load and axle spacing			
6	04 INF - Running characteristics			
7	05 INF - Ride Stability			
8	01 INF - Equivalent concity [4.2.4.4]			
9	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	TSI-LOC&PAS-1.4.2.3.5.2.24.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
10	03 INF - Equivalent concity in service [4.2.11.2]			
11	06 INF - Longitudinal actions			
12	07 INF - Minimum horizontal curve radius			
13	08 INF - Running dynamic behaviour			
14	09 INF - Maximum deceleration			
15	10 INF - Aerodynamic effect			
16	11 INF - Crosswind			
17	12 INF - Installations for servicing trains			

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33

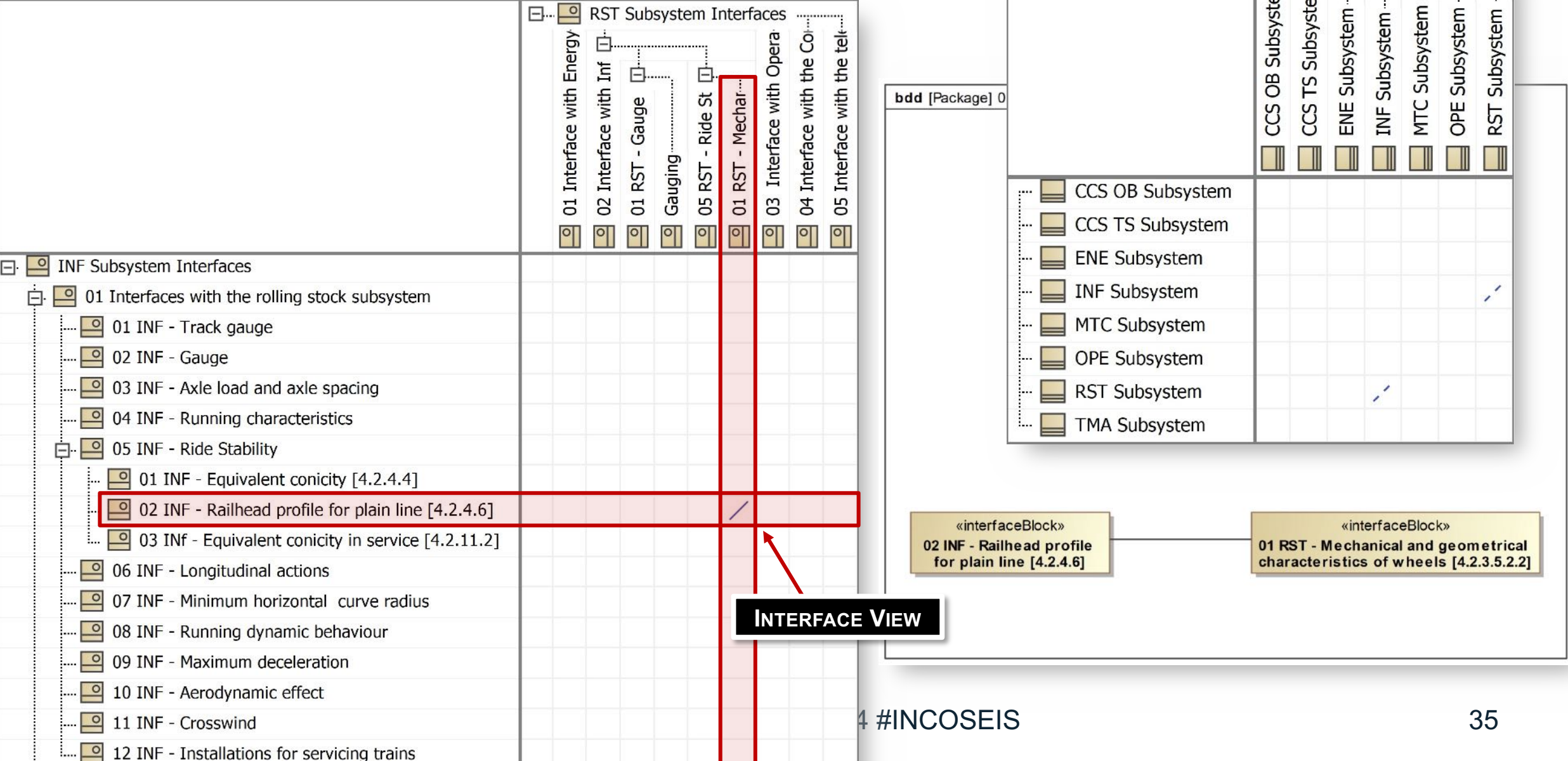
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: DEPENDENCY MATRIX VIEW (N² CHART VIEW)



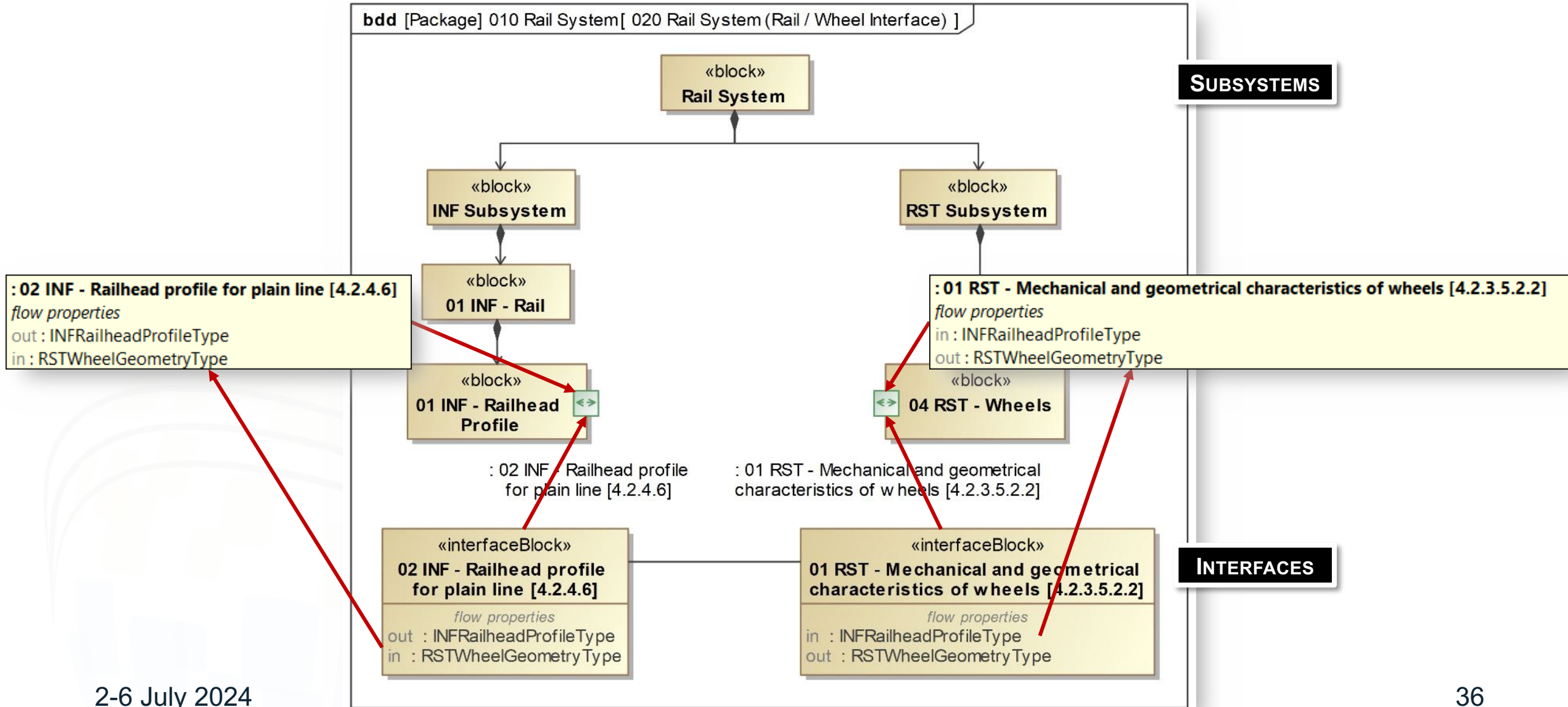
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: SUBSYSTEM ALLOCATION



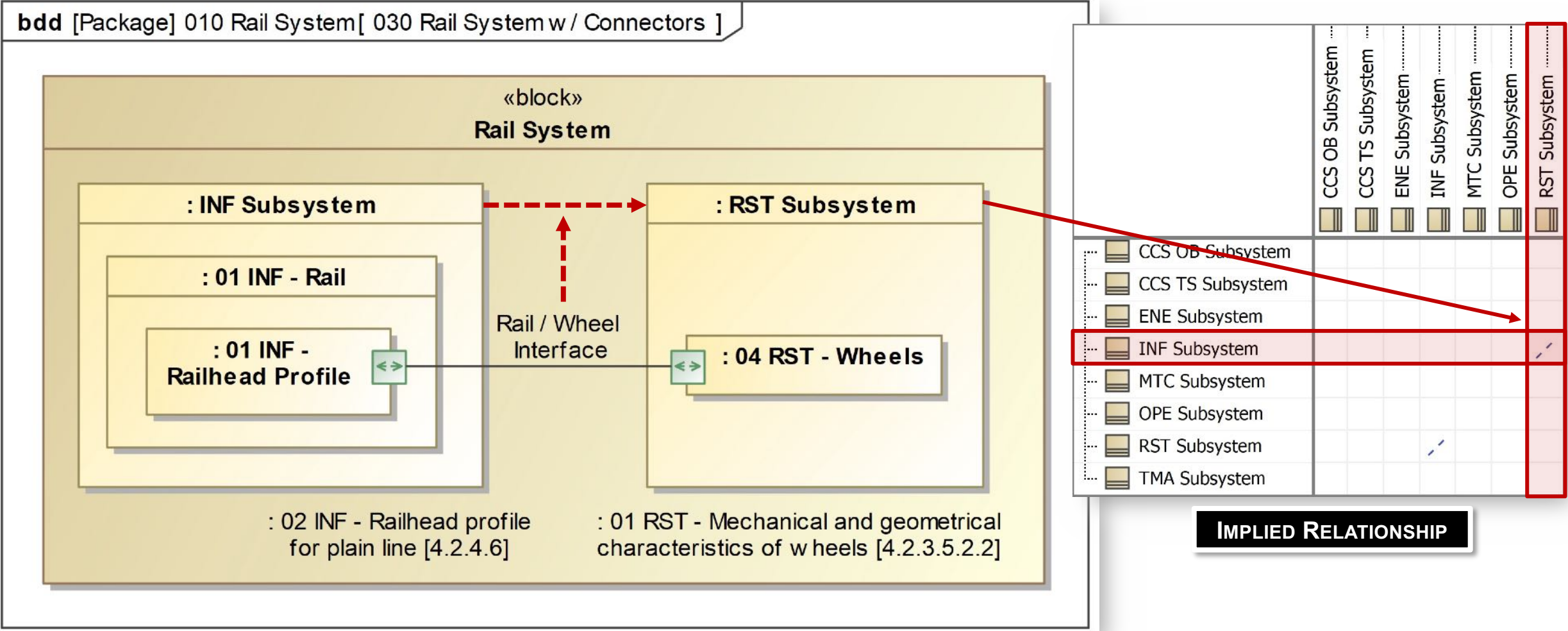
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: SUBSYSTEM ALLOCATION (CONT'D)



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: RAIL SYSTEM WITH INTERNAL STRUCTURE VIEW



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE REGISTER: INFRASTRUCTURE VIEW W/ DETAILS (RAIL/WHEEL INTERFACE)

#	△ Name	VIEWPOINT: INFRASTRUCTURE SUBSYSTEM	Interface Features	Exchange Items	Interfacing Subsystem
1	INF Subsystem Interfaces				
2	01 Interfaces with the rolling stock subsystem	INTERFACE W/ ROLLING STOCK			
3	01 INF - Track gauge				
4	02 INF - Gauge				
5	03 INF - Axle load and axle spacing				
6	04 INF - Running characteristics				
7	05 INF - Ride Stability				
8	01 INF - Equivalent conicity [4.2.4.4]				
9	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 R Railhead profile for plain line	F out : INFRailheadProfileType F in : RSTWheelGeometryType R : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	INFRailheadProfileType RSTWheelGeometryType	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
10	03 INF - Minimum horizontal curve radius [4.2.11.2]	INFRASTRUCTURE RAILHEAD PROFILE	INTERFACE REQUIREMENTS	INTERFACE FEATURES	EXCHANGE ITEMS
11	06 INF - Lateral clearance				INTERFACING ROLLING STOCK WHEELSET CHARACTERISTICS
12	07 INF - Minimum horizontal curve radius				
13	08 INF - Running dynamic behaviour				
14	09 INF - Maximum deceleration				
15	10 INF - Aerodynamic effect				
16	11 INF - Crosswind				
17	12 INF - Installations for servicing trains				
18	02 Interfaces with the energy subsystem				
19	03 Interfaces with the control command and signalling subsystem				
20	04 Interfaces with the operation and traffic management subsystem				

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE REGISTER: BUILDING THE INTERFACE REGISTER

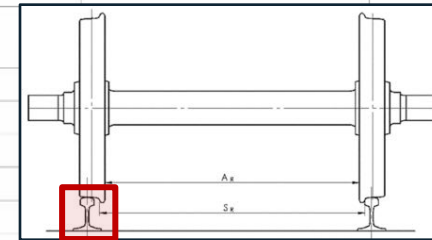
'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



#	△ Name	Interface Requirements	Interface Features	ing Subsystem
1	INF Subsystem Interfaces			
2	01 Interfaces with the rolling stock subsystem			
3	01 INF - Track gauge			
4	01 INF - Nominal track gauge [4.2.4.1]			
5	02 INF - Design geometry of switches and Crossings [4.2.5.1]			
6	03 INF - The immediate action limits for switches and crossings [4.2.8.6]			
7	02 INF - Gauge			
8	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	out : INFStructureGaugeType in : RSTKinematicGaugeType : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFStructureGaugeType RSTKinematicGaugeType 01 RST - Rolling stock kinematic gauge [4.2.3.1]
9	02 INF - Distance between track centres [4.2.3.2]			
10	03 INF - Minimum radius of vertical curve [4.2.3.5]			
11	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	out : INFPlatformOffsetType in : RSTKinematicGaugeType : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFPlatformOffsetType RSTKinematicGaugeType 01 RST - Rolling stock kinematic gauge [4.2.3.1]
12	03 INF - Axle load and axle spacing			
13	01 INF - Track resistance to vertical loads [4.2.6.1]			
14	02 INF - Lateral track resistance [4.2.6.3]			
15	03 INF - Resistance of new bridges to traffic loads [4.2.7.1]			
16	04 INF - Equivalent vertical loading for new earthworks and pressure effects imposed on new structures [4.2.7.2]			
17	05 INF - Resistance of existing bridges and earthworks to traffic [4.2.7.4]			
18	04 INF - Running characteristics			
19	01 INF - Track resistance to vertical loads [4.2.6.1]			
20	02 INF - Lateral track resistance [4.2.6.3]			
21	03 INF - Nosing forces [4.2.7.1.4]			
22	05 INF - Ride Stability			
23	01 INF - Equivalent conicity [4.2.4.4]			
24	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	out : INFRailheadProfileType in : RSTWheelGeometryType : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	INFRailheadProfileType RSTWheelGeometryType 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
25	03 INF - Equivalent conicity in service [4.2.11.2]			
26	06 INF - Longitudinal actions			

How a French rail company spent £12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you



PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
 - Option #1: Use as Template
 - Option #2: Use as Library
 - Option #3: Customize & Taylor
- ❖ **Summary & Conclusion**

MBSI FRAMEWORK USE

[1] USE AS TEMPLATE: DIRECT EDIT (E.G., PROJECT SPECIFIC APPLICATION)

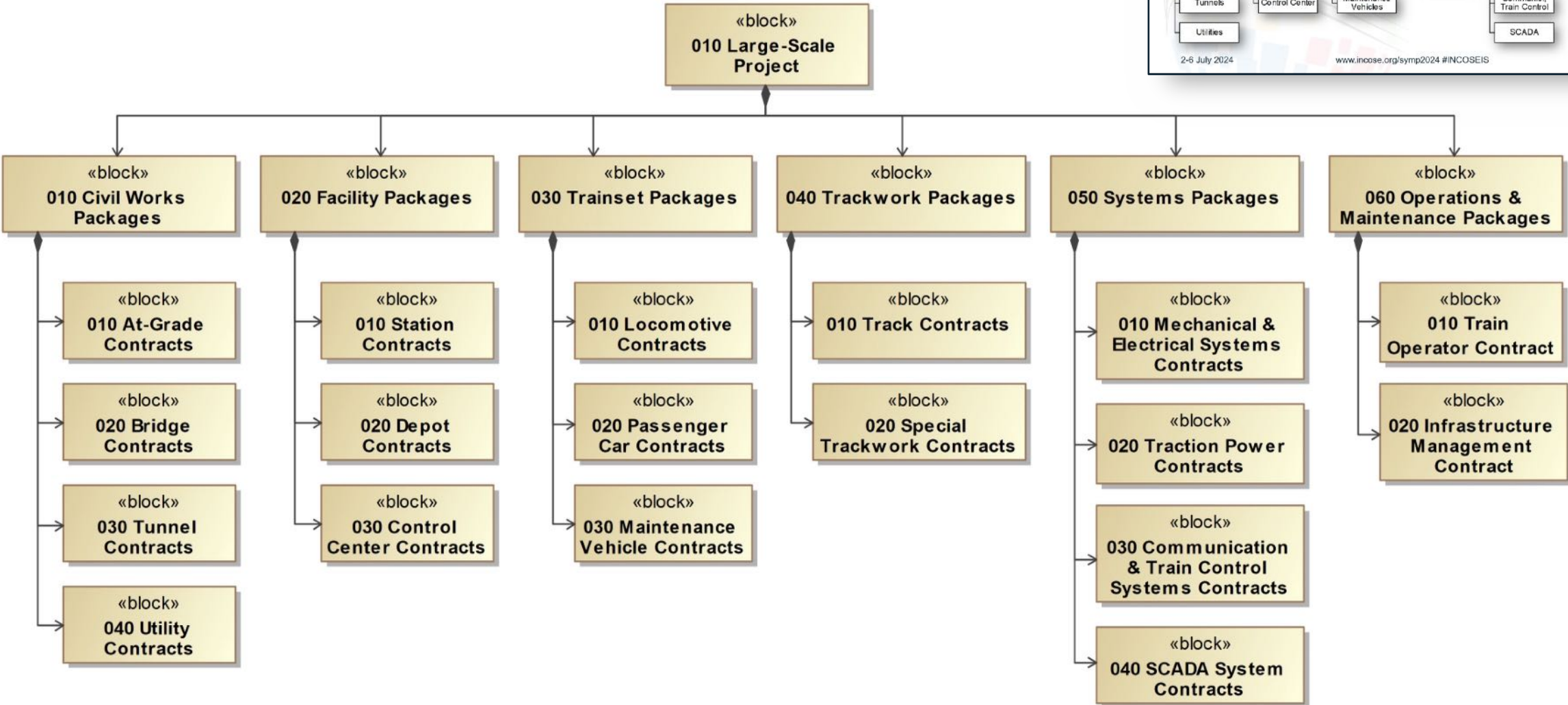
The screenshot displays the MBSI Framework software interface. On the left, a tree view shows the hierarchy of subsystem interfaces, including '01 Interfaces with the rolling stock subsystem' and '02 INF - Gauge'. The main window shows a table of interface requirements and features, filtered by 'Interface Block' and 'INF Subsystem Interfaces'. The table lists various interface requirements and features, such as '01 INF - Nominal track gauge [4.2.4.1]' and '02 INF - Design geometry of switches and Crossings [4.2.5.1]'. A black box with white text is overlaid on the table, stating: 'ADD / EDIT / REMOVE: NOMENCLATURE, SUBSYSTEMS, INTEROPERABLE CONSTITUENTS, REQUIREMENTS, INTERFACES, EXCHANGE ITEMS, ETC.'

#	Name	Interface Requirements	Interface Features	Exchange Items
1	INF Subsystem Interfaces			
2	01 Interfaces with the rolling stock subsystem			
3	01 INF - Track gauge			
4	01 INF - Nominal track gauge [4.2.4.1]			
5	02 INF - Design geometry of switches and Crossings [4.2.5.1]			
6	03 INF - The immediate action limits for switches and crossings [4.2.8.6]			
7	02 INF - Gauge			
8	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	out : INFStructureGaugeType in : RSTKinematicGaugeType 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFStructureGaugeType RSTKinematicGaugeType
9	02 INF - Distance between track centres [4.2.3.2]			
10	03 INF - Minimum radius of vertical curve [4.2.3.5]			
11	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	out : INFPlatformOffsetType in : RSTKinematicGaugeType 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFPlatformOffsetType RSTKinematicGaugeType
12	03 INF - Axle load and axle spacing			
13	01 INF - Track resistance to vertical loads [4.2.6.1]			
14	02 INF - Lateral track resistance [4.2.6.3]			
15	03 INF - Resistance of new bridges to traffic loads [4.2.7.1]			
16	04 INF - Equivalent vertical loading for new earthworks and pressure effects imposed on new structures [4.2.7.2]			
17	05 INF - Resistance of existing bridges and earthworks to traffic [4.2.7.4]			
18	04 INF - Running characteristics			
19	01 INF - Track resistance to vertical loads [4.2.6.1]			
20	02 INF - Lateral track resistance [4.2.6.3]			
21	03 INF - Nosing forces [4.2.7.1.4]			
22	05 INF - Ride Stability			
23	01 INF - Equivalent conicity [4.2.4.4]			

MBSI Framework Use

[2] USE AS LIBRARY: CONTRACT BREAKDOWN STRUCTURE

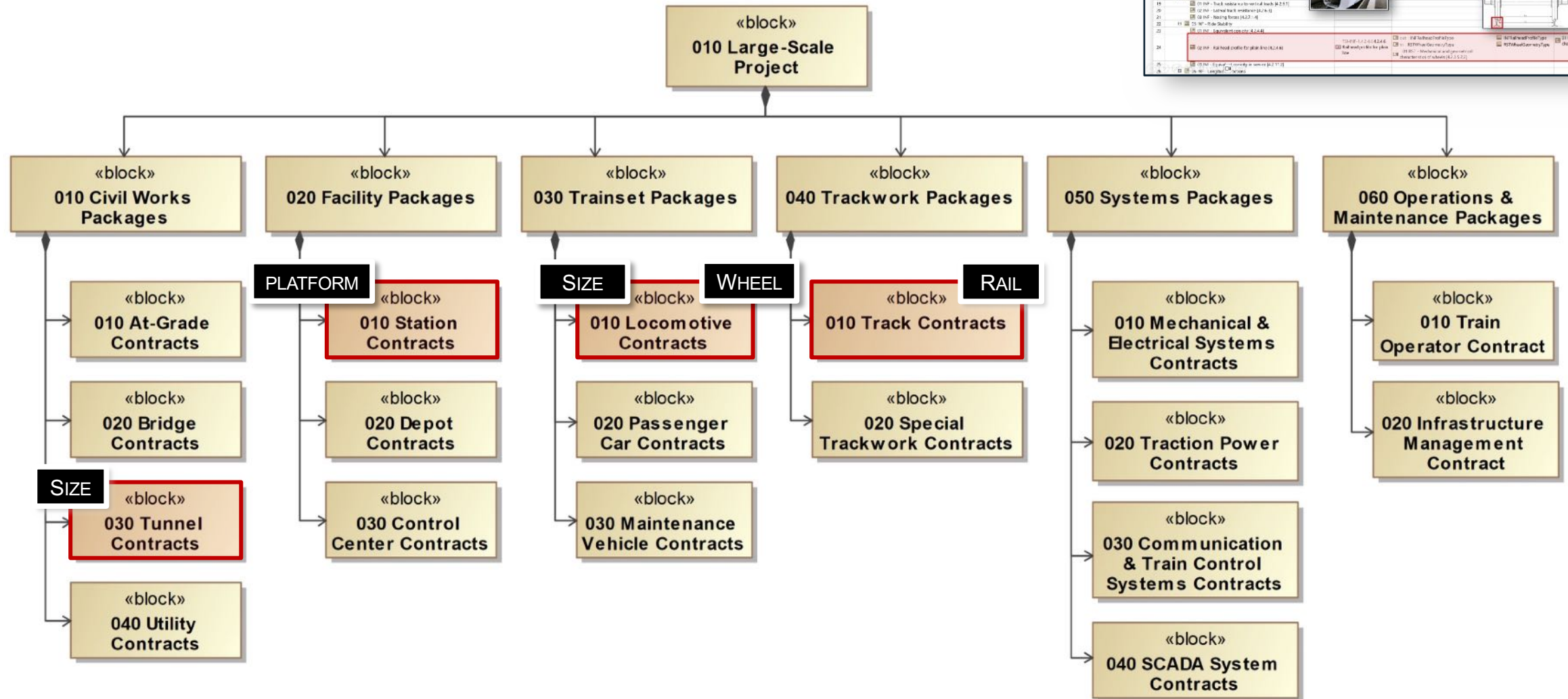
package 020 Contract Breakdown Structure [010 Contract Breakdown Structure]



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: INTERFACE EXAMPLE CHALLENGES

package 020 Contract Breakdown n Structure [010 Contract Breakdown n Structure]

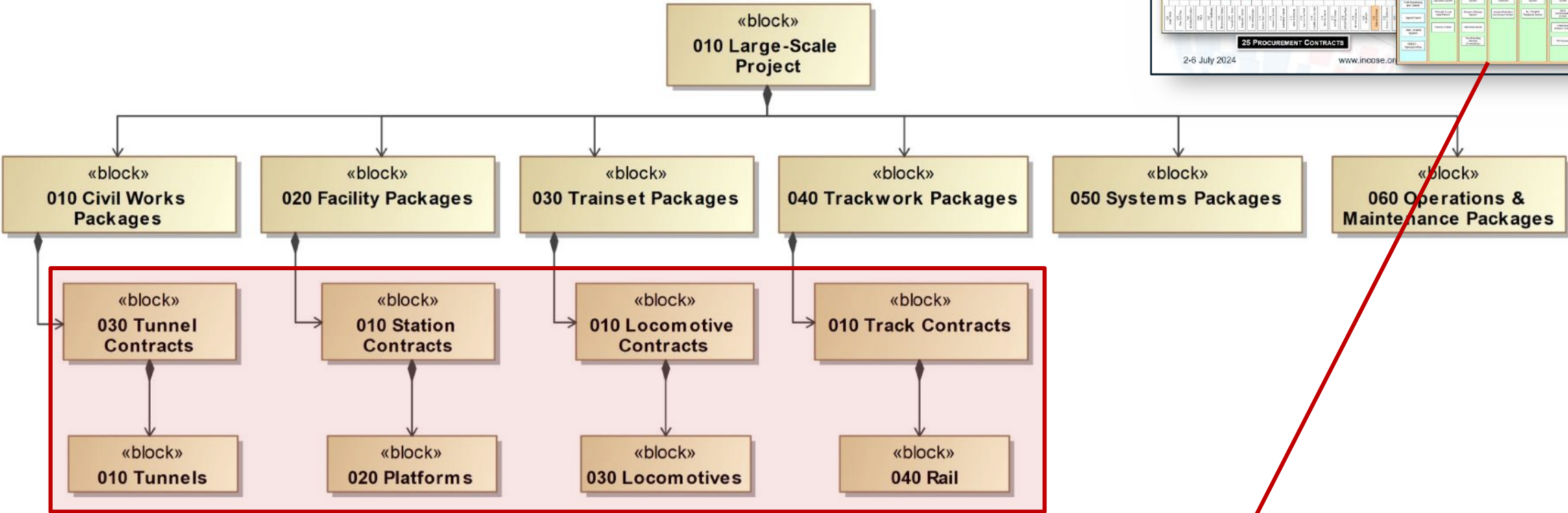


MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK			
INTERFACE REGISTER: BUILDING THE INTERFACE REGISTER			
#	Interface Name	Interface Key elements	Interface Elements
1	010 System Interface	010 System Interface	010 System Interface
2	010 System Interface	010 System Interface	010 System Interface
3	010 System Interface	010 System Interface	010 System Interface
4	010 System Interface	010 System Interface	010 System Interface
5	010 System Interface	010 System Interface	010 System Interface
6	010 System Interface	010 System Interface	010 System Interface
7	010 System Interface	010 System Interface	010 System Interface
8	010 System Interface	010 System Interface	010 System Interface
9	010 System Interface	010 System Interface	010 System Interface
10	010 System Interface	010 System Interface	010 System Interface
11	010 System Interface	010 System Interface	010 System Interface
12	010 System Interface	010 System Interface	010 System Interface
13	010 System Interface	010 System Interface	010 System Interface
14	010 System Interface	010 System Interface	010 System Interface
15	010 System Interface	010 System Interface	010 System Interface
16	010 System Interface	010 System Interface	010 System Interface
17	010 System Interface	010 System Interface	010 System Interface
18	010 System Interface	010 System Interface	010 System Interface
19	010 System Interface	010 System Interface	010 System Interface
20	010 System Interface	010 System Interface	010 System Interface
21	010 System Interface	010 System Interface	010 System Interface
22	010 System Interface	010 System Interface	010 System Interface
23	010 System Interface	010 System Interface	010 System Interface
24	010 System Interface	010 System Interface	010 System Interface
25	010 System Interface	010 System Interface	010 System Interface
26	010 System Interface	010 System Interface	010 System Interface
27	010 System Interface	010 System Interface	010 System Interface
28	010 System Interface	010 System Interface	010 System Interface
29	010 System Interface	010 System Interface	010 System Interface
30	010 System Interface	010 System Interface	010 System Interface
31	010 System Interface	010 System Interface	010 System Interface
32	010 System Interface	010 System Interface	010 System Interface
33	010 System Interface	010 System Interface	010 System Interface
34	010 System Interface	010 System Interface	010 System Interface
35	010 System Interface	010 System Interface	010 System Interface
36	010 System Interface	010 System Interface	010 System Interface
37	010 System Interface	010 System Interface	010 System Interface
38	010 System Interface	010 System Interface	010 System Interface
39	010 System Interface	010 System Interface	010 System Interface
40	010 System Interface	010 System Interface	010 System Interface
41	010 System Interface	010 System Interface	010 System Interface
42	010 System Interface	010 System Interface	010 System Interface
43	010 System Interface	010 System Interface	010 System Interface
44	010 System Interface	010 System Interface	010 System Interface
45	010 System Interface	010 System Interface	010 System Interface
46	010 System Interface	010 System Interface	010 System Interface
47	010 System Interface	010 System Interface	010 System Interface
48	010 System Interface	010 System Interface	010 System Interface
49	010 System Interface	010 System Interface	010 System Interface
50	010 System Interface	010 System Interface	010 System Interface

MBSI FRAMEWORK USE

[2] USE AS LIBRARY: SYSTEM BREAKDOWN STRUCTURE

package 030 System Breakdown n Structure [010 System Breakdown n Structure]



BACKGROUND, CHALLENGES & OBJECTIVES
LARGE-SCALE PROJECTS: EXAMPLE – ARC TUNNEL PROJECT

System Engineering
ARC Project – Contract Packages

System Engineering
Railroad Systems Contract

Thirty (30) RRS sub-systems

25 PROCUREMENT CONTRACTS

2-6 July 2024

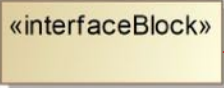
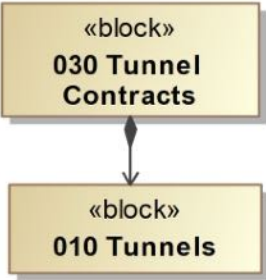
www.incoose.org

DUE TO STAGGERED CONTRACT PROCUREMENTS, SYSTEM BREAKDOWN IS OFTEN PERFORMED BY CONTRACT PACKAGE (BETTER: BY LARGE-SCALE PROJECT W/ CONTRACT ALLOCATION)

MBSI Framework Use

[2] USE AS LIBRARY: INTERFACE ALLOCATION

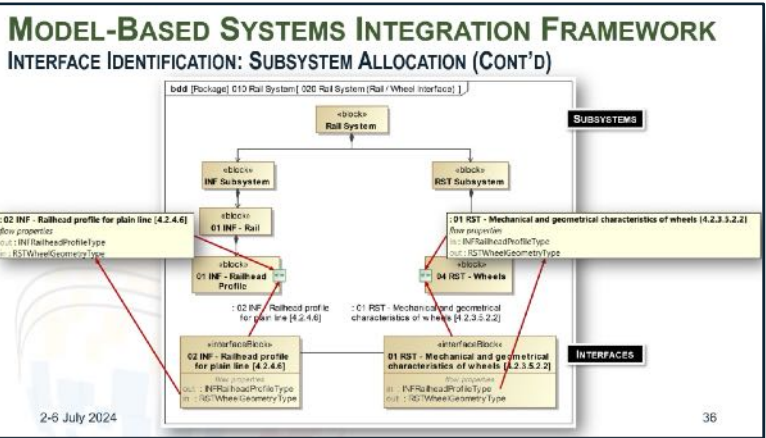
package 040 Interfaces [010 Interface Allocation]



The screenshot shows a tree view of the MBSI Library. The tree structure is as follows:

- MBSI Library MBSI Framework.Rev1.2024-06-22.mdzip
 - 020 Requirements
 - 030 Structure
 - 040 Interfaces
 - 020 INF Subsystem
 - INF Subsystem Interfaces
 - 01 Interfaces with the rolling stock subsystem
 - 01 INF - Track gauge
 - 02 INF - Gauge
 - 01 INF - Structure gauge [4.2.3.1]
 - 02 INF - Distance between track centres [4.2.3.2]
 - 03 INF - Minimum radius of vertical curve [4.2.3.3]
 - 04 INF - Platform offset [4.2.9.3]
 - 03 INF - Axle load and axle spacing

The item "01 INF - Structure gauge [4.2.3.1]" is highlighted with a red box. At the bottom of the window, there is a checkbox for "Apply Filter (Ctrl+Space)" and a "Select" button.



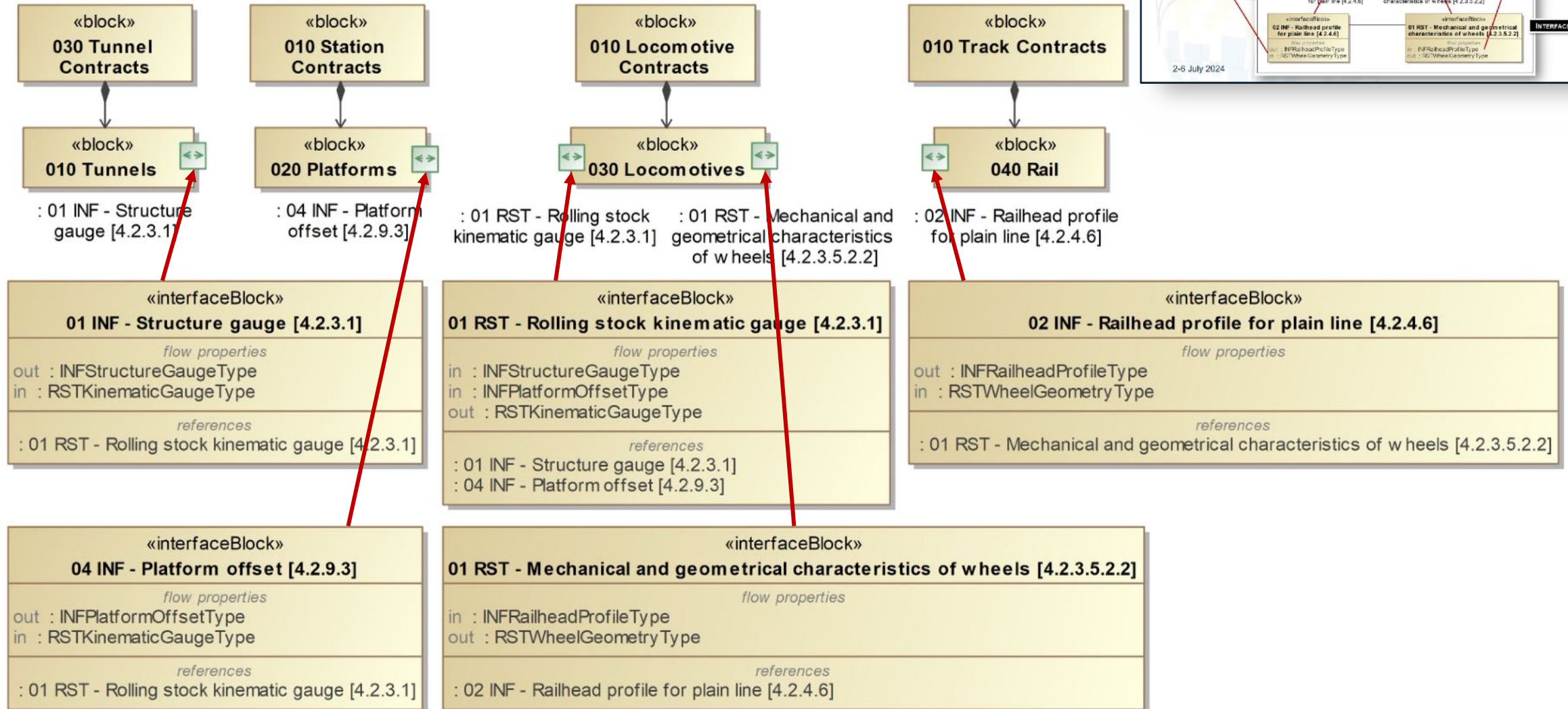
[2] USE AS LIBRARY: INTERFACE ALLOCATION (CONT'D)



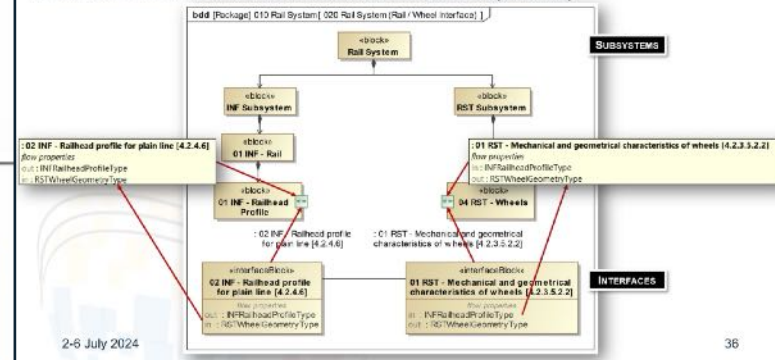
MBSI FRAMEWORK USE

[2] USE AS LIBRARY: INTERFACE ALLOCATION (CONT'D)

package 040 Interfaces [010 Interface Allocation]



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK INTERFACE IDENTIFICATION: SUBSYSTEM ALLOCATION (CONT'D)



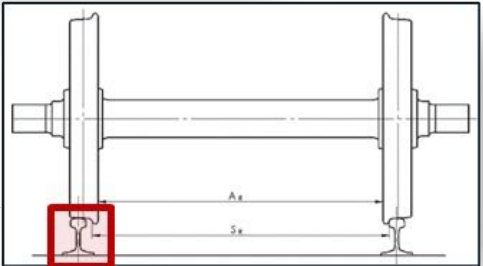
2-8 July 2024

36

MBSI FRAMEWORK USE

[2] USE AS LIBRARY: CONTRACT INTERFACE MATRIX (N² CHART)

	020 Civil Works Cont	010 At-Grade Contra	020 Bridge Contract	030 Tunnel Contract	040 Utility Contracts	030 Facilities Contract	010 Station Contract	020 Depot Contracts	030 Control Center C	040 Trainset Contract	010 Locomotive Con	020 Passenger Car C	030 Maintenance Ve	050 Trackwork Conti	010 Track Contracts	020 Special Trackwo
020 Civil Works Contracts											1					
010 At-Grade Contracts																
020 Bridge Contracts																
030 Tunnel Contracts										1	/					
040 Utility Contracts																
030 Facilities Contracts										1						
010 Station Contracts										1	/					
020 Depot Contracts																
030 Control Center Contracts																
040 Trainset Contracts				1			1								1	
010 Locomotive Contracts	1		/			1	/							1	/	
020 Passenger Car Contracts																
030 Maintenance Vehicle Contracts																
050 Trackwork Contracts											1					
010 Track Contracts											1	/				
020 Special Trackwork Contracts																



SEIS

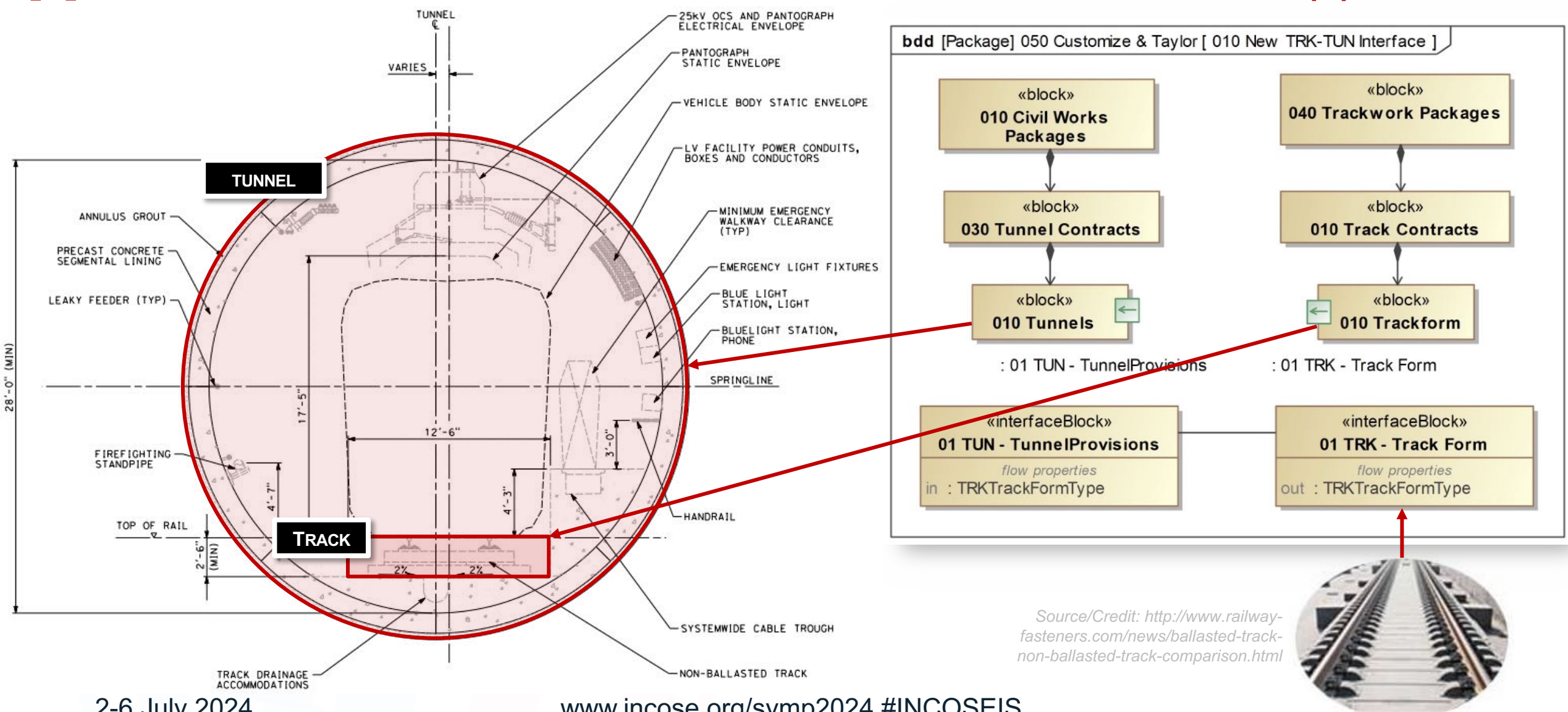
MBSI FRAMEWORK USE

[2] USE AS LIBRARY: CONTRACT SPECIFIC INTERFACE REGISTER

#	△ Name	System Elements	Interfaces	Interface Requirements	Interface Features
1	020 Civil Works				
2	010 At-Grade				
3	020 Bridge Contracts				
4	030 Tunnel Contracts	010 Tunnels	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	out : INFStructureGaugeType in : RSTKinematicGaugeType : 01 RST - Rolling stock kinematic gauge [4.2.3.1]
5	040 Utility Contracts				
6	030 Facilities Contracts				
7	010 Station Contracts	020 Platforms	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	out : INFPlatformOffsetType in : RSTKinematicGaugeType : 01 RST - Rolling stock kinematic gauge [4.2.3.1]
8	020 Depot Contracts				
9	030 Control Center Contracts				
10	040 Trainset Contracts				
11	010 Locomotive Contracts	030 Locomotives	01 RST - Rolling stock kinematic gauge [4.2.3.1] 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	TSI-LOC&PAS-1.4.2.3.14.2.3.1. Gauging	in : INFStructureGaugeType in : INFPlatformOffsetType out : RSTKinematicGaugeType : 01 INF - Structure gauge [4.2.3.1] : 04 INF - Platform offset [4.2.9.3] in : INFRailheadProfileType out : RSTWheelGeometryType : 02 INF - Railhead profile for plain line [4.2.4.6]
12	020 Passenger Car Contracts				
13	030 Maintenance Vehicle Contracts				
14	050 Trackwork Contracts				
15	010 Track Contracts	040 Rail	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	out : INFRailheadProfileType in : RSTWheelGeometryType : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
16	020 Special Trackwork Contracts				

MBSI FRAMEWORK USE

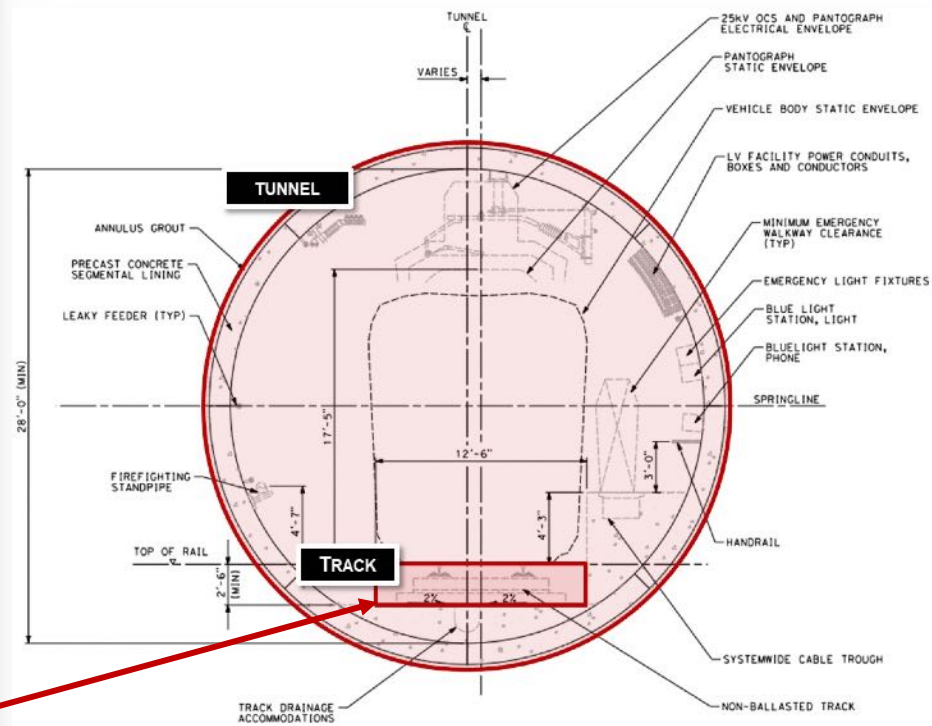
[3] CUSTOMIZE & TAYLOR: ADDING NEW, PROJECT-SPECIFIC INTERFACE(S)



MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: CONTRACT INTERFACE MATRIX (N² CHART)

	020 Civil Works Cont	010 At-Grade Contra	020 Bridge Contract	030 Tunnel Contract	040 Utility Contracts	030 Facilities Contract	010 Station Contract	020 Depot Contracts	030 Control Center C	040 Trainset Contract	010 Locomotive Con	020 Passenger Car C	030 Maintenance Ve	050 Trackwork Conti	010 Track Contracts	020 Special Trackwo
020 Civil Works Contracts										1					1	
010 At-Grade Contracts																
020 Bridge Contracts																
030 Tunnel Contracts										1				1		
040 Utility Contracts																
030 Facilities Contracts										1						
010 Station Contracts										1						
020 Depot Contracts																
030 Control Center Contracts																
040 Trainset Contracts				1		1									1	
010 Locomotive Contracts	1					1								1		
020 Passenger Car Contracts																
030 Maintenance Vehicle Contracts																
050 Trackwork Contracts				1							1					
010 Track Contracts	1									1						
020 Special Trackwork Contracts																



MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: ADDING PROJECT-SPECIFIC INTERFACE REQUIREMENTS

#	△ Name	Interface Requirements	Interface Features	Exchange Items	Interfacing Subsystem
1	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	out : INFStructureGaugeType in : RSTKinematicGaugeType : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFStructureGaugeType RSTKinematicGaugeType	01 RST - Rolling stock kinematic gauge [4.2.3.1]
2	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	LOC&PAS-TSI-1.4.2.3.5.2.2 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels	in : INFRailheadProfileType out : RSTWheelGeometryType : 02 INF - Railhead profile for plain line [4.2.4.6]	INFRailheadProfileType RSTWheelGeometryType	02 INF - Railhead profile for plain line [4.2.4.6]
3	01 RST - Rolling stock kinematic gauge [4.2.3.1]	LOC&PAS-TSI-1.4.2.3.1 4.2.3.1. Gauging	in : INFStructureGaugeType in : INFPlatformOffsetType out : RSTKinematicGaugeType : 01 INF - Structure gauge [4.2.3.1] : 04 INF - Platform offset [4.2.9.3]	INFStructureGaugeType INFPlatformOffsetType RSTKinematicGaugeType	01 INF - Structure gauge [4.2.3.1] 04 INF - Platform offset [4.2.9.3]
4	01 TRK - Track Form	DEFINE CONTRACT –SPECIFIC INTERFACE REQUIREMENTS		out : TRKTrackFormType : 01 TUN - TunnelProvisions	01 TUN - TunnelProvisions
5	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	out : INFRailheadProfileType in : RSTWheelGeometryType : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	INFRailheadProfileType RSTWheelGeometryType	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
6	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	out : INFPlatformOffsetType in : RSTKinematicGaugeType : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFPlatformOffsetType RSTKinematicGaugeType	01 RST - Rolling stock kinematic gauge [4.2.3.1]



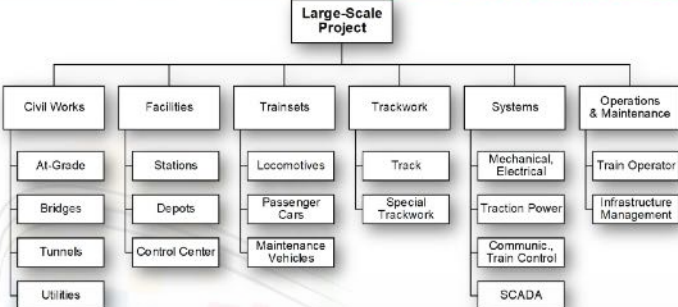
PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

SUMMARY & CONCLUSION

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INDUSTRY TYPICAL **CONTRACT BREAKDOWN STRUCTURE**



BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INTERFACE MANAGEMENT **REALITIES**

How a French rail company spent £12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you.

TRAINS
STATIONS

'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels

OPERATORS
TUNNELS

BACKGROUND, CHALLENGES & OBJECTIVES

OBJECTIVES: PREDICTABLE, REPEATABLE PROCESS, CONVENIENT, INTEROPERABLE

- CMMI Level 1: Initial**
- Unpredictable Processes, relying on SME Expertise (or Lack Thereof)
- CMMI Level 2: Managed**
- Repeatable Processes w/in Project
- CMMI Level 3: Defined**
- Repeatable Processes w/in Organization
 - Project Tailors Processes from Organizational Standards
- Additional Objectives**
- Convenience: Ready (Easy) to Use
 - Interoperable: Compatible w/ Future Contracts

CONCLUSION

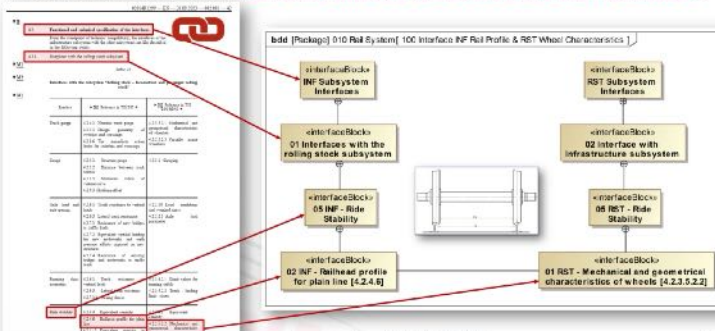


MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI) – **KEY INTERFACES**

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: **CREATING INTERFACE TABLES IN MBSI FRAMEWORK**



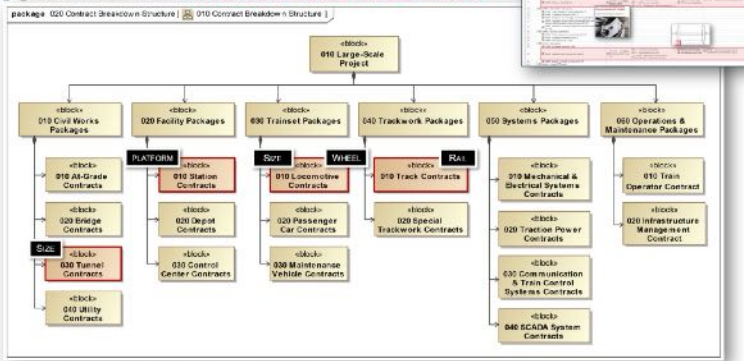
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE REGISTER: **INFRASTRUCTURE VIEW W/ DETAILS (RAIL/WHEEL INTERFACE)**

#	Interface Features	Exchange Items	Interfacing Subsystem
1	01 INF - Subsystem interfaces		
2	02 INF - Track gauge		
3	03 INF - Gauge		
4	04 INF - Rail head and axle spacing		
5	05 INF - Running characteristics		
6	06 INF - Rule Stability		
7	07 INF - Equipment capacity (A.2.4.4)		
8	08 INF - Railhead profile for plain line (A.2.4.4)		
9	09 INF - Minimum horizontal curve radius		
10	10 INF - Running dynamic behavior		
11	11 INF - Minimum speed		
12	12 INF - Aerodynamic effect		
13	13 INF - Occupancy		
14	14 INF - Insulation for working limits		
15	15 INF - Insulation with the energy subsystem		
16	16 INF - Insulation with the control and signaling subsystem		
17	17 INF - Insulation with the operation and traffic management subsystem		
18	18 INF - Insulation with the operation and traffic management subsystem		
19	19 INF - Insulation with the operation and traffic management subsystem		
20	20 INF - Insulation with the operation and traffic management subsystem		

MBSI FRAMEWORK USE

[2] USE AS LIBRARY: **INTERFACE EXAMPLE CHALLENGES**



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: **CONTRACT SPECIFIC INTERFACE REGISTER**

#	Interface Features	Exchange Items	Interfacing Subsystem
1	01 INF - Subsystem interfaces		
2	02 INF - Track gauge		
3	03 INF - Gauge		
4	04 INF - Rail head and axle spacing		
5	05 INF - Running characteristics		
6	06 INF - Rule Stability		
7	07 INF - Equipment capacity (A.2.4.4)		
8	08 INF - Railhead profile for plain line (A.2.4.4)		
9	09 INF - Minimum horizontal curve radius		
10	10 INF - Running dynamic behavior		
11	11 INF - Minimum speed		
12	12 INF - Aerodynamic effect		
13	13 INF - Occupancy		
14	14 INF - Insulation for working limits		
15	15 INF - Insulation with the energy subsystem		
16	16 INF - Insulation with the control and signaling subsystem		
17	17 INF - Insulation with the operation and traffic management subsystem		
18	18 INF - Insulation with the operation and traffic management subsystem		
19	19 INF - Insulation with the operation and traffic management subsystem		
20	20 INF - Insulation with the operation and traffic management subsystem		

MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: **CONTRACT INTERFACE MATRIX (N² CHART)**

#	Interface Features	Exchange Items	Interfacing Subsystem
1	01 INF - Subsystem interfaces		
2	02 INF - Track gauge		
3	03 INF - Gauge		
4	04 INF - Rail head and axle spacing		
5	05 INF - Running characteristics		
6	06 INF - Rule Stability		
7	07 INF - Equipment capacity (A.2.4.4)		
8	08 INF - Railhead profile for plain line (A.2.4.4)		
9	09 INF - Minimum horizontal curve radius		
10	10 INF - Running dynamic behavior		
11	11 INF - Minimum speed		
12	12 INF - Aerodynamic effect		
13	13 INF - Occupancy		
14	14 INF - Insulation for working limits		
15	15 INF - Insulation with the energy subsystem		
16	16 INF - Insulation with the control and signaling subsystem		
17	17 INF - Insulation with the operation and traffic management subsystem		
18	18 INF - Insulation with the operation and traffic management subsystem		
19	19 INF - Insulation with the operation and traffic management subsystem		
20	20 INF - Insulation with the operation and traffic management subsystem		



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