



34th Annual **INCOSE**
international symposium

hybrid event

Dublin, Ireland
July 2 - 6, 2024



Jul 5, 2024: 09:00-09:40 AM (Session 10.5.1: Modular Open Systems Approach [MOSA])

Towards a Reusable Model-Based Systems Integration [MBSI] Framework

2-6 July 2024

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AGENDA

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration [MBSI] Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

MOTIVATION

IS2020 PAPER: CONSIDERATIONS FOR FUTURE WORK



30th Annual INCOS
international symposium
Virtual Event
July 20 - 22, 2020

Case Study: Achieving System Integration through Interoperability in a large System of Systems (SoS)

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Abstract. This paper provides a case study on system of systems engineering (SoSE) being performed in a multi-billion-dollar program – the California High-Speed Rail System – viewed from the systems integration perspective. The paper discusses why the subject program of project (PoP) can be viewed as a system of systems (SoS), identifies the SoSE challenges faced, describes the SoSE activities performed, and summarizes the achieved outcomes and conclusions as today.

Specific SoSE challenges discussed include SoS authority, leadership, architecting, collaborative integration, and emergence. The paper reviews how decision-making in independently operated and managed constituent systems (projects) resulted in unanticipated SoS emergent behavior which is one of the key challenges in the engineering of SoS.

The paper further discusses the performed SoSE activities, including an international best practice review, the tailoring of SoSE to the specific SoSE challenges, and provides examples where SoSE principles are being applied to perform successful SoS integration.

Brief Introduction: System of Systems

A system of systems is a system-of-interest (SOI) whose elements are themselves systems. A SoS brings together a set of systems for a task that none of the systems can accomplish on its own. Each constituent system (CS) retains its own management, goals, and resources while coordinating within the SoS and adapting to meet SoS goals (ISO/IEC/IEEE 15288, 2015).

SoS Characteristics: SoS are characterized by **managerial and operational independence** of the constituent systems, which in many cases were developed and continue to support originally identified users of the constituent concurrently with users of the overall SoS. In other contexts, the SoS is often referred to as a **System of Interest** (SOI) with a set of systems for a task within a SoS.

interface standards (Figure 14) into early civil works contracts, thereby enabling interoperable constituent systems / contracts.

- **SoS Autonomy, Emergence & Constituent Systems:** Considered the primary design-build project delivery methods that encourages innovation within constituent systems (contracts), but may result in unanticipated and/or undesirable SoS behavior. The clear communication of the interoperable interfaces (Figure 15) and compliant implementation of interoperable interface standards (Figure 16 & 17) are numerous changes by contractors during design and construction.
- **SoS Integration:** CHSRS systems integration is anticipated to benefit significantly from interoperable interfaces and contracts (Figure 18), avoiding the late discovery of interfaces and the non-compatibility of existing interfaces many programs suffer when relying on the traditional systems integration approach.

Conclusion

As mentioned in the SoS introduction, identifying and addressing unanticipated and/or unemergent behavior is a frequent challenge in the engineering of SoS.

In summary, the prevailing design-build project delivery methods encourages innovation (changes or emergent behavior) within a constituent system. As contracts are issued independently, there are no incentives to consider their roles in the SoS. Additionally, the traditional integration approach relies on coordinating active contracts once they have been issued and the provision of specific interface definitions, leading potentially to late integration challenges.

In conclusion, it can be confidently stated that the tailored CHSRS systems integration approach addresses the challenges described above. Key interfaces are proactively identified and using industry accepted interoperable standards. Contractors can take full advantage of innovative solutions as long as they can demonstrate conformance to the identified interface standards. The tailored CHSRS systems integration approach creates modular interoperable constituent systems that can be efficiently integrated into a SoS, successfully achieving system integration through interoperability.

Considerations for Future Work

Based on valuable peer review feedback, the following topics are being considered for future INCOSE papers and publications:

- **Lessons Learned:** As of today, only CHSRS Civil Works contracts have been issued. Lessons learned from the high-speed rail system, trainset, and track system integration approach. The discussion will include the use of the agile development approach for the system integration approach.
- **System Integration Framework:** Use this case study to define a System Integration Framework that other projects could follow. The use of agile processes as well as the use of the system integration framework will be discussed.

CHSRS External: Figure 2 presents the CHSRS as a constituent system within a larger SoS. Other interfacing constituent systems and organizations included, but are not limited to adjacent railroads and highways requiring intrusion detection and protection, utilities providing high-voltage power, potential interfaces with U.S. Geological Survey (USGS) for the earthquake hazards program, shared track operation in existing rail corridors in the San Francisco area (Caltrain) and Los Angeles (Metrolink), irrigation canals, local counties, cities, businesses, property owners, and many more.



Figure 2. CHSRS as a Constituent System within a Larger SoS

CHSRS Program: Figure 3 presents a simplified life cycle view. The CHSRS program will be procured (acquired) in form of several projects (supplied). Each project is managed and operated independently by a design-build project manager (DBPM) contractor. Additionally, each contractor will be managed and operated project and construction manager (PM/CM) reporting both to a local program manager (PM) and to the program manager (PM) (DBOM) contractor.

MULTI-CONTRACT PROGRAMS (COMMONLY STAGGERED)

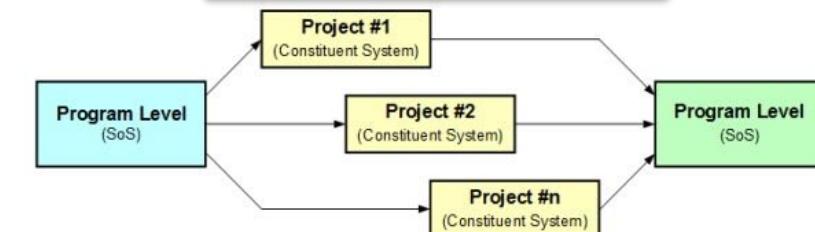


Figure 3. CHSRS as a Program (SoS) of Projects (Constituent Systems)

CHSRS Program Organization: The California High-Speed Rail Authority organization can be characterized as a matrix organization, with three main vertical **program delivery pillars** (strategic delivery, infrastructure delivery, rail systems delivery), supported by horizontal **functional support groups** and **executive support functions**, as presented in Figure 4 below. The **network integration** section, part of the **rail systems delivery** branch, is led by the deputy director of network integration and program compliance responsible for managing the process for integrating all aspects of the rail system and for developing and retaining documentation related to systems engineering, including requirements management, configuration management, interface management, RAM (reliability, availability, maintainability), and system certification (CHSRS, 2018). The **systems integration lead** position reports to deputy director of network integration and program compliance (CHSRS, 2018).

MOTIVATION

IS2020 PAPER: CONSIDERATIONS FOR FUTURE WORK (CONT'D)

SYSTEM OF SYSTEMS (SoS) CHALLENGES

deliverables include interface interface coordination work (interface agreements), coordination of interface demarcation drawings)

Description of the Challenges F

Using the background information provided above, this section provides an overview of the systems integration challenges the CHSRS has faced, provided from the perspective of the program manager.

SoS Authority: While the CHSRS as a whole could be classified as a systems integration function, the authority for systems integration has rather limited power and authority within the three active CHSRS civil works contracts (constituent systems) and the infrastructure delivery branch, not the rail systems branch which oversees the three design and construction contracts managed by independent project and construction managers (PCM).

SoS Architecture & Leadership: There is a lack of recognition in the industry that the program manager becomes the de-facto SoS architect. Figure 5. By decomposing a program into contract/procurement packages, the program manager effectively creates large-scale constituent systems with numerous interfaces that require careful management throughout the life cycle as a precursor to program integration at a later stage.

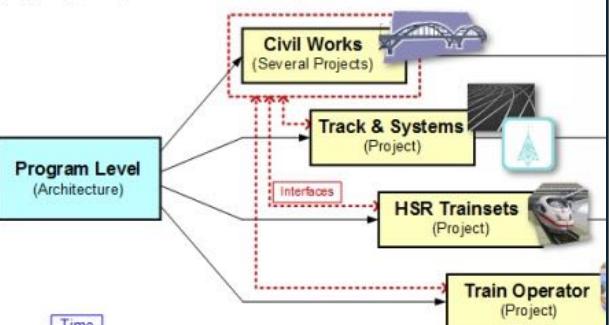


Figure 5. Program Manager as the SoS Architect

SoS Collaboration & Integration: While the traditional U.S. infrastructure industry approach to systems integration may work in a single project, with all interfacing parties present and available for coordination, the same is not true in an SoS/program environment such as the CHSRS, if one or more of the projects/contracts are not available for coordination. For example, the CHSRS tunnel cross-section, highlighting several key interfaces between

takes a long time, a tunnel contract would be issued years after creating a significant challenge in identifying the applicable requirements, and interface implementation in the early civil works

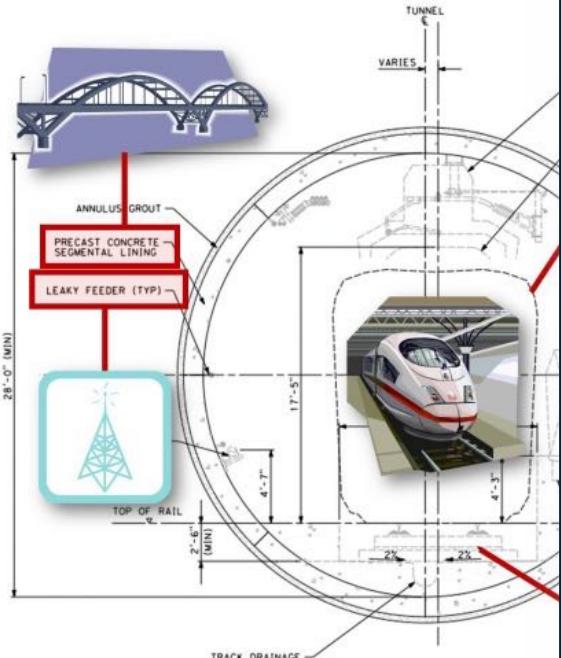


Figure 6. SoS Interface Requirements for Civil Works

The problem is exacerbated due to the fact that owners have implementation (here interface) details out of concern of providing inconsistent information to the contractors, possibly resulting in inconsistent interface requirements. Consequently, contracts often lack interface specificities such as interface requirements. As contracts are commonly fixed-price contracts, there is also a significant risk that any changes during the project may be claimed as additional out-of-scope work.

SoS Autonomy & Emergence: As CHSRS contracts are independently operated, there are no contractual relationships between each other. In the project delivery method, contractors are deliberately encouraged to meet the contract requirements. For example, the CHSRS civil works structure (bridge) for a specific track/guideway area, and waives

INTEROPERABLE INTERFACE SPECIFICATIONS

ifications for the trainset gauge in the European Union. The directive is effective, reliable and cost-effective, and the European Council Directive 91/450/EEC provides a high-level procedure for the implementation of the trainset gauge in the European Union.

For the purposes of the directive, the high-speed rail system was divided into structural and operational HSR subsystems:

- Structural subsystems:** (1) Infrastructure, (2) Energy, (3) Communications, and (4) Rolling stock (trainsets);
- Operational subsystems:** (1) Maintenance, (2) Environment, and (3) Users.

Each TSI subsystem followed the same document structure/outline as the HSR subsystem, including the functional and technical specifications. Figure 7 provides an example of an interface between the infrastructure (INF) and trainset (RST) subsystems. The specific interface ensures that HSR trainsets can pass under bridges, and stay clear of any wayside structures. The infrastructure subsystem perspective (shown in red). Each subsystem specifies the interface requirements and implementation details (shown in blue). Requirements are based on the interoperable interface standard (shown in green). The same interoperable interface standard applies to all types of interfaces, including data interfaces such as functional interfaces between the command, control and signaling (CCS) TSI and Rolling Stock TSI.

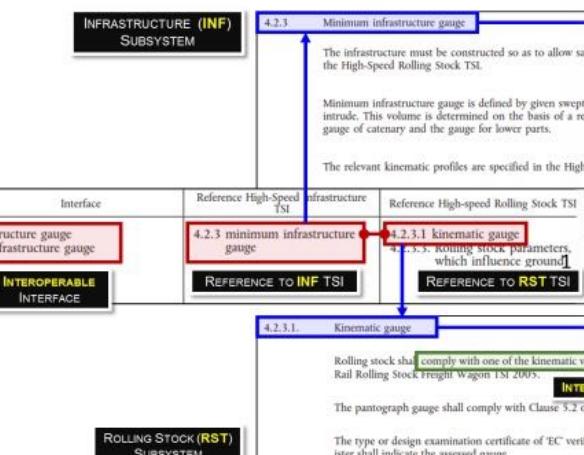


Figure 7. Technical Specifications for Interoperability (TSI)

CREATING INTEROPERABLE CONSTITUENT SYSTEMS

- Step 2: HSR trainset subject matter expert (SME) identifies candidate interfaces.
- Step 3: HSR trainset SME determines interoperable interface requirements.
- Step 4: Civil works SME develops corresponding interoperable interface requirements.
- Step 5: Civil works contractor implements interoperable civil works contracts.
- Step 6: HSR trainset contractor implements interoperable HSR trainset contracts.
- Step 7: SoS system integrator (track & systems contractor) integrates the interoperable contracts and commissions (taking into service) the interoperable contracts.

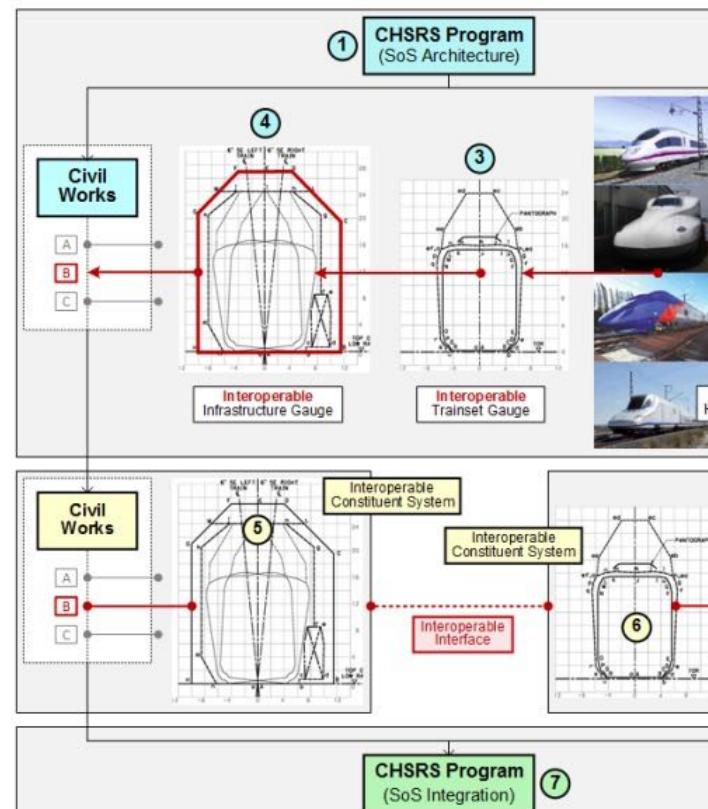


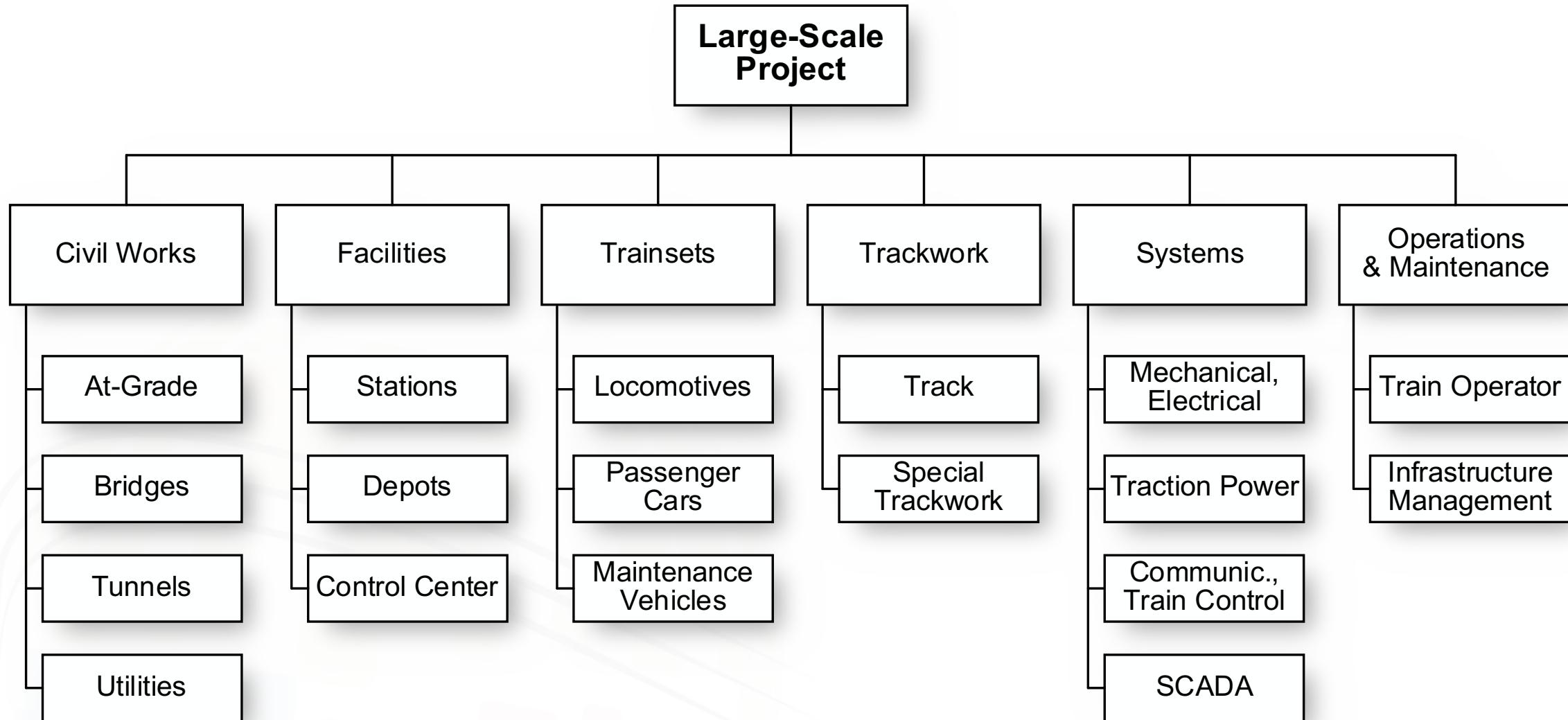
Figure 8. Creating Interoperable Constituent Systems

PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
 - Large Scale Projects
 - Common Contract Breakdown Structures
 - Interface & Integration Challenges
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INDUSTRY TYPICAL CONTRACT BREAKDOWN STRUCTURE



BACKGROUND, CHALLENGES & OBJECTIVES

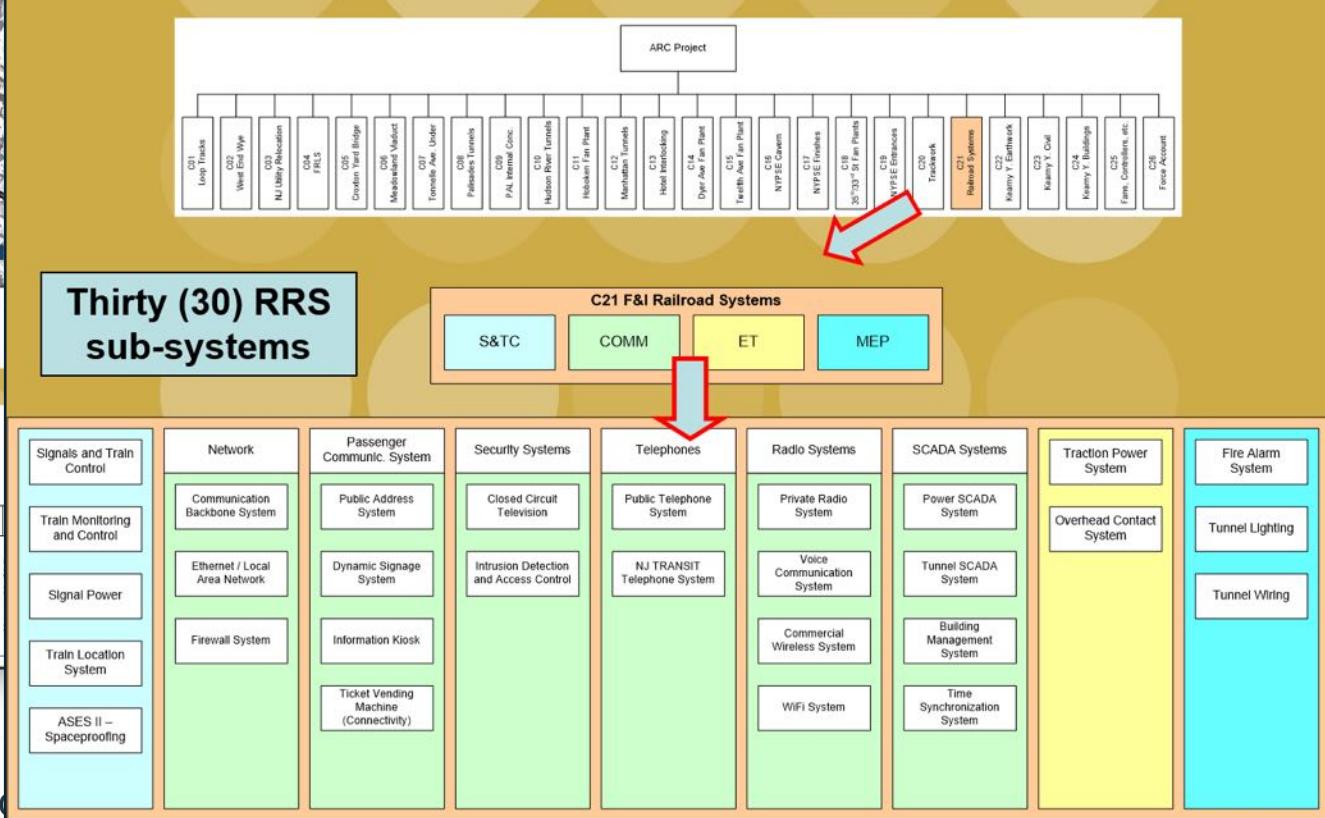
LARGE-SCALE PROJECTS: EXAMPLE – ARC TUNNEL PROJECT

System Engineering ARC Project – Contract Packages



Source: Hoehne, O., 2009, "Access to the Region's Core (ARC) Tunnel, Scaling Systems Engineering to Transit Challenges", 2009 APTA Rail Conference, Chicago, IL, 2009

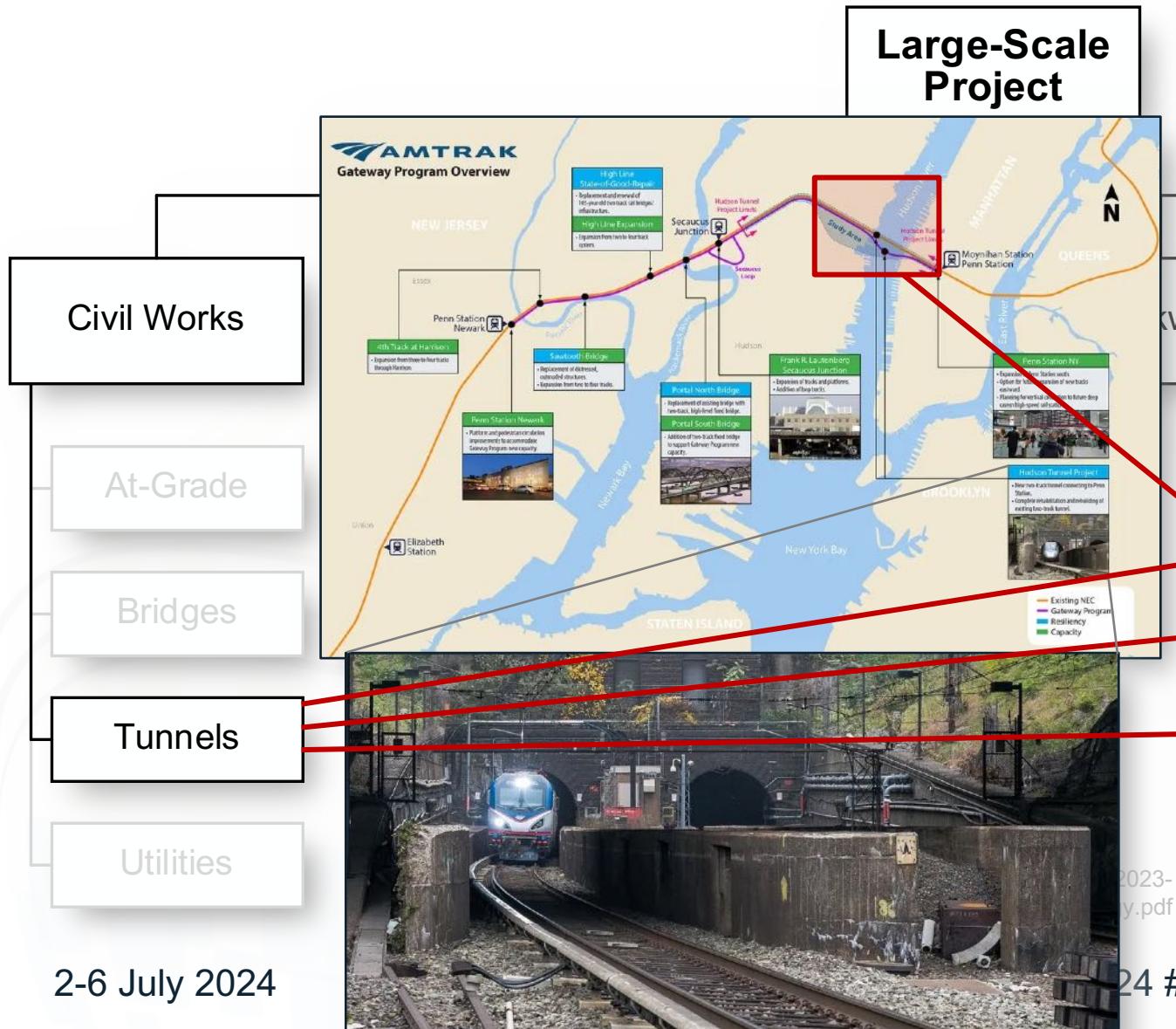
System Engineering Railroad Systems Contract



BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: EXAMPLE – GATEWAY PROGRAM (NY/NJ)

HUDSON TUNNEL PROCUREMENT STRATEGY



Large-Scale Project

**GATEWAY DEVELOPMENT COMMISSION ANNOUNCES IMPROVED
CONTRACTING STRATEGY FOR HUDSON TUNNEL PROJECT TO ENSURE
COMPETITIVE BIDDING POOL AND ADVANCE EARLY WORK**

Newark/New York – The Gateway Development Commission today announced that it has revised its project strategy to build the Hudson Tunnel Project, dividing the “Civil Works” construction of the new tunnel from the package to four packages, including additional early works projects.

The Civil Works is the largest portion of the Hudson Tunnel Project. It encompasses the excavation and construction of a new tunnel under the Palisades in New Jersey and the Hudson River and connecting to Station in Manhattan. This portion of the project alone consists of 2 tubes, each 2.4 miles long.

The Civil Works portion of the Hudson Tunnel Project will now be divided into four contract packages, rather than the one package previously contemplated, to ensure there is a robust and competitive bidding pool for

ckage 1A, the portion of the tunnel through the P
ersey, which will be delivered via Design-Bid-Bid

ckage 1B, the section of the tunnel going through Hudson River Park and connecting to the new c which will be delivered via Design-Build;

and Package 1C, which includes the tunneling under the Hudson River from the new construction shaft in Hoboken to the new construction shaft in Manhattan, which will be delivered via Design-Bid-Build.

THREE DIFFERENT TUNNEL CONTRACTS

Packages 1A and 1B are scheduled to commence work in 2024 after a Full Funding Grant Agreement under FTA's Capital Investment Grants Program is signed by the FTA and GDC. Package 1C is scheduled to commence work in 2025.

In addition, the fourth contract package, **Contract Package EA1**, is an early work project which is expected to commence prior to the project's full construction. This "Hudson River Ground Stabilization" package will reduce the risk of collapse of the eastern portion of the river wall by fortifying and stabilizing the river bottom on the New York side of the Hudson River. This work will create an improved condition in which to bore the new tunnel through the eastern portion of the Hudson River section of the project. The work will also comply with all environmental regulations to ensure the safety of the Hudson River environment.

BACKGROUND, CHALLENGES & OBJECTIVES

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SoS COLLABORATION & INTEGRATION (EARLY INTERFACE NEEDS)

CIVIL WORKS

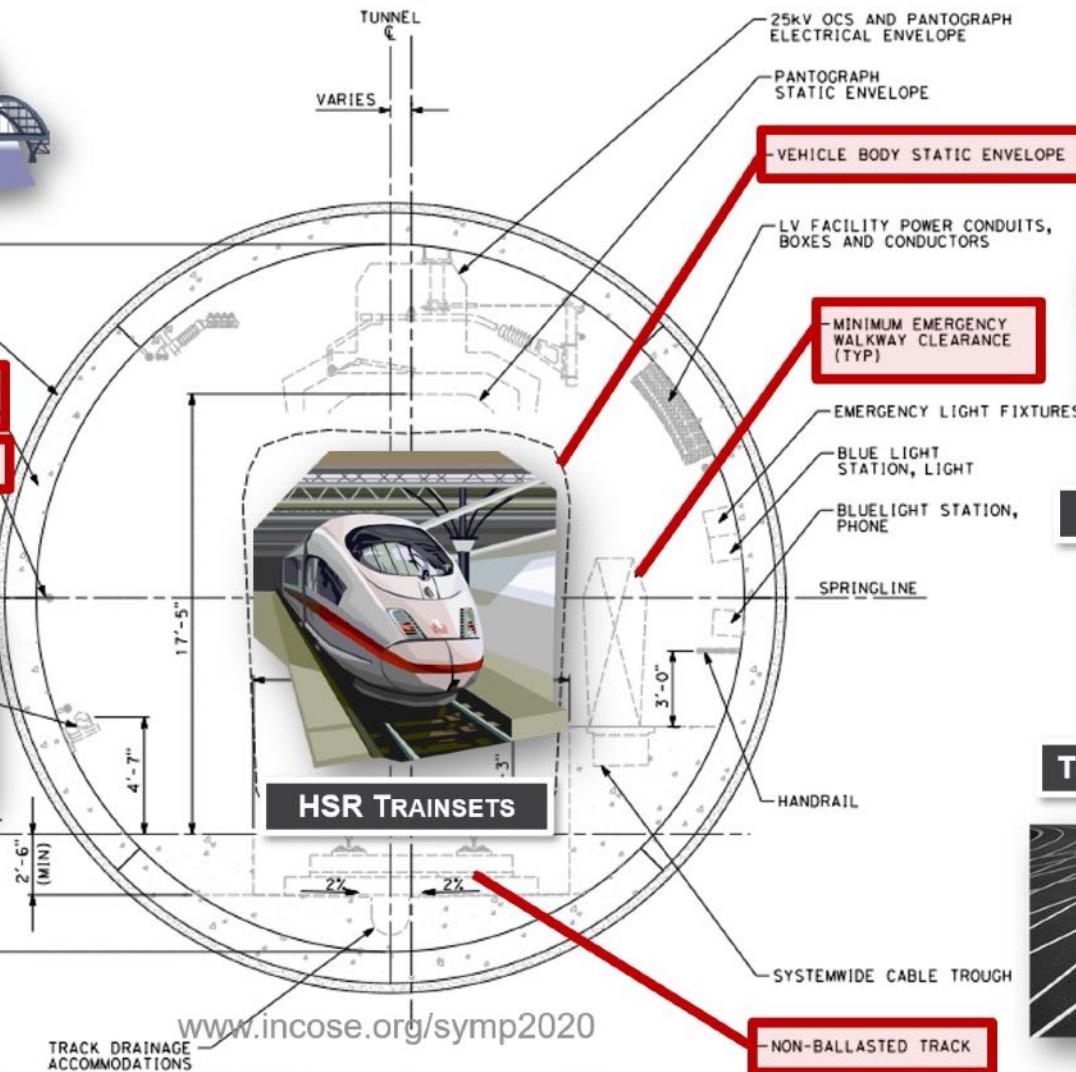


CURRENT NORTH
RIVER TUNNELS

TRACK & SYSTEMS



INTERFACE REQUIREMENTS NEEDED
FROM CONTRACTS NOT ISSUED YET



TRAIN OPERATOR

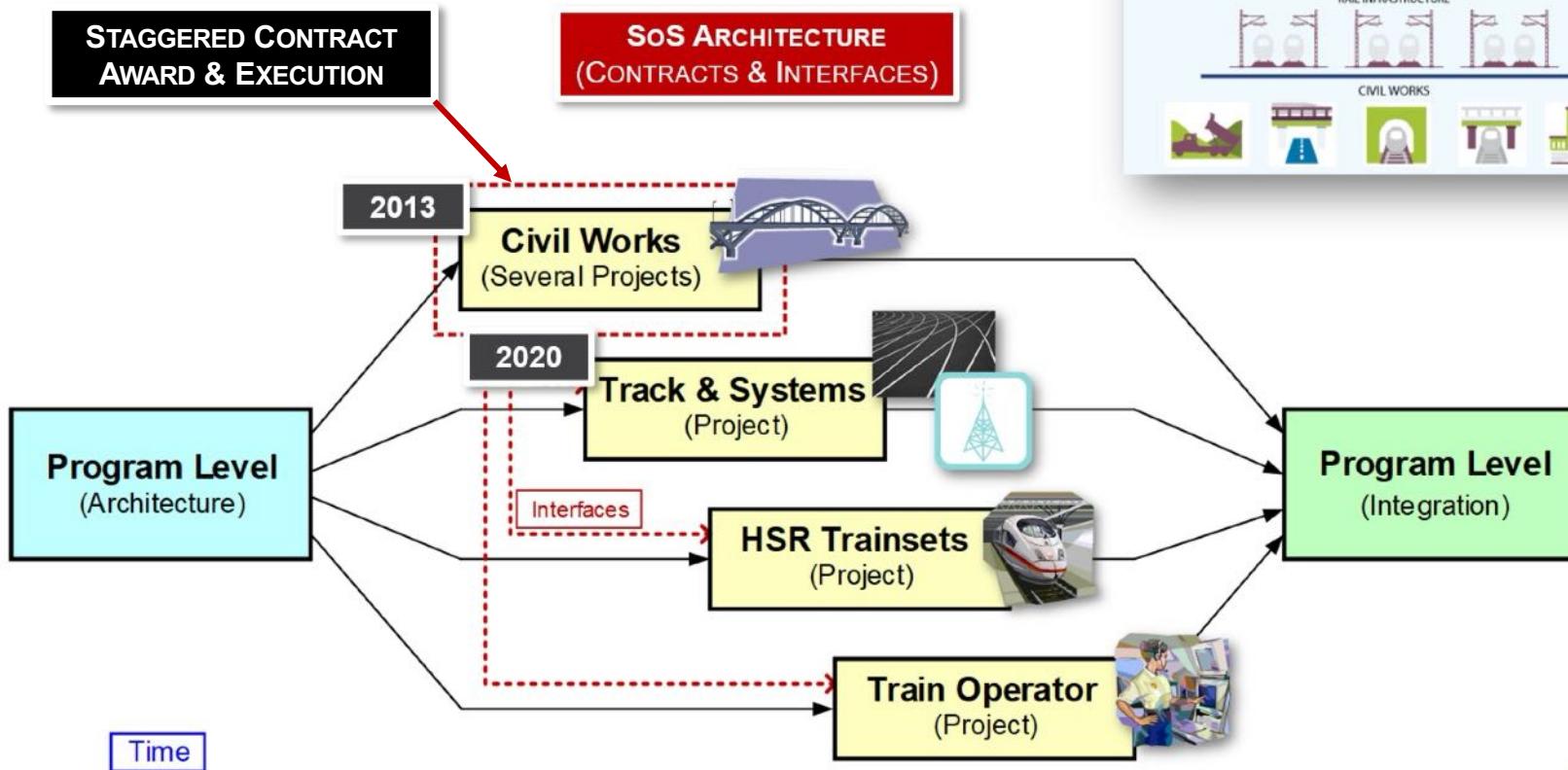
TRACK & SYSTEMS



BACKGROUND, CHALLENGES & OBJECTIVES

SoSE CHALLENGES FACED SoS ARCHITECTURE & LEADERSHIP (CONT'D)

2020 PAPER



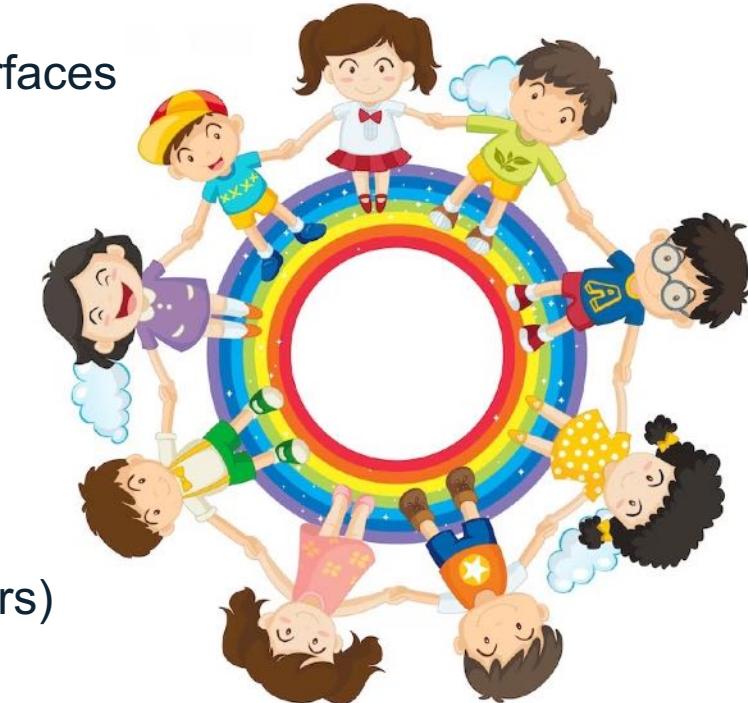
PROGRAM INTERFACE & INTEGRATION CHALLENGES

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INDUSTRY TYPICAL INTERFACE MANAGEMENT APPROACH

❖ Interface Management Working Group(s): (Interface Management “As You Go”)

- Purpose:
 - Regularly meet to “liaise” and “cooperate”, and “coordinate” interfaces
- Attendees:
 - Contractor(s)
 - Interfacing contractors
 - Project Oversight
 - Client
- Scope:
 - Develop interface management program
 - Coordinate schedule development (including site access, handovers)
 - Identify interfaces
 - Develop interface requirements
 - Coordinate design development, including information exchange
 - Address, manage and resolve interface issues as they arise
 - Manage interface status



Sources/Credits:
<https://www.clerk.com/clipart-617868.html>
https://de.freepik.com/vektoren-kostenlos/glaeckliche-kinder-halten-haende-um-regenbogenkreis_1250832.htm

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INTERFACE MANAGEMENT **REALITIES**

How a French rail company spent £12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you



Source/Credit: <https://www.theguardian.com/world/shortcuts/2014/may/21/french-rail-company-sncf-trains-too-wide>

'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



Source/Credit: <https://www.euronews.com/travel/2023/02/21/unspeakable-botch-spain-spends-258-million-on-trains-that-are-too-big-for-its-tunnels>

BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INTERFACE MANAGEMENT REALITIES (CONT'D)

MEXICO CITY METRO



Source/Credit: <https://www.nytimes.com/interactive/2021/06/12/world/americas/mexico-city-train-crash.html?searchResultPosition=3>

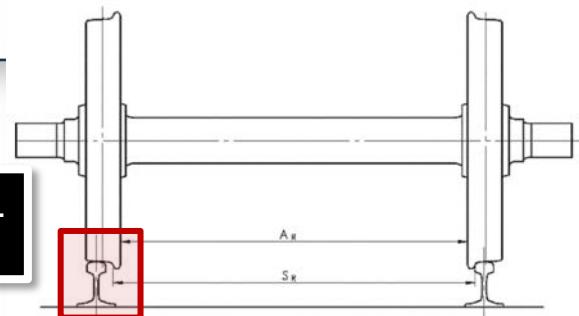
The problem that drew the most public attention was the purchase of trains, which didn't fit tightly enough on the tracks.

The mismatch stemmed from another timesaving decision. The rails were designed for American standards according to testimony in the 2014 investigation by the city legislature. But the government ended up choosing a Spanish supplier, CAF, that provided trains designed for European specifications. The reason: CAF had promised to deliver the trains about a year ahead of its competitor, Canada-based Bombardier.

“Bombardier gave us a longer timeline,” said Francisco Bojorquez, metro director at the time, in 2014 testimony. “It was a question of time and of opportunity.”

The incompatibility caused so much wear that the city had to replace a half mile of rail weeks before the metro even started carrying passengers.

RAIL-WHEEL
INTERFACE



BACKGROUND, CHALLENGES & OBJECTIVES

OBJECTIVES: PREDICTABLE, REPEATABLE PROCESS, CONVENIENT, INTEROPERABLE

CMMI Level 1: Initial

- Unpredictable Processes, relying on SME Expertise (or Lack Thereof)

CMMI Level 2: Managed

- Repeatable Processes w/in Project

CMMI Level 3: Defined

- Repeatable Processes w/in Organization
- Project Tailors Processes from Organizational Standards

Additional Objectives

- Convenience: Ready (Easy) to Use
- Interoperable: Compatible w/ Future Contracts

BACKGROUND, CHALLENGES & OBJECTIVES

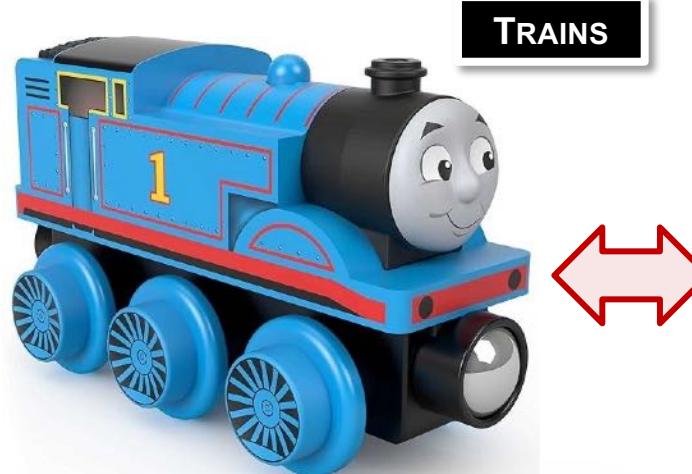
OBJECTIVES: INTEROPERABLE CONSTITUENT SUBSYSTEM(S)



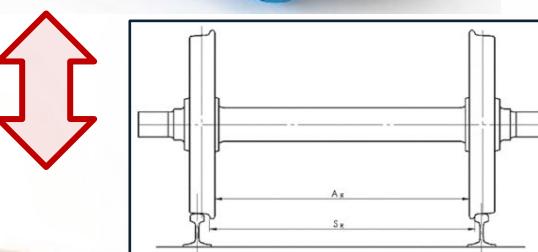
STATIONS

How a French rail company spent £12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you



TRAINS



TRACK



TUNNELS

'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
 - Modular Open Systems Approach
 - Interoperability
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MODULAR OPEN SYSTEMS APPROACH (MOSA)

MODULAR OPEN SYSTEMS APPROACH THE TRANS-EUROPEAN HIGH SPEED-RAIL SYSTEM



Source: Hoehne, O., 2016, "Implementing an Effective Modular Open Systems Approach [MOSA] Framework Insights into the Application of MOSA to Non-Defense Industries", 19th Annual Systems Engineering Conference, Springfield, VA, 2016



MODULAR OPEN SYSTEMS APPROACH APPLICATION OF MOSA PRINCIPLES TO HSR

“Modular Open Systems Approach or MOSA” is the DoD’s implementation of Open Systems. Within the MOSA context, programs should design their system based on adherence to the following five MOSA principles:

Establish an Enabling Environment;
Employ Modular Design;
Designate Key Interfaces;
Use Open Standards; and
Certify Conformance.

[A Modular Open Systems Approach (MOSA) to Acquisition, OSJTF]

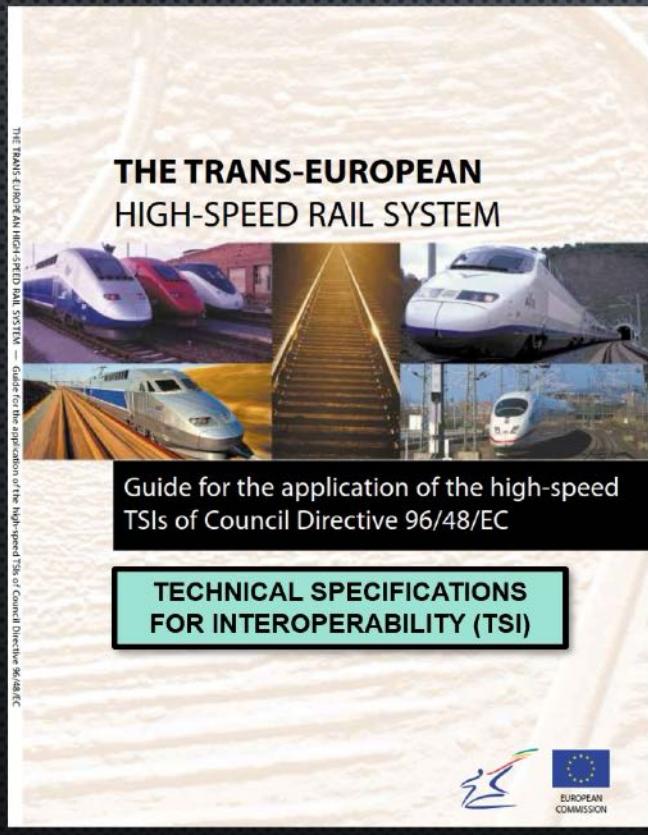


MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MOSA APPLIED TO LARGE RAIL PROJECTS – ENABLING ENVIRONMENT, MODULARITY

MODULAR OPEN SYSTEMS APPROACH

PRINCIPLE #1: ENABLING ENVIRONMENT



THE TRANS-EUROPEAN HIGH-SPEED RAIL SYSTEM

Guide for the application of the high-speed TSIs of Council Directive 96/48/EC

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI)

THE TRANS-EUROPEAN HIGH-SPEED RAIL SYSTEM – Guide for the application of the high-speed TSIs of Council Directive 96/48/EC



Preface by Loyola de Palacio
Vice-President of the European Commission
Commissioner in charge of transport and energy



The railway sector is constrained by barriers within from competing effectively with other modes of transport. The establishment of an internal market for rail depends, on the one hand, on the opening of access and, on the other hand, on the progressive alignment of standards to ensure their interoperability.

Our challenge is to move towards a single European a fully-fledged internal market for railway services. This will play a key role in this and the wider success of a cost-effective, reliable and safe transport alternative.

Harmonisation of technical and operational specific rail system is vital for free movement of trains and related equipment in the European Union.

The interoperability directives, together with European legislation opening up competition, are key factors in increasing the rail sector's productivity and in making the rail system, composed of the leading players in the transport system in the enlarged Europe. The lack of the proper alignment of standards is a major obstacle to the implementation of Directive 96/48/EC and the achievement of the objectives of the TSI.

INTEROPERABILITY
The directive on interoperability of the railway system, composed of the leading players in the transport system in the enlarged Europe. The lack of the proper alignment of standards is a major obstacle to the implementation of Directive 96/48/EC and the achievement of the objectives of the TSI.

OPEN MARKET
Technical and operational barriers work in favour of incumbent companies a players.

COMPETITION
The rail system is constrained by barriers within from competing effectively with other modes of transport. The establishment of an internal market for rail depends, on the one hand, on the opening of access and, on the other hand, on the progressive alignment of standards to ensure their interoperability.

COST-EFFECTIVENESS
This has led to the development of rail transport relative to competing transport modes. This has led to the development of rail transport relative to competing transport modes. This has led to the development of rail transport relative to competing transport modes. This has led to the development of rail transport relative to competing transport modes.

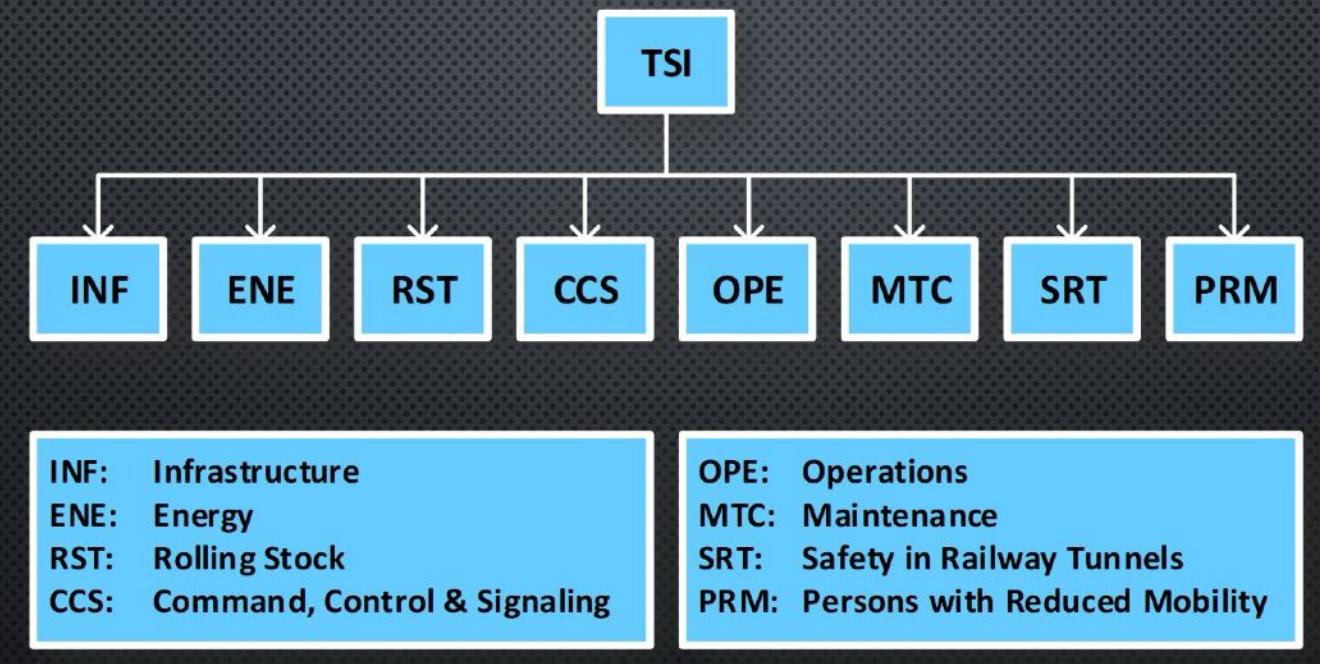
SAFE & RELIABLE
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Source: Hoehne, O., 2016, "Implementing an Effective Modular Open Systems Approach [MOSA] Framework Insights into the Application of MOSA to Non-Defense Industries", 19th Annual Systems Engineering Conference, Springfield, VA, 2016

MODULAR OPEN SYSTEMS APPROACH

PRINCIPLE #2: MODULAR DESIGN



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI) – KEY INTERFACES

TSI INFRASTRUCTURE				02014R1299 — EN — 28.09.2023																																																																				
4.3. Functional and technical specification of the interfaces																																																																								
From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.																																																																								
4.3.1. Interfaces with the rolling stock subsystem																																																																								
Table 15																																																																								
▼M1 Interface: INTERFACING SYSTEMS																																																																								
<table border="1"> <thead> <tr> <th>Interface</th> <th>► M2 Reference in TSI INF</th> <th>► M2 Reference in TSI LOC & PAS</th> </tr> </thead> <tbody> <tr> <td>Track gauge</td> <td>4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings</td> <td>4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets</td> </tr> <tr> <td>Gauge</td> <td>4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset</td> <td>4.2.3.1 Gauging</td> </tr> </tbody> </table> <p>How a French rail company spent £12bn on trains that are "too wide"</p> <p>Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you</p> 				Interface	► M2 Reference in TSI INF	► M2 Reference in TSI LOC & PAS	Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets	Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging																																																												
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4.2.1. Limit values for safely 4.2.2. Track loading values																																																																								
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TSI ROLLING STOCK				02014R1302 — EN — 28.09.2023 — 005.001 — 137																																																																				
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MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY – OPEN STANDARDS (CONT'D)

1. CCS TSI Appendix A – Manda

era.europa.eu/era-folder/1-ccs-tsi-appendix-mandatory-specifications-etcs-b4-r1-rmr-gsm-r-b1-mr1-frmcs-b0-ato-b1

Index	Reference	Title	Approved	Note
000	-	 readme_file_-_mandatory_specs.docx	-	-
003	SUBSET-023	 Glossary of Terms and Abbreviations	4.0.0	-
004	SUBSET-026	 System Requirements Specification	4.0.0	-
005	SUBSET-027	 FIS Juridical Recording	4.0.0	-
006	ERA_ERTMS_015560	 ETCS Driver Machine interface	4.0.0	-
007	SUBSET-034	 Train Interface FIS	4.0.0	-
008	SUBSET-035	 Specific Transmission Module FFFIS	4.0.0	-
009	SUBSET-036	 FFFIS for Eurobalise	4.0.0	-
010a	SUBSET-037-1	 EuroRadio FIS – Part 1 [Communication layer and coordination function]	4.0.0	-
010b	SUBSET-037-2	 EuroRadio FIS – Part 2 [Safety layer]	4.0.0	-
010c	SUBSET-037-3	 EuroRadio FIS – Part 3 [FRMCS interface]	4.0.0	-
010d	SUBSET-146	 ERTMS End-to-End Security	4.0.0	-
011	SUBSET-038	 Offline key management FIS	4.0.0	-
012	SUBSET-039	 FIS for the RBC/RBC handover	4.0.0	-
013	SUBSET-040	 Dimensioning and Engineering rules	4.0.0	-

PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
 - Design Terms, Nomenclature
 - Requirements
 - Structure
 - Interfaces
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – DESIGN TERMS, NOMENCLATURE

Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg (EU) 454/2011/EU TAP TSI								x
Reg (EU) 321/2013 WAG TSI					x		x	
Reg (EU) 1299/2014 INF TSI	x						x	
Reg (EU) 1300/2014 PRM TSI	x				x	x		
Reg (EU) 1301/2014 ENE TSI		x					x	
Reg (EU) 1302/2014 LOC & PAS TSI					x		x	
Reg (EU) 1303/2014 SRT TSI	x	x	x	x	x	x		
Reg (EU) 1304/2014 RST Noise TSI					x		x	
Reg (EU) 1305/2014 TAF TSI								x
Reg (EU) 2016/919 CCS TSI			x	x			x	
Com. Impl. Reg (EU) 2019/773 OPE TSI						x		

Table 6 – Applicability of TSIs to subsystems

#	△ Term	Description
1		Command Control and Signalling (TSI)
2		Energy (TSI)
3		Infrastructure (TSI)
4		Locomotive and passenger rolling stock (TSI)
5		Maintenance (Subsystem)
6		(CCS) Onboard (Subsystem)
7		Operation and Traffic Management
8		Person with Disabilities or Person with Reduced Mobility (TSI)
9		Rolling Stock (Subsystem)
10		Safety in Railway Tunnels (TSI)
11		Telematics Applications for Freight Service (TSI)
12		Telematics Applications for Freight Service (TSI)
13		Telematics Application (Subsystem)
14		(CCS) Trackside (Subsystem)
15		Technical Specification for Interoperability
16		Freight wagon (TSI)

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – REQUIREMENTS

Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg 454/2011/EU TAP TSI								x
Reg (EU) 321/2013 WAG TSI					x	x		
Reg (EU) 1299/2014 INF TSI	x						x	
Reg (EU) 1300/2014 PRM TSI	x				x	x		
Reg (EU) 1301/2014 ENE TSI		x					x	
Reg (EU) 1302/2014 LOC & PAS TSI			x				x	
Reg (EU) 1303/2014 SRT TSI	x	x	x	x	x	x		
Reg (EU) 1304/2014 RST Noise TSI				x			x	
Reg (EU) 1305/2014 TAF TSI								x
Reg (EU) 2016/919 CCS TSI			x	x			x	
Com. Impl. Reg (EU) 2019/773 OPE TSI					x			

Table 6 – Applicability of TSIs to subsystems

#	△ Id	Name
1	TSI-INF-1	TSI-INF-1 INF TSI
2	TSI-INF-1.1	TSI-INF-1.1 1. Introduction
6	TSI-INF-1.2	TSI-INF-1.2 2. Definition and scope of subsystem
17	TSI-INF-1.3	TSI-INF-1.3 3. Essential requirements
18	TSI-INF-1.4	TSI-INF-1.4 4. Description of the infrastructure subsystem
19	TSI-INF-1.4.1	TSI-INF-1.4.1 4.1. Introduction
20	TSI-INF-1.4.2	TSI-INF-1.4.2 4.2. Functional and technical specifications of subsystem
81	TSI-INF-1.4.3	TSI-INF-1.4.3 4.3. Functional and technical specification of the interfaces
105	TSI-INF-1.4.4	TSI-INF-1.4.4 4.4. Operating rules
106	TSI-INF-1.4.5	TSI-INF-1.4.5 4.5. Maintenance rules
109	TSI-INF-1.4.6	TSI-INF-1.4.6 4.6. Professional qualifications
110	TSI-INF-1.4.7	TSI-INF-1.4.7 4.7. Health and safety conditions
111	TSI-INF-1.5	TSI-INF-1.5 5. Interoperability constituents
128	TSI-INF-1.6	TSI-INF-1.6 6. Assessment of conformity of interoperability constituents and EC verification of the subsystems
151	TSI-INF-1.7	TSI-INF-1.7 7. Implementation of the infrastructure TSI
182	TSI-INF-1.8	TSI-INF-1.8 Appendix A — Assessment of interoperability constituents
183	TSI-INF-1.9	TSI-INF-1.9 Appendix B — Assessment of the infrastructure subsystem
184	TSI-INF-1.10	TSI-INF-1.10 Appendix C — Technical characteristics of track design and switches and crossings design
185	TSI-INF-1.11	TSI-INF-1.11 Appendix D — Conditions of use of track design and switches and crossings design
186	TSI-INF-1.12	TSI-INF-1.12 Appendix E — Capability requirements for structures according to traffic code
187	TSI-INF-1.13	TSI-INF-1.13 Appendix F — Capability requirements for structures according to traffic code in the United Kingdom of Great Britain and Northern Ireland
188	TSI-INF-1.14	TSI-INF-1.14 Appendix G — Speed conversion to miles per hour for Ireland and the United Kingdom of Great Britain and Northern Ireland
189	TSI-INF-1.15	TSI-INF-1.15 Appendix H — Structure gauge for the 1 520 mm track gauge system
190	TSI-INF-1.16	TSI-INF-1.16 Appendix I — Reverse curves with radii in the range from 150 m up to 300 m
191	TSI-INF-1.17	TSI-INF-1.17 Appendix J — Safety assurance over fixed obtuse crossings
192	TSI-INF-1.18	TSI-INF-1.18 Appendix K — Basis of minimum requirements for structures for passenger coaches and multiple units
193	TSI-INF-1.19	TSI-INF-1.19 Appendix M — Specific case on the Estonian network
194	TSI-INF-1.20	TSI-INF-1.20 Appendix N — Specific cases of the Hellenic network
195	TSI-INF-1.21	TSI-INF-1.21 Appendix O — Specific case on the Ireland and United Kingdom of Northern Ireland networks
196	TSI-INF-1.22	TSI-INF-1.22 Appendix P — Structure gauge for the lower parts for the 1 668 mm track gauge on the Spanish network
197	TSI-INF-1.23	TSI-INF-1.23 Appendix Q — National technical rules for UK-GB Specific Cases
198	TSI-INF-1.24	TSI-INF-1.24 Appendix R — List of open points
199	TSI-INF-1.25	TSI-INF-1.25 Appendix S — Glossary
200	TSI-INF-1.26	TSI-INF-1.26 Appendix T — List of referenced standards

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – STRUCTURE

Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg (EU) 454/2011/EU TAP TSI								
Reg (EU) 321/2013 WAG TSI								
Reg (EU) 1299/2014 INF TSI								
Reg (EU) 1300/2014 PRM TSI								
Reg (EU) 1301/2014 ENE TSI								
Reg (EU) 1302/2014 LOC & PAS TSI								
Reg (EU) 1303/2014 SRT TSI								
Reg (EU) 1304/2014 RST Noise TSI								
Reg (EU) 1305/2014 TAF TSI								
Reg (EU) 2016/919 CCS TSI		X	X			X		
Com. Impl. Reg (EU) 2019/773 OPE TSI					X			

bdd [Package] 100 Rail System & Subsystems [100 Rail System & Subsystems]

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graph TD
    RS[«block» Rail System] --> INF[«block» INF Subsystem]
    RS --> ENE[«block» ENE Subsystem]
    RS --> CCSOB[«block» CCS OB Subsystem]
    RS --> CCS TS Subsystem
    RS --> RST[«block» RST Subsystem]
    RS --> OPE[«block» OPE Subsystem]
    RS --> MTC[«block» MTC Subsystem]
    RS --> TMA[«block» TMA Subsystem]
  
```

Table 6 – Applicability of TSIs to subsystems

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

MBSI REFERENCE ARCHITECTURE – SATISFY REQUIREMENTS MATRIX

Applicable TSIs	Subsystem							
	Infrastructure	Energy	CCS on board	CCS trackside	Rolling Stock	Operation and Traffic Management	Maintenance	Telematic Applications
Reg (EU) 454/2011/EU TAP TSI								x
Reg (EU) 321/2013 WAG TSI					x		x	
Reg (EU) 1299/2014 INF TSI	x						x	
Reg (EU) 1300/2014 PRM TSI	x				x	x		
Reg (EU) 1301/2014 ENE TSI		x					x	
Reg (EU) 1302/2014 LOC & PAS TSI					x		x	
Reg (EU) 1303/2014 SRT TSI	x	x	x	x	x	x		
Reg (EU) 1304/2014 RST Noise TSI					x		x	
Reg (EU) 1305/2014 TAF TSI								x
Reg (EU) 2016/919 CCS TSI			x	x			x	
Com. Impl. Reg (EU) 2019/773 OPE TSI						x		

Table 6 – Applicability of TSIs to subsystems

Legend

↗ Satisfy

010 Rail System & Subsystems								
010 Rail System & S	INF Subsystem	ENE Subsystem	CCS OB Subsystem	CCS TS Subsystem	RST Subsystem	OPE Subsystem	MTC Subsystem	
INF	INF	ENE	CCS OB	CCS TS	RST	OPE	MTC	
020 Requirements	3	2	2	2	7	3	6	2
1								
2								
2								
3								
2								
2								
6	↗	↗	↗	↗	↗	↗	↗	↗
2								
1								
3								
1								

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

SUBSYSTEM ELEMENTS – INTEROPERABILITY CONSTITUENTS (INF – RAIL)

02014R1299 — EN — 28.09.2023 — 002.001 — 47

▼B

5. INTEROPERABILITY CONSTITUENTS

5.1. Basis on which interoperability constituents have been selected

- (1) The requirements of point 5.3 are based on a traditional design of ballasted track with Vignole (flat-bottom) rail on concrete or wooden sleepers and fastening providing resistance to longitudinal slip by bearing on the rail foot.

- (2) Components and subassemblies used for the construction of other designs of track are not considered to be interoperability constituents.

5.2. List of constituents

- (1) For the purposes of this technical specification for interoperability, only the following elements, whether individual components or subassemblies of the track are declared to be 'interoperability constituents':

- (a) the rail (5.3.1),
- (b) the rail fastening systems (5.3.2),
- (c) track sleepers (5.3.3).

- (2) The following points describe the specifications applicable to each of these constituents.

- (3) Rails, fastenings and sleepers used for short length of track for specific purposes, for example in switches and crossings, at expansion devices, transition slabs and special structures, are not considered to be interoperability constituents.

5.3. Constituents performances and specifications

5.3.1. The rail

The specifications of the 'rail' interoperability constituent concern the following parameters:

- (a) railhead profile,
- (b) rail steel.

5.3.1.1. Railhead profile

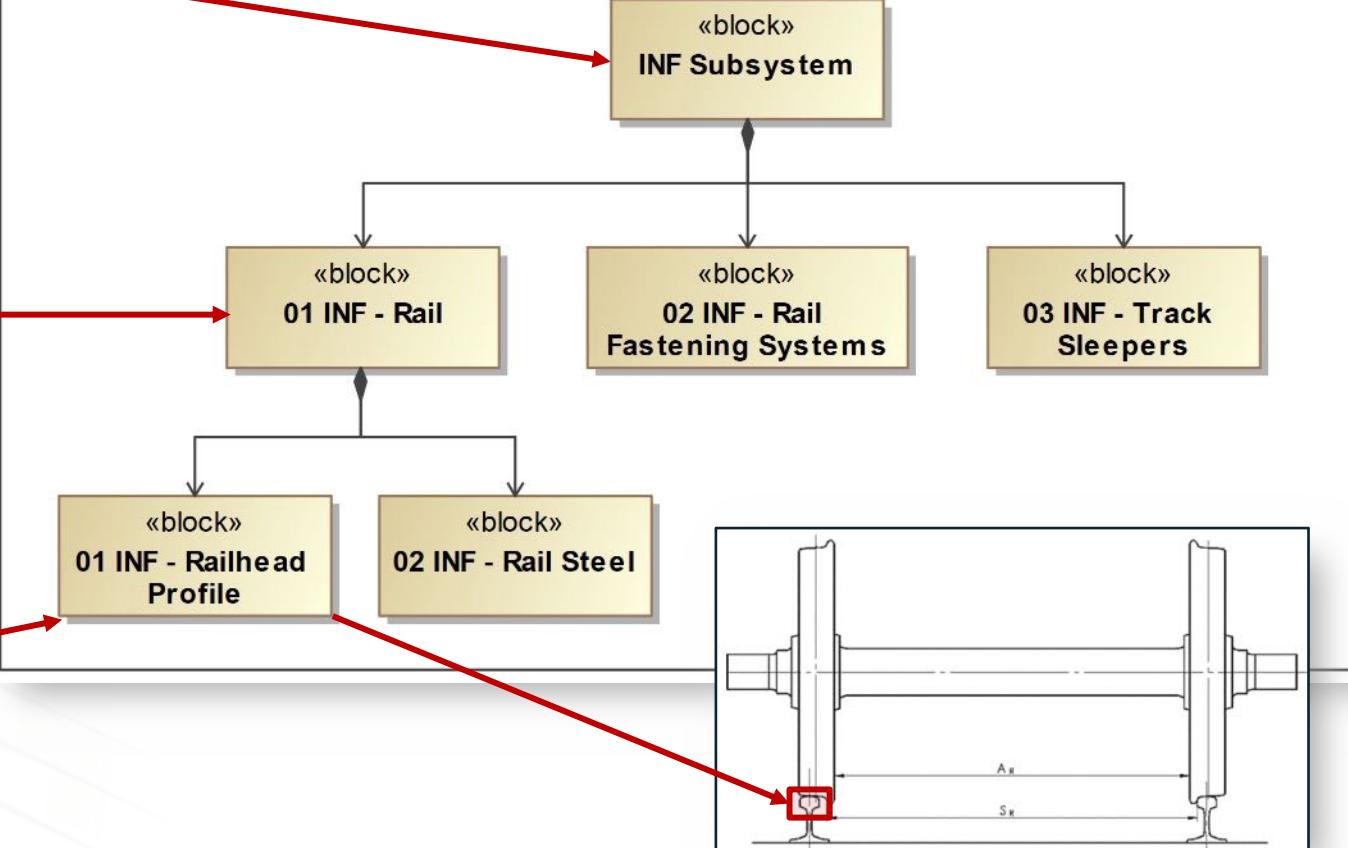
The rail head profile shall fulfil the requirements of point 4.2.4.6 'Railhead profile for plain line'.

5.3.1.2. Rail steel

(1) The rail steel is relevant to the requirements of point 4.2.6 'Track resistance to applied loads'.

TSI INFRASTRUCTURE

package 020 INF Interoperability Constituents [010 INF Interoperability Constituents]



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

SUBSYSTEM ELEMENTS – INTEROPERABILITY CONSTITUENTS REQUIREMENTS

02014R1299 — EN — 28.09.2023 — 002.001 — 47

▼B

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- (b) rail steel.

STRUCTURE

5.3.1.1. Railhead profile

The rail head profile shall fulfil the requirements of point 4.2.4.6 'Railhead profile for plain line'.

5.3.1.2. Rail steel

- (1) The rail steel is relevant to the requirements of point 4.2.6 'Track resistance to applied loads'.

TSI INFRASTRUCTURE

4.2.4.6. Railhead profile for plain line

REQUIREMENTS

(5) Instead of points (1) to (4), for the 1 520 mm track gauge system, no assessment of equivalent conicity is required

▼M2

- (1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).

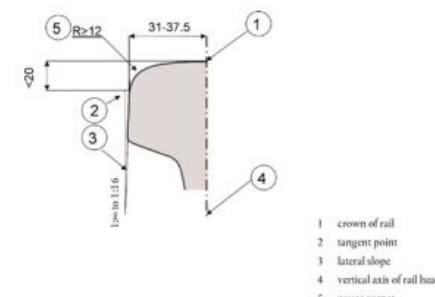
▼B

- (2) The design of railhead profiles for plain line shall comprise:

- (a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;
- (b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;
- (c) a radius of at least 12 mm at the gauge corner;
- (d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.

▼M1

Figure 1
Railhead profile



▼B

- (3) These requirements are not applicable to expansion devices.

4.2.4.7. Rail inclination

4.2.4.7.1. Plain line

(1) The rail head profile shall be in accordance with point 4.2.4.6.

Legend

↗ Satisfy

	020 INF Interoperability	01 INF - Railhead Profile ...
TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile f	7	
TSI-INF-1.4.2.4.6.1	1	↗
TSI-INF-1.4.2.4.6.2	1	↗
TSI-INF-1.4.2.4.6.3	1	↗
TSI-INF-1.4.2.4.6.4	1	↗
TSI-INF-1.4.2.4.6.5	1	↗
TSI-INF-1.4.2.4.6.6	1	↗
TSI-INF-1.4.2.4.6.7	1	↗

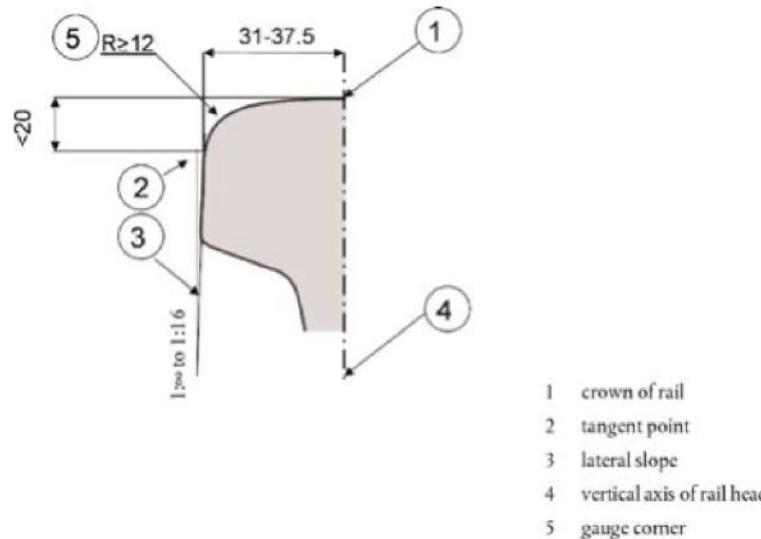
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

SUBSYSTEM ELEMENTS – INTEROPERABILITY CONSTITUENTS REQUIREMENTS (CONT'D)

#	△ Id	Name	Text	Satisfied By
1	TSI-INF-1.4	TSI-INF-1.4.4. Description of the infrastructure subsystem		
3	TSI-INF-1.4.2	TSI-INF-1.4.2.4.2. Functional and technical specifications of subsystem		
17	TSI-INF-1.4.2.4	TSI-INF-1.4.2.4.4.2.4. Track parameters		
23	TSI-INF-1.4.2.4.6	TSI-INF-1.4.2.4.6.4.2.4.6 Railhead profile for plain line		
24	TSI-INF-1.4.2.4.6.1	TSI-INF-1.4.2.4.6.1	(1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).	01 INF - Railhead Profile
25	TSI-INF-1.4.2.4.6.2	TSI-INF-1.4.2.4.6.2	(2) The design of railhead profiles for plain line shall comprise:	01 INF - Railhead Profile
26	TSI-INF-1.4.2.4.6.3	TSI-INF-1.4.2.4.6.3	(a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;	01 INF - Railhead Profile
27	TSI-INF-1.4.2.4.6.4	TSI-INF-1.4.2.4.6.4	(b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;	01 INF - Railhead Profile
28	TSI-INF-1.4.2.4.6.5	TSI-INF-1.4.2.4.6.5	(c) a radius of at least 12 mm at the gauge corner;	01 INF - Railhead Profile
29	TSI-INF-1.4.2.4.6.6	TSI-INF-1.4.2.4.6.6	(d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.	01 INF - Railhead Profile
30	TSI-INF-1.4.2.4.6.7	TSI-INF-1.4.2.4.6.7		01 INF - Railhead Profile
31	TSI-INF-1.4.2.4.6.8	TSI-INF-1.4.2.4.6.8	(3) These requirements are not applicable to expansion devices.	

Figure 1

Railhead profile



Legend

↗ Satisfy

020 INF Interoperability	<input type="checkbox"/>
01 INF - Railhead Profile	<input type="checkbox"/>
TSI-INF-1.4.2.4.6.4.2.4.6 Railhead profile f	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.1	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.2	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.3	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.4	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.5	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.6	<input checked="" type="checkbox"/>
TSI-INF-1.4.2.4.6.7	<input checked="" type="checkbox"/>

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION

02014R1299 — EN — 28.09.2023 — 002.001 — 2

VB

(5) Instead of points (1) to (4), for the 1520 mm track gauge system, no assessment of equivalent conicity is required.

4.2.4.6. Railhead profile for plain line

VM2

(1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).

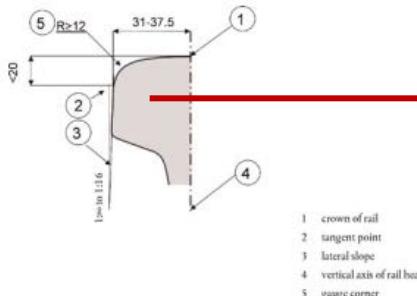
VB

(2) The design of railhead profiles for plain line shall comprise:

- (a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;
- (b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;
- (c) a radius of at least 12 mm at the gauge corner;
- (d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37.5 mm.

VM1

Figure 1
Railhead profile



VB

(3) These requirements are not applicable to expansion devices.

TSI ROLLING STOCK (Loc&Pas)

02014R1302 — EN — 28.09.2023 — 005.001 — 50

4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

Mechanical behaviour of wheel

(1) The characteristics of the wheels shall ensure the safe movement of rolling stock and contribute to the guidance of the rolling stock.

The conformity assessment procedure is described in ►M5 point ◀ 6.1.3.1 of this TSI.

Geometrical dimensions of wheels

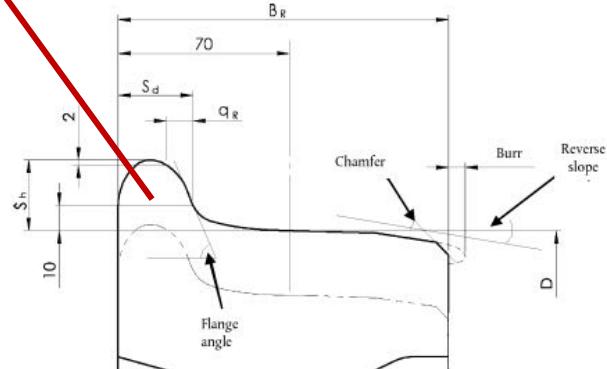
(2) The geometrical dimensions of the wheels (as defined in Figure 2) shall be compliant with limit values specified in Table 2. These limit values shall be taken as design values (new wheel) and as in-service limit values (to be used for maintenance purposes; see also ▶M5 point 4.5).

Table 2

In-service limits of the geometric dimensions of wheel

Designation	Wheel diameter D (mm)	Minimum value (mm)	Maximum value (mm)
Width of the rim ($B_R + \text{Burr}$)	$D \geq 330$	133	145
	$D > 840$	22	
Thickness of the flange (S_{10})	$760 < D \leq 840$	25	33
	$330 \leq D \leq 760$	27,5	
Height of the flange (S_{10})	$D > 760$	27,5	
	$630 < D \leq 760$	29,5	36
	$330 \leq D \leq 630$	31,5	
Face of flange (a_{10})	≥ 330	6,5	

Figure 2
Symbols for wheel



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: TSI INTERFACE TABLES

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▼B 4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.



4.3.1. Interfaces with the rolling stock subsystem

Table 15

Interfaces with the TSI INF or TSI Loc&Pas

Interface	► M2 Reference in TSI INF	► M2 Reference in TSI Loc&Pas
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging

Ride stability	4.2.4.4 Equivalent conicity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent conicity in service	4.2.3.4.3 Equivalent conicity 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
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Running characteristics	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1.4 Nosing forces	4.2.3.4.2.1 Limit values for running safely 4.2.3.4.2.2 Track loading limit values
Ride stability	4.2.4.4 Equivalent conicity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent conicity in service	4.2.3.4.3 Equivalent conicity 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
Longitudinal actions	4.2.6.2 Longitudinal track resistance 4.2.7.1.5 Actions due to traction	4.2.4.5 Braking performance

TSI INFRASTRUCTURE

(5) Instead of points (1) to (4), for the 1 520 mm track gauge system, no assessment of equivalent conicity is required.

4.2.4.6. Railhead profile for plain line

▼M2
▼E
▼M1

(1) The railhead profile shall be selected from the range set out in one of the specifications referenced in Appendix T, Index [7] and Index [8], or shall be in accordance with point (2).

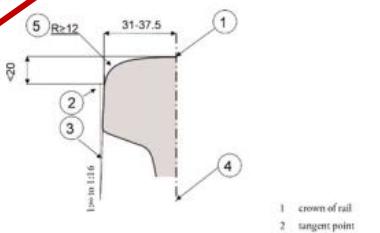
(2) The design of railhead profiles for plain line shall comprise:

- a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;
- the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;
- a radius of at least 12 mm at the gauge corner;
- the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37,5 mm.

▼M1

Figure 1

Railhead profile



1 crown of rail
2 tangent point
3 lateral slope
4 vertical axis of rail head
5 gauge corner

(3) These requirements are not applicable to expansion devices.

▼B
▼M1

4.2.4.7. Rail inclination

4.2.4.7.1. Plain line

(1) The rail shall be inclined towards the centre of the track.

(2) For tracks intended to be operated at speeds greater than 60 km/h, the rail inclination for a given route shall be selected

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TSI ROLLING STOCK (Loc&Pas)

4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

Mechanical behaviour of wheels

(1) The characteristics of the wheels shall ensure the safe movement of rolling stock and contribute to the guidance of the rolling stock.

The conformity assessment procedure is described in ►M5 point ▲ 6.1.3.1 of this TSI.

Geometrical dimensions of wheels

(2) The geometrical dimensions of the wheels (as defined in Figure 2) shall be compliant with limit values, specified in Table 2. These limit values shall be taken as design values (new wheel) and as in-service limit values (to be used for maintenance purposes; see also ►M5 point ▲ 4.5).

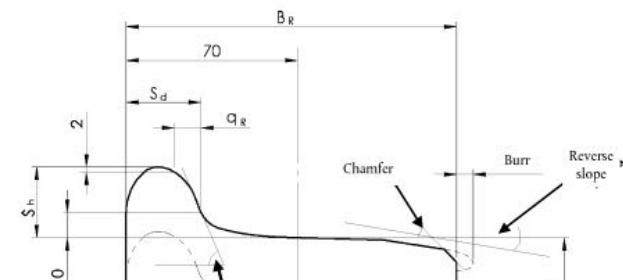
Table 2

In-service limits of the geometric dimensions of wheel

Designation	Wheel diameter D (mm)	Minimum value (mm)	Maximum value (mm)
Width of the rim ($B_R + Burr$)	$D \geq 330$	133	145
	$D > 840$	22	33
Thickness of the flange (S_d)	$760 < D \leq 840$	25	
	$330 \leq D \leq 760$	27,5	
Height of the flange (S_h)	$D > 760$	27,5	36
	$630 < D \leq 760$	29,5	
Face of flange (q_R)	$330 \leq D \leq 630$	31,5	
	≥ 330	6,5	

Figure 2

Symbols for wheels



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: CREATING INTERFACE TABLES IN MBSI FRAMEWORK

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▼B 4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

Table 15

Interfaces with the subsystem 'Rolling stock - locomotives and passenger rolling stock'

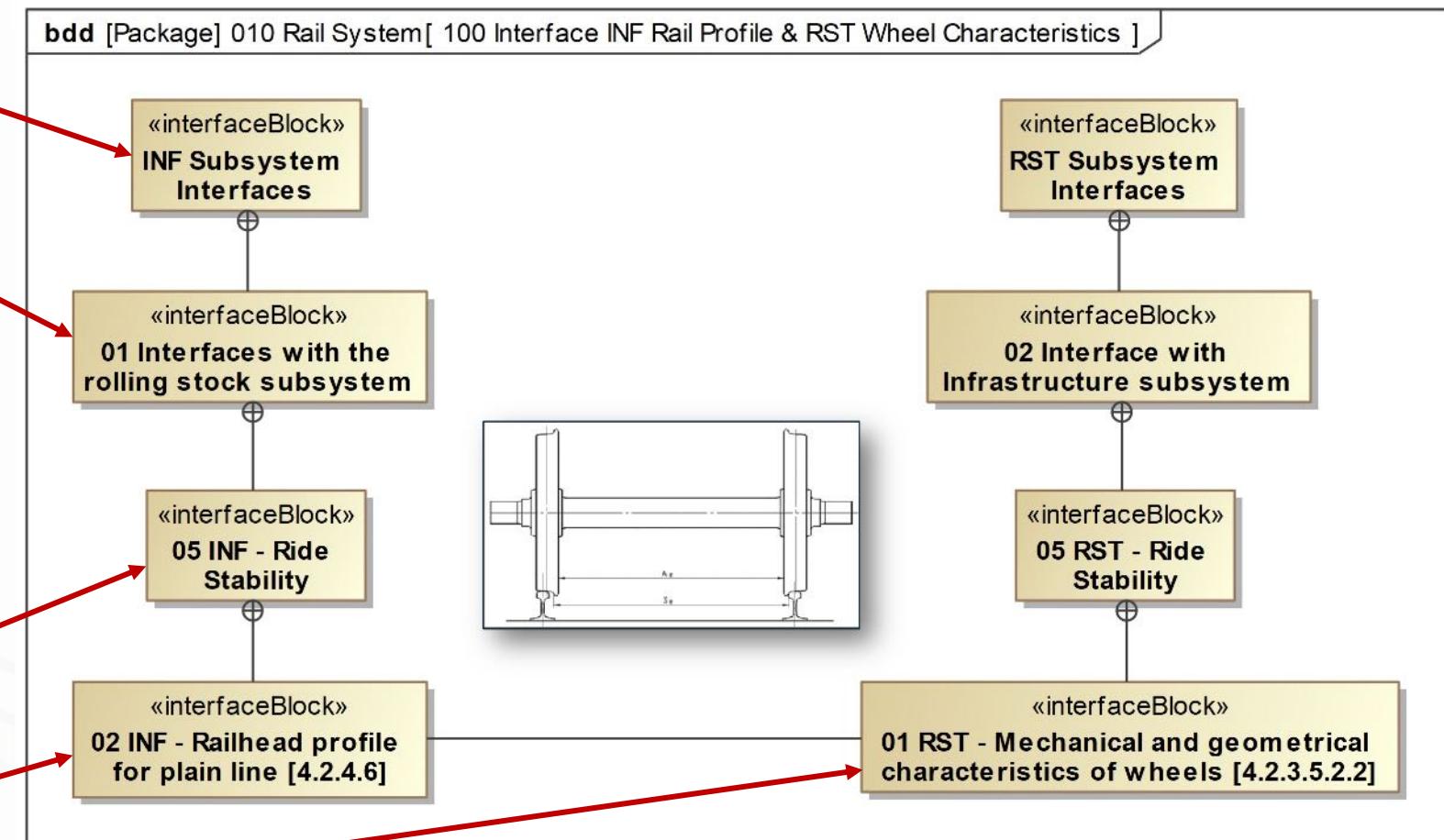
▼M1

▼M2

▼M1

Interface ► M2 Reference in TSI INF ▲ ► M2 Reference in TSI LOC&PAS ▲

Interface	► M2 Reference in TSI INF ▲	► M2 Reference in TSI LOC&PAS ▲
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelsets 4.2.3.5.2.3 Variable gauge wheelsets
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging
Axle load and axle spacing	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1 Resistance of new bridges to traffic loads 4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures 4.2.7.4 Resistance of existing bridges and earthworks to traffic loads	4.2.2.10 Load conditions and weighed mass 4.2.3.2.1 Axle load parameter
Running characteristics	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1.4 Losing forces	4.2.3.4.2.1 Limit values for running safely 4.2.3.4.2.2 Track loading limit values
Ride stability	4.2.4.4 Equivalent concavity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent concavity in service	4.2.3.4.5 Equivalent concavity 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
Longitudinal actions	4.2.6.2 Longitudinal track resistance 4.2.7.1.5 Actions due to traction	4.2.4.5 Braking performance



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: TABLE VIEW (INTERFACE REGISTER VIEW)

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▼B 4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

Table 15

▼M1

▼M2

▼M1

Interfaces with the subsystem 'Rolling stock - locomot stock'

Interface ► M2 Reference in TSI INF ▲

Track gauge

- 4.2.4.1 Nominal track gauge
- 4.2.5.1 Design geometry of switches and crossings
- 4.2.8.6 The immediate action limits for switches and crossings

Gauge

- 4.2.3.1 Structure gauge
- 4.2.3.2 Distance between track centres
- 4.2.3.5 Minimum radius of vertical curve
- 4.2.9.3 Platform offset

Axle load and axle spacing

- 4.2.6.1 Track resistance to vertical loads
- 4.2.6.3 Lateral track resistance
- 4.2.7.1 Resistance of new bridges to traffic loads
- 4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures
- 4.2.7.4 Resistance of existing bridges and earthworks to traffic loads

Running characteristics

- 4.2.6.1 Track resistance to vertical loads
- 4.2.6.3 Lateral track resistance
- 4.2.7.1.4 Nosing forces

Ride stability

- 4.2.4.4 Equivalent conicity
- 4.2.4.6 Railhead profile for plain line
- 4.2.11.2 Equivalent conicity in service

Longitudinal actions

- 4.2.6.2 Longitudinal track resistance
- 4.2.7.1.5 Actions due to traction

INF Subsystem Interfaces

01 Interfaces with the rolling stock subsystem

01 INF - Track gauge

02 INF - Gauge

03 INF - Axle load and axle spacing

04 INF - Running characteristics

05 INF - Ride Stability

01 INF - Equivalent conicity [4.2.4.4]

02 INF - Railhead profile for plain line [4.2.4.6]

03 INF - Equivalent conicity in service [4.2.11.2]

06 INF - Longitudinal actions

07 INF - Minimum horizontal curve radius

08 INF - Running dynamic behaviour

09 INF - Maximum deceleration

10 INF - Aerodynamic effect

11 INF - Crosswind

12 INF - Installations for servicing trains

TSI INF

Interfacing Subsystem

TSI RST (LOC&PAS)

TSI-INF-1.4.2.4.6 4.2.4.6
Railhead profile for plain line

01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]

TSI-LOC&PAS-1.4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

▼B 4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

Table 15

▼M1

▼M2

▼M1

Interfaces with the subsystem 'Rolling stock - locomot stock'

Interface ► M2 Reference in TSI INF ▲

Track gauge

- 4.2.4.1 Nominal track gauge
- 4.2.5.1 Design geometry of switches and crossings
- 4.2.8.6 The immediate action limits for switches and crossings

Gauge

- 4.2.3.1 Structure gauge
- 4.2.3.2 Distance between track centres
- 4.2.3.5 Minimum radius of vertical curve
- 4.2.9.3 Platform offset

Axle load and axle spacing

- 4.2.6.1 Track resistance to vertical loads
- 4.2.6.3 Lateral track resistance
- 4.2.7.1 Resistance of new bridges to traffic loads
- 4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures
- 4.2.7.4 Resistance of existing bridges and earthworks to traffic loads

Running characteristics

- 4.2.6.1 Track resistance to vertical loads
- 4.2.6.3 Lateral track resistance
- 4.2.7.1.4 Nosing forces

Ride stability

- 4.2.4.4 Equivalent conicity
- 4.2.4.6 Railhead profile for plain line
- 4.2.11.2 Equivalent conicity in service

Longitudinal actions

- 4.2.6.2 Longitudinal track resistance
- 4.2.7.1.5 Actions due to traction

INF Subsystem Interfaces

01 Interfaces with the rolling stock subsystem

01 INF - Track gauge

02 INF - Gauge

03 INF - Axle load and axle spacing

04 INF - Running characteristics

05 INF - Ride Stability

01 INF - Equivalent conicity [4.2.4.4]

02 INF - Railhead profile for plain line [4.2.4.6]

03 INF - Equivalent conicity in service [4.2.11.2]

06 INF - Longitudinal actions

07 INF - Minimum horizontal curve radius

08 INF - Running dynamic behaviour

09 INF - Maximum deceleration

10 INF - Aerodynamic effect

11 INF - Crosswind

12 INF - Installations for servicing trains

TSI INF

Interfacing Subsystem

TSI RST (LOC&PAS)

TSI-INF-1.4.2.4.6 4.2.4.6
Railhead profile for plain line

01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]

TSI-LOC&PAS-1.4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: DEPENDENCY MATRIX VIEW (N² CHART VIEW)

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▼ B

4.3. Functional and technical specification of the interfaces
From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

Table 15

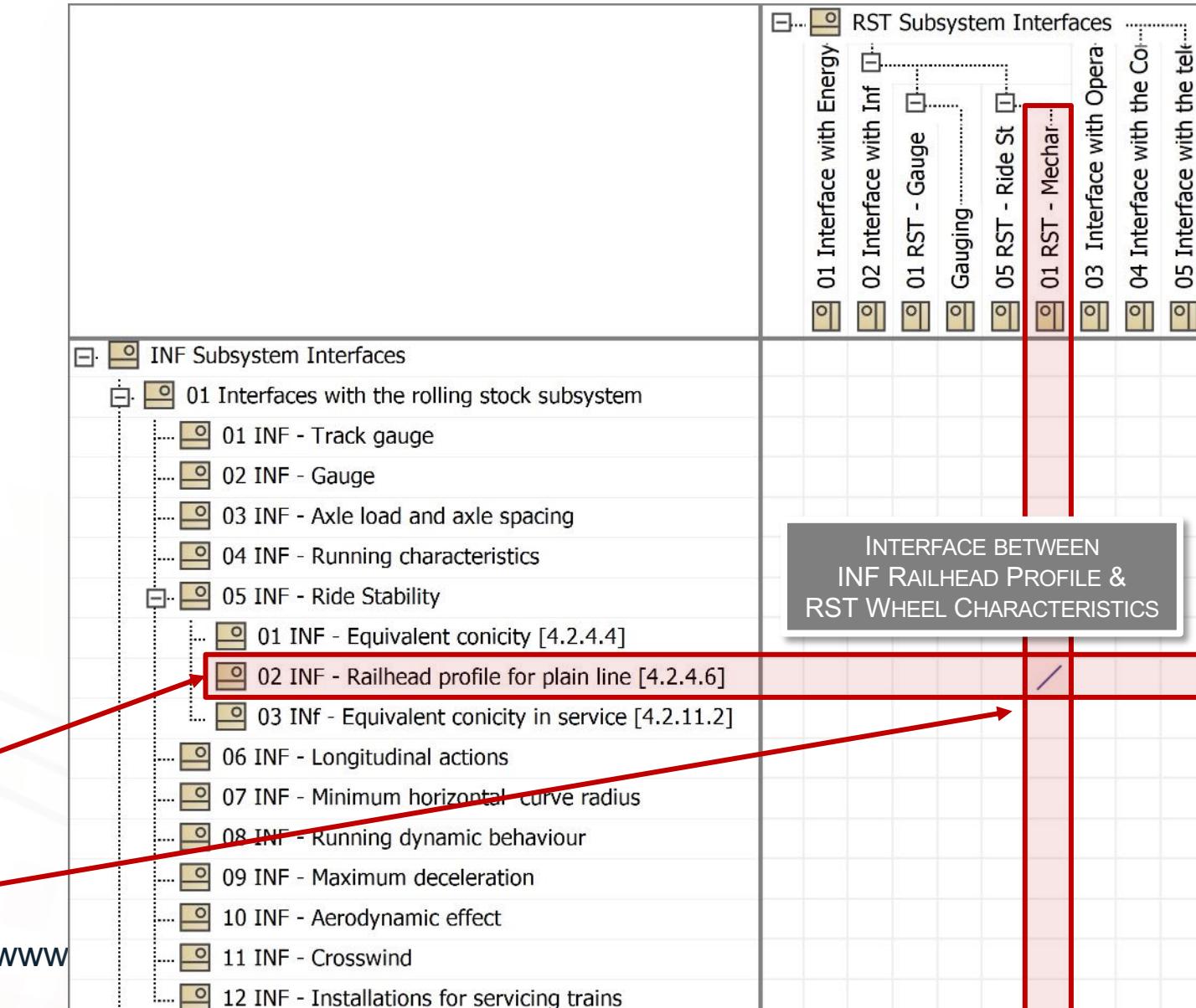
▼ M1

▼ M2

▼ M1

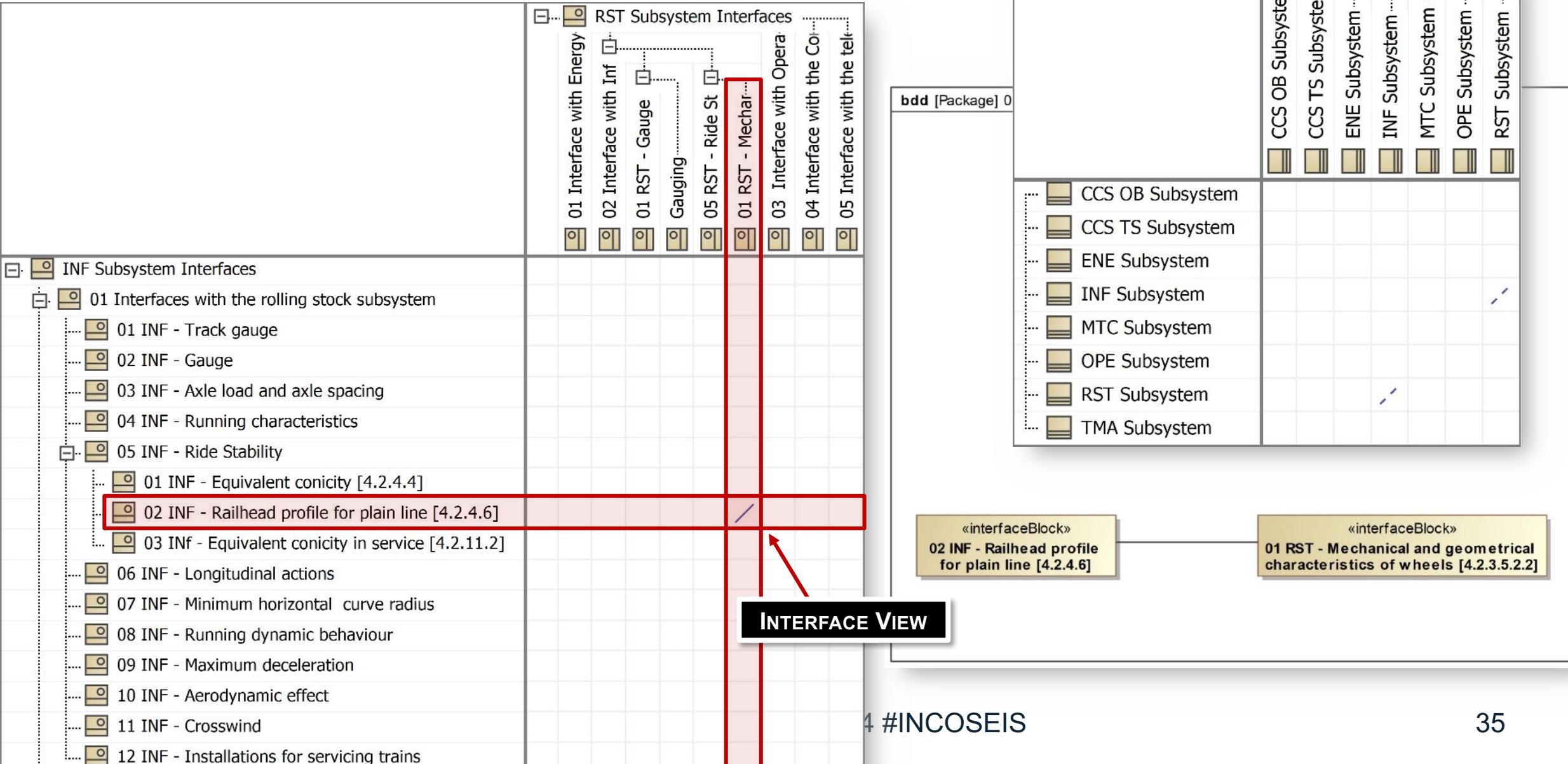
Interfaces with the subsystem 'Rolling stock – locomotives and passenger rolling stock'

Interface	► M2 Reference in TSI INF	► M2 Reference in TSI LOC&PAS
Track gauge	4.2.4.1 Nominal track gauge 4.2.5.1 Design geometry of switches and crossings 4.2.8.6 The immediate action limits for switches and crossings	4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset 4.2.3.5.2.3 Variable gauge wheelsets
Gauge	4.2.3.1 Structure gauge 4.2.3.2 Distance between track centres 4.2.3.5 Minimum radius of vertical curve 4.2.9.3 Platform offset	4.2.3.1 Gauging
Axle load and axle spacing	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1 Resistance of new bridges to traffic loads 4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures 4.2.7.4 Resistance of existing bridges and earthworks to traffic loads	4.2.2.10 Load conditions and weighed mass 4.2.3.2.1 Axle load parameter
Running characteristics	4.2.6.1 Track resistance to vertical loads 4.2.6.3 Lateral track resistance 4.2.7.1.4 Nosing forces	4.2.3.4.2.1 Limit values for running safely 4.2.3.4.2.2 Track loading limit values
Ride stability	4.2.4.4 Equivalent conicity 4.2.4.6 Railhead profile for plain line 4.2.11.2 Equivalent conicity in service	4.2.3.4.3 Equivalent conicity 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels
Longitudinal actions	4.2.6.2 Longitudinal track resistance 4.2.7.1.5 Actions due to traction	4.2.4.5 Braking performance



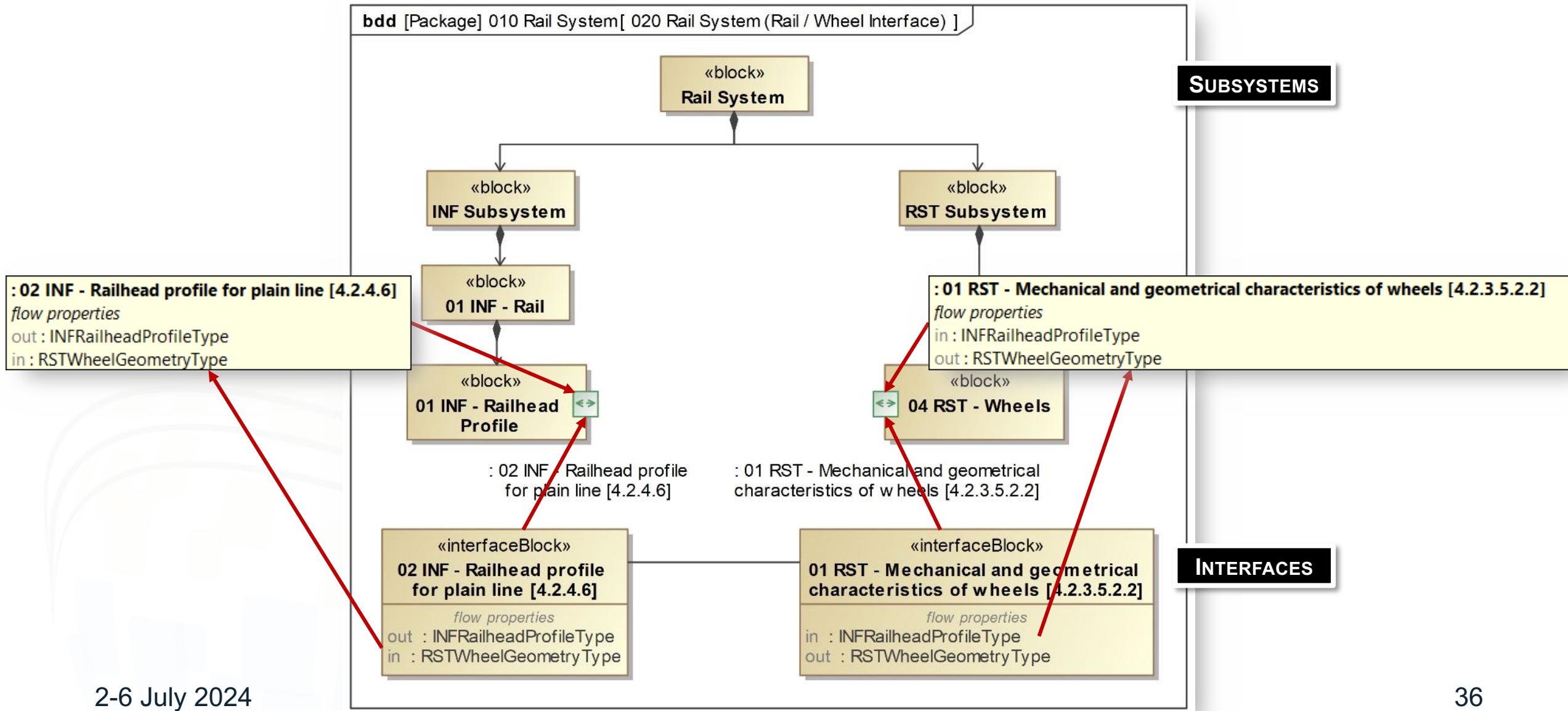
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: SUBSYSTEM ALLOCATION



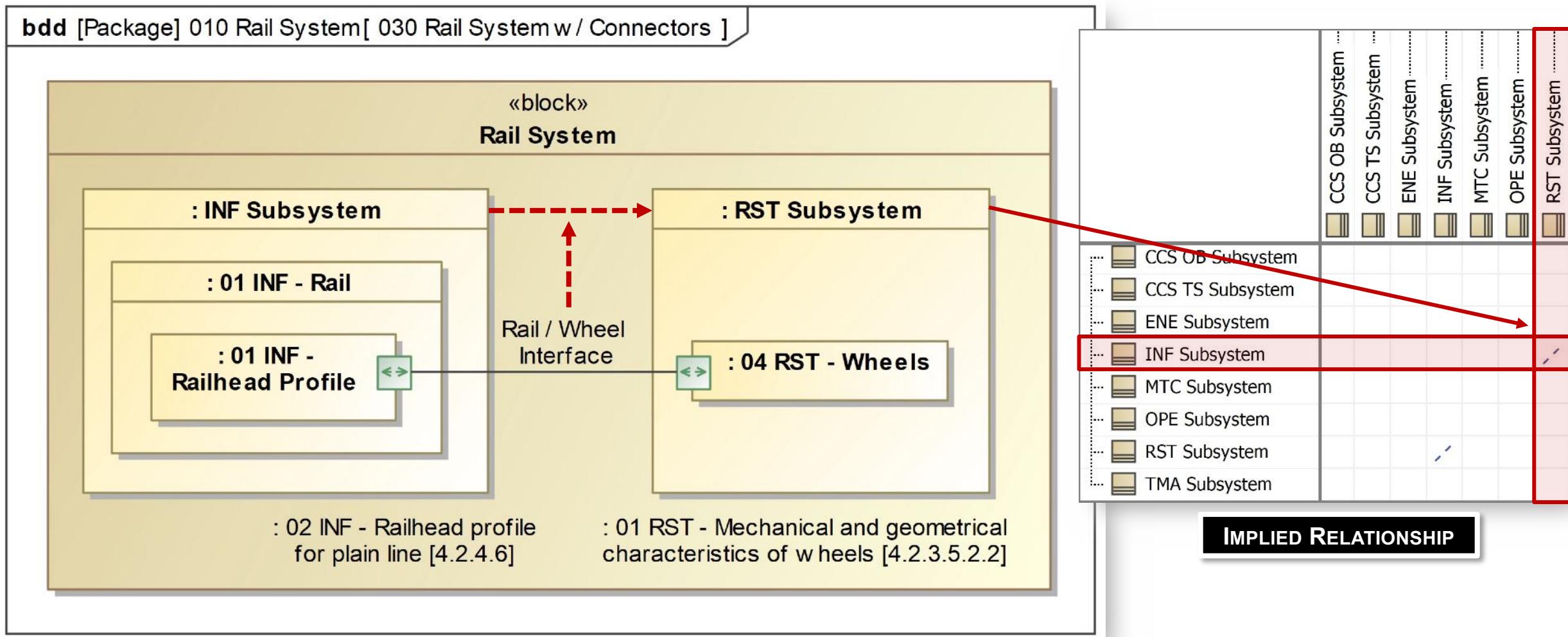
MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: SUBSYSTEM ALLOCATION (CONT'D)



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: RAIL SYSTEM WITH INTERNAL STRUCTURE VIEW



MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE REGISTER: INFRASTRUCTURE VIEW W/ DETAILS (RAIL/WHEEL INTERFACE)

#	△ Nam	VIEWPOINT: INFRASTRUCTURE SUBSYSTEM	Interface Features	Exchange Items	Interfacing Subsystem
1	INF Subsystem Interfaces				
2	01 Interfaces with the rolling stock subsystem	INTERFACE W/ ROLLING STOCK			
3	01 INF - Track gauge				
4	02 INF - Gauge				
5	03 INF - Axle load and axle spacing				
6	04 INF - Running characteristics				
7	05 INF - Ride Stability				
8	01 INF - Equivalent conicity [4.2.4.4]				
9	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	F out : INFRailheadProfileType F in : RSTWheelGeometryType : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	INFRailheadProfileType RSTWheelGeometryType	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
10	03 INF - Infrastructure railhead profile [4.2.11.2]	INFRASTRUCTURE RAILHEAD PROFILE	INTERFACE REQUIREMENTS	INTERFACE FEATURES	EXCHANGE ITEMS
11	06 INF - 1				INTERFACING ROLLING STOCK WHEELSET CHARACTERISTICS
12	07 INF - Minimum horizontal curve radius				
13	08 INF - Running dynamic behaviour				
14	09 INF - Maximum deceleration				
15	10 INF - Aerodynamic effect				
16	11 INF - Crosswind				
17	12 INF - Installations for servicing trains				
18	02 Interfaces with the energy subsystem				
19	03 Interfaces with the control command and signalling subsystem				
20	04 Interfaces with the operation and traffic management subsystem				

MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE REGISTER: BUILDING THE INTERFACE REGISTER

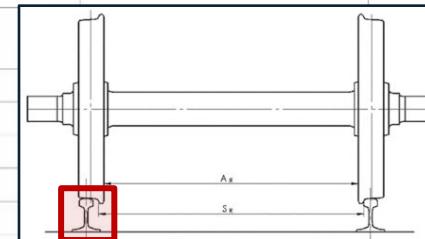
#	Name	Interface Requirements	Interface Features	Notes
1	INF Subsystem Interfaces			
2	01 Interfaces with the rolling stock subsystem			
3	01 INF - Track gauge			
4	01 INF - Nominal track gauge [4.2.4.1]			
5	02 INF - Design geometry of switches and Crossings [4.2.5.1]			
6	03 INF - The immediate action limits for switches and crossings [4.2.8.6]			
7	02 INF - Gauge			
8	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	[F] out : INFStructureGaugeType [F] in : RSTKinematicGaugeType [R] : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	[R] 01 RST - Rolling stock kinematic gauge [4.2.3.1]
9	02 INF - Distance between track centres [4.2.3.2]			
10	03 INF - Minimum radius of vertical curve [4.2.3.5]			
11	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	[F] out : INFPlatformOffsetType [F] in : RSTKinematicGaugeType [R] : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	[R] 01 RST - Rolling stock kinematic gauge [4.2.3.1]
12	03 INF - Axle load and axle spacing			
13	01 INF - Track resistance to vertical loads [4.2.6.1]			
14	02 INF - Lateral track resistance [4.2.6.3]			
15	03 INF - Resistance of new bridges to traffic loads [4.2.7.1]			
16	04 INF - Equivalent vertical loading for new earthworks and pressure effects imposed on new structures [4.2.7.2]			
17	05 INF - Resistance of existing bridges and earthworks to traffic [4.2.7.4]			
18	04 INF - Running characteristics			
19	01 INF - Track resistance to vertical loads [4.2.6.1]			
20	02 INF - Lateral track resistance [4.2.6.3]			
21	03 INF - Nosing forces [4.2.7.1.4]			
22	05 INF - Ride Stability			
23	01 INF - Equivalent conicity [4.2.4.4]			
24	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	[F] out : INFRailheadProfileType [F] in : RSTWheelGeometryType [R] : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	[R] 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
25	03 INF - Equivalent conicity in service [4.2.11.2]			
26	06 INF - Longitudinal actions			

'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



How a French rail company spent £12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you



[R] INFRailheadProfileType
[R] RSTWheelGeometryType

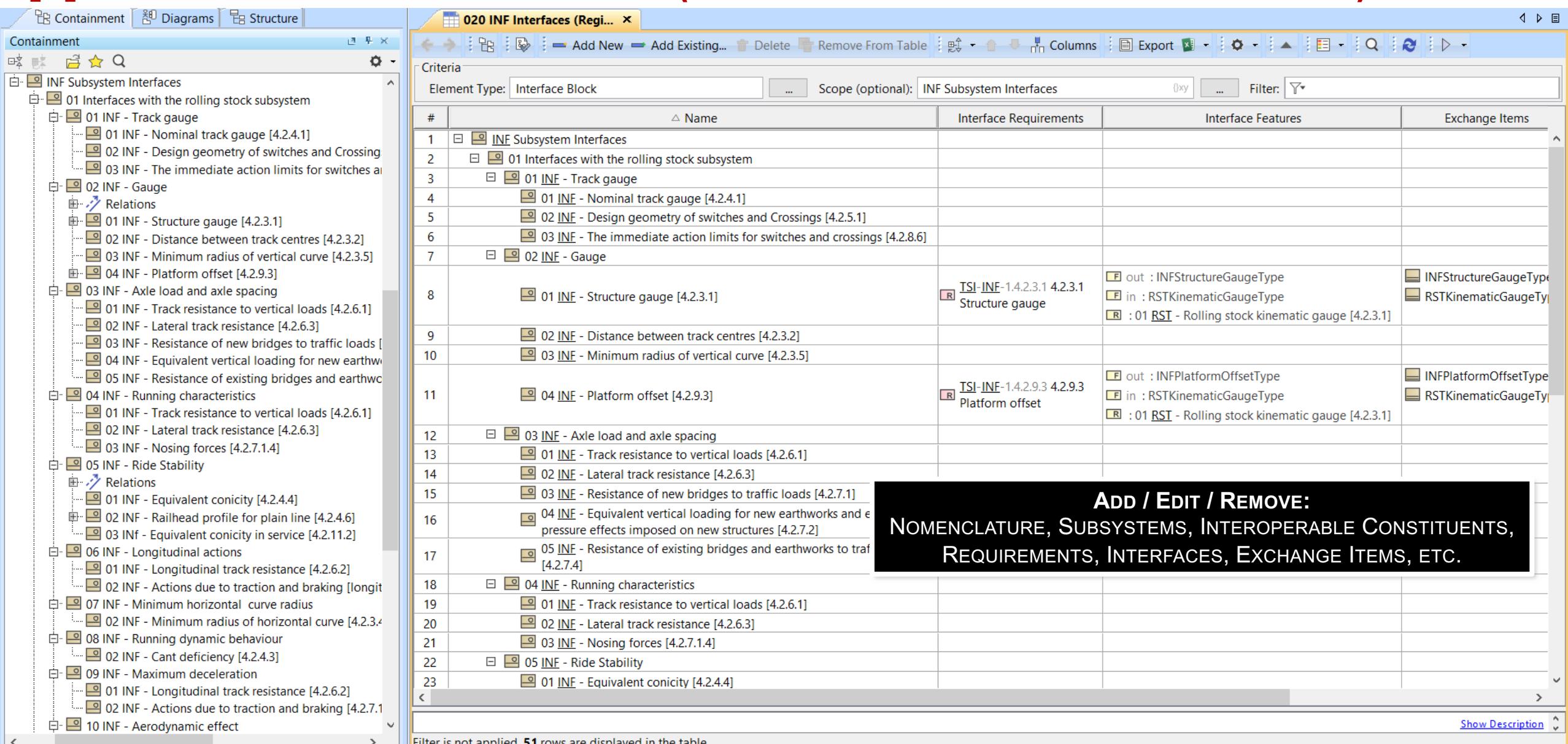
[R] 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]

PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
 - Option #1: Use as Template
 - Option #2: Use as Library
 - Option #3: Customize & Taylor
- ❖ **Summary & Conclusion**

MBSI FRAMEWORK USE

[1] USE AS TEMPLATE: DIRECT EDIT (E.G., PROJECT SPECIFIC APPLICATION)



Containment Diagrams Structure

Containment

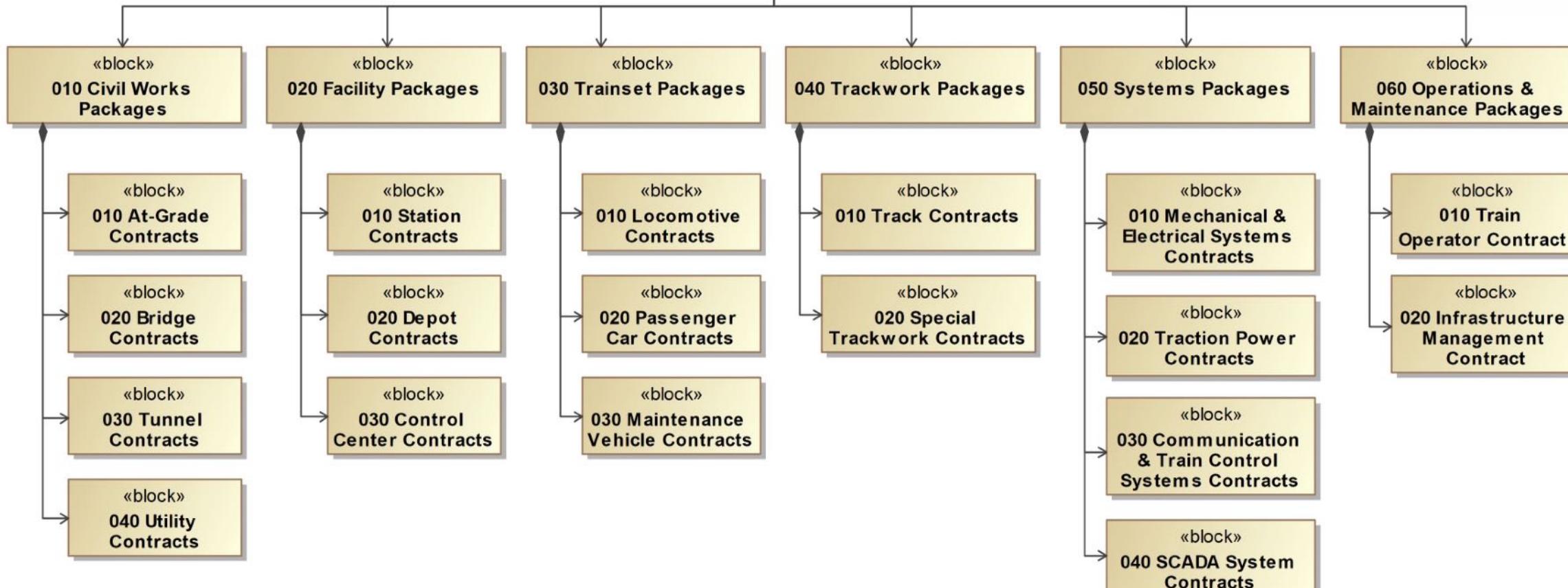
INF Subsystem Interfaces

- 01 Interfaces with the rolling stock subsystem
 - 01 INF - Track gauge
 - 01 INF - Nominal track gauge [4.2.4.1]
 - 02 INF - Design geometry of switches and Crossings
 - 03 INF - The immediate action limits for switches and crossings
 - 02 INF - Gauge
 - 01 INF - Structure gauge [4.2.3.1]
 - 02 INF - Distance between track centres [4.2.3.2]
 - 03 INF - Minimum radius of vertical curve [4.2.3.5]
 - 04 INF - Platform offset [4.2.9.3]
 - 03 INF - Axle load and axle spacing
 - 01 INF - Track resistance to vertical loads [4.2.6.1]
 - 02 INF - Lateral track resistance [4.2.6.3]
 - 03 INF - Resistance of new bridges to traffic loads [4.2.7.1]
 - 04 INF - Equivalent vertical loading for new earthworks and structures [4.2.7.2]
 - 05 INF - Resistance of existing bridges and earthworks to traffic loads [4.2.7.4]
 - 04 INF - Running characteristics
 - 01 INF - Track resistance to vertical loads [4.2.6.1]
 - 02 INF - Lateral track resistance [4.2.6.3]
 - 03 INF - Nosing forces [4.2.7.1.4]
 - 05 INF - Ride Stability
 - 01 INF - Equivalent conicity [4.2.4.4]
 - 02 INF - Railhead profile for plain line [4.2.4.6]
 - 03 INF - Equivalent conicity in service [4.2.11.2]
 - 06 INF - Longitudinal actions
 - 01 INF - Longitudinal track resistance [4.2.6.2]
 - 02 INF - Actions due to traction and braking [longitudinal]
 - 07 INF - Minimum horizontal curve radius
 - 02 INF - Minimum radius of horizontal curve [4.2.3.4]
 - 08 INF - Running dynamic behaviour
 - 02 INF - Cant deficiency [4.2.4.3]
 - 09 INF - Maximum deceleration
 - 01 INF - Longitudinal track resistance [4.2.6.2]
 - 02 INF - Actions due to traction and braking [4.2.7.1]
 - 10 INF - Aerodynamic effect

ADD / EDIT / REMOVE:
NOMENCLATURE, SUBSYSTEMS, INTEROPERABLE CONSTITUENTS,
REQUIREMENTS, INTERFACES, EXCHANGE ITEMS, ETC.

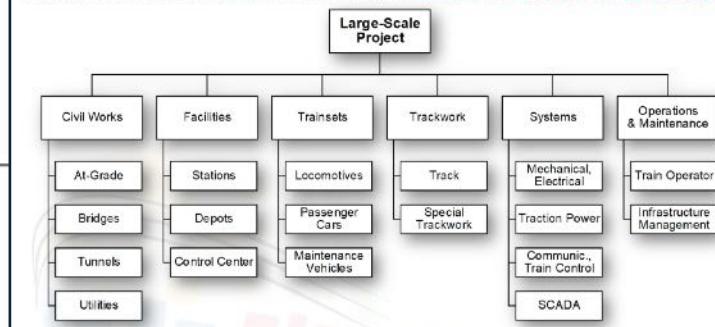
MBSI FRAMEWORK USE

[2] USE AS LIBRARY: CONTRACT BREAKDOWN STRUCTURE



BACKGROUND & CHALLENGES

LARGE-SCALE PROJECTS: INDUSTRY TYPICAL CONTRACT BREAKDOWN STRUCTURE



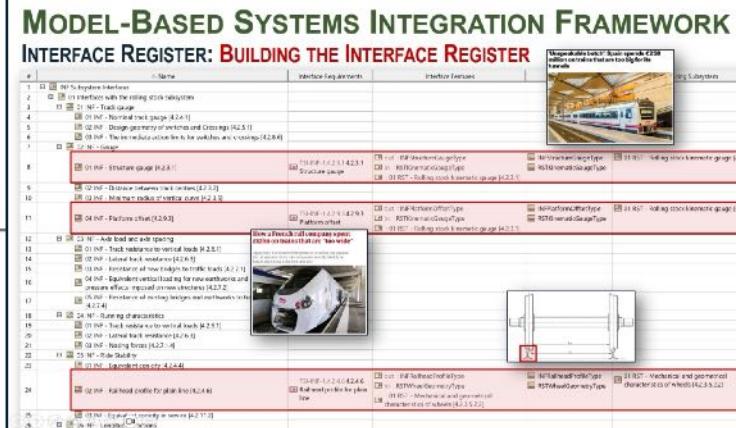
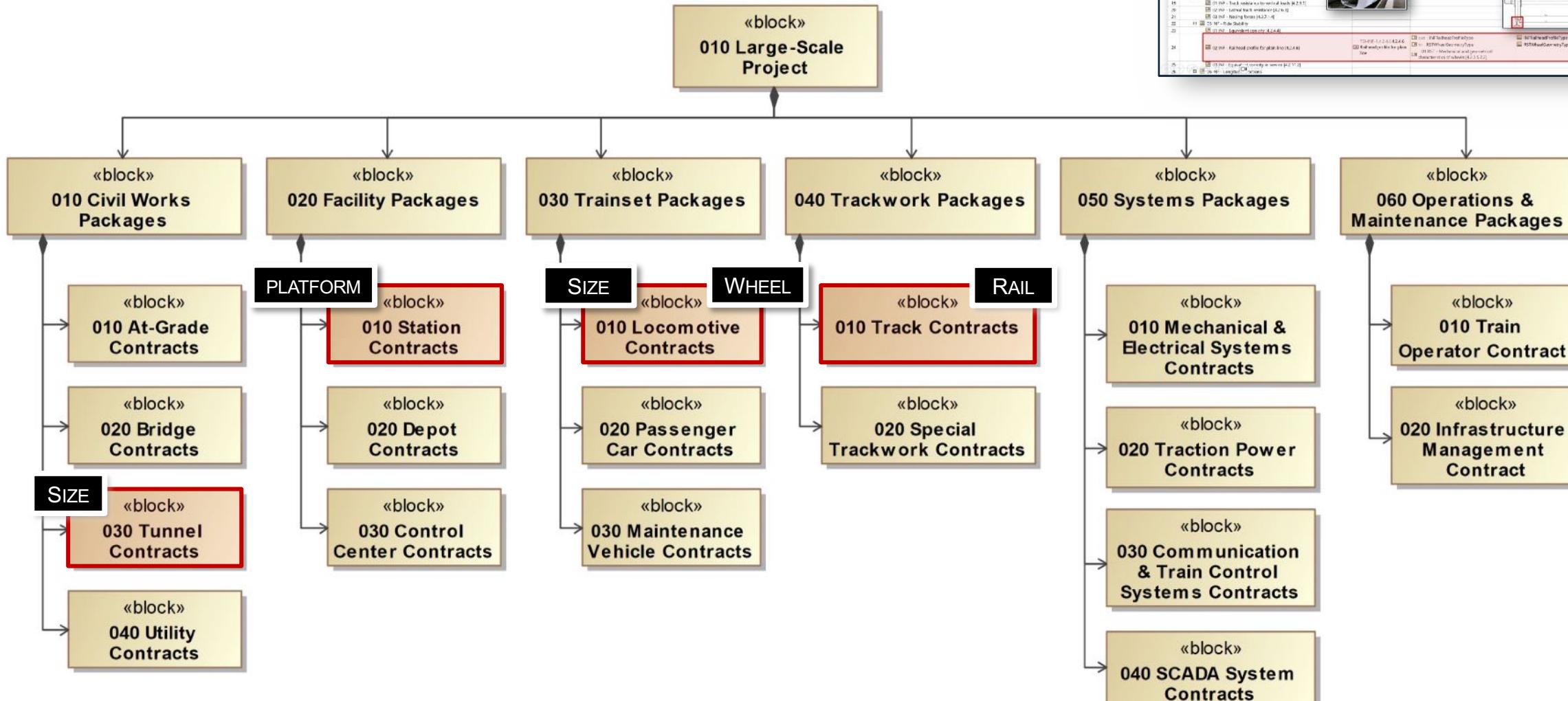
2-6 July 202

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MBSI FRAMEWORK USE

[2] USE AS LIBRARY: INTERFACE EXAMPLE CHALLENGES

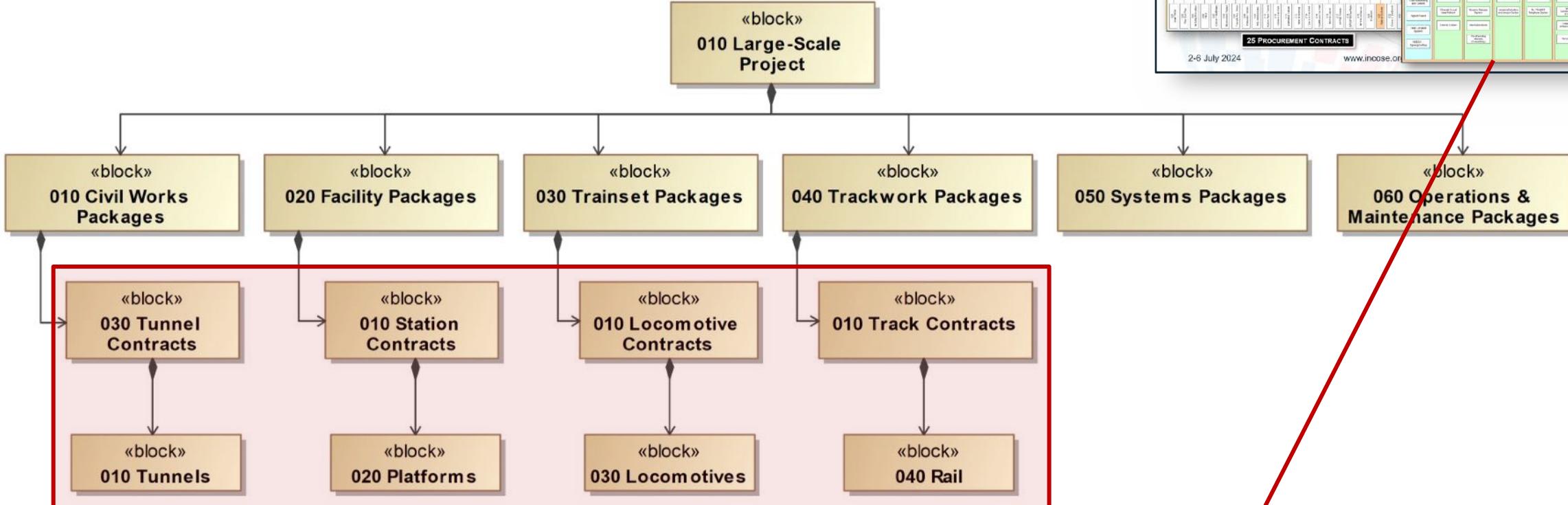
package 020 Contract Breakdown n Structure [010 Contract Breakdown Structure]



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: SYSTEM BREAKDOWN STRUCTURE

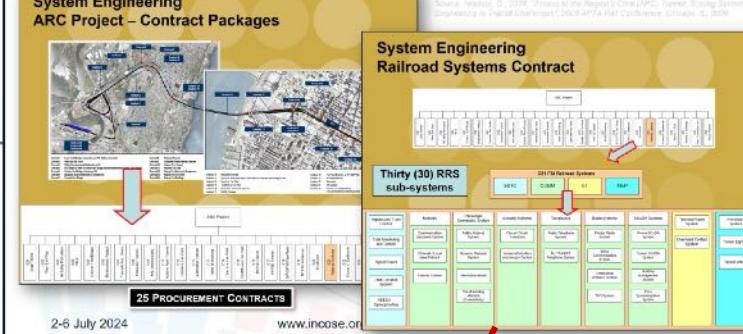
package 030 System Breakdown Structure [ 010 System Breakdown Structure]



BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: EXAMPLE – ARC TUNNEL PROJECT

System Engineering
ARC Project – Contract Packages

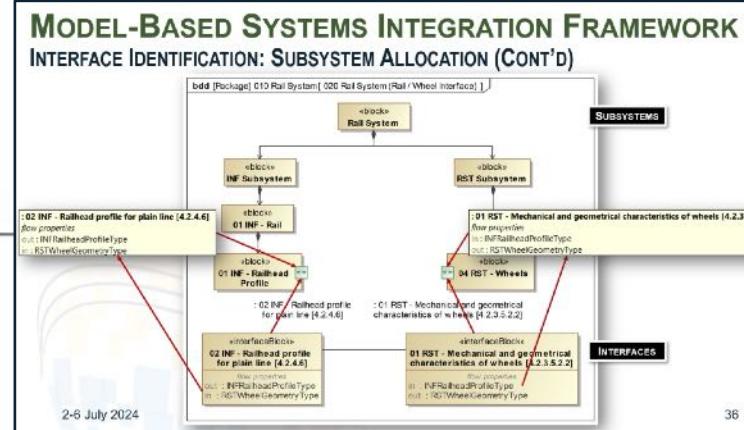
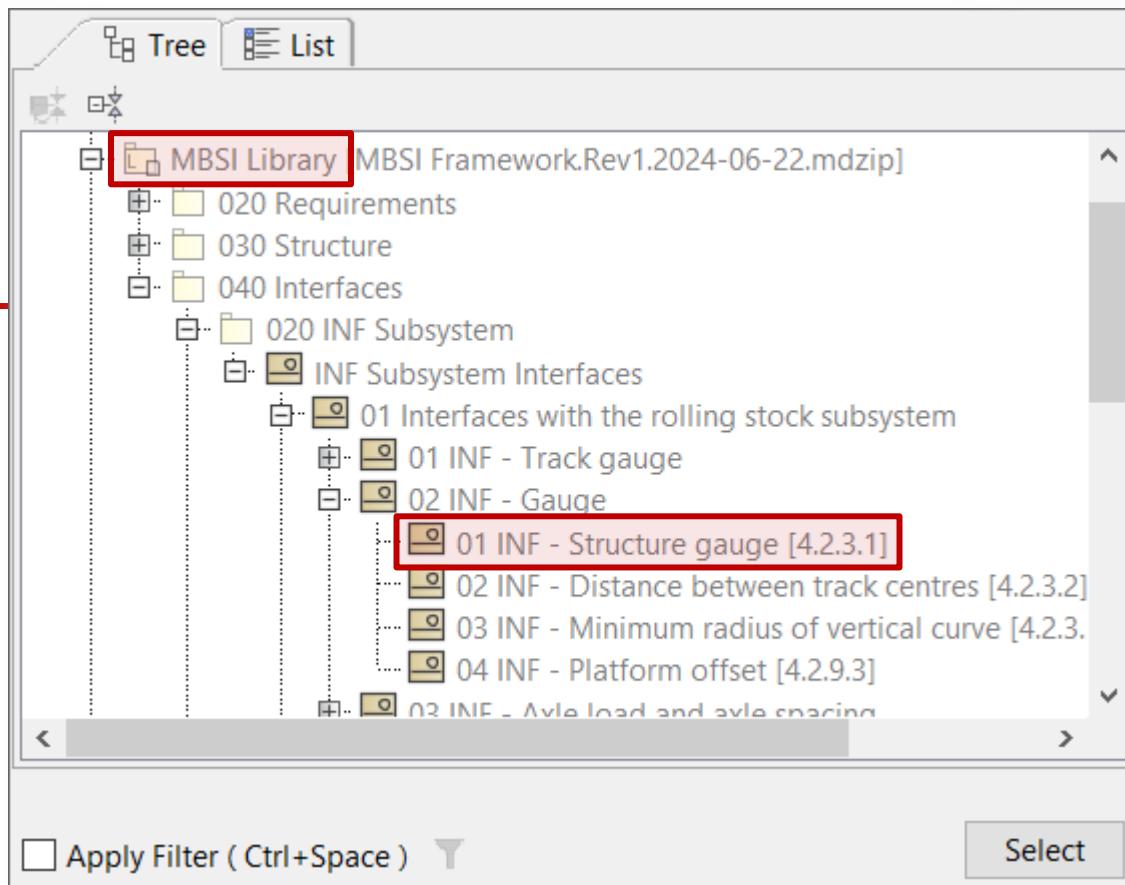
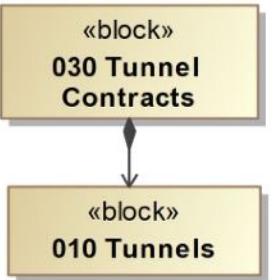


DUE TO STAGGERED CONTRACT PROCUREMENTS,
SYSTEM BREAKDOWN IS OFTEN PERFORMED
BY CONTRACT PACKAGE (BETTER: BY LARGE-
SCALE PROJECT w/ CONTRACT ALLOCATION)

MBSI FRAMEWORK USE

[2] USE AS LIBRARY: INTERFACE ALLOCATION

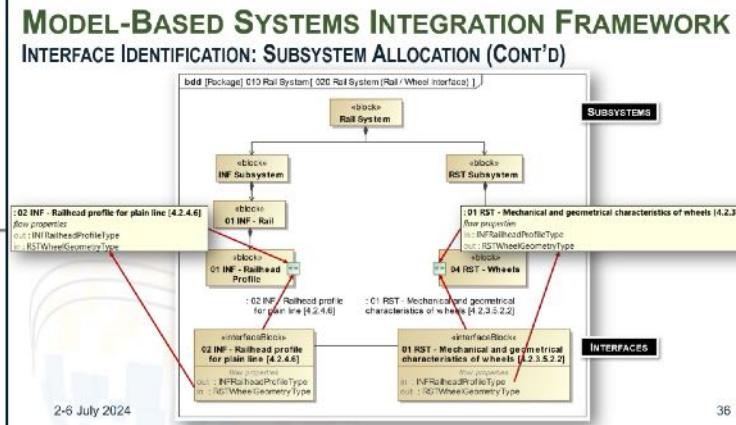
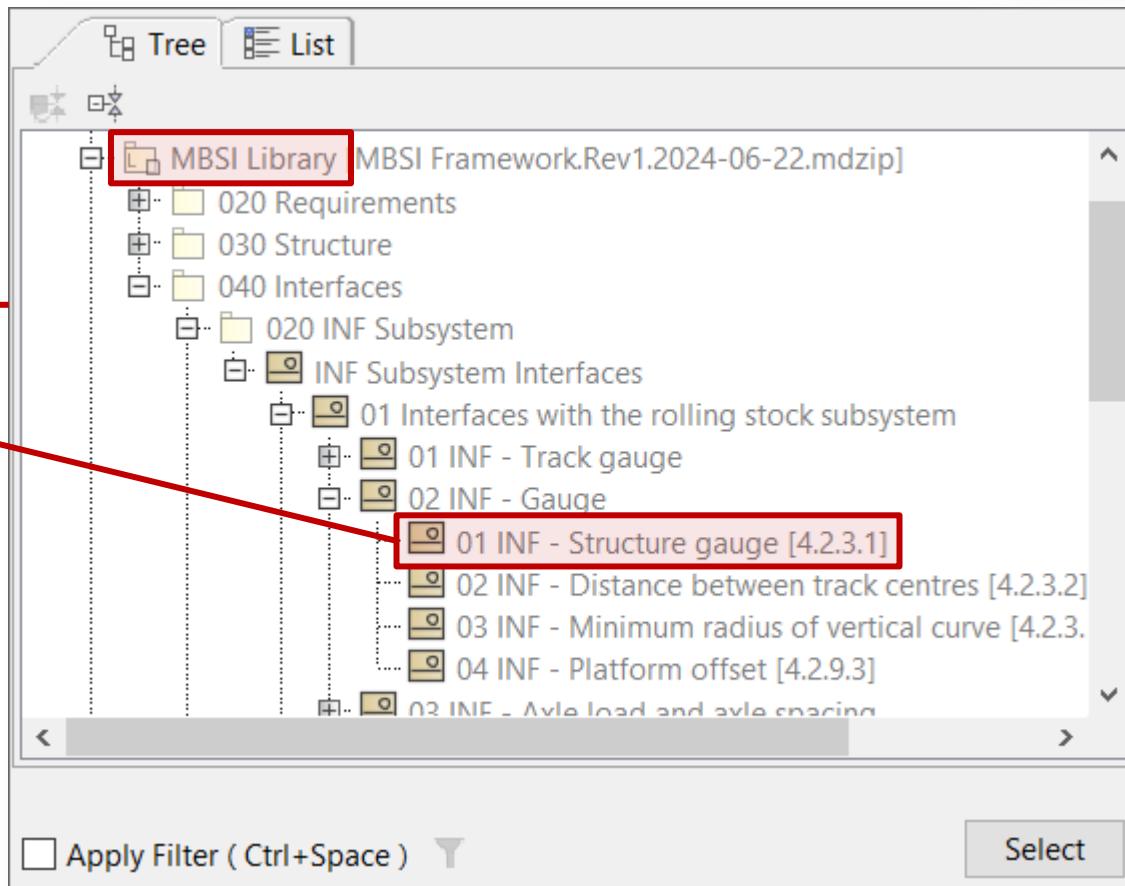
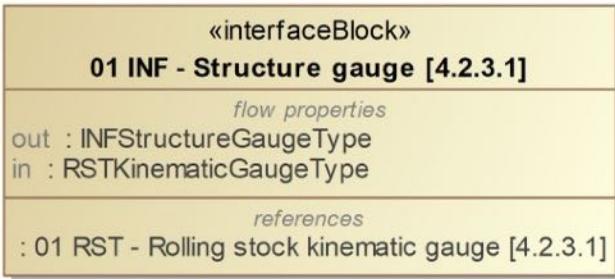
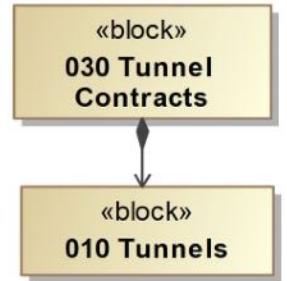
package 040 Interfaces [010 Interface Allocation]



MBSI FRAMEWORK USE

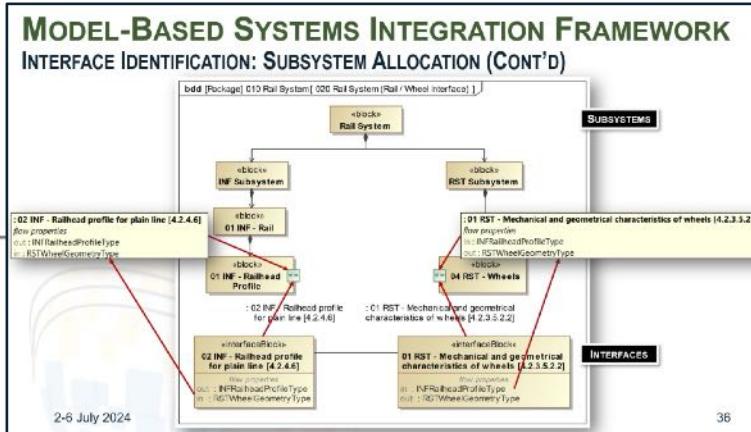
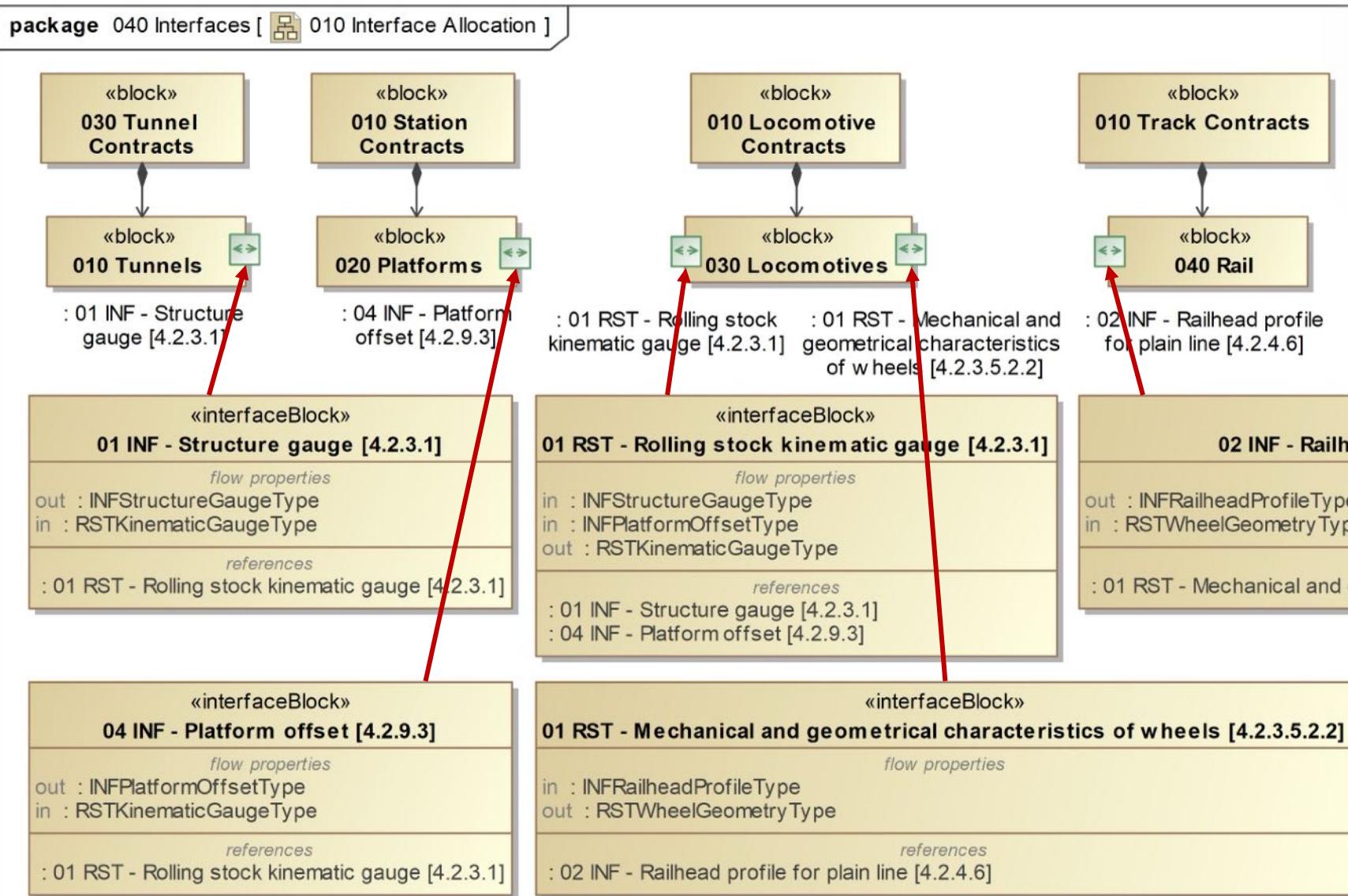
[2] USE AS LIBRARY: INTERFACE ALLOCATION (CONT'D)

package 040 Interfaces [010 Interface Allocation]



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: INTERFACE ALLOCATION (CONT'D)



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: CONTRACT INTERFACE MATRIX (N² CHART)

	020 Civil Works Contracts	010 At-Grade Contracts	020 Bridge Contracts	030 Tunnel Contracts	040 Utility Contracts	030 Facilities Contracts	010 Station Contracts	020 Depot Contracts	030 Control Center Contracts	040 Trainset Contracts	010 Locomotive Contracts	020 Passenger Car Contracts	030 Maintenance Vehicle Contracts	050 Trackwork Contracts	010 Track Contracts	020 Special Trackwork Contracts
020 Civil Works Contracts																
010 At-Grade Contracts																
020 Bridge Contracts																
030 Tunnel Contracts																
040 Utility Contracts																
030 Facilities Contracts																
010 Station Contracts																
020 Depot Contracts																
030 Control Center Contracts																
040 Trainset Contracts																
010 Locomotive Contracts																
020 Passenger Car Contracts																
030 Maintenance Vehicle Contracts																
050 Trackwork Contracts																
010 Track Contracts																
020 Special Trackwork Contracts																

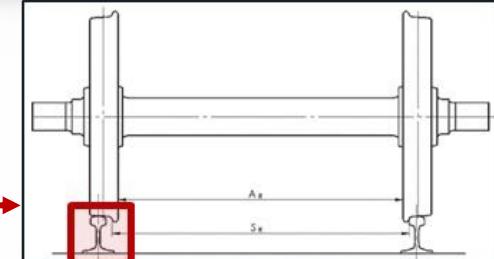


How a French rail company spent £12bn on trains that are "too wide"

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SEIS



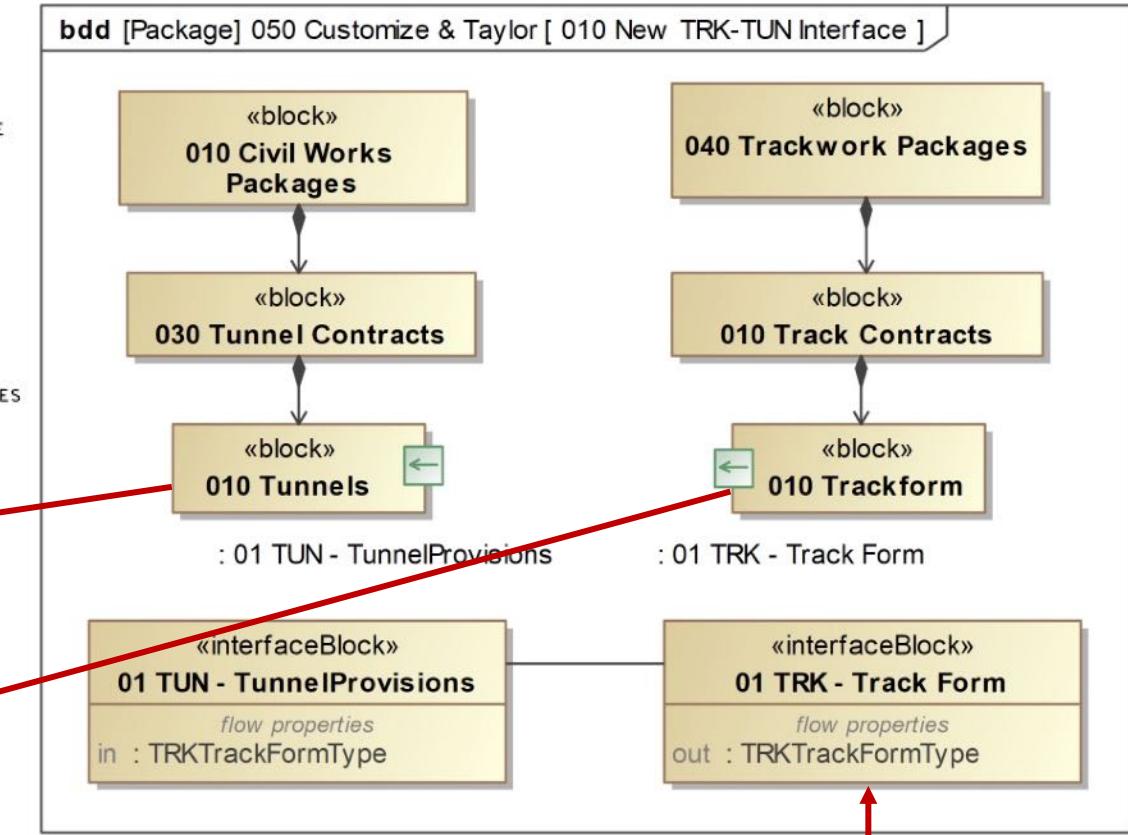
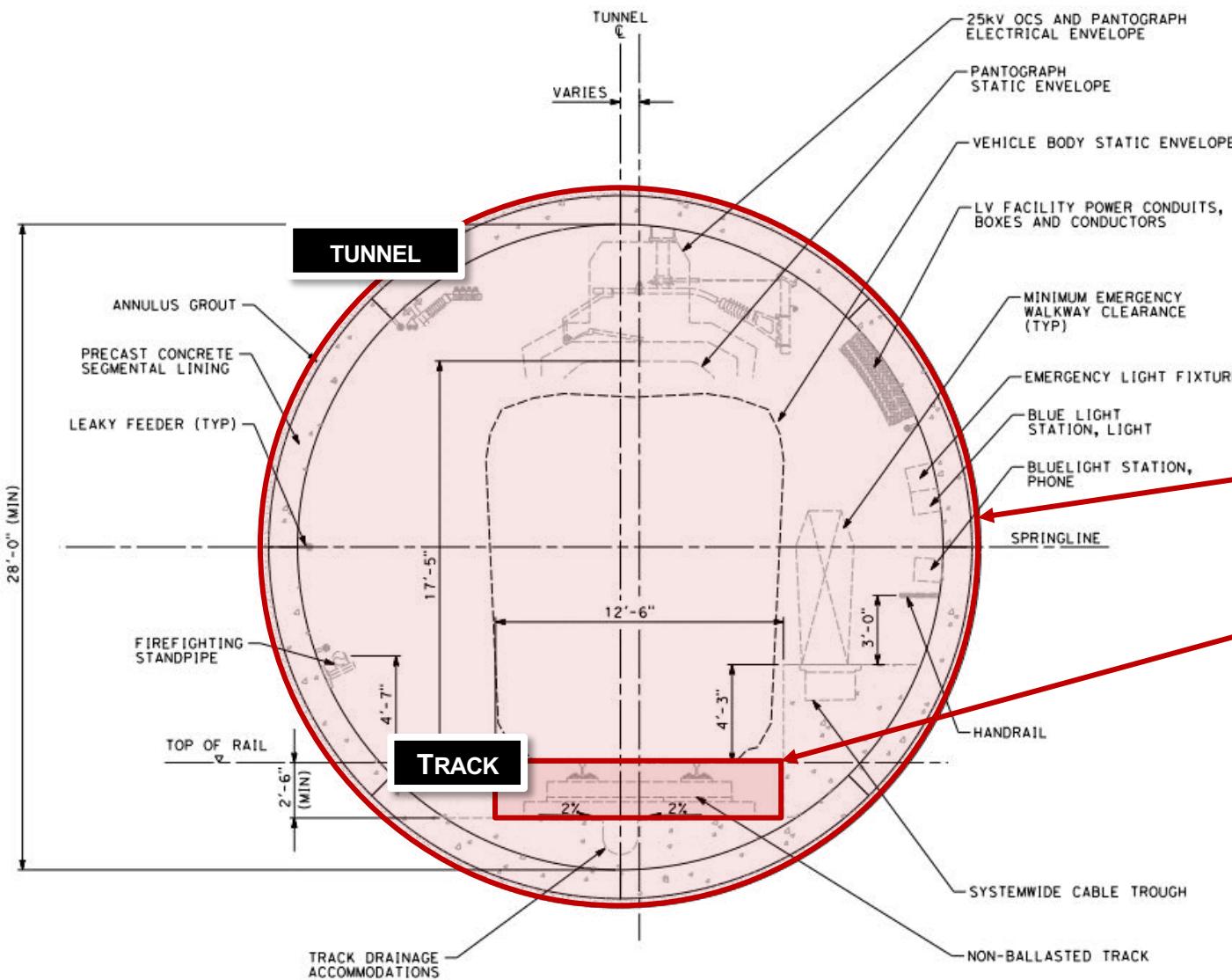
MBSI FRAMEWORK USE

[2] USE AS LIBRARY: CONTRACT SPECIFIC INTERFACE REGISTER

#	Name	System Elements	Interfaces	Interface Requirements	Interface Features
1	020 Civil Works				
2	010 At-Grade				
3	020 Bridge Contracts				
4	030 Tunnel Contracts	010 Tunnels	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	<input type="checkbox"/> out : INFStructureGaugeType <input type="checkbox"/> in : RSTKinematicGaugeType <input type="checkbox"/> : 01 RST - Rolling stock kinematic gauge [4.2.3.1]
5	040 Utility Contracts				
6	030 Facilities Contracts				
7	010 Station Contracts	020 Platforms	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	<input type="checkbox"/> out : INFPlatformOffsetType <input type="checkbox"/> in : RSTKinematicGaugeType <input type="checkbox"/> : 01 RST - Rolling stock kinematic gauge [4.2.3.1]
8	020 Depot Contracts				
9	030 Control Center Contracts				
10	040 Trainset Contracts				
11	010 Locomotive Contracts	030 Locomotives	01 RST - Rolling stock kinematic gauge [4.2.3.1] 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	TSI-LOC&PAS-1.4.2.3.14.2.3.1. Gauging	<input type="checkbox"/> in : INFStructureGaugeType <input type="checkbox"/> in : INFPlatformOffsetType <input type="checkbox"/> out : RSTKinematicGaugeType <input type="checkbox"/> : 01 INF - Structure gauge [4.2.3.1] <input type="checkbox"/> : 04 INF - Platform offset [4.2.9.3] <input type="checkbox"/> in : INFRailheadProfileType <input type="checkbox"/> out : RSTWheelGeometryType <input type="checkbox"/> : 02 INF - Railhead profile for plain line [4.2.4.6]
12	020 Passenger Car Contracts				
13	030 Maintenance Vehicle Contracts				
14	050 Trackwork Contracts				
15	010 Track Contracts	040 Rail	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	<input type="checkbox"/> out : INFRailheadProfileType <input type="checkbox"/> in : RSTWheelGeometryType <input type="checkbox"/> : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
16	020 Special Trackwork Contracts				

MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: ADDING NEW, PROJECT-SPECIFIC INTERFACE(S)



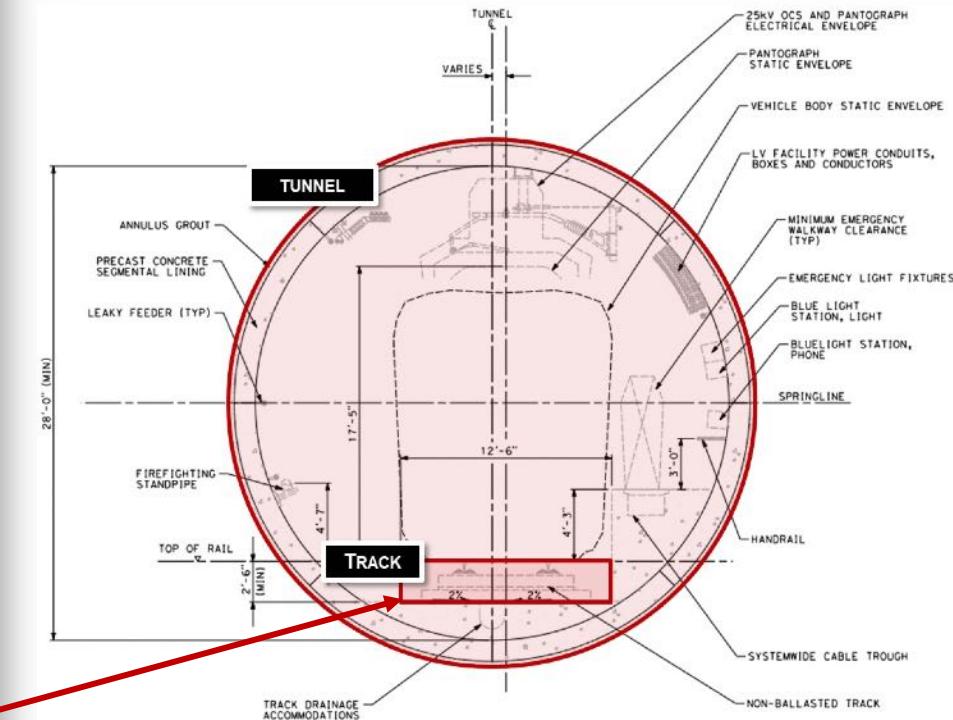
Source/Credit: <http://www.railway-fasteners.com/news/ballasted-track-non-ballasted-track-comparison.html>



MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: CONTRACT INTERFACE MATRIX (N² CHART)

	020 Civil Works Cont	010 At-Grade Contra	020 Bridge Contract	030 Tunnel Contract	040 Utility Contracts	030 Facilities Contract	010 Station Contract	020 Depot Contracts	030 Control Center C	040 Trainset Contract	010 Locomotive Con	020 Passenger Car C	030 Maintenance Ve	050 Trackwork Cont	010 Track Contracts	020 Special Trackwo
020 Civil Works Contracts																
010 At-Grade Contracts																
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040 Trainset Contracts																
010 Locomotive Contracts																
020 Passenger Car Contracts																
030 Maintenance Vehicle Contracts																
050 Trackwork Contracts																
010 Track Contracts	1															
020 Special Trackwork Contracts																



MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: ADDING PROJECT-SPECIFIC INTERFACE REQUIREMENTS

#	Name	Interface Requirements	Interface Features	Exchange Items	Interfacing Subsystem
1	01 INF - Structure gauge [4.2.3.1]	TSI-INF-1.4.2.3.1 4.2.3.1 Structure gauge	[F] out : INFStructureGaugeType [F] in : RSTKinematicGaugeType [R] : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFStructureGaugeType RSTKinematicGaugeType	01 RST - Rolling stock kinematic gauge [4.2.3.1]
2	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	LOC&PAS-TSI-1.4.2.3.5.2.2 4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels	[F] in : INFRailheadProfileType [F] out : RSTWheelGeometryType [R] : 02 INF - Railhead profile for plain line [4.2.4.6]	INFRailheadProfileType RSTWheelGeometryType	02 INF - Railhead profile for plain line [4.2.4.6]
3	01 RST - Rolling stock kinematic gauge [4.2.3.1]	LOC&PAS-TSI-1.4.2.3.1 4.2.3.1. Gauging	[F] in : INFStructureGaugeType [F] in : INFPlatformOffsetType [F] out : RSTKinematicGaugeType [R] : 01 INF - Structure gauge [4.2.3.1] [R] : 04 INF - Platform offset [4.2.9.3]	INFStructureGaugeType INFPlatformOffsetType RSTKinematicGaugeType	01 INF - Structure gauge [4.2.3.1] 04 INF - Platform offset [4.2.9.3]
4	01 TRK - Track Form	DEFINE CONTRACT -SPECIFIC INTERFACE REQUIREMENTS			01 TUN - TunnelProvisions
5	02 INF - Railhead profile for plain line [4.2.4.6]	TSI-INF-1.4.2.4.6 4.2.4.6 Railhead profile for plain line	[F] out : INFRailheadProfileType [F] in : RSTWheelGeometryType [R] : 01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]	INFRailheadProfileType RSTWheelGeometryType	01 RST - Mechanical and geometrical characteristics of wheels [4.2.3.5.2.2]
6	04 INF - Platform offset [4.2.9.3]	TSI-INF-1.4.2.9.3 4.2.9.3 Platform offset	[F] out : INFPlatformOffsetType [F] in : RSTKinematicGaugeType [R] : 01 RST - Rolling stock kinematic gauge [4.2.3.1]	INFPlatformOffsetType RSTKinematicGaugeType	01 RST - Rolling stock kinematic gauge [4.2.3.1]



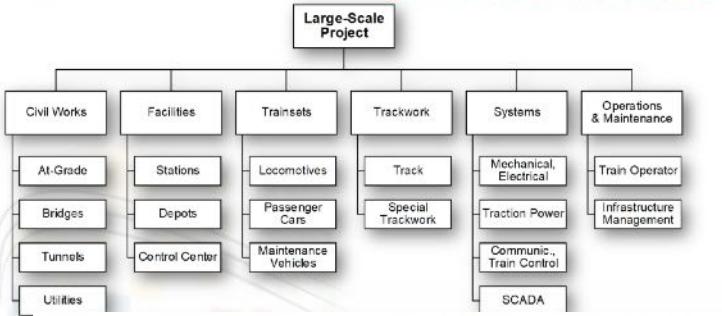
PROGRESS

- ❖ **Motivation**
- ❖ **Background, Challenges & Objectives**
- ❖ **Model-Based Systems Integration Framework**
- ❖ **MBSI Framework Development**
- ❖ **MBSI Framework Use**
- ❖ **Summary & Conclusion**

SUMMARY & CONCLUSION

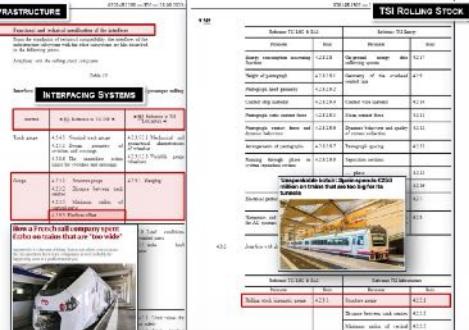
BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INDUSTRY TYPICAL CONTRACT BREAKDOWN STRUCTURE



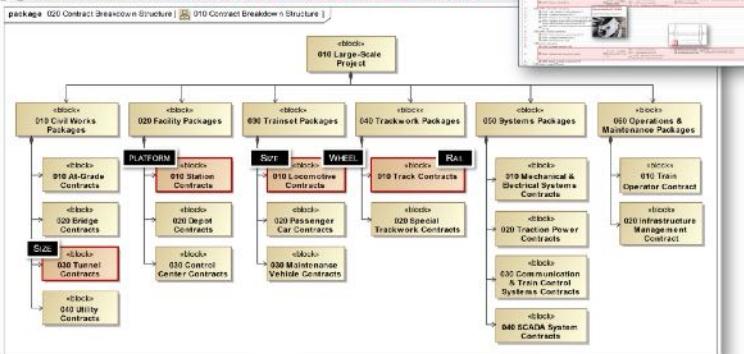
2. MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI) – KEY INTERFACES



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: INTERFACE EXAMPLE CHALLENGES



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BACKGROUND, CHALLENGES & OBJECTIVES

LARGE-SCALE PROJECTS: INTERFACE MANAGEMENT REALITIES

How a French rail company spent €12bn on trains that are "too wide"

Apparently, it's the sort of thing that occurs when you separate the rail operators from train companies, so will probably be happening soon at a platform near you.

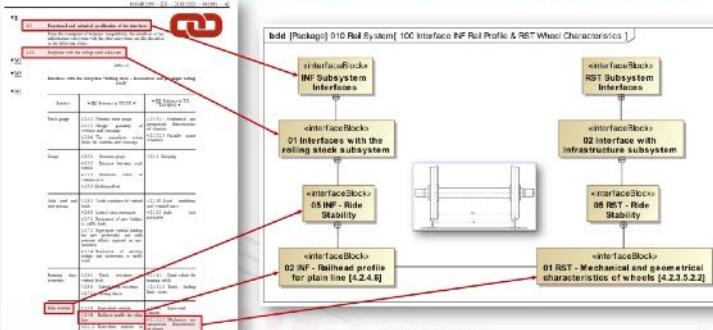


'Unspeakable botch': Spain spends €258 million on trains that are too big for its tunnels



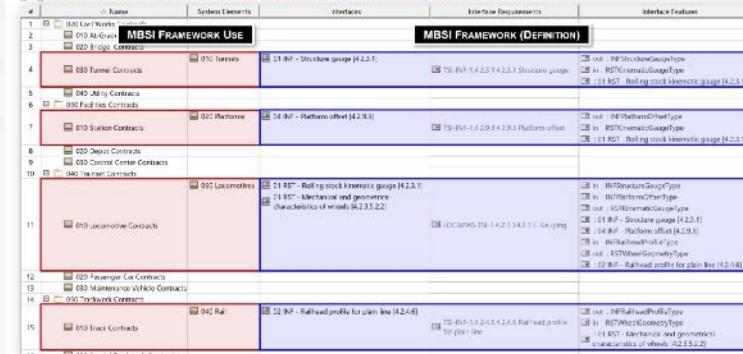
2. MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE IDENTIFICATION: CREATING INTERFACE TABLES IN MBSI FRAMEWORK



MBSI FRAMEWORK USE

[2] USE AS LIBRARY: CONTRACT SPECIFIC INTERFACE REGISTER



BACKGROUND, CHALLENGES & OBJECTIVES

OBJECTIVES: PREDICTABLE, REPEATABLE PROCESS, CONVENIENT, INTEROPERABLE

CMMI Level 1: Initial

- Unpredictable Processes, relying on SME Expertise (or Lack Thereof)

CMMI Level 2: Managed

- Repeatable Processes w/in Project

CMMI Level 3: Defined

- Repeatable Processes w/in Organization
- Project Tailors Processes from Organizational Standards

CONCLUSION

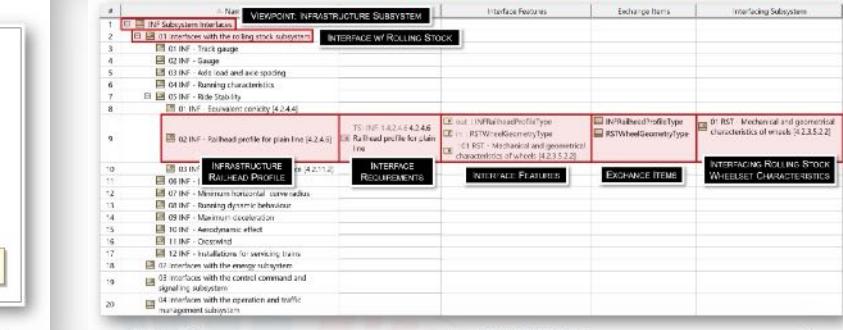


Additional Objectives

- Convenience: Ready (Easy) to Use
- Interoperable: Compatible w/ Future Contracts

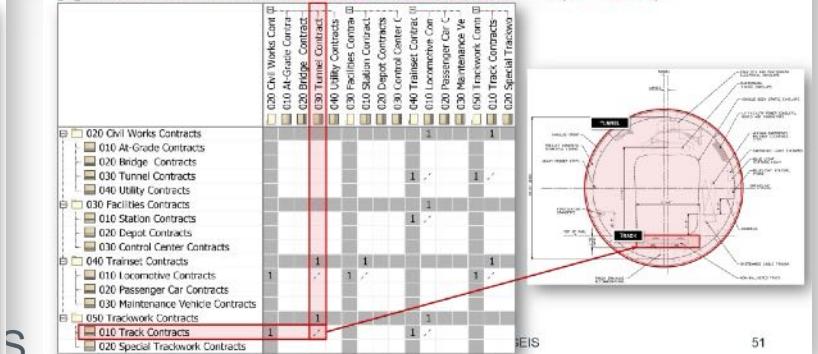
2. MODEL-BASED SYSTEMS INTEGRATION FRAMEWORK

INTERFACE REGISTER: INFRASTRUCTURE VIEW w/ DETAILS (RAIL/WHEEL INTERFACE)



MBSI FRAMEWORK USE

[3] CUSTOMIZE & TAYLOR: CONTRACT INTERFACE MATRIX (N² CHART)



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international symposium

hybrid event

Dublin, Ireland
July 2 - 6, 2024

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